# Alireza Kargar

**23/10/1994** 

Tehran, Iran.

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in Alireza Kargar

## RESEARCH INTEREST

• Computer-Aided Design & Manufacturing.

• Robotics & System Design.

• Service Robots.

- Human-Robot Interaction.
- Rehabilitation Robotics.
- Social Robots.

## **EDUCATION**

## M.Sc. in Mechatronics Engineering

2017-2021

University of Tehran

**Tehran-Iran** 

• Thesis: Design and prototype a robot for cleaning glass façade buildings.

• Supervisor: Dr. Manuchehr (Hadi) Moradi Sabzevar.

• Overall GPA: 16.07/20.

#### **B.Sc.** in Mechanical Engineering

2013-2017 Tehran-Iran

Islamic Azad University, West Tehran Branch

• Thesis: Vehicle's mini wind turbine.

• Supervisor: Dr. Hamed Moayeri Kashani.

• Overall GPA: 15.81/20.

## **PUBLICATION**

 Mehralizadeh B, Soleiman P, Nikkhoo S, Rahimi M, Kargar A, Masoumi F, Moradi H. Multi-Modal ASD Screening System: A Preliminary Study. In2023 11th RSI International Conference on Robotics and Mechatronics (ICRoM) 2023 Dec 19 (pp. 228-234). IEEE

• Koochakzadeh E, **Kargar A**, Sattari P, Ravanshid Shirazi D, Nasiri R. Seven benefits of using series elastic actuators in the design of affordable prosthetic hands. In The 2024 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS 2024) – **Accepted** 

#### **EXPERIENCE**

## RESEARCH EXPERIENCE

2023-Present

Research Assistant
Research Institute for Robotics, Artificial Intelligence & Information Science (RAIIS).

Supervisor: Rezvan Nasiri

• **Prosthetic Hand:** Developing design and implementation of a 3D printed prosthetic hand powered by a series of elastic actuators controlled by Electromyography (EMG) signals.

Research Assistant 2017- Present

Advanced Robotics & Intelligent Systems (ARIS) Lab.

Supervisor: Manouchehr (Hadi) Moradi Sabzevar

- Glass façade buildings cleaner robot: Designed, prototyped, and controlled a compliant robotic system with significant irregularities on the building surface for cleaning or maintenance tasks.
- **Multi-modal ASD screening system:** Designed, developed, and tested the required Robotic tools and equipment for the ASD Screening system.
- **NeuroLight:** Developing design and implementation of a cyber-physical system comprised of programmable wireless light modules to improve individuals' speed and agility.
- **BAMS.V2:** Designed and developed a holonomic-drive social robot platform that interacts with children for education and entertainment.
- Elbow rehabilitation robotic system: Redesigned and prototyped an active series elastic mechanism for elbow rehabilitation.

Research Assistant 2015-2017

College of Engineering, Islamic Azad University, West Tehran Branch

Supervisor: Dr. Hamed Moayeri Kashani.

Mechanical design using CATIA software.

GD&T Geometric Tolerancing

• **Vehicle's mini wind turbine:** Developed and prototyped a mini wind turbine for vehicles based on the concept of vertical-axis wind turbines.

• **Automatic parasol:** Design and prototype an automatic parasol for urban open spaces to protect people from sunlight or rain.

or rain.		
<ul> <li>Automatic ca</li> </ul>	<b>Inopy:</b> Designing and prototyping a lightweight and inexpensive automatic canopy.	
TEACHING & N	MENTORING EXPERIENCE	
Lecturer		2022- 2023
School of Electric	cal and Computer Engineering, University of Tehran.	
• General	Workshop course: CAD/CAM, SOLIDWORKS, Simplify3D.	
Instructor		2021-2022
·	ntion of Chemical and Polymer Engineering.	
<ul> <li>Course: Computer-aided Design, SOLIDWORKS.</li> </ul>		
Teaching Assistant		2021-2022
· ·	cal and Computer Engineering, University of Tehran.	
• General Workshop course Chief-TA: CAD/CAM, SOLIDWORKS, Simplify3D.		
Teaching Assistant		2019-2020
	f Electrical and Computer Engineering, University of Tehran	
	s course TA: Project design and grading.	2010 2022
Mentor		2018-2023
	cs & Intelligent Systems Lab, University of Tehran.	
• Trained new members in SOLIDWORKS, 3D printing, Arduino, and MATLAB.		2015-2016
<b>Teaching Assistant</b> College of Engineering, Islamic Azad University, West Tehran Branch.		2015-2010
<ul> <li>Statics course TA: Supervisor of student Homework</li> </ul>		
	ming Mentor: MATLAB & Simulink	
1 0		
VOLUNTEER E	XPERIENCE	• • • • • • • • • • • • • • • • • • • •
Introduce technology-based ASD systems for children with Autism.		Oct.2018
Tehran Annual D	Digital Art Exhibition.	
Introduce the novel research achievements of Azad University engineering students.		Dec.2016
Research Week E	Exhibition.	
TEST SCOR	${f E}$	
TOEFL	Overall Score: 107 (Listening:30, Reading:29, speaking:22, writing:26)	
GRE General	Overall Score: 328 (Quantitive:170, Verbal:158, Analytical Writing:5)	
<b>ACADEMIC</b>	PROJECTS	
<b>HSRD:</b> Developing design and implementation of a Hand spasticity rehabilitation device for post-stroke recovery.		2021-2022
•	n and Develop an open-source interactive social robot head with sound-based	
localization and hand-tracking ability with the help of an IR sensors Array.		2016
B-bot: Design and Implement a differential drive Mobile Robot that follows the path drawn by		2016
the user on the co	omputer precisely on the ground with a particular scale.	2010
WORKSHOP	PS & SEMINAR	
		2018
Industrial automation expert training course		
Mechatronics and Robotics course (Advanced)		2018
Mechatronics and Robotics course (Introductory)		2017
MATLAB and Simulink for Mechanical Engineers		2017
3.5	· CLATETA C	2017

2017

2017

# **SKILLS**

CAD/CAM/CAE SOLIDWORKS, CATIA, MSC Adams, 3D Printing Software, ABAQUS

**Programming** Python, MATLAB, C/C++ (Arduino), Ladder (PLC), ROS, Git

Professional skills Pneumatic & Hydraulic Systems

Soft Skills Critical thinking, R&D team leadership, Systematic thinking

Language skill English (Proficient), Farsi (Native)

## REFERENCES

Dr. Manouchehr (Hadi) Moradi Sabzevar, Professor, University of Tehran, Tehran, Iran.

• Email: moradih@ut.ac.ir

Dr. Seyed Kamaledin Setarehdan, Professor, University of Tehran, Tehran, Iran.

• Email: <u>ksetareh@ut.ac.ir</u>

Dr. Rezvan Nasiri, Assistant Professor, University of Tehran, Tehran, Iran.

• Email: rezvan.nasiri@ut.ac.ir