11/19/2020 DBSCAN.py

```
1 from hw4code.KMeans import KMeans,compute_purity,compute_NMI,getEuclideanDist
 2 from hw4code.DataPoints import DataPoints
 3 import random
 4
 5
 6 class DBSCAN:
 7
       # ----
8
       def init (self):
 9
           self.e = 0.0
10
           self.minPts = 3
11
           self.noOfLabels = 0
12
13
       def main(self, dataname):
14
           seed = 71
15
16
           self.dataname = dataname[5:-4]
17
           print("\nFor " + self.dataname)
           self.dataSet = KMeans.readDataSet(dataname)
18
19
           random.Random(seed).shuffle(self.dataSet)
20
           self.noOfLabels = DataPoints.getNoOFLabels(self.dataSet)
21
           self.e = self.getEpsilon(self.dataSet)
           print("Esp :" + str(self.e))
22
           self.dbscan(self.dataSet)
23
24
25
26
27
       def getEpsilon(self, dataSet):
28
           distances = []
29
           sumOfDist = 0.0
           for i in range(len(dataSet)):
30
31
               point = dataSet[i]
32
               for j in range(len(dataSet)):
33
                    if i == j:
34
                        continue
35
                   pt = dataSet[j]
36
                   dist = getEuclideanDist(point.x, point.y, pt.x, pt.y)
37
                   distances.append(dist)
38
39
               distances.sort()
40
               sumOfDist += distances[7]
               distances = []
41
42
           return sumOfDist/len(dataSet)
43
44
       def dbscan(self, dataSet):
45
           clusters = []
46
           visited = set()
47
           noise = set()
48
49
           # Iterate over data points
50
           for i in range(len(dataSet)):
51
               point = dataSet[i]
52
               if point in visited:
53
                   continue
54
               visited.add(point)
55
               N = []
56
               minPtsNeighbours = 0
57
               # check which point satisfies minPts condition
58
59
               for j in range(len(dataSet)):
```

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 61
                         continue
 62
                     pt = dataSet[i]
 63
                     dist = getEuclideanDist(point.x, point.y, pt.x, pt.y)
 64
                     if dist <= self.e:</pre>
 65
                         minPtsNeighbours += 1
 66
                         N.append(pt)
 67
 68
                 if minPtsNeighbours >= self.minPts:
 69
                     cluster = set()
 70
                     cluster.add(point)
 71
                     point.isAssignedToCluster = True
 72
 73
 74
                     while i < len(N):
 75
                         point1 = N[i]
 76
                         minPtsNeighbours1 = 0
 77
                         N1 = []
 78
                         if not point1 in visited:
 79
                             visited.add(point1)
 80
                             for l in range(len(dataSet)):
 81
                                 pt = dataSet[l]
 82
                                 dist = getEuclideanDist(point1.x, point1.y, pt.x,
    pt.y)
 83
                                 if dist <= self.e:</pre>
 84
                                     minPtsNeighbours1 += 1
 85
                                     N1.append(pt)
 86
                             if minPtsNeighbours1 >= self.minPts:
 87
                                 self.removeDuplicates(N, N1)
 88
 89
                         # Add point1 is not yet member of any other cluster then
    add it to cluster
 90
                         # Hint: use self.isAssignedToCluster function to check if
    a point is assigned to any clusters
 91
                         # =======#
 92
                         # STRART YOUR CODE HERE #
 93
                         # ========#
 94
                         if not point1.isAssignedToCluster:
 95
                             cluster.add(point1)
 96
                             noise.discard(point1)
 97
                         # ========#
 98
                             END YOUR CODE HERE
 99
                         # ========#
100
                         i += 1
101
102
                     # add cluster to the list of clusters
103
                     clusters.append(cluster)
104
105
                else:
106
                     noise.add(point)
107
108
109
            # List clusters
            print("Number of clusters formed :" + str(len(clusters)))
110
111
            print("Noise points :" + str(len(noise)))
112
113
            # Calculate purity
            compute_purity(clusters,len(self.dataSet))
114
115
            compute_NMI(clusters, self.no0fLabels)
            DataPoints.writeToFile(noise, clusters, "DBSCAN_"+ self.dataname +
116
```

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```
117
        def removeDuplicates(self, n, n1):
118
119
             for point in n1:
120
                 isDup = False
                 for point1 in n:
121
                      if point1 == point:
    isDup = True
122
123
                          break
124
125
                 if not isDup:
                      n.append(point)
126
127
128
```