

Help:

Shift register allocation and initialization::

myShiftRegister.Update();

delay(1000);

Shift595Arduino(int datapin, int clockpin, int latchpin, int nbregisters=1);

```
/*
Allocation function:
    - datapin: specifies the Arduino pin connected to the 595 data input
    - clockpin: specifies the Arduino pin connected to the 595 clock input
    - latchpin: specifies the Arduino pin connected to the 595 latch output
    - nbregisters: specifies the number of cascaded registers. Default is 1.
ex: Shift595Arduino myShiftRegister(2, 3, 4, 2);
*/
```

boolean Setup();

```
/*
Setup function:
    Inits the Arduino pins.
    This function must be called in the setup()
    function of the Arduino progam.

ex: myShiftRegister.Setup();
*/
```

Shift register actions::

boolean OffRegister(int reg_index);

```
/*
Turn Off ('0') values of a specifc register:
    - reg_index: specify a register index.

ex: myShiftRegister.OffRegister(1);
*/
```

boolean OffAllRegisters();

```
/*
Turn Off ('0') values of all registers.
ex: myShiftRegister.OffAllRegisters();
*/
```

boolean OnRegister(int reg_index);

```
/*
turn On ('1') values of a specifc register:
   - reg_index: specify a register index.

ex: myShiftRegister.OnRegister(1);
*/
```

boolean OnAllRegisters();

```
/*
Turn On ('1') values of all registers.
ex: myShiftRegister.OnAllRegisters();
*/
```

boolean OnSingleRegister(int position, int reg_index);

boolean OnSingleAllRegisters(int position);

boolean OnSingleEachRegisters(int position);

boolean OffSingleRegister(int position, int reg_index);

boolean OffSingleAllRegisters(int position);

boolean OffSingleEachRegisters(int position);

boolean OnSingleOnlyRegister(int position, int reg_index);

```
/*
Turn On ('1') value at a specific position of a specific register,
and Turn Off all other values for this register:
```

boolean OnSingleOnlyAllRegisters(int position);

boolean OnSingleOnlyEachRegisters(int position);

boolean OffSingleOnlyRegister(int position, int reg_index);

boolean OffSingleOnlyAllRegisters(int position);

boolean OffSingleEachRegisters(int position);

```
/*
Turn Off ('0') value at a specific position for each register,
and Turn On all other values:
```

boolean ShiftLeftRegister(boolean circular, int reg_index);

boolean ShiftLeftAllRegisters(boolean circular);

boolean ShiftLeftEachRegisters(boolean circular);

boolean ShiftRightRegister(boolean circular, int reg_index);

boolean ShiftRightAllRegisters(boolean circular);

boolean ShiftRightEachRegisters(boolean circular);

boolean NegateRegister(int reg_index);

```
/*
Negate values of a specific register. On values are turned Off,
Off values are turned On:
    - reg_index: specify a register index.
ex: myShiftRegister.NegateRegister(1);
*/
```

boolean NegateAllRegisters();

```
/*
Negate values of all registers.
ex: myShiftRegister.NegateAllRegisters();
*/
```

boolean Update();

```
/*
Update register state. Register output pins are updated
to their current values.

ex: myShiftRegister.Update();
*/
```

boolean Blink(int iter, int delay_val);

```
/*
Update Off then update to their current values the
output pins of the registers.

- iter: number of blinks.
- delay_val: blink delay in milliseconds.

ex: myShiftRegister.Blink(5, 100);
*/
```

boolean TestSequence();

```
/*
Run a test sequence for N cascaded registers with LEDs.
```

```
- Turn On all LEDs
- Blink LEDs 5 times @ 100ms
- Turn Off all LEDs
- Turn On 3 LEDs
- Shift the 3 LEDs positions to the left x times
- Turn On / Off groups of 8 LEDs in alternance
- Switch On / Off LED states in alternance

ex: myShiftRegister.TestSequence();
*/
```

Shift register parameters::

boolean verbose;

```
/*
Enable/Disable verbose output.
When enabled, each operation outpus a string with its name.
Default value is false.

ex: myShiftRegister.verbose = true
*/
```

boolean auto_update;

```
/*
Enable/Disable register state auto update.
When enabled, each action updates values of the registers' output pins,
then wait some amount of time defined by the update_delay value.
When disabled, registers' output pins remain unchanged until
an explicit call to Update().
Default value is true.

ex: myShiftRegister.auto_update = false;
   myShiftRegister.OffAllRegisters();
   myShiftRegister.OnSingleAllRegisters(7);
   myShiftRegister.OnSingleAllRegisters(12);
   myShiftRegister.Update();
   delay(1000);
*/
```

int update_delay;

```
/*
Set the amount of time, in milliseconds, an action auto update
is maintained before returning.
Default value is 0.

ex: myShiftRegister.update_delay = 250;
*/
```

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