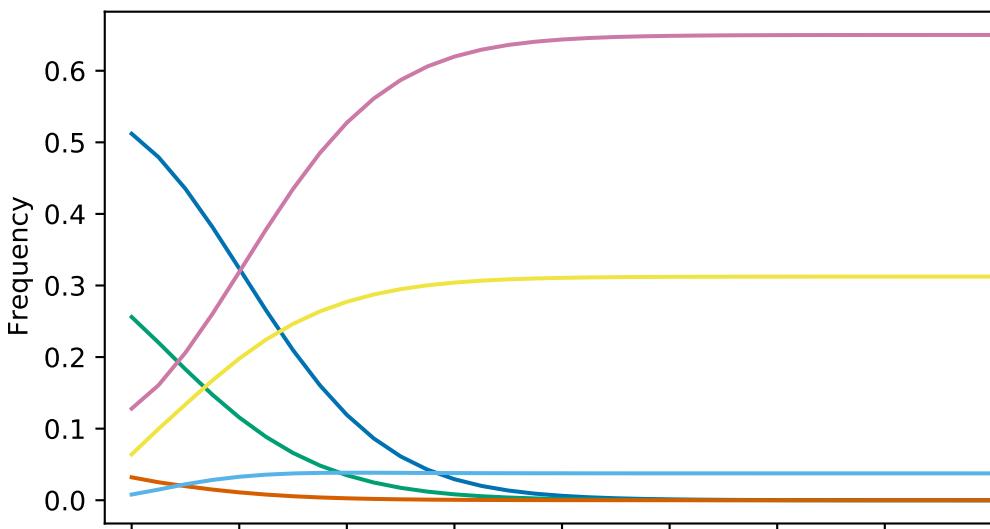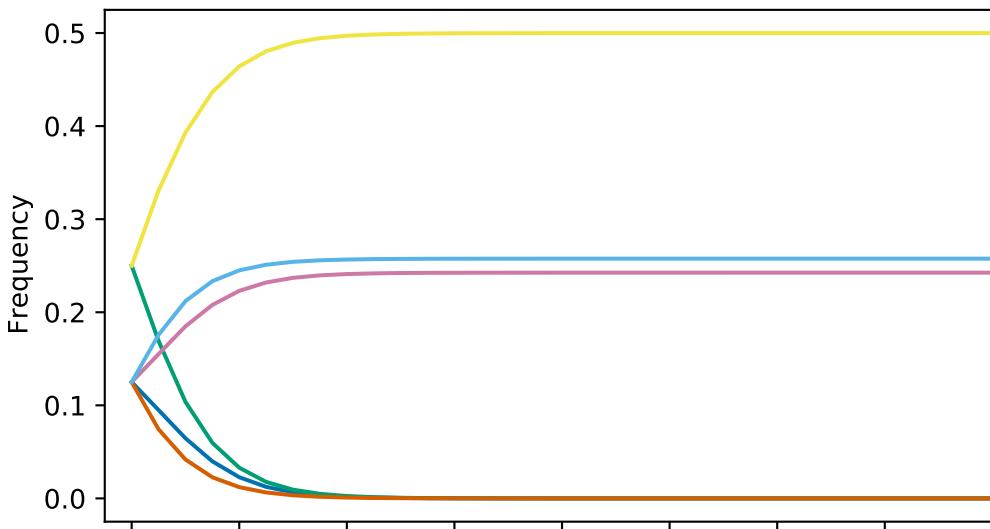Dynamics of the model with parameters
$b_3 = 1, b_2 = 0.3, b_1 = 0.3, b_0 = 0, s = 0.4, h = 1, a = 3.$
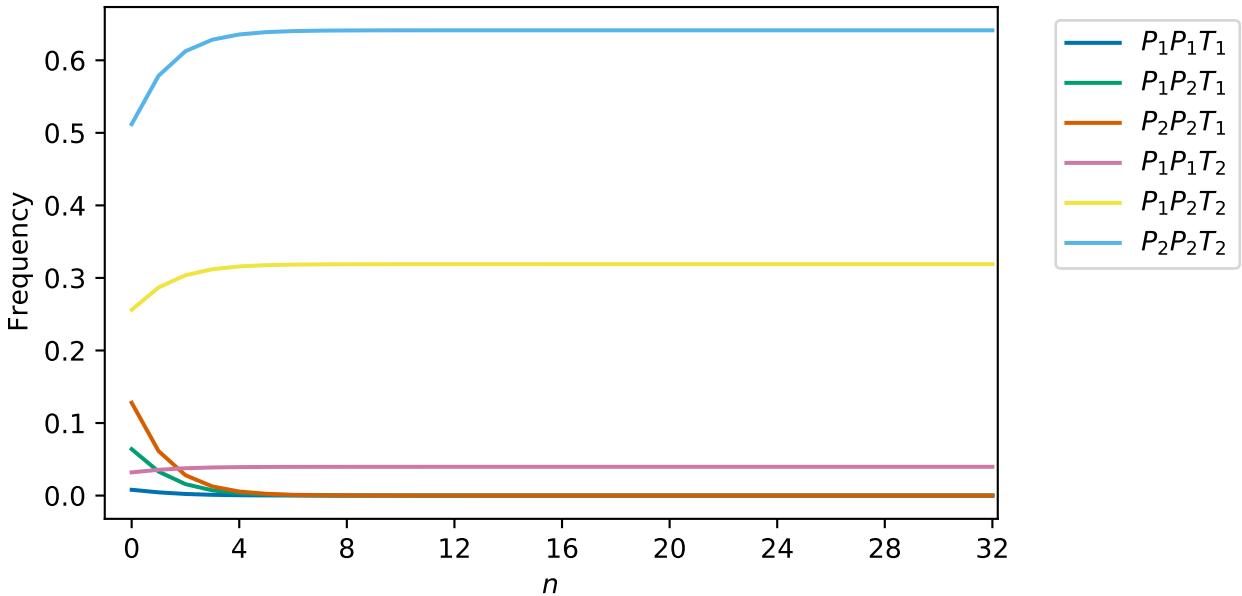
Low frequencies of T_2 and P_2

Intermediate frequencies of T_2 and P_2

High frequencies of T_2 and P_2

Legend:
$P_1P_1T_1$
$P_1P_2T_1$
$P_2P_2T_1$
$P_1P_1T_2$
$P_1P_2T_2$
$P_2P_2T_2$