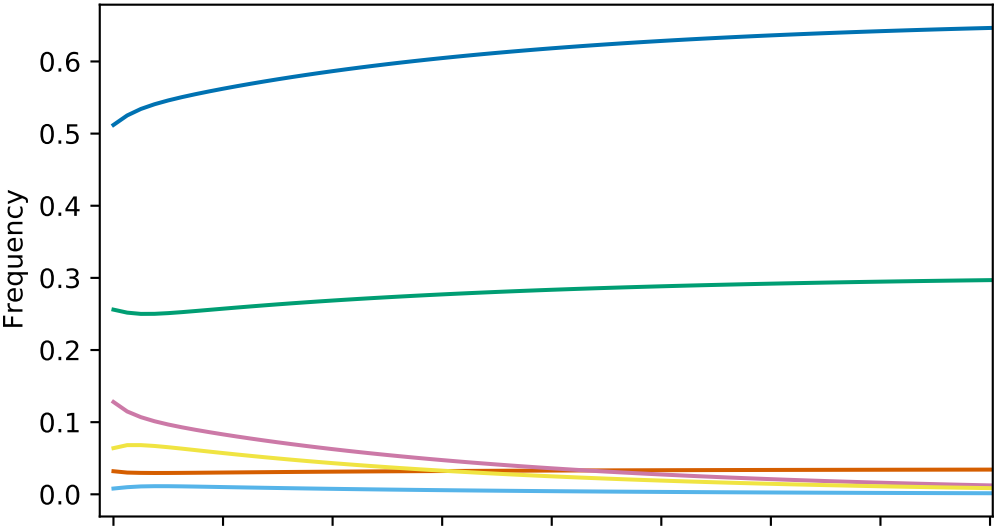
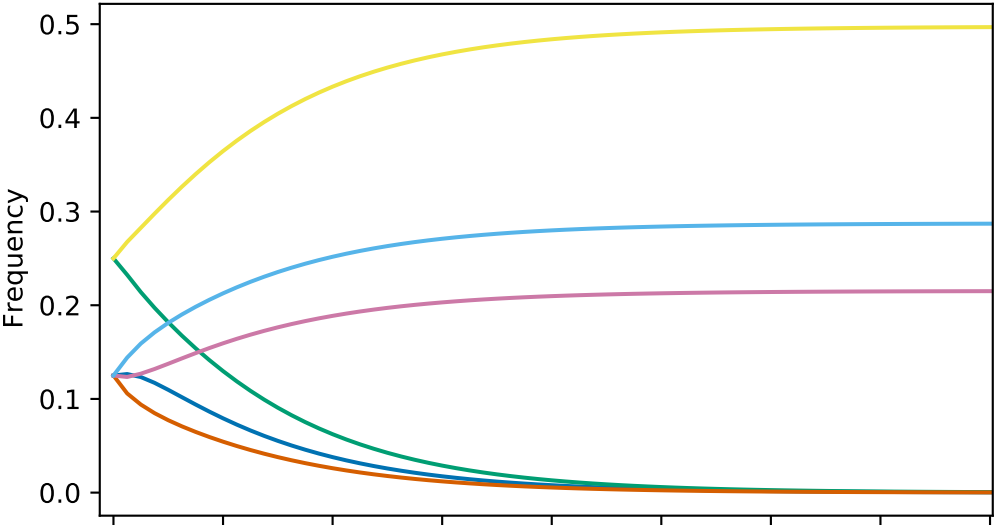


Dynamics of the model with parameters  
 $b_3 = 1, b_2 = 0.5, b_1 = 0.5, b_0 = 0, s = 0.4, h = 0.5, a = 3.$

Low frequencies of  $T_2$  and  $P_2$



Intermediate frequencies of  $T_2$  and  $P_2$



High frequencies of  $T_2$  and  $P_2$

