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$$\begin{aligned} dl &= \sqrt{dx^2 + dy^2 + dz^2} \\ ds &= \sqrt{dx^2 + dy^2 + dz^2} \\ dv &= \sqrt{dx^2 + dy^2 + dz^2} \end{aligned} \quad \leftarrow \quad \text{نکته}$$

$$A(u_1, u_2, u_3)$$



$$B(u_1+du_1, u_2+du_2, u_3+du_3)$$

$$\overline{dl}_1 : \begin{cases} u_1 \rightarrow u_1 + du_1 \\ u_2 = \text{ثابت} \\ u_3 = \text{ثابت} \end{cases}$$

$$\overline{dl}_2 : \begin{cases} u_2 \rightarrow u_2 + du_2 \\ u_1 = \text{ثابت} \\ u_3 = \text{ثابت} \end{cases}$$

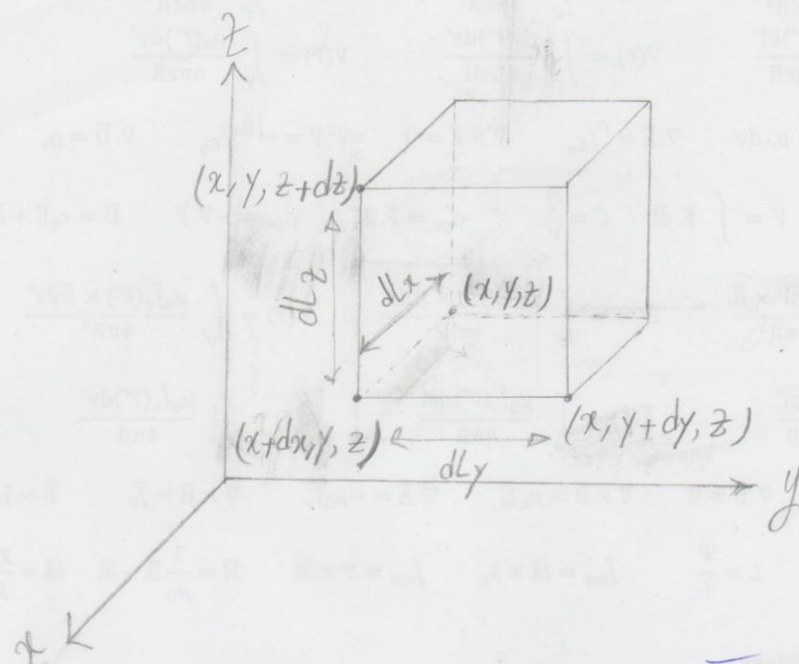
$$\overline{dl}_3 : \begin{cases} u_3 \rightarrow u_3 + du_3 \\ u_1 = \text{ثابت} \\ u_2 = \text{ثابت} \end{cases}$$

برای هر i ($i=1,2,3$) du_i و \overline{dl}_i

$$\overline{dl}_i = h_i du_i \hat{a}_{L_i}, \quad i=1,2,3$$

$$h_i(u_1, u_2, u_3)$$

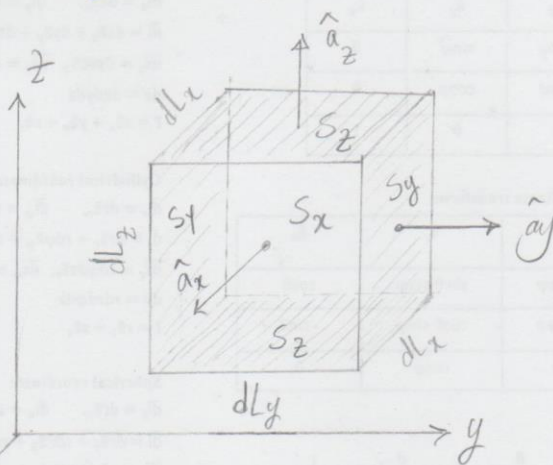
مساحت و حجم یک عنصر:



مساحت:

$$\begin{cases} dx = dx \hat{a}_x, & h_x = 1 \\ dy = dy \hat{a}_y, & h_y = 1 \\ dz = dz \hat{a}_z, & h_z = 1 \end{cases}$$

$$\begin{aligned} d\vec{r} &= dx \hat{a}_x + dy \hat{a}_y + dz \hat{a}_z \\ &= dx \hat{a}_x + dy \hat{a}_y + dz \hat{a}_z \end{aligned}$$



مساحت:

$$\begin{cases} ds_x = \pm dy dz \hat{a}_x \\ ds_y = \pm dx dz \hat{a}_y \\ ds_z = \pm dx dy \hat{a}_z \end{cases} \rightarrow$$

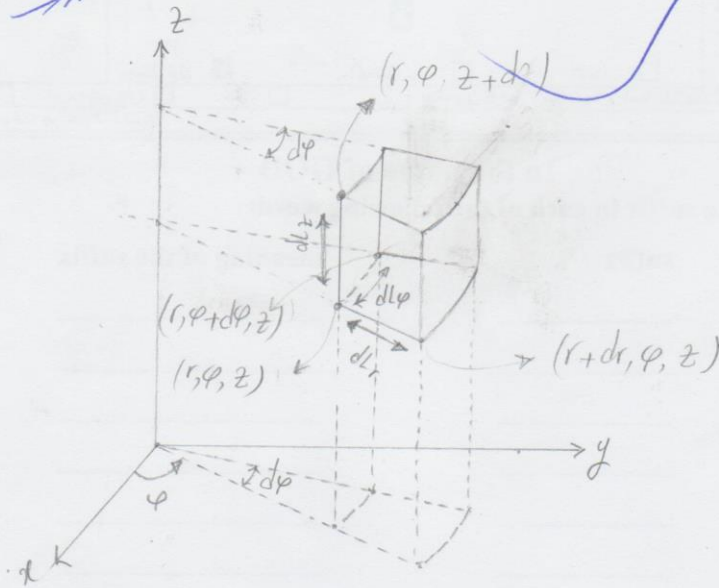
مساحت:

$$\begin{cases} ds_x = \pm dy dz \hat{a}_x \\ ds_y = \pm dx dz \hat{a}_y \\ ds_z = \pm dx dy \hat{a}_z \end{cases}$$

حجم:

$$\begin{aligned} dv &= dx dy dz \\ &= dx dy dz \end{aligned}$$

مساحة مقطع الزوايا :

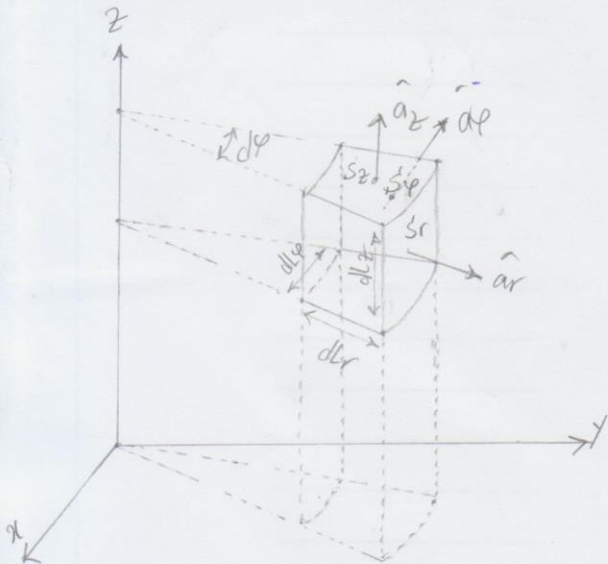


مساحة مقطع الزوايا :

مساحة مقطع الزوايا :

$$\begin{aligned} \overline{dlr} &= dr \hat{a}_r, \quad h_r = 1 \\ \overline{dl\phi} &= r d\phi \hat{a}_\phi, \quad h_\phi = 1 \\ \overline{dlz} &= dz \hat{a}_z, \quad h_z = 1 \end{aligned}$$

$$\begin{aligned} \overline{dh} &= \overline{dlr} + \overline{dl\phi} + \overline{dlz} \\ &= dr \hat{a}_r + r d\phi \hat{a}_\phi + dz \hat{a}_z \end{aligned}$$

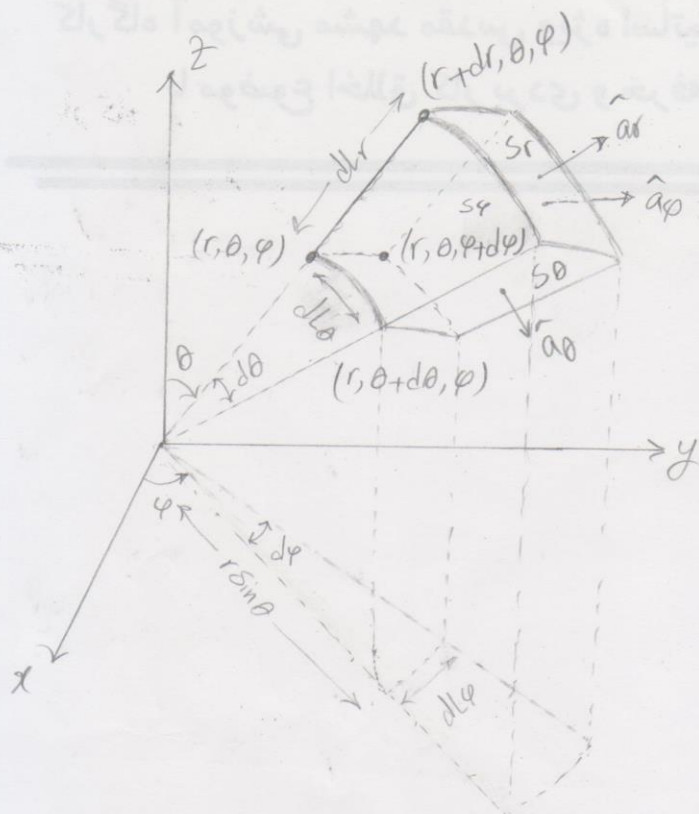


مساحة مقطع الزوايا :

$$\begin{aligned} \overline{ds_r} &= \pm dl\phi dlz \hat{a}_\phi \pm r d\phi dz \hat{a}_r \\ \overline{ds_\phi} &= \pm dlr dlz = \pm dr dz \hat{a}_\phi \\ \overline{ds_z} &= \pm dl\phi dlr = \pm r dr d\phi \hat{a}_z \end{aligned}$$

مساحة مقطع الزوايا :

$$\begin{aligned} dv &= dlr \cdot dl\phi \cdot dlz \\ &= r dr d\phi dz \end{aligned}$$



دifferential elements:

$$\begin{cases} dr = dr \hat{r}, & h_r = 1 \\ d\theta = r d\theta \hat{\theta}, & h_\theta = r \\ d\phi = r \sin\theta d\phi \hat{\phi}, & h_\phi = r \sin\theta \end{cases}$$

Differential displacement vector:

$$\begin{aligned} d\vec{r} &= dr \hat{r} + r d\theta \hat{\theta} + r \sin\theta d\phi \hat{\phi} \\ &= dr \hat{r} + r d\theta \hat{\theta} + r \sin\theta d\phi \hat{\phi} \end{aligned}$$

Differential surface elements:

$$\begin{cases} ds_r = \pm d\theta d\phi \hat{r} = \pm r^2 \sin\theta d\theta d\phi \hat{r} \\ ds_\theta = \pm dr d\phi \hat{\theta} = \pm r \sin\theta dr d\phi \hat{\theta} \\ ds_\phi = \pm dr d\theta \hat{\phi} = \pm r dr d\theta \hat{\phi} \end{cases}$$

Differential volume element:

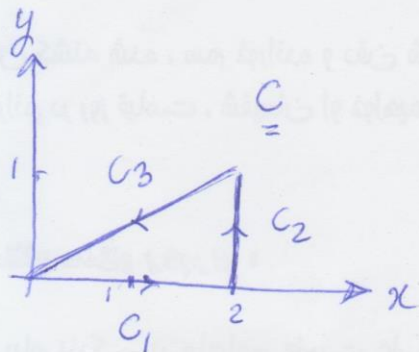
$$dV = dr d\theta d\phi = r^2 \sin\theta dr d\theta d\phi$$

2)

مسألة

$$\int_C \bar{A} \cdot d\bar{L}, \int_C \bar{A} \times d\bar{L}, \int_C \bar{A} dL, \int_C A dL$$

C: منحني مغلق



$$\int \bar{A} \cdot d\bar{L}$$

مسألة

$$\bar{A} = (2x + y^2) \hat{a}_x + (3y - 4x) \hat{a}_y$$

مسألة

$$\oint_C \bar{A} \cdot d\bar{L} = \int_{C_1} \bar{A} \cdot d\bar{L} + \int_{C_2} \bar{A} \cdot d\bar{L} + \int_{C_3} \bar{A} \cdot d\bar{L}$$

$$C_1: \begin{cases} y=0, \\ z=0, \\ 0 \leq x \leq 2 \end{cases} \rightarrow d\bar{L} = dx \hat{a}_x$$

$$\bar{A} = 2x \hat{a}_x - 4x \hat{a}_y, \quad \bar{A} \cdot d\bar{L} = (2x \hat{a}_x - 4x \hat{a}_y) \cdot dx \hat{a}_x = 2x dx$$

$$\int_{C_1} \bar{A} \cdot d\bar{L} = \int_{x=0}^{x=2} 2x dx = x^2 \Big|_{x=0}^2 = 4$$

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$$\underline{C_2}: \begin{cases} z=2, \text{ sub} \\ z=0, \text{ sub} \\ 0 \leq y \leq 1 \end{cases} \rightarrow d\vec{L} = d\vec{L}_y = dy \hat{a}_y$$

$$\vec{A} = (4+y^2) \hat{a}_x + (3y-8) \hat{a}_y$$

$$\vec{A} \cdot d\vec{L} = [(4+y^2) \hat{a}_x + (3y-8) \hat{a}_y] \cdot dy \hat{a}_y = (3y-8) dy$$

$$\int_{C_2} \vec{A} \cdot d\vec{L} = \int_{y=0}^{y=1} (3y-8) dy = \left. \frac{3}{2} y^2 - 8y \right|_{y=0}^1 = \frac{3}{2} - 8 = -\frac{13}{2}$$

$$\underline{C_3}: \begin{cases} z=0, \text{ sub} \\ 2 \leq x \leq 0 \\ 1 \leq y \leq 0 \end{cases} \quad d\vec{L} = d\vec{L}_x + d\vec{L}_y = dx \hat{a}_x + dy \hat{a}_y$$

$$\begin{cases} y = \frac{1}{2}x \\ dy = \frac{1}{2}dx \end{cases} \quad ; C_3 \text{ clockwise}$$

$$\vec{A} = (2x+y^2) \hat{a}_x + (3y-4x) \hat{a}_y = (2x + \frac{1}{4}x^2) \hat{a}_x + (\frac{3}{2}x - 4x) \hat{a}_y$$

$$= (2x + \frac{x^2}{4}) \hat{a}_x - \frac{5}{2}x \hat{a}_y \quad |_{y=\frac{1}{2}x}$$

$$\vec{A} \cdot d\vec{L} = \left[(2x + \frac{x^2}{4}) \hat{a}_x - \frac{5}{2}x \hat{a}_y \right] \cdot (dx \hat{a}_x + \frac{1}{2}dx \hat{a}_y)$$

$$= (2x + \frac{x^2}{4}) dx - \frac{5}{2}x \cdot \frac{1}{2}dx = (\frac{3}{4}x + \frac{x^2}{4}) dx$$

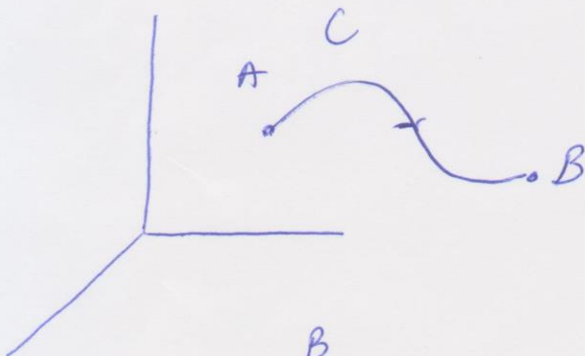
$$\int_{C_3} \bar{A} \cdot d\bar{u} = \int_{x=2}^0 \left(\frac{3}{4}x + \frac{x^2}{4} \right) dx = \left. \frac{3}{8}x^2 + \frac{x^3}{12} \right|_{x=2}^0 = -\frac{13}{6}$$

$$\therefore \oint_C \bar{A} \cdot d\bar{u} = +4 - \frac{13}{2} - \frac{13}{6} = -\frac{14}{3}$$

$$\oint_C \bar{A} \cdot d\bar{u} = \oint_C (A_x \hat{a}_x + A_y \hat{a}_y + A_z \hat{a}_z) \cdot (dx \hat{a}_x + dy \hat{a}_y + dz \hat{a}_z)$$

$$= \oint_C (A_x dx + A_y dy + A_z dz)$$

الحلقة مغلقة (على رؤسها)



مسار مفتوح في مستوى:

$$\int_A^B |d\bar{u}| = \int_C d\bar{u} \quad , \quad d\bar{u} = dx \hat{a}_x + dy \hat{a}_y + dz \hat{a}_z$$

$$|d\bar{u}| = (dx^2 + dy^2 + dz^2)^{1/2}$$

$$= dx \left(1 + \left(\frac{dy}{dx} \right)^2 + \left(\frac{dz}{dx} \right)^2 \right)^{1/2}$$

$$\vec{ds} = ds \hat{a}_n$$

\hat{a}_n : بردار عمود بر سطح

$$\oint_S \vec{A} \cdot \vec{ds}$$

نگرش سطح

- در حالت کلی بردار \vec{ds} در جهت مخالف تندیر وجود دارد

- اگر سطح بسته باشد، جهت \vec{ds} عمود بر سطح به سمت خارج سطح است.

$$f(u_1, u_2, u_3) = K$$

معادله سطح S

نموده حالت بردار عمود بر سطح

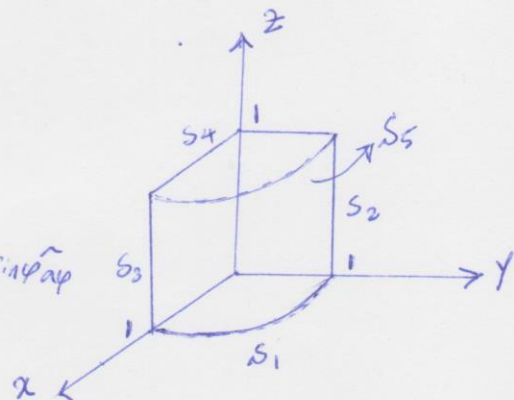
$$\vec{ds} = ds \hat{a}_n, \quad \hat{a}_n = \frac{\vec{N}}{|\vec{N}|}$$

$$\vec{N} = \nabla f = \frac{\partial f}{\partial x} \hat{a}_x + \frac{\partial f}{\partial y} \hat{a}_y + \frac{\partial f}{\partial z} \hat{a}_z$$

مسئله

$$\oint_S \vec{A} \cdot \vec{ds}$$

$$\vec{A} = r \cos \varphi \hat{a}_r - r \sin \varphi \hat{a}_\varphi$$



حل:

$$\oint_S \vec{A} \cdot \vec{ds} = \int_{S_1} \vec{A} \cdot \vec{ds} + \int_{S_2} \vec{A} \cdot \vec{ds} + \int_{S_3} \vec{A} \cdot \vec{ds} + \int_{S_4} \vec{A} \cdot \vec{ds} + \int_{S_5} \vec{A} \cdot \vec{ds}$$

درست! فقط استوانه ای

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Jo

$$S_1: \begin{cases} z=0 \\ 0 \leq \varphi \leq \pi/2 \\ 0 \leq r \leq 1 \end{cases} \rightarrow \begin{aligned} \overline{ds} &= ds_z = \pm r dr d\varphi \hat{a}_z \\ \overline{ds} &= -r dr d\varphi \hat{a}_z \end{aligned}$$

$$\vec{A} \cdot \overline{ds} = (r \cos \varphi \hat{a}_r - r \sin \varphi \hat{a}_\varphi) \cdot (-r dr d\varphi \hat{a}_z) = 0 \rightarrow \int_{S_1} \vec{A} \cdot \overline{ds} = 0$$

$$S_2: \begin{cases} \varphi = \pi/2 \\ 0 \leq r \leq 1 \\ 0 \leq z \leq 1 \end{cases} \rightarrow \begin{aligned} \overline{ds} &= \overline{ds}_\varphi = \pm dr dz \hat{a}_\varphi \\ \overline{ds} &= + dr dz \hat{a}_\varphi \end{aligned}$$

$$\vec{A} \cdot \overline{ds} = (r \cos \varphi \hat{a}_r - r \sin \varphi \hat{a}_\varphi) \cdot (dr dz \hat{a}_\varphi) = -r \sin \varphi dr dz$$

$$\int_{S_2} \vec{A} \cdot \overline{ds} = \int_{\varphi=\pi/2} \int_{r=0}^1 \int_{z=0}^1 -r \sin \varphi dr dz = -\frac{r^2}{2} \Big|_{r=0}^1 \Big|_{z=0}^1 = -\frac{1}{2}$$

$$S_3: \begin{cases} \varphi = 0 \\ 0 \leq r \leq 1 \\ 0 \leq z \leq 1 \end{cases} \rightarrow \begin{aligned} \overline{ds} &= \overline{ds}_\varphi = \pm dr dz \hat{a}_\varphi \\ \overline{ds} &= -dr dz \hat{a}_\varphi \end{aligned}$$

$$\vec{A} \cdot \overline{ds} = (r \cos \varphi \hat{a}_r - r \sin \varphi \hat{a}_\varphi) \cdot (-dr dz \hat{a}_\varphi) = +r \sin \varphi dr dz = 0 \quad | \varphi=0$$

$$\int_{S_3} \vec{A} \cdot \overline{ds} = 0$$

$$26 \quad \overline{S_4}: \begin{cases} z=1 \\ 0 \leq r \leq 1 \\ 0 \leq \varphi \leq \pi/2 \end{cases} \rightarrow \begin{aligned} \overline{ds} &= ds_z = \pm r dr d\varphi \hat{a}_z \\ \overline{ds} &= +r dr d\varphi \hat{a}_z \end{aligned}$$

$$\overline{A} \cdot \overline{ds} = (r \cos \varphi \hat{a}_r - r \sin \varphi \hat{a}_\varphi) \cdot (r dr d\varphi \hat{a}_z) =$$

$$\int_{S_4} \overline{A} \cdot \overline{ds} = 0$$

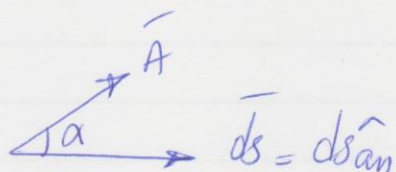
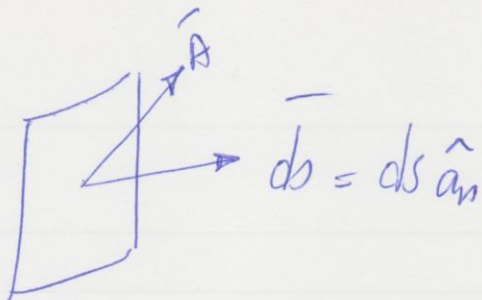
$$S_5: \begin{cases} r=1 \\ 0 \leq \varphi \leq \pi/2 \\ 0 \leq z \leq 1 \end{cases} \rightarrow \begin{aligned} \overline{ds} &= ds_r = \pm r d\varphi dz \hat{a}_r \\ \overline{ds} &= +r d\varphi dz \hat{a}_r \end{aligned}$$

$$\overline{A} \cdot \overline{ds} = (r \cos \varphi \hat{a}_r - r \sin \varphi \hat{a}_\varphi) \cdot (r d\varphi dz \hat{a}_r) = r^2 \cos \varphi d\varphi dz = \cos \varphi d\varphi dz \Big|_{r=1}$$

$$\int_{S_5} \overline{A} \cdot \overline{ds} = \int_{z=0}^1 \int_{\varphi=0}^{\pi/2} \cos \varphi d\varphi dz = \sin \varphi \cdot z \Big|_{\varphi=0}^{\pi/2} \Big|_{z=0}^1 = 1$$

$$\therefore \oint_S \overline{A} \cdot \overline{ds} = 0 - \frac{1}{2} + 0 + 0 + 1 = \frac{1}{2}$$

$$\vec{A} \cdot d\vec{s} :$$



$$\vec{A} \cdot d\vec{s} = |\vec{A}| ds \cos \alpha$$

$$= |\vec{A}| \cos \alpha \cdot ds$$

یہ نیکل \vec{A} ، درائنس محور پر ہے مولفہ دار

یہ نیکل \vec{A} درائنس خارج ہو رہا ہے، فوسل از غصہ ہے ds

$$\int_S \vec{A} \cdot d\vec{s} :$$

نیکل ہے، فوسل از غصہ ہے S

$$\int_V |\vec{A}| dv$$

انٹرکٹو علم :