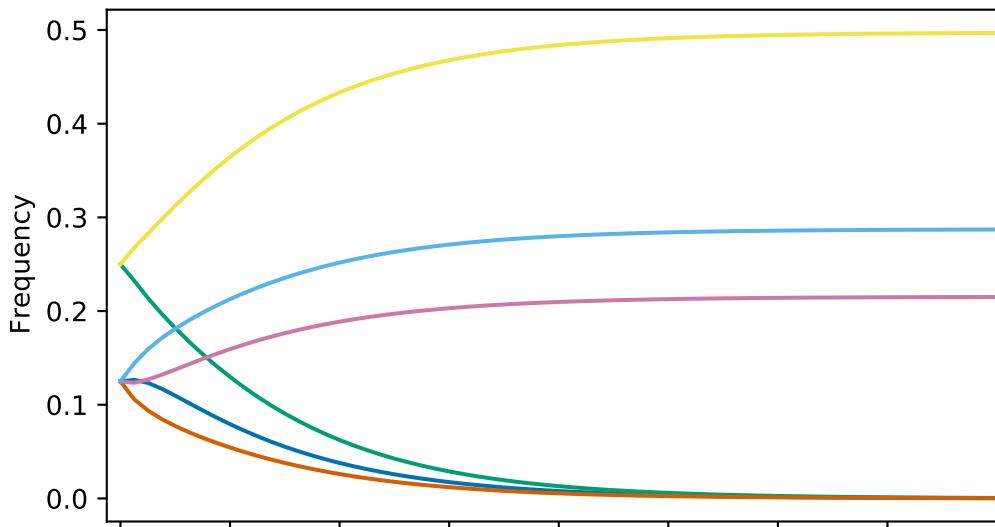
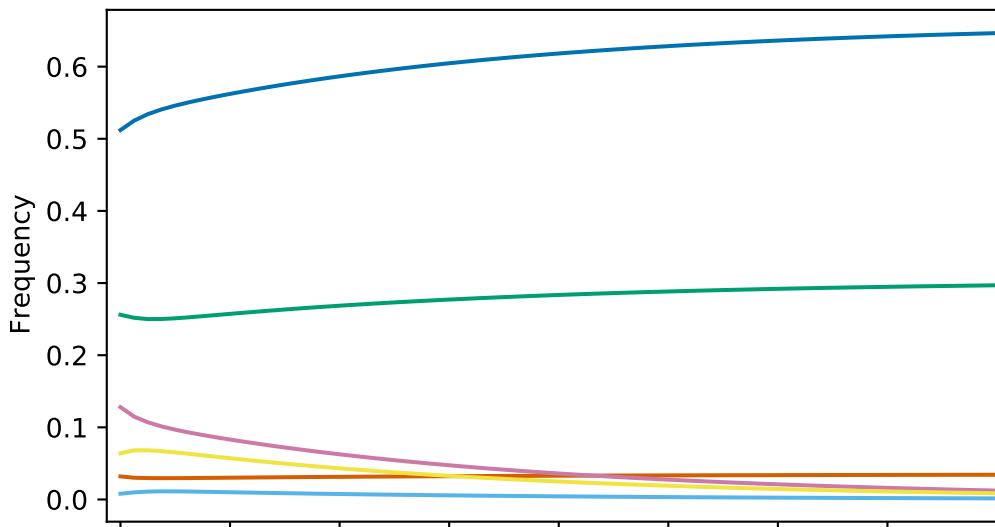


Dynamics of the model with parameters
 $b_3 = 1.0, b_2 = 0.5, b_1 = 0, s = 0.4, h = 0.5, a = 3$.

Intermediate frequencies of T_2 and P_2



Low frequencies of T_2 and P_2



High frequencies of T_2 and P_2

