# Introduction to Data Shift & Concept Drift

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## Outline

- Chapter I: Introduction
  - What is Data Shift?
  - Why Data Shift Happens?
  - Why Handle Data Shift?
    - What are the consequences of not properly addressing data shift?
  - How to approach data shift?
- Chapter II: Data Shift
  - Data Shift Types and Patterns
  - Data Shift Detection & Correction
  - Transfer and Active Learning
  - Evaluation and Discussion
  - Packages
- Chapter III: Discussion and Q&A

## Introduction





## Definition What is Data Shift?

- In classic Machine learning, models are trained under the premise that the training and the real-world (i.e., both source and target) data are from the same distribution
- Such assumption may potentially result in predictive problems in dynamic industries and environments where the distribution of data changes over time
- The existence of such a difference between the dataset distributions is called as dataset shift in the machine learning community.
- In fact, most real-world applications should cope with some form of shift as the distribution of the data used to train a model differs from the distribution of the data that the model encounters after its deployment.

# Why Data Shift Happens?

- Reasons for experiences data shift could be:
  - Political
  - Industrial (Solar & Clean Energy)
  - Financial (Shift from Fiat to Crypto...!)
  - Retail (supply and demand)
  - Pandemic, e.g., COVID 19 and SARS
  - War & Immigration
  - House Price (2007)
  - IT & Internet (e.g., Dot-com)
  - Security & Privacy (Cyber attack)
  - Environmental (Global warming, weather)
  - Natural (Bird Migrations)
  - Dynamic nature (Smart Houses)
  - Unexpected

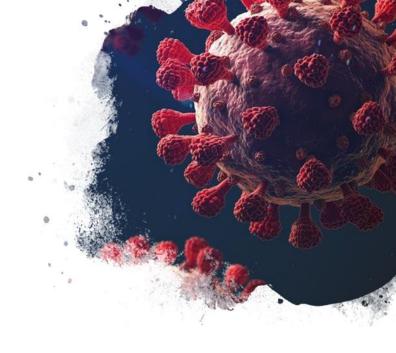


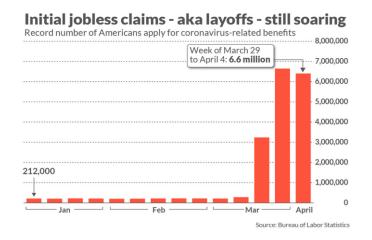




## Motivation Why Handle Data Shift?

- We train a model to predict "Jobless Claims" in the US
- In practice, the model correctly predicts 200k claims for the fourth week of March 2020
- COVID 19 hits and unemployment claims skyrocket
- The model now predicts 800k claims; it's higher than normal, but is it reliable? (In reality, it is over 6 millions...)
- After pandemic, the model parameters (e.g., layoffs, closures, mobility, data, etc.) may have dramatically changed
- The model trained on historical jobless claims data may underestimate the effect of the pandemic





## Motivation Why Handle Data Shift?

#### Pre-COVID:

- Trained a model to predict bankruptcy of an entity
- Data:
  - 70% Non-bankrupted,
  - 20% Likely to Bankrupt,
  - 10% Will Bankrupt
- The model had an accuracy of 80% (vs. 33% for a random classifier)

#### Post-COVID:

- After COVID, we observed:
  - 40% Non-bankrupted,
  - 60% bankrupted
  - Class distribution changed
  - The number of classes reduced
- The model accuracy worsens although the problem is easier (a random classifier is now 50% accurate)



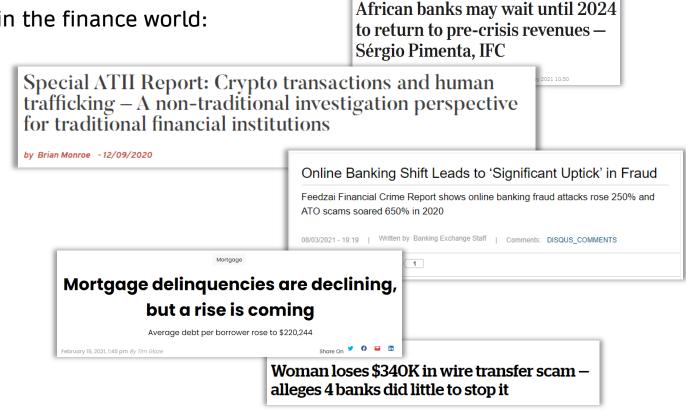
# Motivation – Cont. Why Handle Data Shift?

- Consequences of not handling data shift could be loss of:
  - Lives
  - Clients
  - Resources
  - Funds
  - Time
  - Trust
  - Reputation



## Motivation – Cont. Why Handle Data Shift?

- Consequences of not handling data shift in the finance world:
  - Financial crimes:
    - Terrorist financing
    - Money laundering
    - Fraudulent transactions
    - Scamming
    - Slavery and human trafficking
  - Client focused:
    - Inadequate financial plans
    - Poor product recommendation
    - Mortgage delinquency
    - Credit and loan defaults
    - Attrition & losing clients
    - etc.



## How to approach data shift?

#### Reactive

- React once something happened
  - Transfer learning (reusing old models)
  - Adaptive learning (efficiently retraining)
  - Statistical correction
- It is easier but more risky



#### **Proactive**

- React before something happens
  - Adding mitigation steps in ML pipelines
  - Using historical data to retrain the model (using COVID data for future pandemics)
  - Using synthetic datasets to estimate data shift e.g., adversarial training
  - It's not perfect. Must be an oracle.
- It is harder but less risky

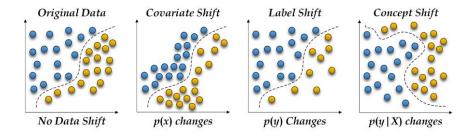
## Data Shift





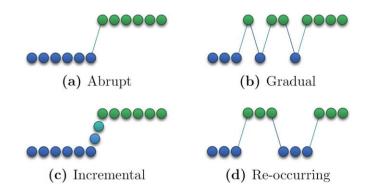
### Data Shift

- Common types of data shift:
  - Covariate shift
  - Label shift
  - Concept shift



#### Data shift patterns:

- Abrupt
- Gradual
- Incremental
- Re-occurring (or recurring)



### Data Shift Covariate Shift

#### **Covariate Shift**

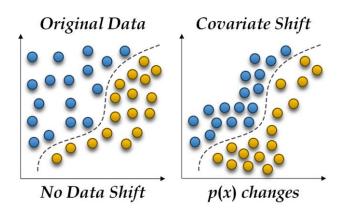
• Covariate shift happens when the conditional distribution  $P_S(y|x)$  remains the same, i.e., that conditional distribution of the source and target domains are equal, but  $P_S(x)$  changes. So, we have:

$$P_S(x)P_S(y|x) \neq P_T(x)P_T(y|x)$$

where

$$P_S(y|x) = P_T(y|x)$$

 Covariate shift appears in data due to lack of randomness, inadequate sampling, biased sampling, and non-stationary environment.



## Data Shift Label Shift

#### **Label Shift**

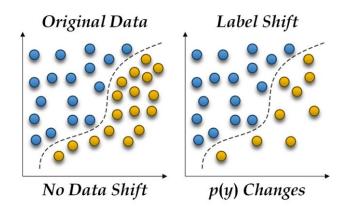
• Label shift is experienced when the conditional distribution  $P_S(x|y)$  remains the same but  $P_S(y)$  changes. So, we have:

$$P_S(y)P_S(x|y) \neq P_T(y)P_T(x|y)$$

where

$$P_S(x|y) = P_T(x|y)$$

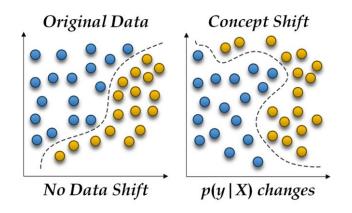
• Having  $P_S(y) \neq P_T(y)$  implies that label shift happens when some concepts are undersampled or oversampled in the target domain compared to the source domain.



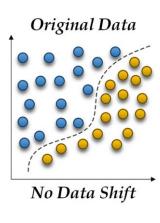
## Data Shift Concept Shift

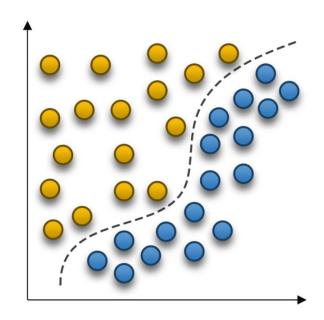
#### **Concept Shift**

- In the case of concept shift,  $P_S(y)$  and  $P_T(y)$  follow the same distribution but  $P_S(y|x)$  differs from  $P_T(y|x)$ .
- To address concept shift, we adapt our model globally or locally.
- Global adaptation is training our model from scratch using the target data whereas local adaptation works for learning algorithms that can be refitted for some part of their decision regions; for example consider decision trees where we may update some branches to reflect the change in the real world.
- Concept shift detectors compare the performance of a learner against both the source and target data; and if there is a significant difference they alarm for a drift.



## Quiz





What kind of shift is this?

## **Data Shift Detection**





## Covariate Shift Domain Classifier

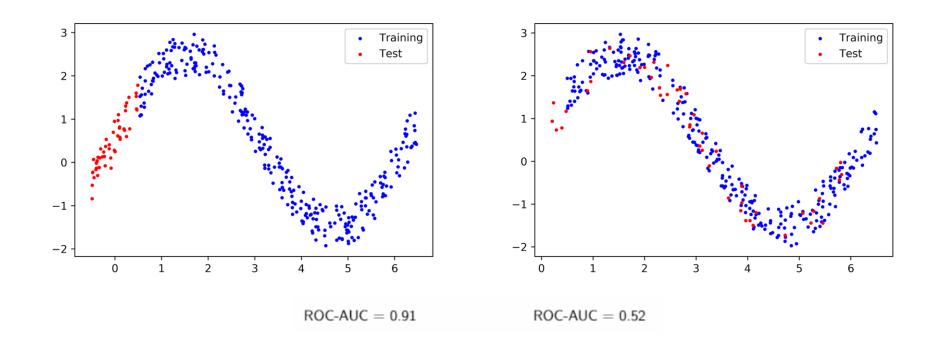
#### **Covariate Shift Detection**

Domain Classifier

- Train a **domain classifier** to detect whether new data is from  $P_S$  or  $P_T$
- That means we want to see if a data point is from source or target domain
- Domain classifier reduces dataset dimension to a single dimension, which specifically discriminate between source and target data
- The higher the error of the classifier → the closer the distributions (i.e., unlikely to observe covariate shift)
- Applicable to high-dimensional data
- Can detect what feature(s) caused the shift using feature importance analysis
- Offline

## Covariate Shift – Cont. Domain Classifier

- ROC-AUC score can be used to check if the performance of the classifier is statistically better than random chance (i.e., ROC-AUC score of 0.5)
- ROC-AUC score larger than 0.8 can be considered major shift
- Bi-nominal testing can be used as well



## Covariate Shift & Domain Classifier – Cont. Important considerations

#### Considerations

- Requires training a classifier
- Requires access to large samples from  $x_i \sim P_T$  and may perform poorly with small samples
- Choosing a classifier to distinguish between two distributions at high level is equivalent to picking a measure between distributions distances
- The choice of the classifier may yield very different results
- To improve the shift detection confidence, one may consider using multiple classifiers and aggregate their predictions in some manner

### Label Shift Black Box Shift Detection

#### **Label Shift Detection**

- Detecting label shift is harder as we don't have access to labelled distribution
- Solution: Estimate it using a **pre-trained** classifier (Let's call it as *label classifier*)
- The label classifier must have an invertible confusion matrix
  - This condition is easily satisfied if the classifier is well-trained
- **Black Box Shift Detection**: Given a pre-trained label classifier f(x) with invertible confusion matrix, detecting that the source distribution  $P_S$  is different from the target distribution  $P_T$  only requires detecting that  $P_S(f(x)) \neq P_T(f(x))$

## **Concept Drift Detection**

#### **Concept Drift Detection**

- **Idea**: Use probabilistic or statistical methods to bound the difference between  $P_S(y|x)$  and  $P_T(y|x)$  a significant difference suggests concept shift.
- **In practice**: The *performance* of a learner is monitored; if it dropped significantly below a threshold, statistically bounded, system triggers for a drift
- Drift detection methods are categorized into three groups:
  - Sequential Analysis based Methods:

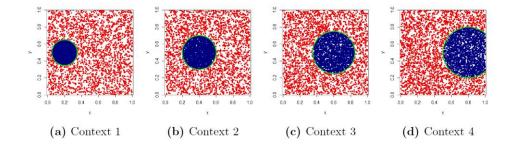
Cumulative Sum (CUSUM), PageHinkley (PH)

– Statistical based Methods:

Drift Detection Method (DDM), Early Drift Detection Method (EDDM), Reactive Drift Detection Method (RDDM)

Window based Methods:

Adaptive Windowing (ADWIN), SeqDrift detectors, Non-parametric Methods; e.g., HDDM, FHDDM, and MDDM



## Concept Drift Detection – Cont. FHDDM

The **FHDDM** algorithm slides a window with a size of *n* on the prediction results:

It inserts a 1 into the window if the prediction result is *correct*, and 0, otherwise.

FHDDM updates two registers, while the predictions are processed:

 $\mu^t$ : the mean of elements in the window at time t.  $\mu^m$ : the maximum mean observed so far.

Considering the PAC learning model:

 $\mu^m$  should increase or remains steady as we process instances.

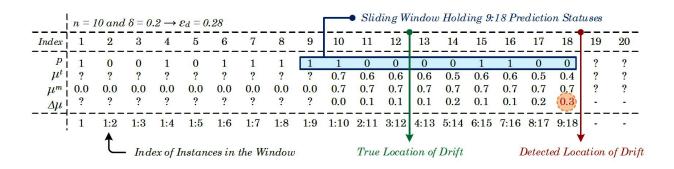
*Or* the possibility of facing a concept drift increases if  $\mu^m$  does not change and  $\mu^t$  decreases over time

Eventually, a significant difference between  $\mu^m$  and  $\mu^t$  indicates the occurrence of a drift in the stream

In a streaming setting, assume  $\mu^t$  is the mean of a sequence of n random entries, each in  $\{0, 1\}$ , at time t, and  $\mu^m$  is the maximum mean observed so far.

Let  $\Delta \mu = \mu^m - \mu^t \ge 0$  be the difference between the two mean. Then, given  $\delta$ , i.e., the probability of error allowed, Hoeffding's inequality guarantees a drift has happened if  $\Delta \mu \ge \varepsilon_d$ , where:

$$\varepsilon_d = \sqrt{\frac{1}{2n} \ln \frac{1}{\delta}}$$



## **Data shift Correction**





## Sample Re-weighting

#### Sample Re-weighting

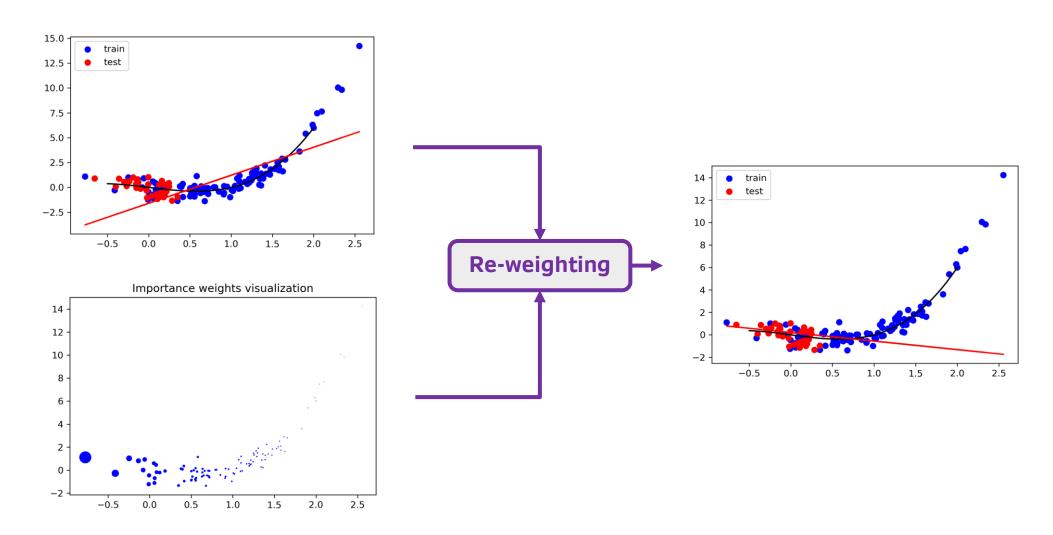
Idea: Re-weight each data point by the ratios of the probabilities:

$$\beta_i \equiv \frac{P_T(x)}{P_S(x)}$$

- In order to calculate  $\beta_i$ , we need to estimate the distribution ratios
- One of the ways to estimate  $\beta$  is to train a classifier to distinguish between the training and test sets
- If the training and test data is drawn from the same distribution, the classifier would not be able to distinguish between them (equal likelihood that a sample is drawn from either one of the distributions)
- We hope that the classifier can find a useful re-weighting factor
- NOTE: The classifier may fail to detect a dataset shift (false negative)

$$\beta = \frac{p(z = -1|x)}{p(z = 1|x)}$$

## Sample Re-weighting Example



### **Label Shift Correction**

#### **Label Shift Correction**

Idea: Re-weight each class using the ratio below:

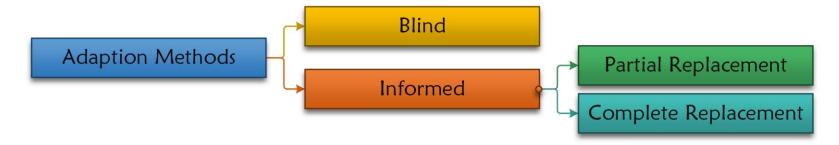
$$\beta_i \equiv \frac{P_T(y)}{P_S(y)}$$

- **Challenge**: How to estimate  $y_i \sim P_T(y)$ ?
- To estimate target label distribution, we use *confusion matrix*  $C_{k \times k}$  of a classifier that is trained on the source data
- Since we don't have access to the labels in the target data, we average model predictions on the test data to create  $\mu(\hat{y})$  whose its *i*th element is the fraction of total prediction on the test set where the classifier predicted label *i*
- **Assuming that the confusion matrix is invertible** we can estiamte  $\beta$  by solving the following linear system:

$$C_{k\times k} \equiv \mu(\hat{y})$$

## **Concept Drift Correction**

- Passive (Blind)
  - Update your model once a while without applying any shift detection
- Active (Informed)
  - Adapt your model once a shift detection triggers for a shift
  - Adaption or replacement could be globally or locally depending on the learning algorithm



### Advanced

# Transfer Learning & Active Learning





### What if we could not correct a model?

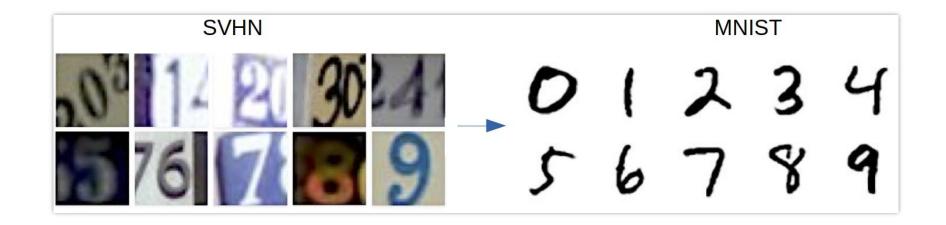
- Transfer learning Reusing an existing model
  - Same domain, different tasks
    - Target data has more/less classes (CIFAR-10 vs CIFAR-100)
    - Completely different tasks (trained for question-answering, used in sentiment analysis)
  - Different domains, same task
    - Training on grayscale images and testing on colored images
- Active learning Learning interactively with fewer training labels
  - Not enough data from the target domain
  - Significant difference between the source and target distributions (no overlap)
  - We have the option to collect new samples: how can we do it more efficiently and effectively?

## Transfer Learning

#### **Transfer Learning**

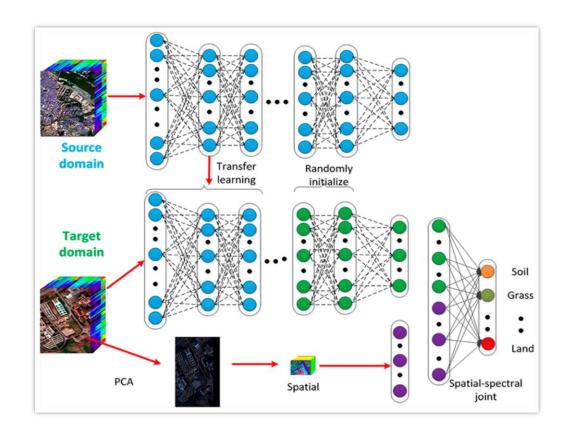
- Idea:
  - Layers in a neural network can be considered as feature representations
  - A common transfer paradigm is to maintain the weights in the earlier layers
    of network trained on some source task, and adapt only the weights in the last
    layer for a target task
  - Earlier layers may learn about abstract features such as edges and corners,
     which are common among different domains and tasks

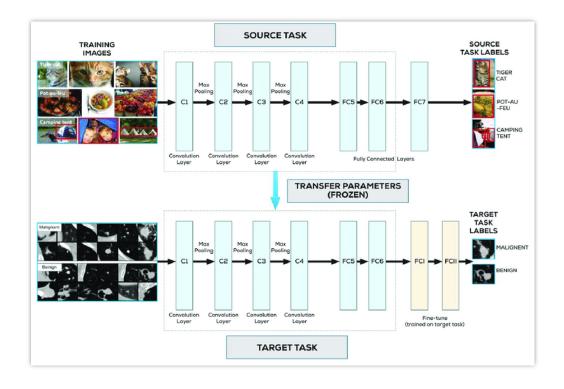
## Transfer Learning – Cont.



**Different domains, same task** 

## Transfer Learning – Cont.





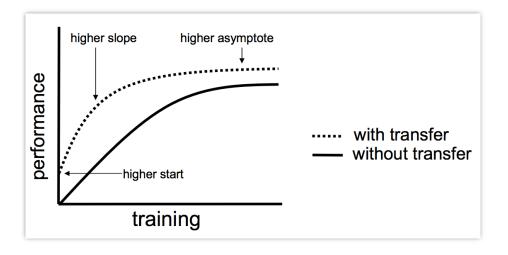
https://www.mdpi.com/2076-3417/9/7/1379/htm

https://pubmed.ncbi.nlm.nih.gov/30383900/

Same domain (colored images), different tasks

## Transfer Learning – Cont. Benefits

- Use the knowledge gained by a machine learning model from one task and apply it to a different task
- Possibility of reusing the same model
- The model training may have a higher start
- The training rate would improve
- The overall model performance may increase



## **Active Learning**

- The model prioritize the labeling of new data such that training the model on the new data would have the maximum impact on model performance
- Interactively query the user to label new data points
- Can significantly reduce the number of new labeled data points required
- Query selection strategies
  - Uncertainty Sampling
    - Classification uncertainty: Being less confident about the model predictions probabilities are not significantly different
    - Classification entropy: Uncertainty is proportional to the average number of guesses one must make to find the correct class

## Active Learning – Cont. Types

- Pool-based active learning
  - The model has access to a large pool of unlabeled data points
  - Query or rank the most informative samples
- Stream-based active learning
  - Stream of unlabeled samples
  - Decide to query the user for labeling of the streamed sample or not

## Discussion

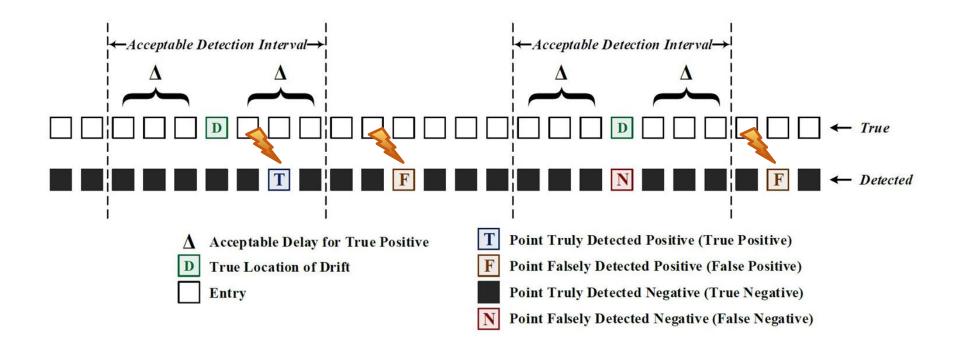




### **Evaluation Measures**

- What shift detector is preferred?
  - Highest true positive, lowest false positive and the lowest false negative
  - The resources will be kept busy if the drift detector incorrectly alarms for concept drift repeatedly.
  - The error-rate of classification typically increases as does the false negative number.
- The delay of detection:
  - Shorter detection delay results in losing less data for learning, it means more instances from the new distribution can be used for learning.
- How about the model accuracy or loss:
  - It confirms whether using drift detection methods are beneficial or not!

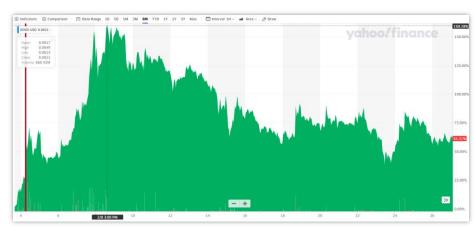
### **Evaluation Measures**



### Discussion

- Always keep track of your data and your model performance
- If your model accuracy dropped (significantly), something is off... most likely due to some shift in data
- The significant level varies from my domain to another
- If you are not detecting a shift, there could still be a shift in your data
- Domain knowledge helps a lot
- Different types of data shift can co-occur
- Model repository for recurring concepts Potentially for transfer learning
  - Some models trained in 2008 could be potentially used in 2020
- Track influencers





## Packages





### **TORNADO**



