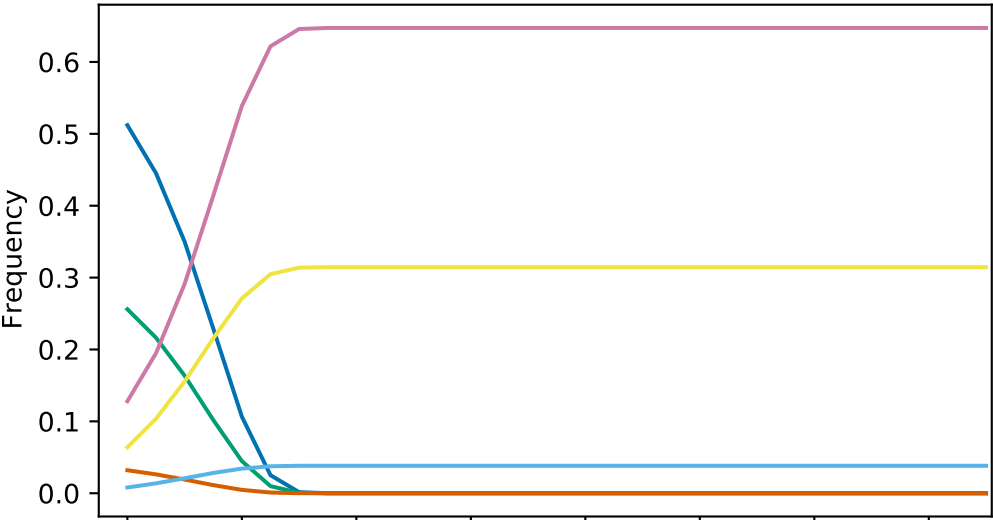Dynamics of the model with parameters
$b_3 = 1$, $b_2 = 0$, $b_1 = 0$, $b_0 = 0$, $s = 0.4$, $h = 0$, $a = 3$.

Low frequencies of T_2 and P_2

Intermediate frequencies of T_2 and P_2

High frequencies of T_2 and P_2

$P_1P_1T_1$
$P_1P_2T_1$
$P_2P_2T_1$
$P_1P_1T_2$
$P_1P_2T_2$
$P_2P_2T_2$

Frequency

n