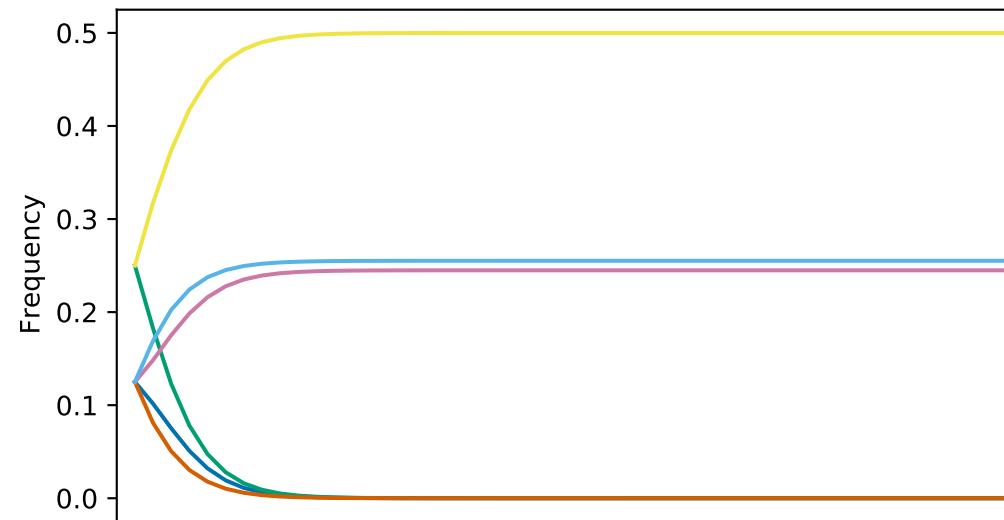
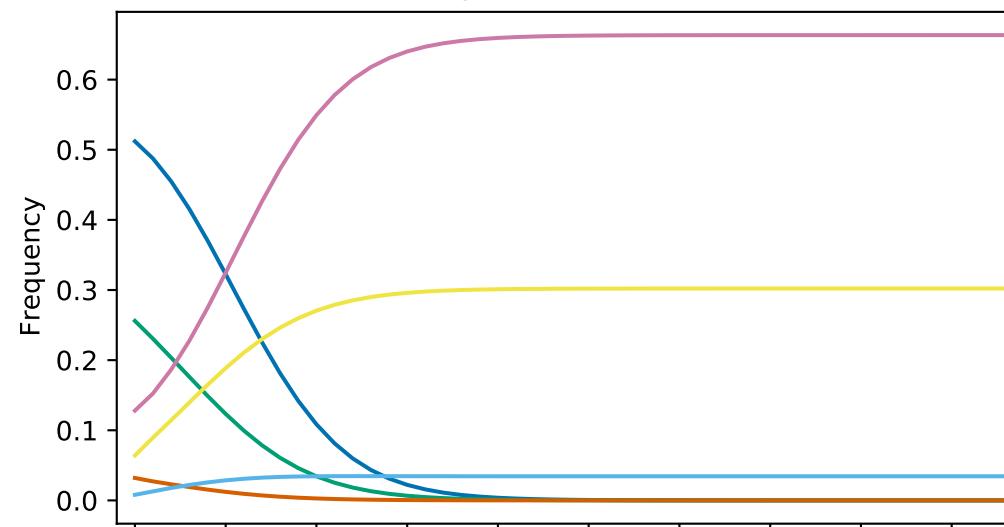


Dynamics of the model with parameters
 $b_3 = 1.0$, $b_2 = 0.3$, $b_1 = 0$, $s = 0.4$, $h = 0.5$, $a = 3$.

Intermediate frequencies of T_2 and P_2



Low frequencies of T_2 and P_2



High frequencies of T_2 and P_2

