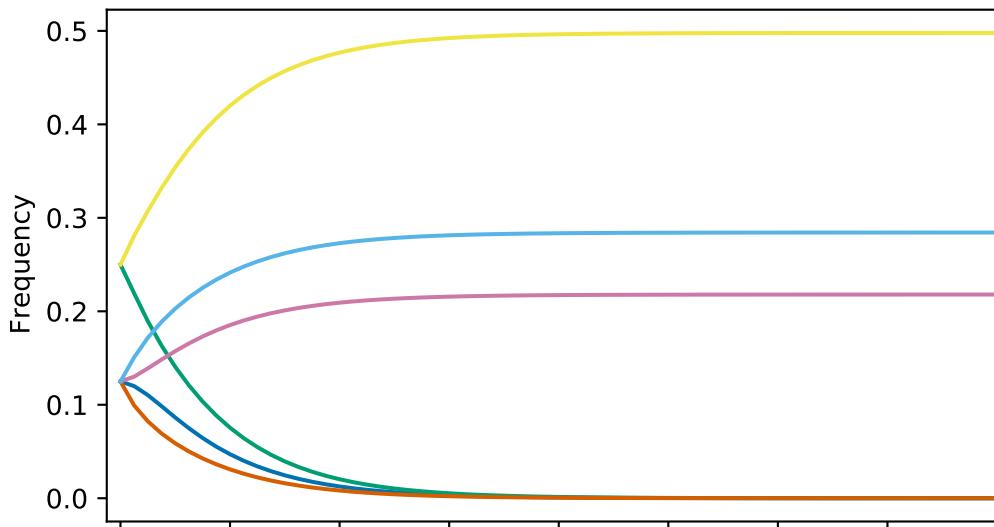
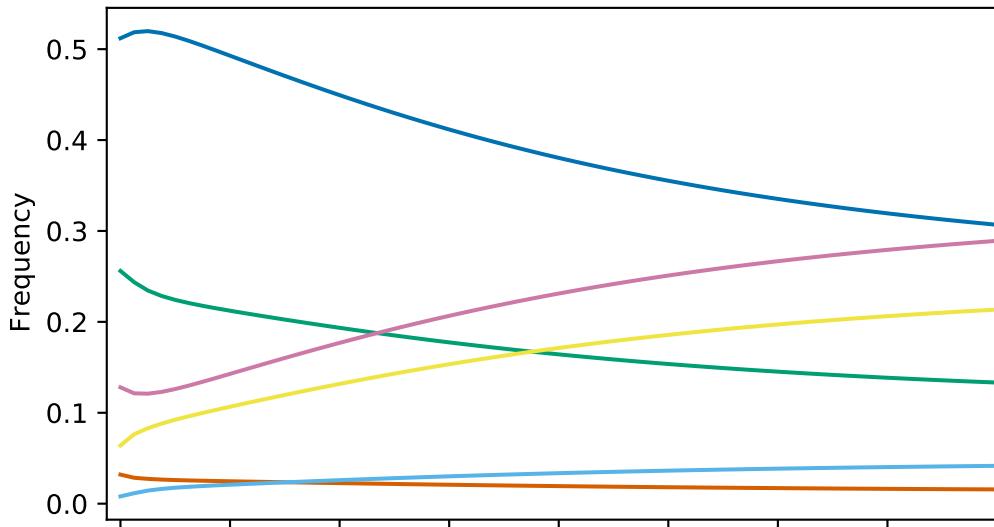


Dynamics of the model with parameters  
 $b_3 = 1.0, b_2 = 0.5, b_1 = 0, s = 0.4, h = 1, a = 3$ .

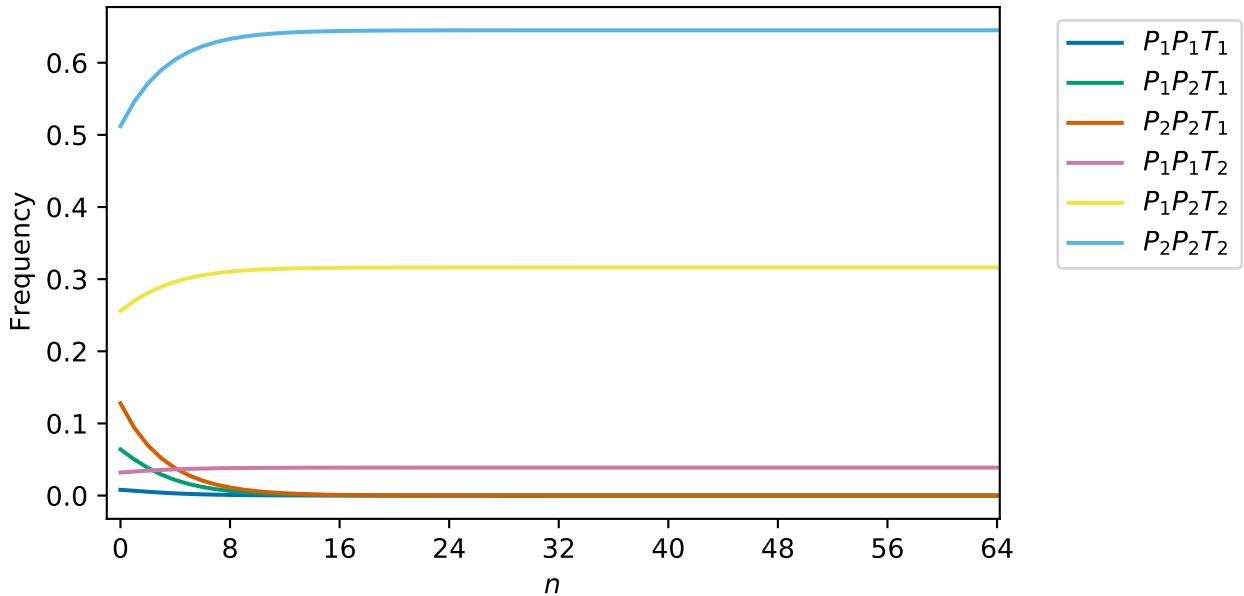
Intermediate frequencies of  $T_2$  and  $P_2$



Low frequencies of  $T_2$  and  $P_2$



High frequencies of  $T_2$  and  $P_2$



- $P_1P_1T_1$
- $P_1P_2T_1$
- $P_2P_2T_1$
- $P_1P_1T_2$
- $P_1P_2T_2$
- $P_2P_2T_2$