Dynamics of the model with parameters
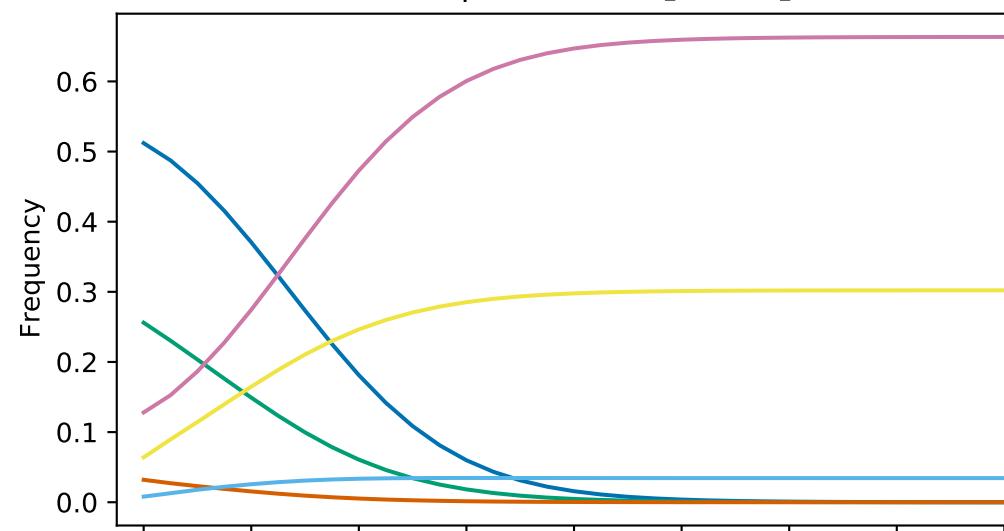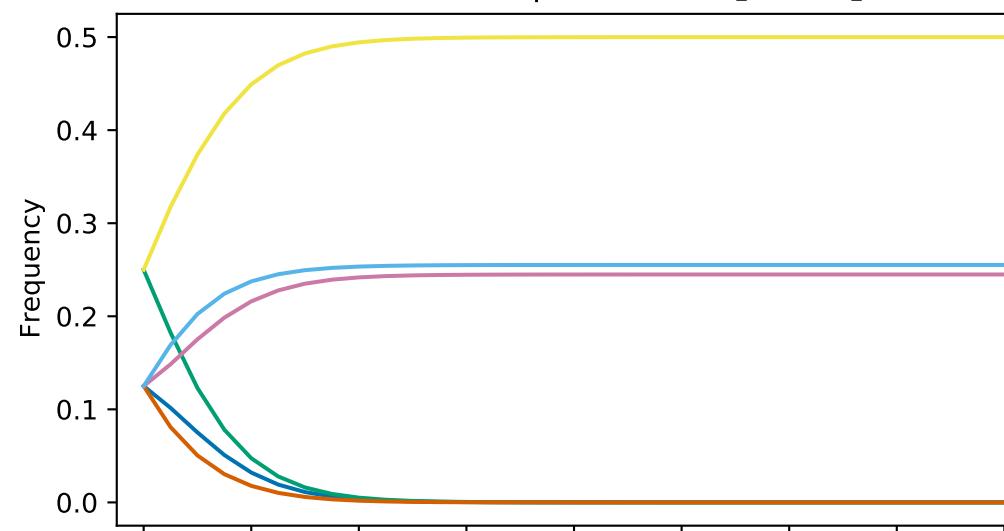## $b_3 = 1$, $b_2 = 0.3$, $b_1 = 0.3$, $b_0 = 0$, $s = 0.4$, $h = 0.5$, $a = 3$.

Low frequencies of T_2 and P_2

Intermediate frequencies of T_2 and P_2

High frequencies of T_2 and P_2

Legend:
- $P_1P_1T_1$
- $P_1P_2T_1$
- $P_2P_2T_1$
- $P_1P_1T_2$
- $P_1P_2T_2$
- $P_2P_2T_2$

Axis labels: Frequency (y-axis), n (x-axis)