

# Hashing

## Hash Tables

Hash function  $h$ : search key  $\rightarrow [0, \dots, B-1]$ .

Buckets are blocks, numbered  $[0, \dots, B-1]$ .

General idea: If a record with search key  $K$  exists, then it must be in bucket  $h(K)$ .

- Cuts search down by a factor of  $B$ .
- One disk I/O if there is only one block per bucket.

## Hash Table Operations

### HashTable Lookup

- For record(s) with search key  $K$ , compute  $h(K)$ ; search that bucket.

### HashTable Insertion

- Put in bucket  $h(K)$  if it fits; otherwise create an overflow block.
- Overflow block(s) are part of bucket.

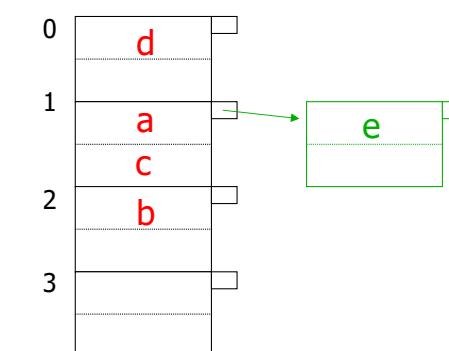
### HashTable Deletion

- Compute  $h(K)$ ; search bucket for record(s) with key  $K$  and delete entry

## Example with 2 Records/Bucket

### INSERT:

$h(a) = 1$   
 $h(b) = 2$   
 $h(c) = 1$   
 $h(d) = 0$



$h(e) = 1$

## Implementation of DBMS

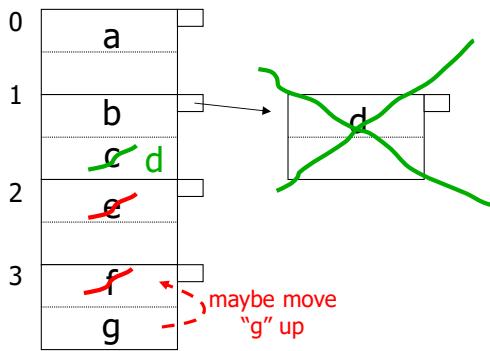
# Example: Deletion

Delete:

e

f

c



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# How full should a Block be?

Try to keep space utilization

between 50% and 80%

$$\text{Utilization} = \frac{\# \text{ keys used}}{\text{total } \# \text{ keys that fit}}$$

If < 50%, wasting space

If > 80%, overflows significant  
depends on how good hash function is and on # keys/bucket

Implementation of DBMS

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## Implementation of DBMS

# How do we cope with growth?

Overflows and reorganizations  
Dynamic hashing

Extensible  
Linear

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# Implementation of DBMSDynamic Hashing Framework

Hash function  $h$  produces a sequence of bits.

Only some of the bits are used at any time to determine placement of keys in buckets.

### Extensible Hashing

- Keep parameter  $i$  = number of bits from the beginning of  $h(K)$  determine the bucket.
- Bucket array now = pointers to blocks.
- A block can serve as several buckets.
- For each block, a parameter  $j \leq i$  tells how many bits of  $h(K)$  determine membership in the block.
- I.e., a block represents  $2^{i-j}$  buckets that share the first  $j$  bits of their number.

Implementation of DBMS

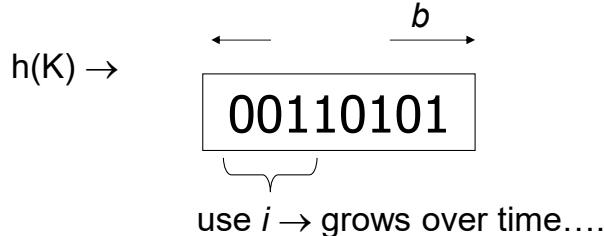
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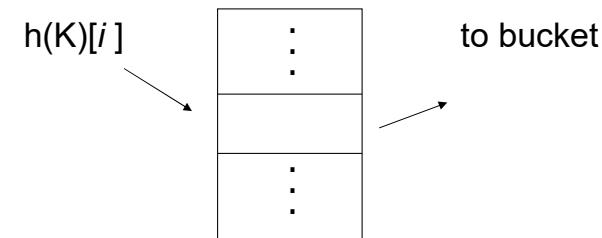
# Implementation of DBMS

## Extensible hashing: two ideas

(a) Use  $i$  of  $b$  bits output by hash function



(b) Use directory



## Implementation of DBMS

### Extensible Hashtable Insert

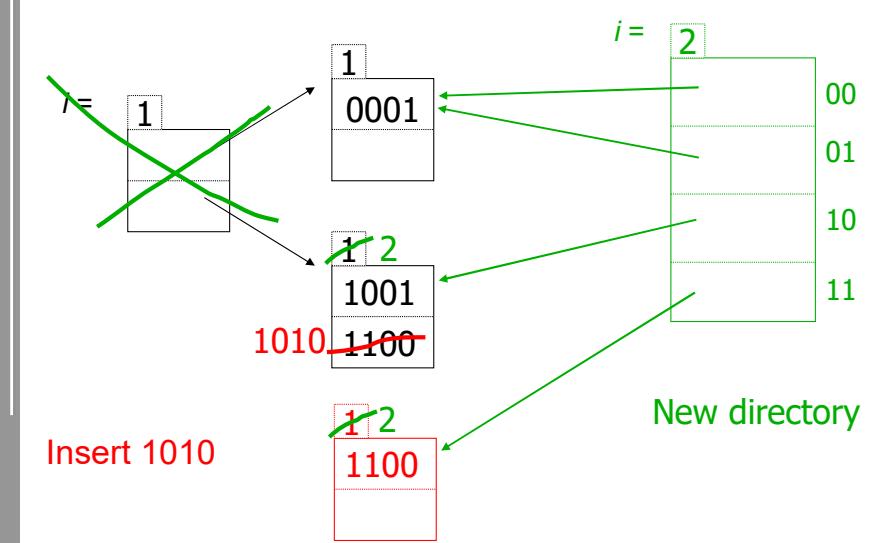
If record with key K fits in the block pointed to by  $h(K)$ , put it there.

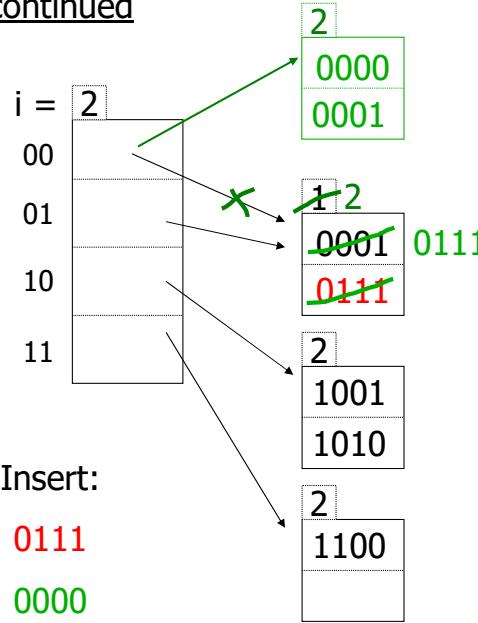
If not, let this block represent  $j$  bits.

- Case 1:  $j < i$ : Split block according to  $(j + 1)$ st bit; set  $j := j + 1$ .
- Case 2:  $j = i$ : Set  $i := i + 1$ ; split bucket array; proceed as in (1).

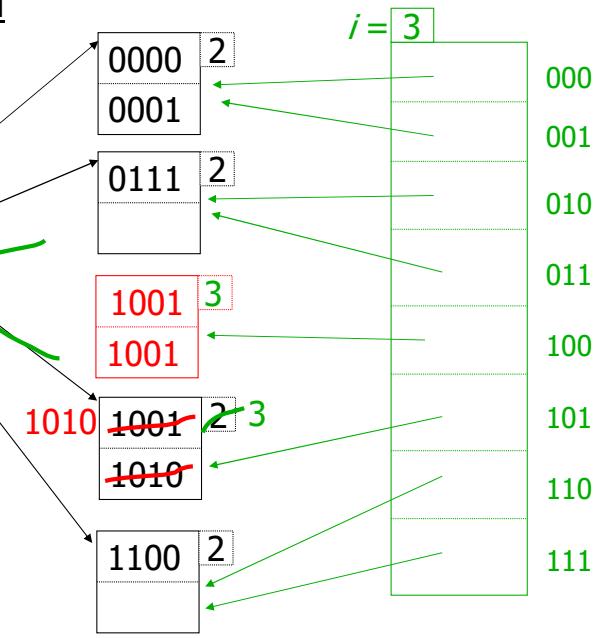
## Implementation of DBMS

### Example: $h(k)$ is 4 bits; 2 records/block



Example continued

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## Summary Extensible Hashing

- + Can handle growing files
  - with less wasted space
  - with no full reorganizations

- Indirection  
(Not bad if directory in memory)

- Directory doubles in size