

# Alireza Kargar

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in Alireza Kargar

## RESEARCH INTEREST

- Computer-Aided Design & Manufacturing.
- Robotics & System Design.
- Service Robots.
- Human-Robot Interaction.
- Rehabilitation Robotics.
- Social Robots.

## EDUCATION

- M.Sc. in Mechatronics Engineering** 2017–2021  
*University of Tehran* Tehran-Iran
- Thesis: Design and prototype a robot for cleaning glass façade buildings.
  - Supervisor: Dr. Manuchehr (Hadi) Moradi Sabzevar.
  - Overall GPA: 16.07/20.
- B.Sc. in Mechanical Engineering** 2013-2017  
*Islamic Azad University, West Tehran Branch* Tehran-Iran
- Thesis: Vehicle's mini wind turbine.
  - Supervisor: Dr. Hamed Moayeri Kashani.
  - Overall GPA: 15.81/20.

## PUBLICATION

- Mehralizadeh B, Soleiman P, Nikkhoo S, Rahimi M, **Kargar A**, Masoumi F, Moradi H. [Multi-Modal ASD Screening System: A Preliminary Study](#). In 2023 11th RSI International Conference on Robotics and Mechatronics (ICRoM) 2023 Dec 19 (pp. 228-234). IEEE
- Koochakzadeh E, **Kargar A**, Sattari P, Ravanshid Shirazi D, Nasiri R. Seven benefits of using series elastic actuators in the design of affordable prosthetic hands. In The 2024 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS 2024) – **Submitted**
- Nasiri R, Koochakzadeh E, **Kargar A**, Sattari P. A Novel Slippage Detection Method for Underactuated and Compliant Prosthetic Hands. – **Under Preparation**

## EXPERIENCE

### RESEARCH EXPERIENCE

- Research Assistant** 2023-Present  
*Research Institute for Robotics, Artificial Intelligence & Information Science (RAIIS).*  
Supervisor: Rezvan Nasiri
- **Prosthetic Hand:** Developing design and implementation of a 3D printed prosthetic hand powered by a series of elastic actuators controlled by Electromyography (EMG) signals.
- Research Assistant** 2017-2023  
*Advanced Robotics & Intelligent Systems (ARIS) Lab.*  
Supervisor: Manouchehr (Hadi) Moradi Sabzevar
- **Glass façade buildings cleaner robot:** Designed, prototyped, and controlled a compliant robotic system with significant irregularities on the building surface for cleaning or maintenance tasks.
  - **Multi-modal ASD screening system:** Designed, developed, and tested the required Robotic tools and equipment for the ASD Screening system.
  - **NeuroLight:** Developing design and implementation of a cyber-physical system comprised of programmable wireless light modules to improve athletes' speed and agility.
  - **BAMS.V2:** Designed and developed a holonomic-drive social robot platform that interacts with children for education and entertainment.
  - **Elbow rehabilitation robotic system:** Redesigned and prototyped an active series elastic mechanism for elbow rehabilitation.

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| <b>Research Assistant</b>  | <b>2015-2017</b> |
| <i>College of Engineering, Islamic Azad University, West Tehran Branch</i>   |                  |
| Supervisor: Dr. Hamed Moayeri Kashani.   |                  |
| <ul style="list-style-type: none"> <li>• <b>Vehicle's mini wind turbine:</b> Developed and prototyped a mini wind turbine for vehicles based on the concept of vertical-axis wind turbines.</li> <li>• <b>Automatic parasol:</b> Design and prototype an automatic parasol for urban open spaces to protect people from sunlight or rain.</li> <li>• <b>Automatic canopy:</b> Designing and prototyping a lightweight and inexpensive automatic canopy.</li> </ul> |                  |

## TEACHING & MENTORING EXPERIENCE .....

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|---|-------------------|
| <b>Lecturer</b>   | <b>2021- 2023</b> |
| <i>School of Electrical and Computer Engineering, University of Tehran.</i>   |                   |
| <ul style="list-style-type: none"> <li>• General Workshop course: CAD/CAM, SOLIDWORKS, Simplify3D.</li> </ul>   |                   |
| <b>Instructor</b>   | <b>2021-2022</b>  |
| <i>Scientific Association of Chemical and Polymer Engineering.</i>  |                   |
| <ul style="list-style-type: none"> <li>• Course: Computer-aided Design, SOLIDWORKS.</li> </ul>  |                   |
| <b>Teaching Assistant</b>   | <b>2020-2021</b>  |
| <i>School of Electrical and Computer Engineering, University of Tehran.</i>   |                   |
| <ul style="list-style-type: none"> <li>• General Workshop course Chief-TA: CAD/CAM, SOLIDWORKS, Simplify3D.</li> </ul>  |                   |
| <b>Teaching Assistant</b>   | <b>2019-2020</b>  |
| <ul style="list-style-type: none"> <li>• <i>School of Electrical and Computer Engineering, University of Tehran</i></li> <li>• Robotics course TA: Project design and grading.</li> </ul> |                   |
| <b>Mentor</b>   | <b>2018-2023</b>  |
| <i>Advanced Robotics &amp; Intelligent Systems Lab, University of Tehran.</i>   |                   |
| <ul style="list-style-type: none"> <li>• Trained new members in SOLIDWORKS, 3D printing, Arduino, and MATLAB.</li> </ul>  |                   |
| <b>Teaching Assistant</b>   | <b>2015-2016</b>  |
| <i>College of Engineering, Islamic Azad University, West Tehran Branch.</i>   |                   |
| <ul style="list-style-type: none"> <li>• Statics course TA: Supervisor of student Homework</li> <li>• programming Mentor: MATLAB &amp; Simulink</li> </ul>                                |                   |

## WORK EXPERIENCE.....

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|---|---------------------|
| <b>Freelancer</b>   | <b>2016-Present</b> |
| <i>Self-Employment</i>  |                     |
| Design and Implementation of Mechatronic systems and Mechanical goods.  |                     |
| <b>Mechatronics Engineer</b>  | <b>2022</b>         |
| <i>Tehran Platform Co.</i>  |                     |
| <ul style="list-style-type: none"> <li>• <b>XY plotter:</b> Design and develop a 2D plotter for drawing Architectural plans on a painting canvas.</li> </ul>        |                     |
| <b>Mechatronics Engineer</b>  | <b>2018</b>         |
| <i>Tehran Platform Co.</i>  |                     |
| <ul style="list-style-type: none"> <li>• <b>WELLOGRAPH - painter robot:</b> Redesign and Optimize the painting module of a holonomic-drive mobile robot.</li> </ul> |                     |
| <b>Research and Development team member</b>   | <b>2017-2018</b>    |
| <i>Hamyar Mechanic Kousha Co.</i>   |                     |
| <ul style="list-style-type: none"> <li>• Design and produce rehabilitation and easy-access equipment.</li> </ul>  |                     |
| <b>Internship</b>   | <b>2015</b>         |
| <i>Mehrsa Sanat Hooshmand</i>   |                     |
| <ul style="list-style-type: none"> <li>• Designed and Manufactured Hydraulic scrap car press baler (Compactor Machine)</li> </ul>                                   |                     |

## VOLUNTEER EXPERIENCE .....

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|---|-----------------|
| <b>Introduce technology-based ASD systems for children with Autism.</b>                   | <b>Oct.2018</b> |
| <i>Tehran Annual Digital Art Exhibition.</i>  |                 |
| <b>Introduce the novel research achievements of Azad University engineering students.</b> | <b>Dec.2016</b> |
| <i>Research Week Exhibition.</i>  |                 |

## TEST SCORE

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| <b>TOEFL</b>       | Overall Score: 107 (Listening:30, Reading:29, speaking:22, writing:26)  |
| <b>GRE General</b> | Overall Score: 328 (Quantitative:170, Verbal:158, Analytical Writing:5) |

## ACADEMIC PROJECTS

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|---|------------------|
| <b>HSRD:</b> Developing design and implementation of a Hand spasticity rehabilitation device for post-stroke recovery.  | <b>2021-2022</b> |
| <b>BAMS.V1:</b> Design and Develop an open-source interactive social robot head with sound-based localization and hand-tracking ability with the help of an IR sensors Array. | <b>2016</b>      |
| <b>B-bot:</b> Design and Implement a differential drive Mobile Robot that follows the path drawn by the user on the computer precisely on the ground with a particular scale. | <b>2016</b>      |

## WORKSHOPS & SEMINAR

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|---|-------------|
| Industrial automation expert training course    | <b>2018</b> |
| Mechatronics and Robotics course (Advanced)     | <b>2018</b> |
| Mechatronics and Robotics course (Introductory) | <b>2017</b> |
| MATLAB and Simulink for Mechanical Engineers    | <b>2017</b> |
| Mechanical design using CATIA software.         | <b>2017</b> |
| GD&T Geometric Tolerancing                      | <b>2017</b> |

## SKILLS

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|----------------------------|---|
| <b>CAD/CAM/CAE</b>         | SOLIDWORKS, CATIA, MSC Adams, 3D Printing Software, ABAQUS  |
| <b>Programming</b>         | Python, MATLAB, C/ C++ (Arduino), Ladder (PLC), ROS, Git    |
| <b>Professional skills</b> | Pneumatic & Hydraulic Systems                               |
| <b>Soft Skills</b>         | Critical thinking, R&D team leadership, Systematic thinking |
| <b>Language skill</b>      | English (Proficient), Farsi (Native)                        |

## REFERENCES

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**Dr. Manouchehr (Hadi) Moradi Sabzevar**, Professor, University of Tehran, Tehran, Iran.

- Email: [moradih@ut.ac.ir](mailto:moradih@ut.ac.ir)

**Dr. Seyed Kamaledin Setarehdan**, Professor, University of Tehran, Tehran, Iran.

- Email: [ksetareh@ut.ac.ir](mailto:ksetareh@ut.ac.ir)

**Dr. Rezvan Nasiri**, Assistant Professor, University of Tehran, Tehran, Iran.

- Email: [rezvan.nasiri@ut.ac.ir](mailto:rezvan.nasiri@ut.ac.ir)