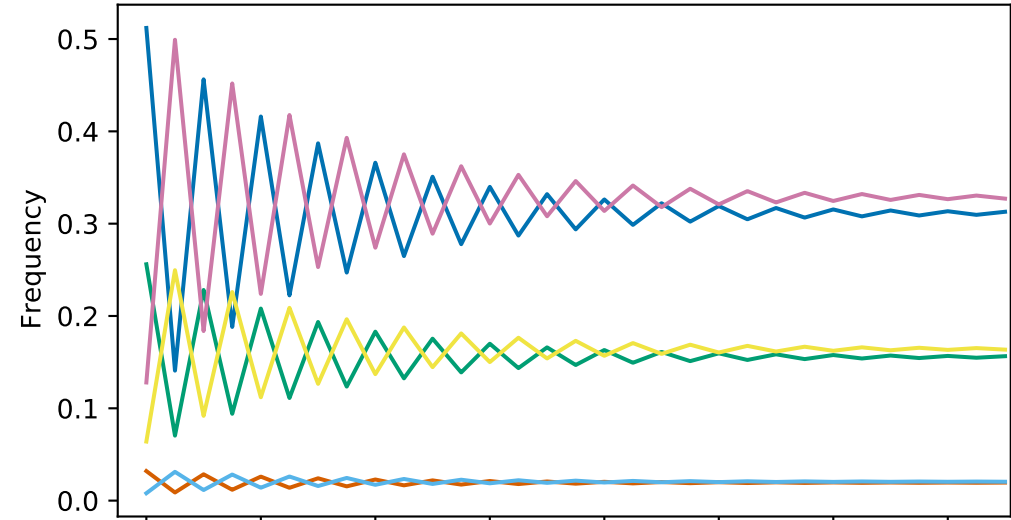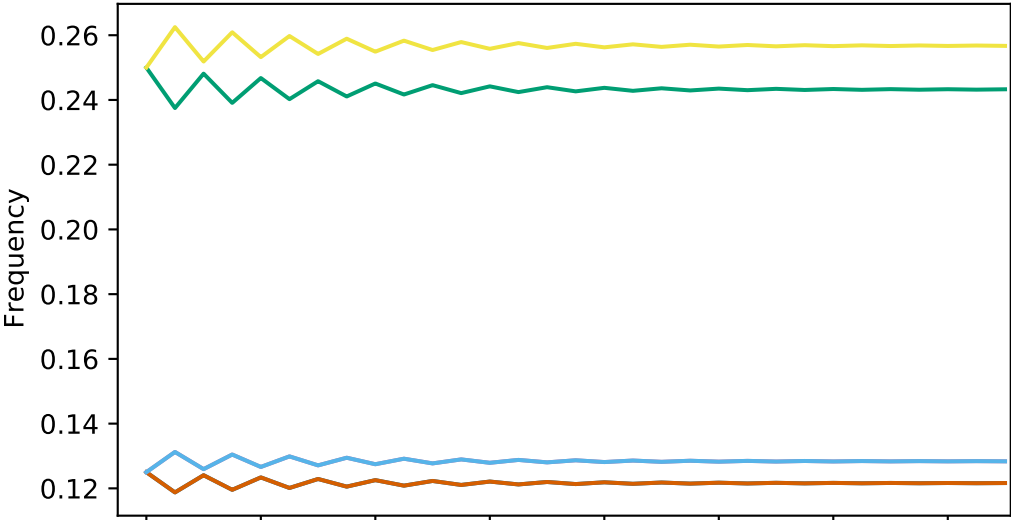Dynamics of the model with parameters
$b_3 = 0.05$, $b_2 = 0.05$, $b_1 = 0.9$, $b_0 = 0.9$, $s = 0.4$, $h = 0$, $a = 3$.
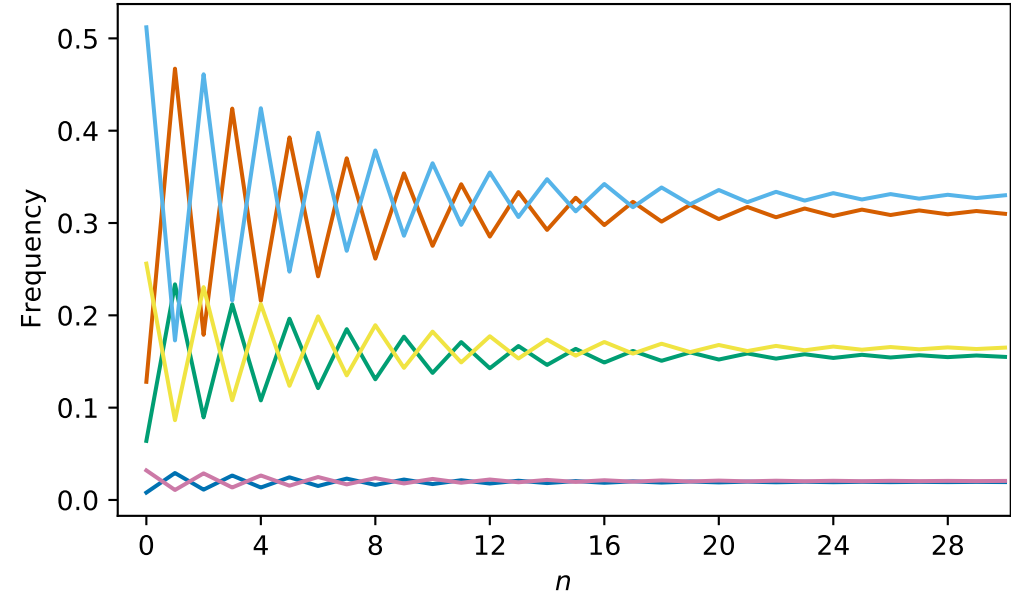
Low frequencies of T_2 and P_2

Intermediate frequencies of T_2 and P_2

High frequencies of T_2 and P_2

Legend:
- $P_1P_1T_1$
- $P_1P_2T_1$
- $P_2P_2T_1$
- $P_1P_1T_2$
- $P_1P_2T_2$
- $P_2P_2T_2$