

We are uncertain about the hidden variables.

We cannot observe them.

We capture this uncertainty by defining a posterior distribution over $Y = y_i$ given every training example

$X = x_i$.

$P[Y = y_i]$

$P[Y = y_i] = \text{prior}$ ✓

$P[Y = y_i | X = x_i] : \text{posterior}$ ✓

Y

y_i is the sampled value

X

$P[X = x_i | Y = y_i] : \text{likelihood}$ ✓

Generating an observation by sampling the likelihood function

The matrix Q captures the posterior distribution

$G(Q, \theta)$

$Q_{i,y} = P[Y = y_i | X = x_i]$

responsibility that the y_i^{th} Gaussian takes for the feature x_i

The surrogate function $G(Q, \theta)$ is formulated as

$$G(Q, \theta) = \overset{\text{I}}{F(Q, \theta)} - \overset{\text{II}}{\sum_{i=1}^m \sum_{y=1}^k Q_{i,y} \log Q_{i,y}}$$

for every row i : Entropy of the cat dist

$$\overset{\text{I}}{F(Q, \theta)} = \sum_{i=1}^m \sum_{y=1}^k Q_{i,y} \log \left(\underset{\text{obs}}{P_{\theta}[X = x_i]} \underset{\text{latent}}{P_{\theta}[Y = y_i]} \right)$$

Expectation

Posterior dist over $Y = y_i$ for $X = x_i$

likelihood of complete data: observed + hidden random variables

∴ the function $F(Q, \theta)$ gives the expectation of the log likelihood of the complete data with respect to the posterior distribution over the latent (hidden) variable Y .

Data
Given Array

$$a_1 a_2 a_3 \dots a_d$$

Distribution

$$p_1 p_2 \dots p_d$$

$$\sum_i p_i = 1$$

Expectation of
the array w.r.t.
the distribution

$$\sum_{i=1}^d p_i a_i$$

Complete data log likelihood

$$\log \left(P_{\theta} [x = x_i, y = y_i] \right)$$

$y=1$ $y=2$ $y=3$

x_i

$m \times d$

Posterior over the latent
variable y

$$P[y = y_i | x = x_i]$$

θ_{iy}

$m \times d$

Mean of a data
array \equiv

Expect Uniform distri-
bution w.r.t Uniform
distr

$$\sum_i \frac{1}{d} a_i = \frac{1}{d} \sum a_i$$

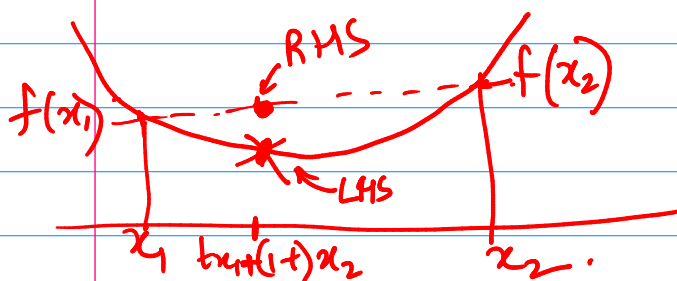
$$Q = \begin{matrix} & y & \xrightarrow{1} & 2 & 3 & 4 \\ \begin{matrix} x_1 \\ x_i \\ x_2 \\ x \end{matrix} & \begin{bmatrix} \frac{1}{p_1} & \frac{1}{p_2} & \frac{1}{p_3} & \dots \\ = & = & = & = \\ = & = & = & = \end{bmatrix} & \begin{matrix} \Sigma = 1. \\ \Sigma = 1. \end{matrix} \end{matrix}$$

Entropy

$$\sum_i p_i \log \frac{1}{p_i}$$

Jensen's Inequality

$$f \left(\underbrace{t x_1 + (1-t) x_2}_{\text{LHS}} \right) \leq \underbrace{t f(x_1) + (1-t) f(x_2)}_{\text{RHS}}$$



f is a convex function

likelihood of \underline{x}_i : $Y = y_i$ $\underline{x}_i \sim P(X|Y=y_i)$. (\underline{x}_i y_i)

Posterior $\frac{x_i}{P(Y=y_i|X=x_i)}$

The $G(Q, \theta)$ can be simplified as:

$F(Q, \theta)$

$$Q = \begin{bmatrix} y & \rightarrow & \dots & \rightarrow \\ \vdots & & \ddots & \\ i & & & Q_{i,y} \end{bmatrix}$$

$$G(Q, \theta) = \sum_{i=1}^m \sum_{y_i=1}^k Q_{i,y_i} \log P_{\theta}[X = \underline{x}_i, Y = y_i] - \sum_{i=1}^m \sum_{y_i=1}^k Q_{i,y_i} \log Q_{i,y_i}$$

$y = y_i$ ($Y = y$)

entropy of posterior over latent variables

\underline{x}_i
 $y_i \equiv y$
 $P(y|X=\underline{x}_i)$

Since it is implied that the random variable Y takes the value y_i in the context of example \underline{x}_i we write y instead of y_i

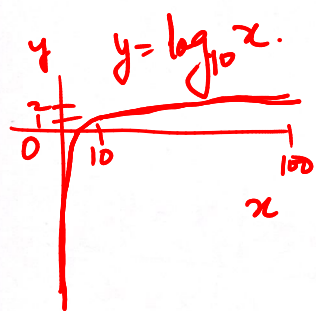
$$\log \frac{A}{B} = \log A - \log B$$

$$G(Q, \theta) = \sum_{i=1}^m \sum_{y=1}^k Q_{i,y} \log \frac{P_{\theta}[X = \underline{x}_i, Y = y]}{Q_{i,y}}$$

$Q_{i,y}$: responsibility taken by the y^{th} category for generating \underline{x}_i

✓ The upper bound of $G(Q, \theta)$ is $L(\theta)$.

$$G(Q, \theta) = \sum_{i=1}^m \sum_{y=1}^k Q_{i,y} \log \frac{P_{\theta}[X = \underline{x}_i, Y = y_i]}{Q_{i,y}}$$



$$\leq \sum_{i=1}^m \log \left(\sum_{y=1}^k Q_{i,y} \frac{P_{\theta}[X = \underline{x}_i, Y = y_i]}{Q_{i,y}} \right)$$

Jensen's inequality

$$= \sum_{i=1}^m \log \left(\sum_{y=1}^k P_{\theta}[X = \underline{x}_i, Y = y_i] \right)$$

Summing out the latent var

$$= \sum_{i=1}^m \log P_{\theta}[X = \underline{x}_i]$$

observed data log likelihood.

$$= L(\theta)$$

$$\therefore G(Q, \theta) \leq L(\theta)$$

The maximization procedure involves alternating between two steps

$t = 0, 1, 2, \dots$
 t : step equivalent steps

I E-step $Q^{(t+1)} = \underset{Q}{\operatorname{argmax}} G(Q, \underline{\theta}^{(t)})$ closed form Compute $Q^{(t+1)}$ with elements
 $Q_{i,y}^{(t+1)} = \underline{P_{\underline{\theta}^{(t)}}[Y=y_i | X=x_i]}$

II M-step $\underline{\theta}^{(t+1)} = \underset{\underline{\theta}}{\operatorname{argmax}} G(Q^{(t+1)}, \underline{\theta})$ $\underline{\theta}^{(t+1)} = \underset{\underline{\theta}}{\operatorname{argmax}} F(Q^{(t+1)}, \underline{\theta})$

EM algorithm

(Y) We know the property of G function that $G(Q, \underline{\theta}) \leq L(\underline{\theta})$
(X) that means $G(Q, \underline{\theta}^{(t)}) \leq L(\underline{\theta}^{(t)})$

Now, if we substitute a Q matrix with elements $Q_{i,y} = P_{\underline{\theta}}[Y=y_i | X=x_i]$ in $G(Q, \underline{\theta})$

$$G(Q, \underline{\theta}) = \sum_{i=1}^m \sum_{y_i=1}^k (Q_{i,y} \log P_{\underline{\theta}}[X=x_i, Y=y_i] - Q_{i,y} \log Q_{i,y})$$

$$= \sum_{i=1}^m \sum_{y_i=1}^k Q_{i,y} \log \frac{P_{\underline{\theta}}[X=x_i, Y=y_i]}{Q_{i,y}} \quad y_i \equiv y$$

$$= \sum_{i=1}^m \sum_{y_i=1}^k P_{\underline{\theta}}[Y=y_i | X=x_i] \log \frac{P_{\underline{\theta}}[X=x_i, Y=y_i]}{P_{\underline{\theta}}[Y=y_i | X=x_i]}$$

$$= \sum_{i=1}^m \sum_{y_i=1}^k P_{\underline{\theta}}[Y=y_i | X=x_i] \log P_{\underline{\theta}}[X=x_i]$$

$$= \sum_{i=1}^m \log P_{\underline{\theta}}[X=x_i] \sum_{y_i=1}^k P_{\underline{\theta}}[Y=y_i | X=x_i]$$

$$= \sum_{i=1}^m \log P_{\underline{\theta}}[X=x_i] = L(\underline{\theta})$$