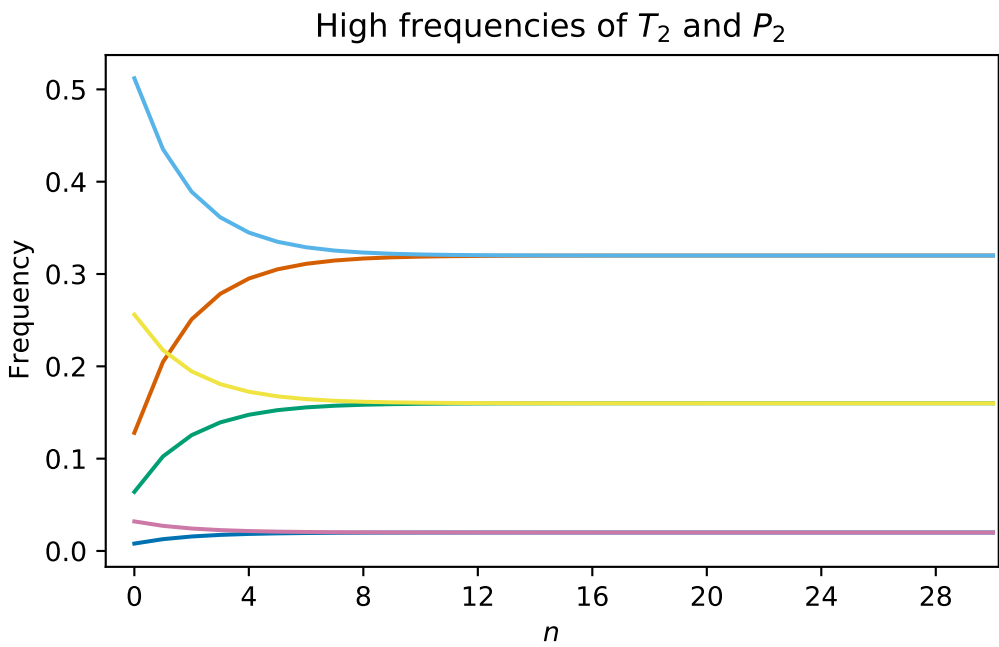
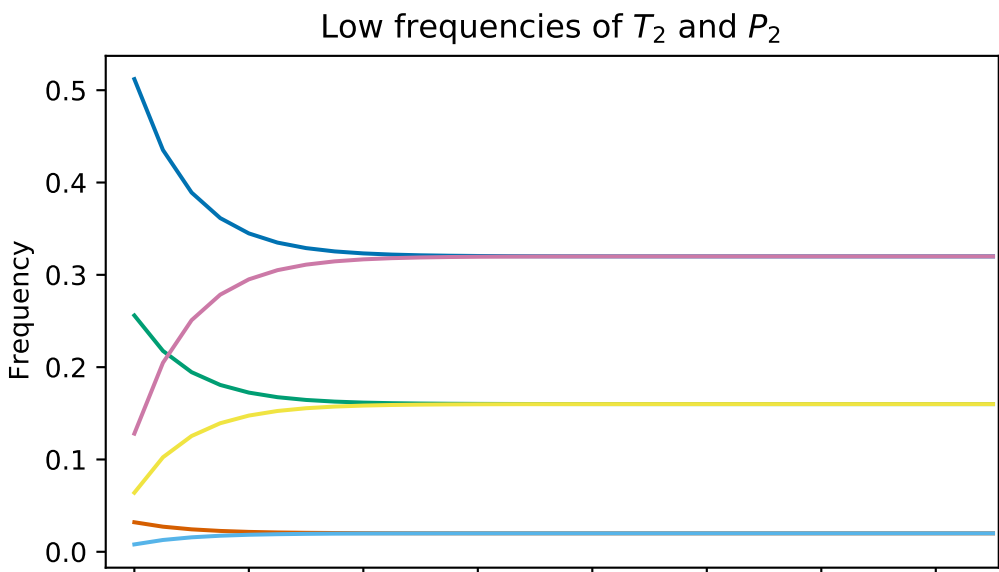
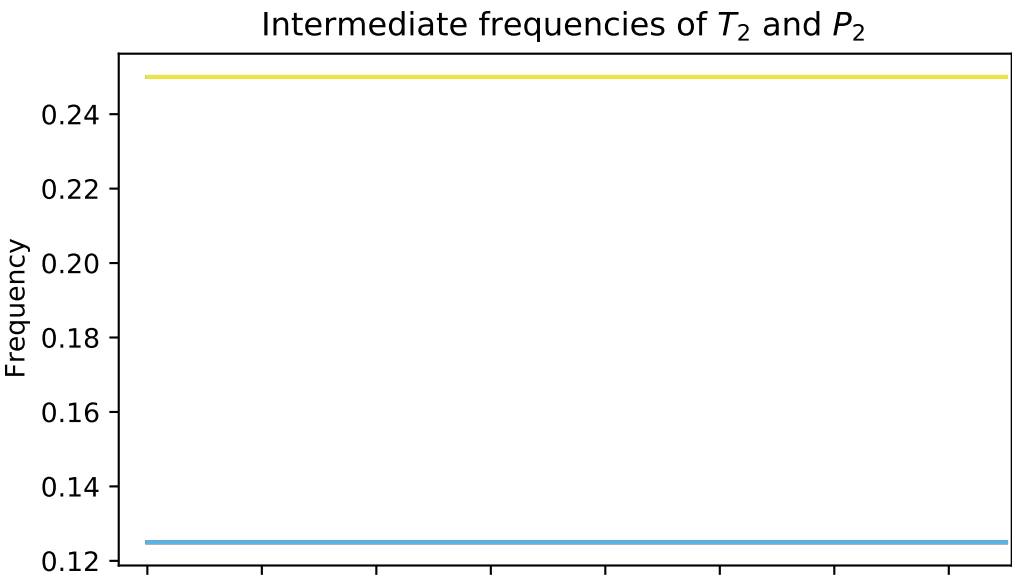


Dynamics of the model with parameters
 $b_3 = 0.8, b_2 = 0.8, b_2 = 0.2, b_1 = 0.2, s = 0.4, h = 1, a = 3.$



- $P_1P_1T_1$
- $P_1P_2T_1$
- $P_2P_2T_1$
- $P_1P_1T_2$
- $P_1P_2T_2$
- $P_2P_2T_2$