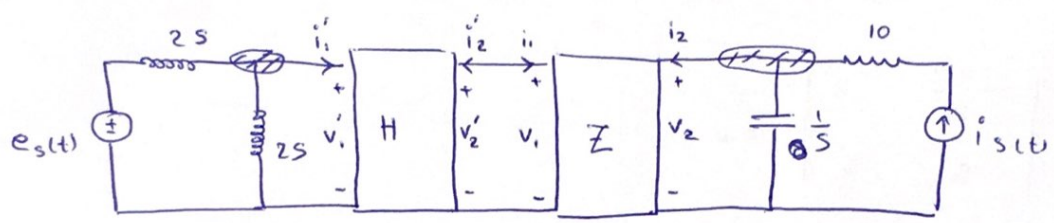


#3



$$H = \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix}, \quad Z = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \Rightarrow \begin{cases} V_1 = I_1 + I_2 \\ V_2 = I_1 + I_2 \end{cases}$$

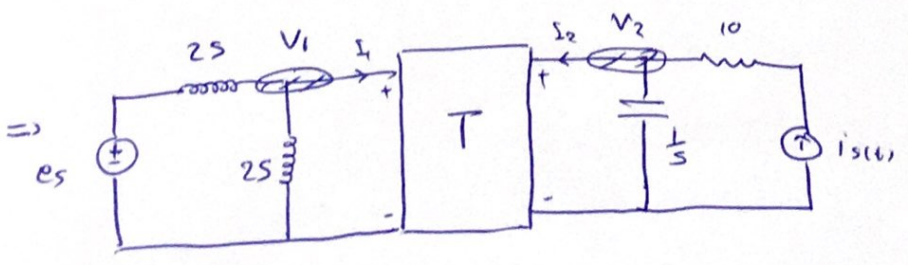
$$\begin{cases} -V_1' = I_1' + V_2' \\ I_2' = -I_1' + V_2' \end{cases} \Rightarrow V_1 = V_2', \quad i_1 = -i_2'$$

$$\Rightarrow I_1 + I_2 = I_2' + I_1' \xrightarrow{I_1' = -I_2'} -I_2' + I_2 = I_2' + I_1 \Rightarrow \boxed{-2I_2' = I_1 - I_2}$$

$$H \rightarrow T: T_1 = \begin{bmatrix} \frac{-\det(H)}{h_{21}} & \frac{h_{11}}{h_{21}} \\ \frac{-h_{22}}{h_{21}} & \frac{-1}{h_{21}} \end{bmatrix} = \begin{bmatrix} 2 & -1 \\ 1 & 1 \end{bmatrix}$$

$$Z \rightarrow T: T_2 = \begin{bmatrix} \frac{Z_{11}}{Z_{21}} & \frac{\det(Z)}{Z_{21}} \\ \frac{1}{Z_{21}} & \frac{Z_{22}}{Z_{21}} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}$$

$$\Rightarrow T = T_1 T_2 = \begin{bmatrix} 2 & -1 \\ 1 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 2 & 0 \end{bmatrix}$$



$$\Rightarrow \begin{cases} V_1 = V_2 \\ I_1 = 2V_2 \end{cases}$$

$$\text{Kcl in } V_1: +I_1 + \frac{V_1}{2S} + \frac{V_1 - E_s}{2S} \stackrel{I=2V_1}{=} 0 \rightarrow V_1 \left(2 + \frac{1}{2S} + \frac{1}{2S} \right) = \frac{E_s}{2S}$$

$$V_1 \left(\frac{2S+1}{S} \right) = \frac{E_s}{2S}$$

$$\text{Kcl in } V_2: I_2 + SV_2 - i_s = 0 \xrightarrow{V_1=V_2} \cancel{I_2} + SV_1 = i_s \Rightarrow SV_1 = i_s$$

$$\Rightarrow \det \begin{vmatrix} \frac{2S+1}{S} & 0 \\ S & 0 \end{vmatrix} = 0$$