neural network using Keras.

A Quick Guide on Training a



TensorFlow and Keras

Keras

- Open source
- High level, less flexible
- Easy to learn
- Perfect for quick implementations
- Starts by François Chollet from a project and developed by lots of people.
- Written in Python, wrapper for Theano, TensorFlow, and CNTK

TensorFlow

- Open Source
- Low level, you can do everything!
- Complete documentation
- Deep learning research, complex networks
- Was developed by the Google Brain team
- Written mostly in C++ and CUDA and Python

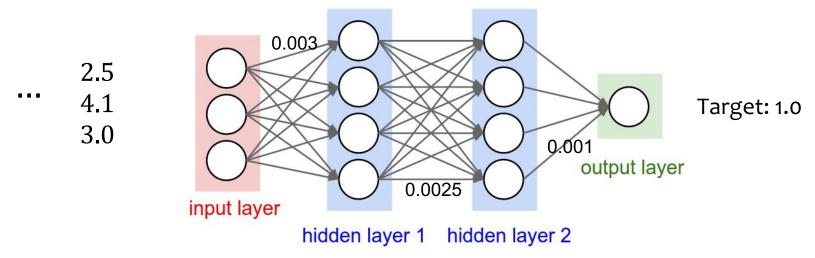


Feed Forward MNIST

Recurrent networks, cosine function

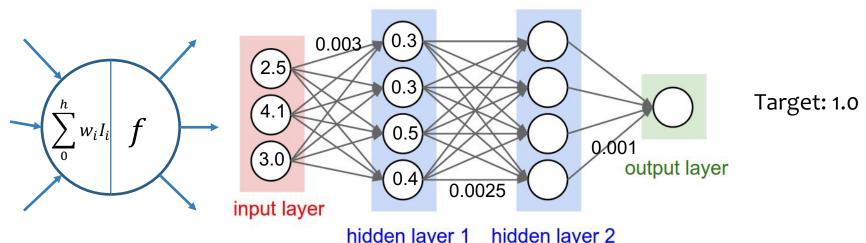
Convolutional MNIST





Weight Initialization and Loading the Data

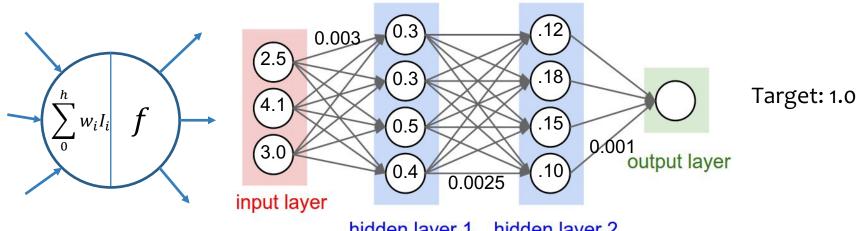




hidden layer 1 hidden layer 2

Going forward (Regularization, Dropout, Batch Normalization, ...)

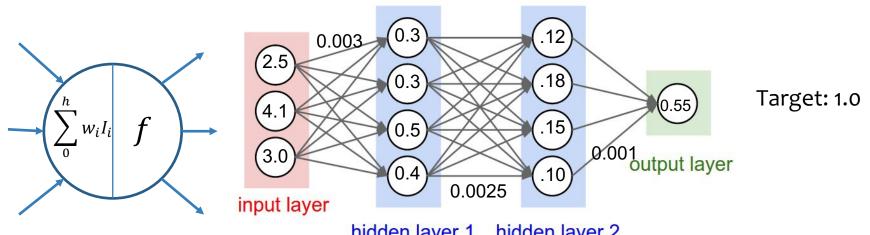




hidden layer 1 hidden layer 2

Going forward (Regularization, Dropout, Batch Normalization, ...)

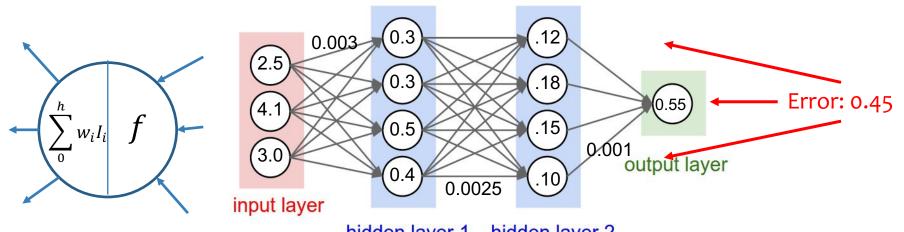




hidden layer 1 hidden layer 2

Loss Function: $(T - O) \Rightarrow Loss: 0.45$





hidden layer 1 hidden layer 2

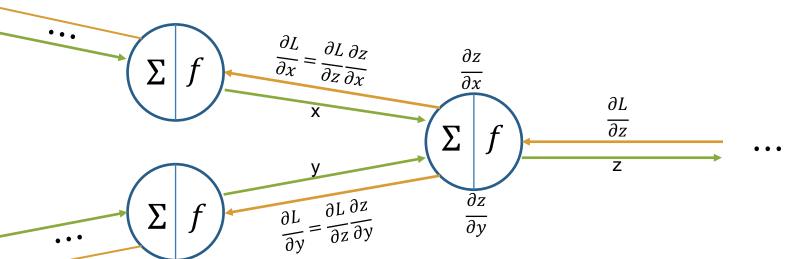
Updating the weights using Backpropagation $\frac{\partial E}{\partial w_i^i}$

http://cs231n.github.io/optimization-2/

More on Backpropagation:

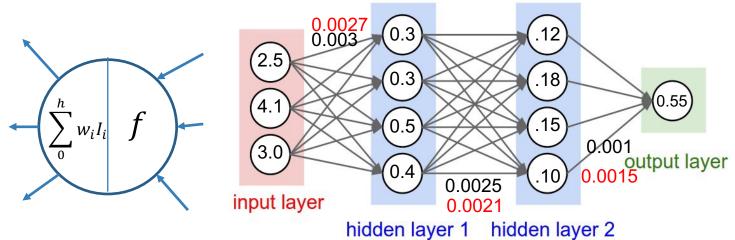
http://arxiv.org/abs/1502.05767





Backpropagation





By Choosing the Optimizer, new weights will be computed $w_{new} = w - \eta \frac{\partial w}{\partial w}$

Now Let's Code!



Sequential Model

Add layers

Define all operations

Define the output layer

Instantiate an object from Keras.model.Sequential class. All information about your network such as weights, layers, operations will be stored in this object.



Sequential Model

Add layers

Define all operations

Define the output layer

The magic "add" method, makes your life easier!

You can create any layer of your choice in the network using model.add(layer_name).

This method will preserve the order of layers you add.



Sequential Model

Add layers

Define operations per layer

Define the output layer

There are lots of layers implemented in keras. When you add a layer to you model, a gradient operation will be created in the background and it will take care of computing the backward gradient automatically!



Sequential Model

Add layers

Define all operations

Define the output layer

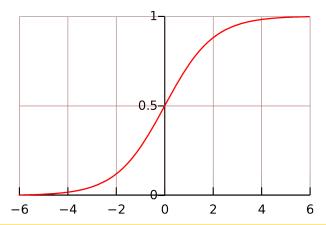
In this example we use Dense layer, which is the basic feed forward fully connected layer.

All operations of a layer can be passed as args to the Dense Object.

- Number of hidden units
- Activation function
- 3. Bias
- 4. Weight/bias initialization
- 5. Weight/bias regularization
- 6. Activation regularization

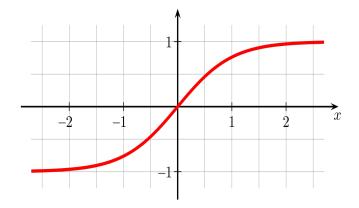


$$sigmoid: f(x) = \frac{1}{1 + e^{-x}}$$



- The output is not zero centered!
- Exp() is a relatively expensive operation.
- Small active region

$$tanh: f(x) = \tanh(x)$$



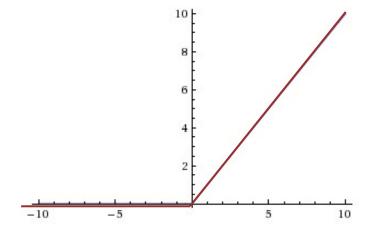
- Out put is zero centered (good)
- Exp() is an expensive operation
- Smaller active region!



Sigmoid() is not a good choices!

Think about the backward path when all then inputs to a neuron are positive numbers.

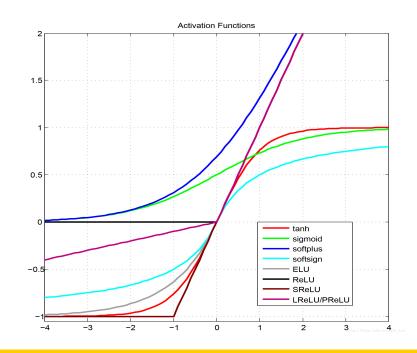
ReLU (Rectifier Linear Unit):
$$f(x) = \begin{cases} 0, & x < 0 \\ x, & x \ge 0 \end{cases}$$



A neuron will be active during the backprop if the out put was a positive number.



Other activation functions





Weight initialization

Initialize all the Ws at Zero!

Small random numbers

Xavier Initialization

Other Ideas



What happen when you initialize all the weights at Zero?

Hint: Think about backpropagation



Small random numbers?

o.oo1*np.random.randn(M, N)

Not good for deep networks! What happened during the backpropagation?



Xavier Initialization [Glorot et al., 2010]

np.random.randn(fan_in, fan_out) / np.sqrt(fan_in)

Fixes the problem of small random numbers with linear activation.



You can use other available initializations e.g. [He et al., 2015]
Or you can write your own initialization.

- Exact solutions to the nonlinear dynamics of learning in deep linear neural networks
- Random walk initialization for training very deep feedforward networks
- Delving deep into rectifiers: Surpassing human-level performance on ImageNet classification
- Data-dependent Initializations of Convolutional Neural Networks
- All you need is a good init



Regularization

L1 Regularization
$$loss += \lambda(\sum_{i=0}^{n} |w_i|)$$

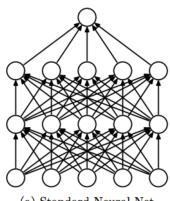
L2 Regularization
$$loss += \lambda(\sum_{i=0}^{h} w_i^2)$$

Sanity Check: your loss should become larger when you use regularization.

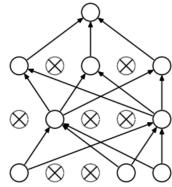


keras.layers.Dropout(rate)

Randomly setting a fraction rate of input units to o at each update during training time.



(a) Standard Neural Net



(b) After applying dropout.



Sequential Model

Add layers

Define all operations

Define the output layer

Based on the task of prediction, you need to define your output layer properly.

For classification task on MNIST dataset, we have ten possible classes, so it's a multiclass classification. So it's better to use softmax activation for a ten unit output layer.



Compile your model

model.compile(loss, optimizer, metrics)

Losses: mean_squared_error, squared_hinge, categorical_hinge, binary_crossentropy, ...

Optimizers: SGD, Adam, RMSprop, ...

Metrics: binary_accuracy, categorical_accuracy, top_k_categorical_accuracy



Categorical crossentropy is the appropriate loss function for the softmax output

For linear outputs use mean_squared_error

For logisticoutputs use binomial crossentropy

Optimizers

```
while True:
    batch_of_data = training_set.sample_data_batch()
    loss = NN.forward_path()
    dw = NN.backward_path()
    w += -learning_rate * dx
```

Optimizers

```
#Momentum update
v = mu * v - learning_rate * dw #think of v as velocity.
w += v
```

```
#Nestrov momentum update
v_previous = v
v = mu * v -learning_rate * dw
w += -mu * v_previous + (1+mu) * v
```

SP

Optimizers

```
#Adagrad update
epsilon = 1e-7
mem += dw**2
w += -learning_rate * dw / (np.sqrt(mem) + epsilon)
```

```
#RMSProp
epsilon = 1e-7
mem = decay_rate * mem + (1 - decay_rate) * (dw**2)
w += -learning_rate * dw / (np.sqrt(mem) + epsilon)
```



Train the model

History = model.fit(X_train, Y_train, batch_size, ...)

Batch_size

Epoches

Validation split, Validation data

Callbacks

Shuffle

Class_weights



Train the model

History Object

Attribute **History.history** sotres training loss, validation loss, metrics, validation metrics values at successive epochs in a python dictionary.



Evaluate the performance

model.evaluate(X_test, Y_test, verbose)

Returns a list of score. First element is the loss and the rest are the metrics you specified during the compilation of your model.



Do the prediction!

model.predict_classes(data)

You can use your trained model to predict the class of a given input.

How can we make it better?

LL



Feed Forward MNIST

Recurrent networks, Learning cosine function

Convolutional MNIST

Anrej Karpathy note

Colah's blog



Recurrent Network

• What is the digit written in the image?



What is the next character?

Hell_



Recurrent Network

What is the digit written in the image?



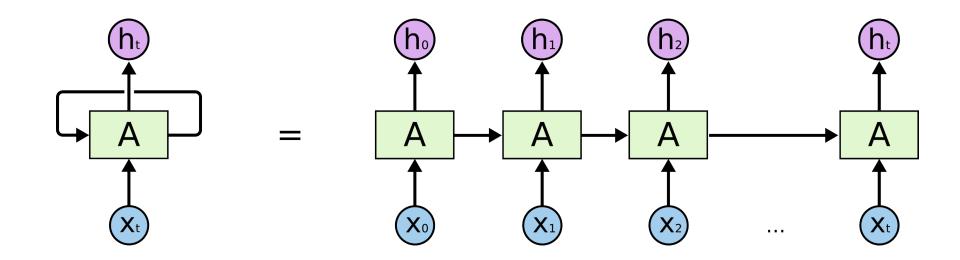
Input: an Image (a matrix of numbers)
Output: one of the 10 possible classes

What is the next character?



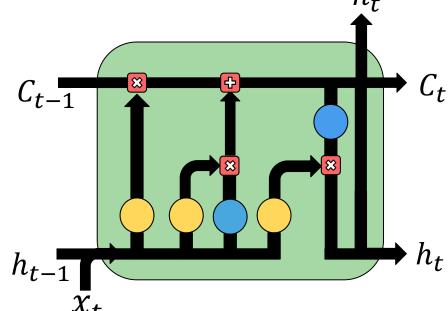
Input: ?

Output: one of the 26 possible classes





- 🛑 : σ
- : Tanh



Learn the cosine function by

looking at previous inputs.



Vanilla LSTM

Stateful LSTM

Wider Window



Vanilla LSTN

How can we make it better?

Wider Window



Vanilla LSTM

Stateful LSTM

Wider Window



Vanilla LSTN

How can we make it better?

Wider Window



Vanilla LSTM

Stateful LSTM

Wider Window



Vanilla LSTM

How can we make it better?

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Vanilla LSTM

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Vanilla LSTN

Let's try a feed forward network!

Wider Window