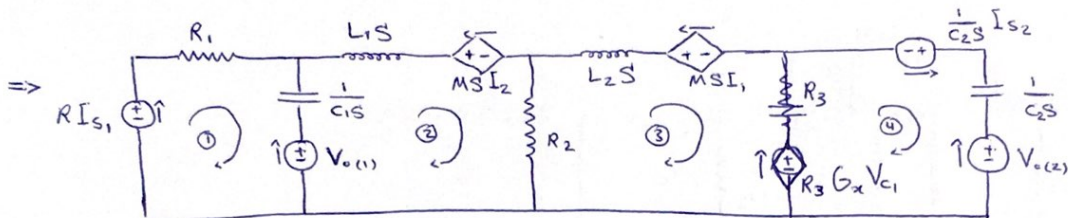
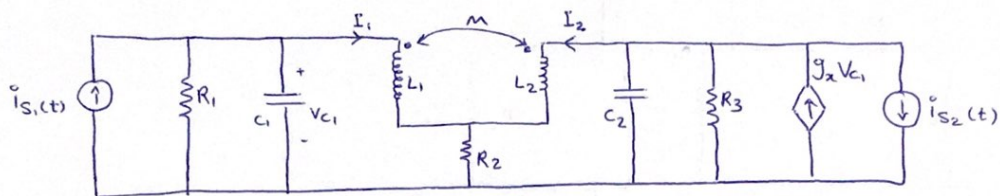


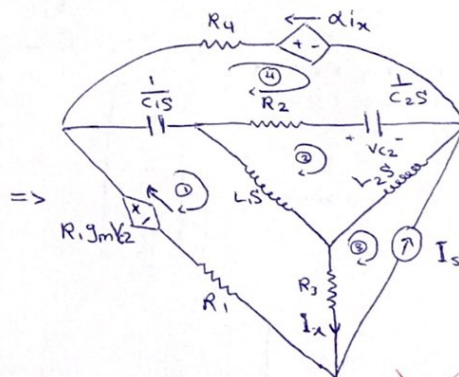
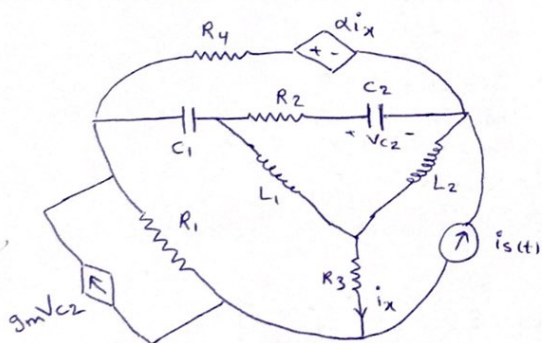
#4



$$\begin{aligned}
 & \text{①} \begin{bmatrix} R_1 + \frac{1}{C_1 s} & -\frac{1}{C_1 s} & 0 & 0 \\ -\frac{1}{C_1 s} & L_1 s + R_2 + \frac{1}{C_1 s} & -R_2 - M s & 0 \\ \frac{R_3 g_m}{C_1 s} & +M s - R_2 - \frac{R_3 g_m}{C_1 s} & L_2 s + R_3 + R_2 & R_3 \\ 0 & 0 & -R_3 & R_3 + \frac{1}{C_2 s} \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \\ I_3 \\ I_4 \end{bmatrix} = \begin{bmatrix} R I_{s1} \\ V_{c(1)} - M s I_2 \\ -M s I_1 - R_3 g_m V_{c1} \\ \frac{1}{C_2 s} I_{s2} - V_{c(2)} \end{bmatrix} \\
 & \text{②} \quad \text{③} \quad \text{④}
 \end{aligned}$$

$$\left. \begin{aligned} \text{node 1: } I_2 &= -I_3 \\ \text{node 2: } I_1 &= I_2 \\ V_{c1} &= \frac{1}{C_1 s} (I_1 - I_2) \end{aligned} \right\}$$

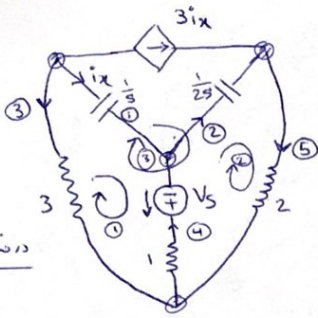
#5



$$\begin{aligned}
 & \text{①} \begin{bmatrix} \frac{1}{C_1 s} + L_1 s + R_3 + R_1 & +\frac{R_1 g_m}{C_2 s} - L_1 s & -R_3 & 0 \\ -L_1 s & R_2 + \frac{1}{C_2 s} + L_2 s + L_1 s & -L_2 s & -R_2 - \frac{1}{C_2 s} \\ -R_3 & -L_2 s & L_2 s + R_3 & 0 \\ -\frac{1}{C_1 s} + \alpha & -R_2 - \frac{1}{C_2 s} & 0 & R_4 + \frac{1}{C_2 s} + R_2 + \frac{1}{C_1 s} \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \\ I_3 \\ I_4 \end{bmatrix} = \begin{bmatrix} R_1 g_m V_{c2} \\ 0 \\ -I_s \\ -\alpha i_x \end{bmatrix} \\
 & \text{②} \quad \text{③} \quad \text{④}
 \end{aligned}$$

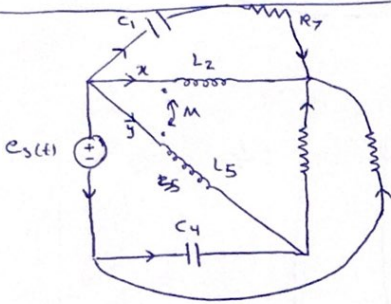
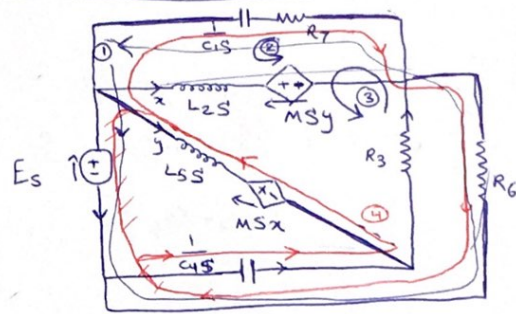
$$\left. \begin{aligned} V_{c2} &= I_2 \times \frac{1}{C_2 s} \\ I_x &= I_1 - I_3 \\ I_n &= I_1 + I_5 \end{aligned} \right\}$$

#6

3, 4, 5 → ∞

$$\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \begin{bmatrix} \frac{1}{S} + 1 + 3 & 1 & 3 \\ 1 & \frac{1}{2S} + 3 & 2 \\ 3 & 2 & \frac{2+3}{2S} \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix} = \begin{bmatrix} V_s \\ -V_s \\ 0 \end{bmatrix}$$

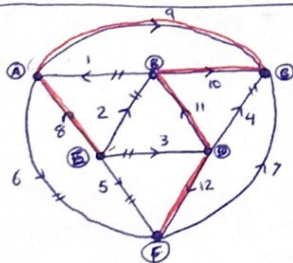
#7

 $R_7, R_6, L_5 \rightarrow \infty$ \Rightarrow 

$$\begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix} \begin{bmatrix} R_6 + R_7 + \frac{1}{C_1S} & R_7 + \frac{1}{C_1S} & R_7 + \frac{1}{C_1S} & -R_7 - \frac{1}{C_1S} \\ R_7 + \frac{1}{C_1S} & R_7 + \frac{1}{C_1S} + L_2S & \frac{1}{C_1S} + R_7 + MS & -\frac{1}{C_1S} - R_7 - MS \\ R_7 + \frac{1}{C_1S} & R_7 + \frac{1}{C_1S} + MS & R_3 + R_7 + \frac{1}{C_1S} + L_5S & -L_5S - R_7 - \frac{1}{C_1S} \\ -R_7 - \frac{1}{C_1S} & -\frac{1}{C_1S} - R_7 - MS & -L_5S - R_7 - \frac{1}{C_1S} & L_5S + R_7 + \frac{1}{C_1S} + R_6 + \frac{1}{C_4S} \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \\ I_3 \\ I_4 \end{bmatrix} = \begin{bmatrix} -E_s \\ -MSy \\ -MSx \\ MSx \end{bmatrix}$$

$x = I_2, y = I_3 - I_4$

#8

تعداد درونی: $6 - 1 = 5 \rightarrow (8, 9, 10, 11, 12)$ سین: $12 - 5 = 7 \rightarrow (1, 2, 3, 4, 5, 6, 7)$

①: (1, 9, 10)

④: (10, 4, 11)

⑦: (12, 11, 10, 7)

②: (8, 9, 10, 2)

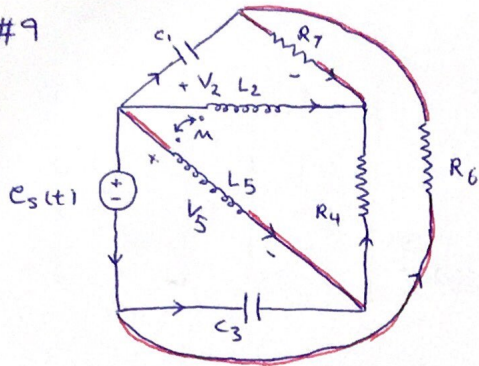
⑤: (8, 9, 10, 11, 12, 5)

③: (9, 10, 11, 3, 8)

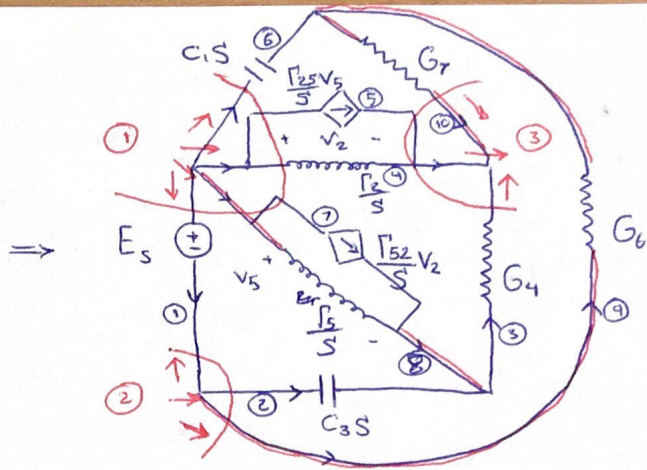
⑥: (12, 11, 10, 9, 6)

$$B = \begin{bmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 & 10 & 11 & 12 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & -1 & -1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & -1 & -1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & -1 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & -1 & -1 & 1 & 0 & -1 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & -1 & 1 & 1 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & -1 & -1 & 1 \end{bmatrix}$$

#9



$$C_{\text{نوع}} = \begin{cases} L_5 \\ R_6 \\ R_7 \end{cases}$$



$$\begin{bmatrix} \frac{I_5}{S} + \frac{I_2}{S} + C_1 S + \frac{I_{25}}{S} + \frac{I_{52}}{S} & 0 & \frac{I_2}{S} - \frac{I_{52}}{S} \\ 0 & C_3 S + G_6 & 0 \\ \frac{I_2}{S} + \frac{I_{25}}{S} & 0 & G_7 + \frac{I_2}{S} + G_4 \end{bmatrix} \begin{bmatrix} E_1 \\ E_2 \\ E_3 \end{bmatrix} = \begin{bmatrix} -\frac{I_{25}}{S} V_5 - \frac{I_{52}}{S} V_2 \\ 0 \\ -\frac{I_{25}}{S} V_5 \end{bmatrix}$$

$$Q = \begin{array}{l} 1, 8, 7, 4, 5, 6 \leftarrow ① \\ 1, 2, 9 \leftarrow ② \\ 3, 4, 5, 10 \leftarrow ③ \end{array} \begin{bmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 & 10 \\ 1 & 0 & 0 & 1 & 1 & 1 & 1 & 1 & 0 & 0 \\ -1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 & 1 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\left. \begin{array}{l} V_2 = E_1 - E_3 \\ V_5 = E_3 \end{array} \right\}$$

#10

$$Q = \begin{bmatrix} \boxed{1} & 1 & -1 & \boxed{0} & -1 & -1 & 0 & \boxed{0} & 0 \\ 0 & 0 & 0 & 1 & -1 & -1 & 0 & 0 & 0 \\ 0 & 0 & -1 & 0 & 0 & 0 & -1 & 1 & 0 \\ 0 & 0 & -1 & \boxed{0} & 0 & -1 & -1 & 0 & 1 \end{bmatrix}$$

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$$\Rightarrow \bar{F} = \begin{bmatrix} 1 & -1 & -1 & -1 & 0 \\ 0 & 0 & -1 & -1 & 0 \\ 0 & -1 & 0 & 0 & -1 \\ 0 & -1 & 0 & -1 & -1 \end{bmatrix} \Rightarrow -F^T = E = \begin{bmatrix} -1 & 0 & 0 & 0 \\ 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 0 \\ 1 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

$$\Rightarrow B = \begin{bmatrix} -1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 & 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 1 \end{bmatrix}$$