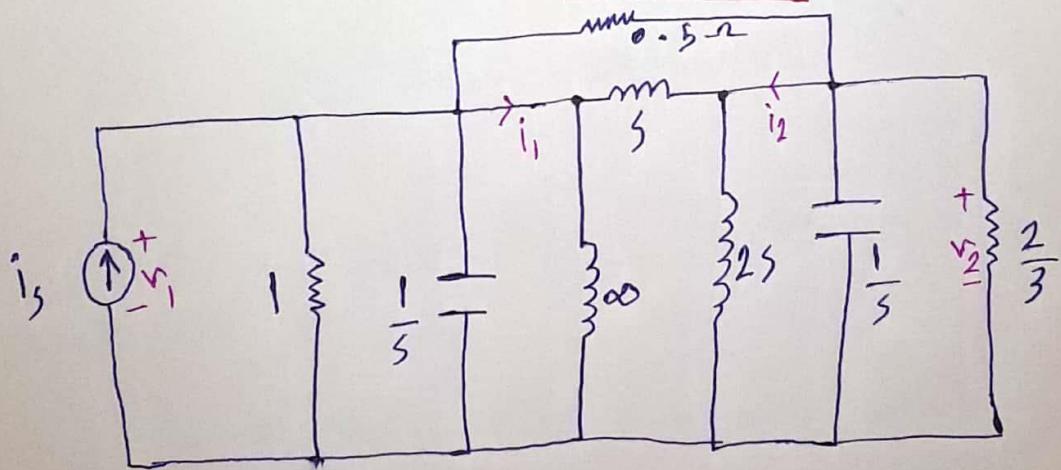
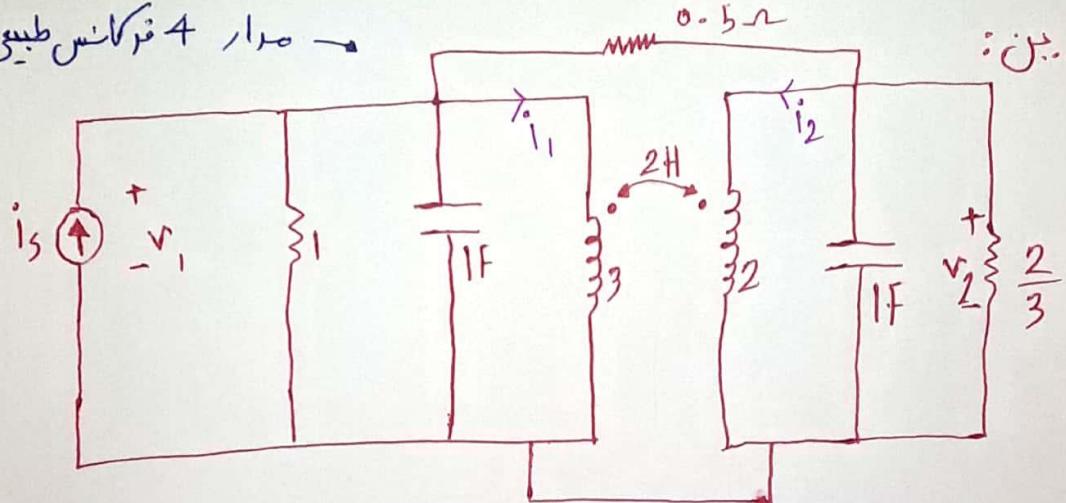


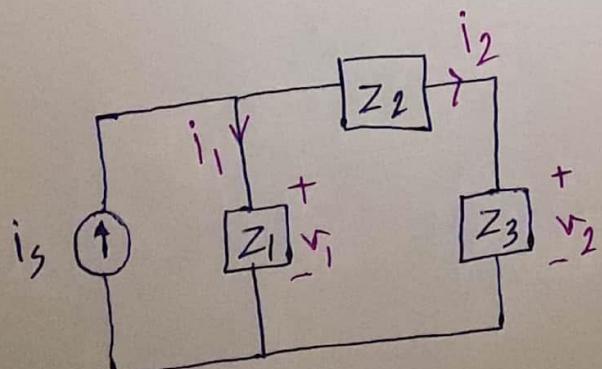
مدار ۴ فرکانس طبیعی دارد



$$Z_1 = \frac{1}{s+1}$$

$$Z_2 = \frac{s}{2s+1}$$

$$Z_3 = \frac{2s}{2s^2 + 3s + 1}$$



$$i_1 = \frac{z_2 + z_3}{z_1 + z_2 + z_3} \text{ is } \quad z_2 + z_3 = \frac{s^2 + 3s}{(s+1)(2s+1)}$$

$$z_1 + z_2 + z_3 = \frac{s^2 + 5s + 1}{(s+1)(2s+1)}$$

$$i_1 = \frac{(s^2 + 3s)}{s^2 + 5s + 1} \text{ is } \rightarrow v_1 = z_1 i_1 \rightarrow H_1(s) = \frac{v_1}{i_1} = \frac{s^2 + 3s}{(s+1)(s+0.21)(s+4.79)} \checkmark$$

$$H_1(s) = \frac{s^2 + 3s}{(s+1)(s+0.21)(s+4.79)} \checkmark$$

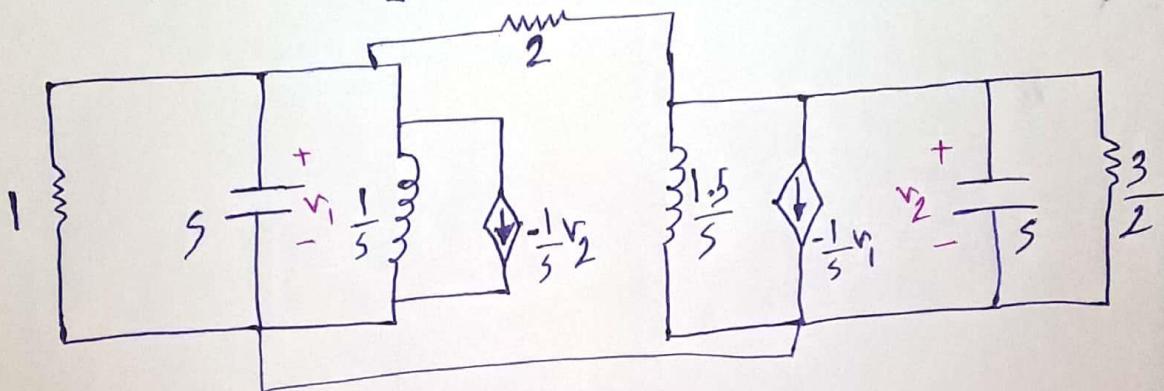
$$i_2 = \frac{z_1 i_1 s}{z_1 + z_2 + z_3} = \frac{(2s+1)i_1 s}{(s+0.21)(s+4.79)} \rightarrow v_2 = z_3 i_2$$

$$\frac{v_2}{i_1 s} = H_2(s) = \frac{2s}{(s+1)(s+0.21)(s+4.79)} \checkmark \quad H_2(s) = \frac{H_2}{H_1} = \frac{2s}{s^2 + 3s}$$

$$H_3(s) = \frac{2}{s+3} \checkmark$$

در ادامه فرکانس های طبیعی کل مدار با روش گره های امی کنیم.

$$L = \begin{bmatrix} 3 & 2 \\ 2 & 32 \end{bmatrix} \rightarrow M = \frac{1}{6-4} \begin{bmatrix} 2 & -2 \\ -2 & 3 \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ -1 & 1.5 \end{bmatrix}$$



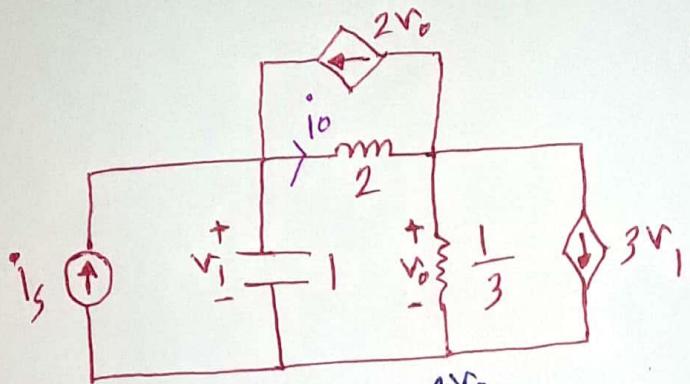
$$\begin{bmatrix} s+1+\frac{1}{s}+2 & -2-\frac{1}{s} \\ -2-\frac{1}{s} & 2+\frac{1.5}{s}+s+1.5 \end{bmatrix} \begin{bmatrix} E_1 \\ E_2 \end{bmatrix} = \begin{bmatrix} \frac{1}{s}v_2 \\ \frac{1}{s}v_1 \end{bmatrix}$$

$\underbrace{\quad}_{A}$

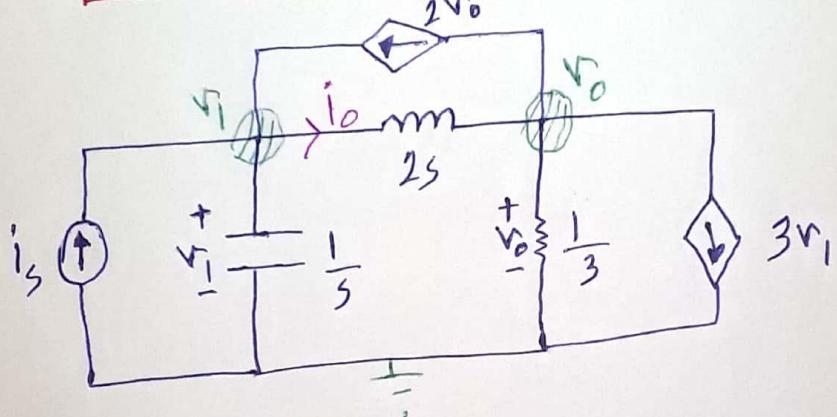
$$\det\{A\} = \frac{2s^4 + 13s^3 + 18s^2 + 8s + 1}{2s^2} \rightarrow \det\{A\} = 0 \rightarrow \begin{cases} s_1 = -4.79 \\ s_2 = -1 \\ s_3 = -0.05 \\ s_4 = -0.21 \end{cases}$$

s_4, s_2, s_1 مامل $H_2(s)$ * s_4, s_2, s_1 مامل $H_1(s)$

$H_3(s)$ اصل تابع انتقال نمیست که قطبی های آن شامل ۴، ۰.۲ و ۰.۵ باشد.
تا برو انتقال (نقطه تحریر یا مقابل) با ۳ یا ۰.۷۵ درجه / دوری نوشت شود.



$$H_2 = \frac{i_2}{i_s} \quad H_1 = \frac{v_o}{i_s}$$



$$KCL @ v_o: \frac{v_o - v_1}{2s} + 3v_o + 3v_1 + 2v_o = 0$$

$$v_1 = \frac{\frac{5}{2s} + \frac{1}{2s}}{\frac{1}{2s} - 3} v_o \quad (I)$$

$$KCL @ v_1: i_s = 5v_1 + \frac{v_1 - v_o}{2s} - 2v_o$$

$$(5 + \frac{1}{2s})v_1 - (2 + \frac{1}{2s})v_o = i_s \quad (II) \rightarrow$$

$$\left[\frac{(5 + \frac{1}{2s})(2 + \frac{1}{2s})}{\frac{1}{2s} - 3} - (2 + \frac{1}{2s}) \right] v_o = i_s$$

$$\frac{5s + 2.5}{s} + \frac{1}{2} + \frac{1}{4s^2} - \left(\frac{1}{s} + \frac{1}{4s^2} - \cancel{\frac{6}{s}} - \cancel{\frac{3}{2s}} \right) v_o = i_s$$

$\times \quad \frac{1-6s}{2s}$

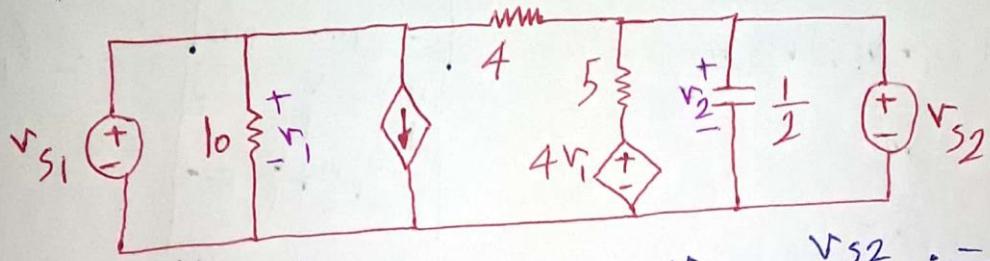
$$H_1(s) = \frac{v_o}{i_s} = \frac{1-6s}{10s^2 + 13s + 6s} \quad \checkmark \text{ (II)}$$

$$H_2(s) = \frac{i_o}{i_s} = ?$$

$$i_o = \frac{v_1 - v_o}{2s} \xrightarrow{(I)} v_1 = \frac{10s+1}{1-6s} v_o \rightarrow v_1 - v_o = \left(\frac{16s}{1-6s} \right) v_o$$

$$i_o = \frac{16s}{(1-6s)2s} v_o \xrightarrow{(II)} i_o = \frac{16s}{(1-6s)(2s)} \times \frac{(1-6s)i_s}{10s^2 + 13s + 6s}$$

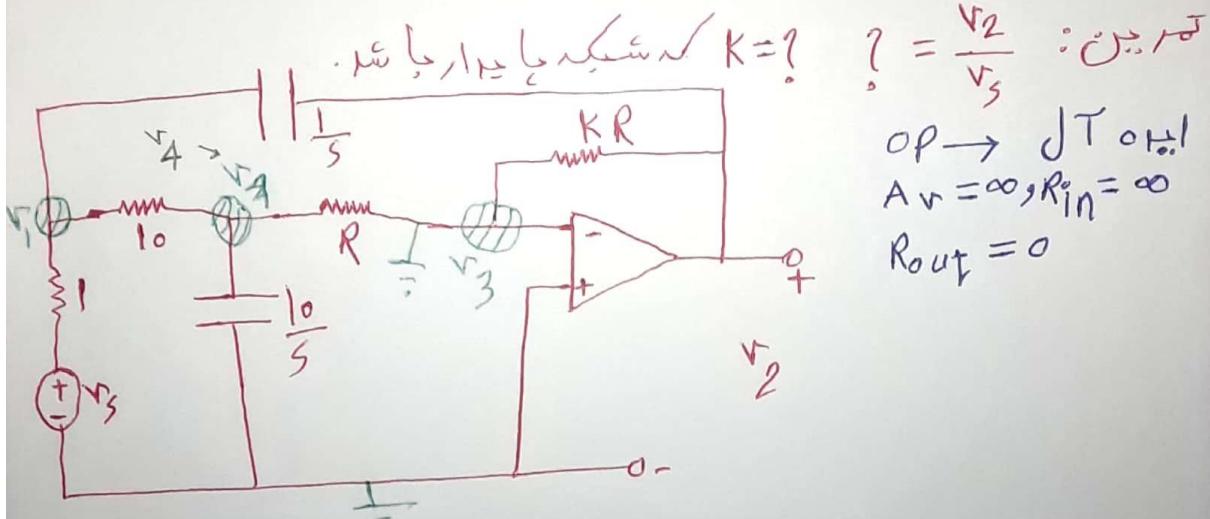
$$\rightarrow H_2(s) = \frac{i_o}{i_s} = \frac{8}{10s^2 + 13s + 6s} \quad \checkmark$$



$$H(s) = \frac{v_2}{v_1} = \frac{v_{s2}}{v_{s1}}$$

مقدار عایق بین مدار

48



$$\text{KCL at } v_1: v_1 - v_s + v_1 - \frac{v_4}{10} + (v_1 - v_2)s = 0$$

$$(s+1.1)v_1 - 0.1v_4 - sv_2 = v_s \quad (\text{I})$$

$$\text{KCL at } v_4: \frac{v_4 - v_1}{10} + \frac{sv_4}{10} + \frac{v_4 - v_3}{R} = 0$$

$$-0.1v_1 + \left(\frac{1}{R} + \frac{s}{10} + \frac{1}{10}\right)v_4 = 0 \quad (\text{II})$$

$$\text{KCL at } v_3: \frac{v_3 - v_4}{R} + \frac{v_3 - v_2}{KR} = 0 \rightarrow +\frac{v_4}{R} + \frac{v_2}{KR} = 0 \quad (\text{III})$$

$$v_2 = \frac{-\frac{v_s}{10R}}{\begin{vmatrix} s+1.1 & 0.1 & v_s \\ -0.1 & \frac{1}{R} + \frac{s}{10} + \frac{1}{10} & 0 \\ 0 & \frac{1}{R} & 0 \end{vmatrix}} = \frac{-\frac{v_s}{10R}}{\frac{10Rs^2 + (2(R + \frac{100}{R} + 10KR)s + \frac{100 + 10R}{R})}{100KR^2}}$$

$$\frac{v_2}{v_3} = - \frac{K}{s^2 + (2 \cdot 1 + \frac{10}{R} + K)s + 1 + \frac{11}{R}}$$

خط P(s) $\xrightarrow{R=1}$ $s^2 + (12 \cdot 1 + K)s + 12 = 0$

$$\left. \begin{array}{l} (I) 12 \\ \text{نیز} \\ \text{می} \\ \text{باشد} \end{array} \right\} \Delta < 0 \rightarrow s_{1,2} = \frac{-(12 \cdot 1 + K) \pm \sqrt{(12 \cdot 1 + K)^2 - 48}}{2}$$

$$\Delta < 0 \rightarrow (12 \cdot 1 + K)^2 - 48 < 0 \rightarrow -6.9 < 12 \cdot 1 + K < 6.9$$

$$-19 < K < -5.2 \quad (\text{I})$$

$$\alpha < 0$$

$$\alpha = -\frac{(12 \cdot 1 + K)}{2} < 0 \rightarrow K > -12 \cdot 1 \quad (\text{II})$$

$$\xrightarrow{(\text{I}) \cap (\text{II})} -12 \cdot 1 < K < -5 \cdot 2 \quad \text{X}$$

$$\left. \begin{array}{l} (\text{III}) 2 \\ \text{نیز} \\ \text{باشد} \end{array} \right\} \Delta > 0 \rightarrow (12 \cdot 1 + K)^2 - 48 > 0 \rightarrow 12 \cdot 1 + K > 6.9$$

$$K > -5.2 \quad \underline{\text{کے}} \quad K < -19 \quad (\text{III}) \quad 12 \cdot 1 + K < -6.9$$

$$- (12 \cdot 1 + K) \pm \sqrt{(12 \cdot 1 + K)^2 - 48} < 0 \rightarrow K > -12 \cdot 1 \quad (\text{IV})$$

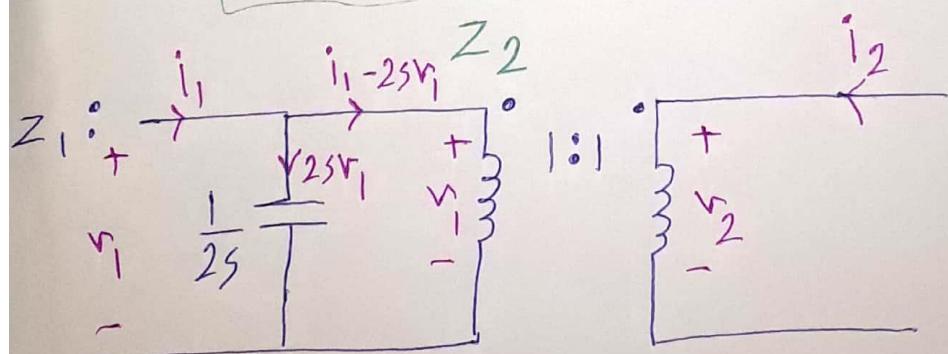
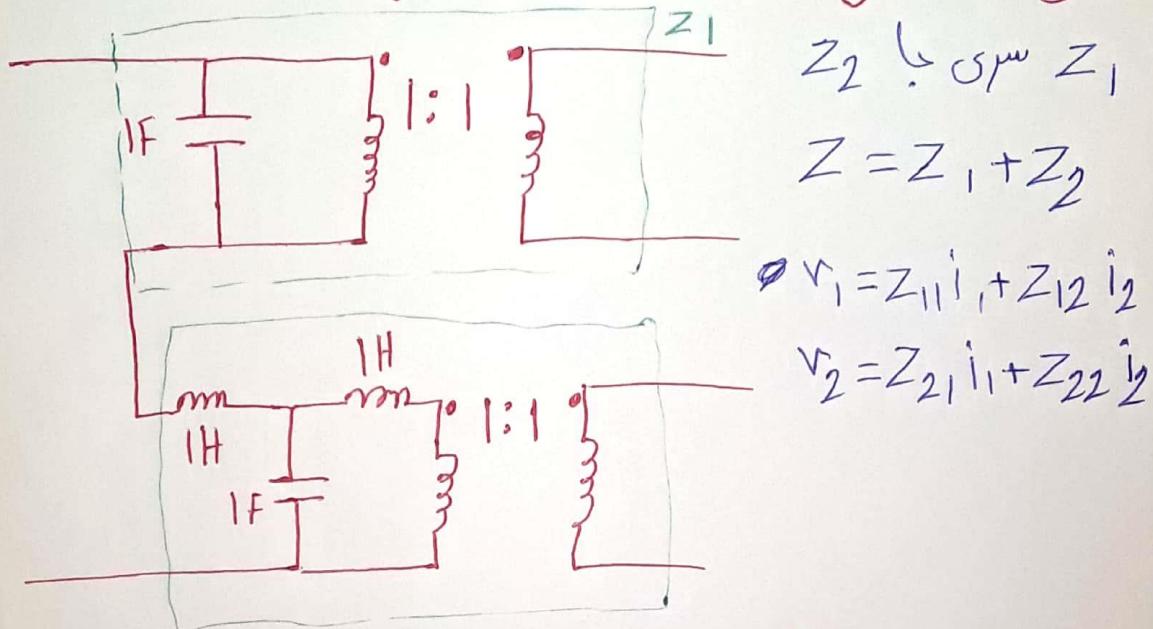
$$\xrightarrow{(\text{III}) \cap (\text{IV})} K > -5 \cdot 2 \quad \text{X} \quad \xrightarrow[\text{ایضاً}]{\oplus \cup \text{X}} K > -12 \cdot 1$$

بنابراین، اگر $K > -12 \cdot 1$ باشد

$$K > -12 \cdot 1 \leftarrow \alpha = 0 \leftarrow K = -12 \cdot 1 \quad (\text{V})$$

دوقطبي:

تمرين: ماترسيس او مترانس شكل مقابل:

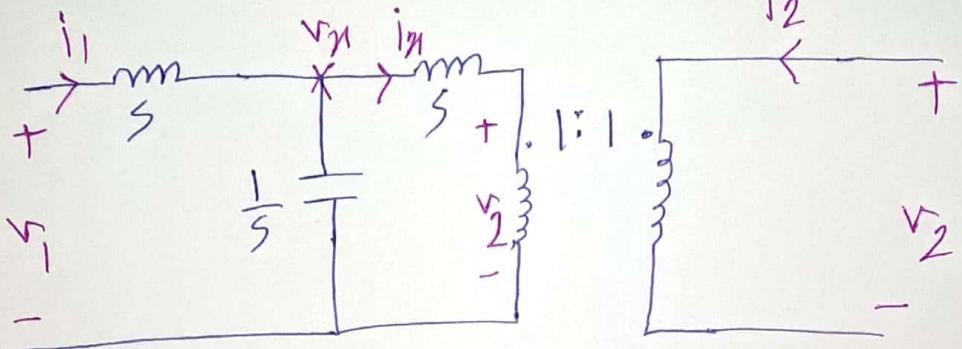


$$Z_1 : \frac{v_1}{v_2} = 1 \quad \text{طبق روابط مترانس} \quad \frac{i_1 - 2sv_1}{i_2} = -1 \rightarrow v_1 = v_2 \rightarrow Z_1 \text{ مترانس} \rightarrow \text{متقابل ومتقارن}$$

$$i_1 - 2sv_1 = -i_2 \rightarrow v_1 = v_2 = \frac{1}{2s}i_1 + \frac{1}{2s}i_2$$

$$Z_1 = \begin{bmatrix} \frac{1}{2s} & \frac{1}{2s} \\ \frac{1}{2s} & \frac{1}{2s} \end{bmatrix}$$

اولا حل
صفر دینامیک

Z_2^0 

$$KCL @ V_n: -i_1 + sV_n + \frac{V_n - V_2}{s} = 0$$

$$\rightarrow V_n = \frac{s i_1 + V_2}{s^2 + 1}$$

$$i_n = \frac{V_n - V_2}{s} = \frac{\frac{s i_1 + V_2}{s^2 + 1} - V_2}{s} = \frac{\frac{s i_1 + V_2 - s V_2 - V_2}{s^2 + 1}}{s} = \frac{s i_1 + V_2 - s V_2 - V_2}{s^3 + s}$$

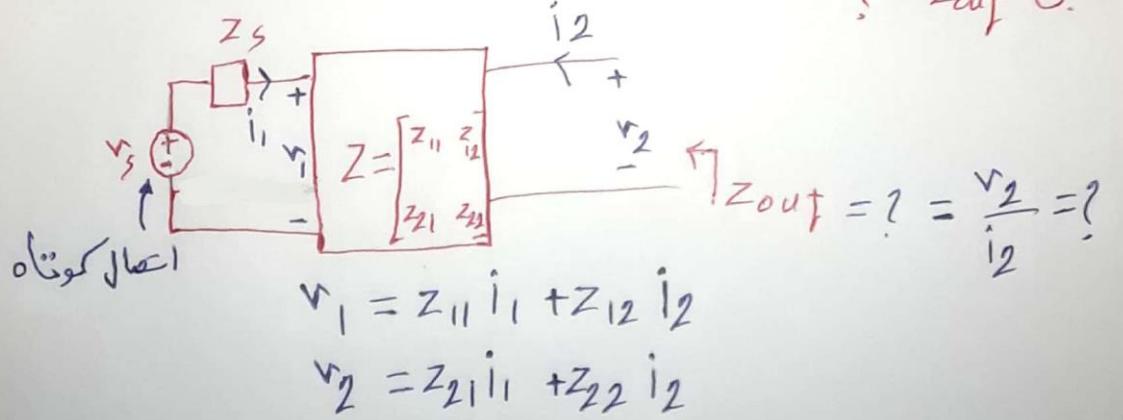
$$\frac{i_n}{i_2} = -1 \rightarrow s i_1 + V_2 - s^2 V_2 - V_2 = -s i_2 (s^2 + 1)$$

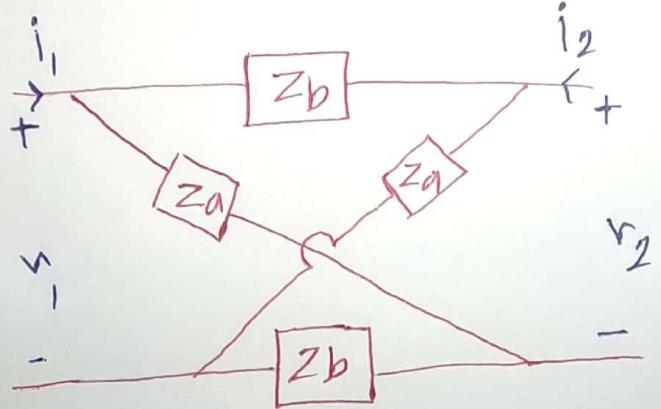
$$V_2 = \frac{1}{s} i_1 + \left(\frac{1}{s} + s \right) i_2 \rightarrow$$

$$V_1 = s i_1 + \frac{s i_1 + V_2}{s^2 + 1} \rightarrow V_1 = s i_1 + \frac{1}{s} i_1 + \frac{1}{s^2 + 1} i_2$$

$$Z_2 = \begin{bmatrix} s+1/s & 1/s \\ 1/s & 1/s + s \end{bmatrix}$$

$$Z = Z_1 + Z_2 = \begin{bmatrix} s+1/s + 1/2s & 1/s + 1/2s \\ 1/s + 1/2s & s+1/s + 1/2s \end{bmatrix}$$





$$v_1 = Z_{11} i_1 + Z_{12} i_2$$

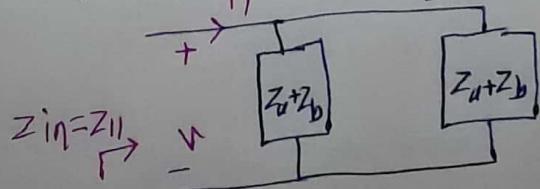
$$v_2 = Z_{21} i_1 + Z_{22} i_2$$

$? = Z$

$$Z_{11} = \frac{v_1}{i_1} \quad | i_2 = 0$$

$$\frac{v_1}{i_1} = Z_{11} = Z_{in} = (Z_a + Z_b) \parallel (Z_a + Z_b)$$

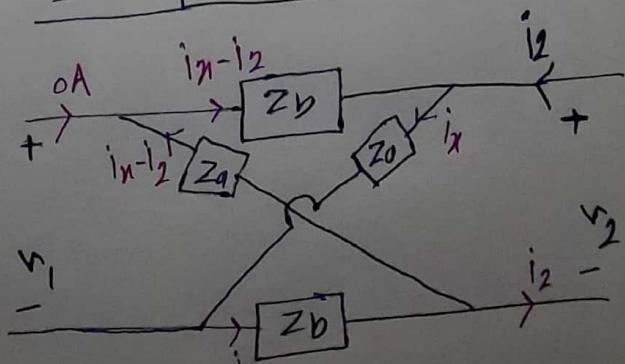
$$Z_{11} = (Z_a + Z_b) \parallel (Z_a + Z_b) = \frac{1}{2} (Z_a + Z_b)$$



$$Z_{12} = \frac{v_1}{i_2} \quad | i_1 = 0$$

$$i_n = \frac{v_2}{Z_a + Z_b}$$

$$v_2 = \frac{|Z_a + Z_b|}{2} i_2$$



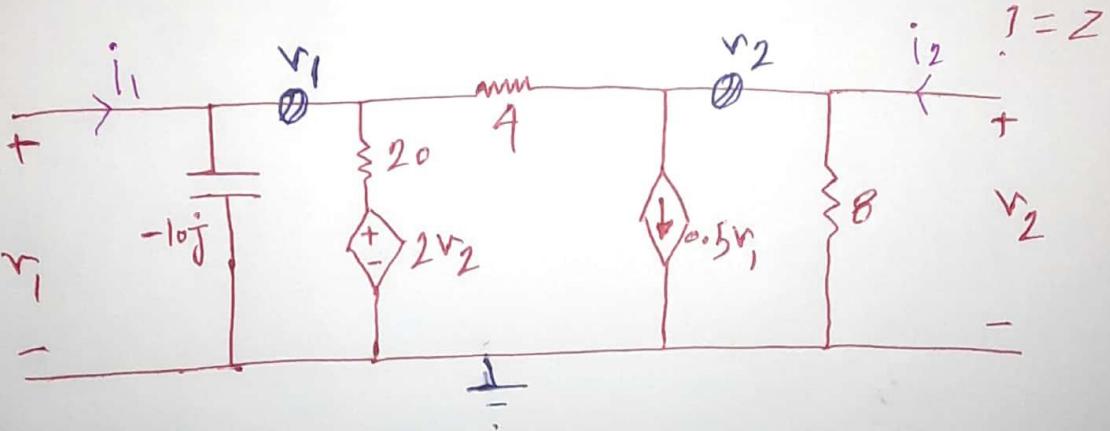
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$$KVL: v_1 = Z_b i_n - Z_b i_2 + v_2 - Z_b i_n$$

$$v_1 = \frac{(Z_a - Z_b)}{2} i_2 \rightarrow Z_{12} = \frac{(Z_a)}{2} - \frac{Z_b}{2}$$

$$Z = \begin{bmatrix} \frac{Z_a}{2} + \frac{Z_b}{2} & \frac{Z_a}{2} - \frac{Z_b}{2} \\ \frac{Z_a}{2} - \frac{Z_b}{2} & \frac{Z_a}{2} + \frac{Z_b}{2} \end{bmatrix}$$

منبع واحد سالن متر
 $Z_{12} = Z_{21}$
 $Z_{22} = \frac{v_2}{i_2} \mid i_1 = 0 = \frac{Z_a}{2} + \frac{Z_b}{2}$



$$KCL @ v_1: i_1 = \frac{v_1}{10} + \frac{v_1 - 2v_2}{20} + \frac{v_1 - v_2}{4} \approx$$

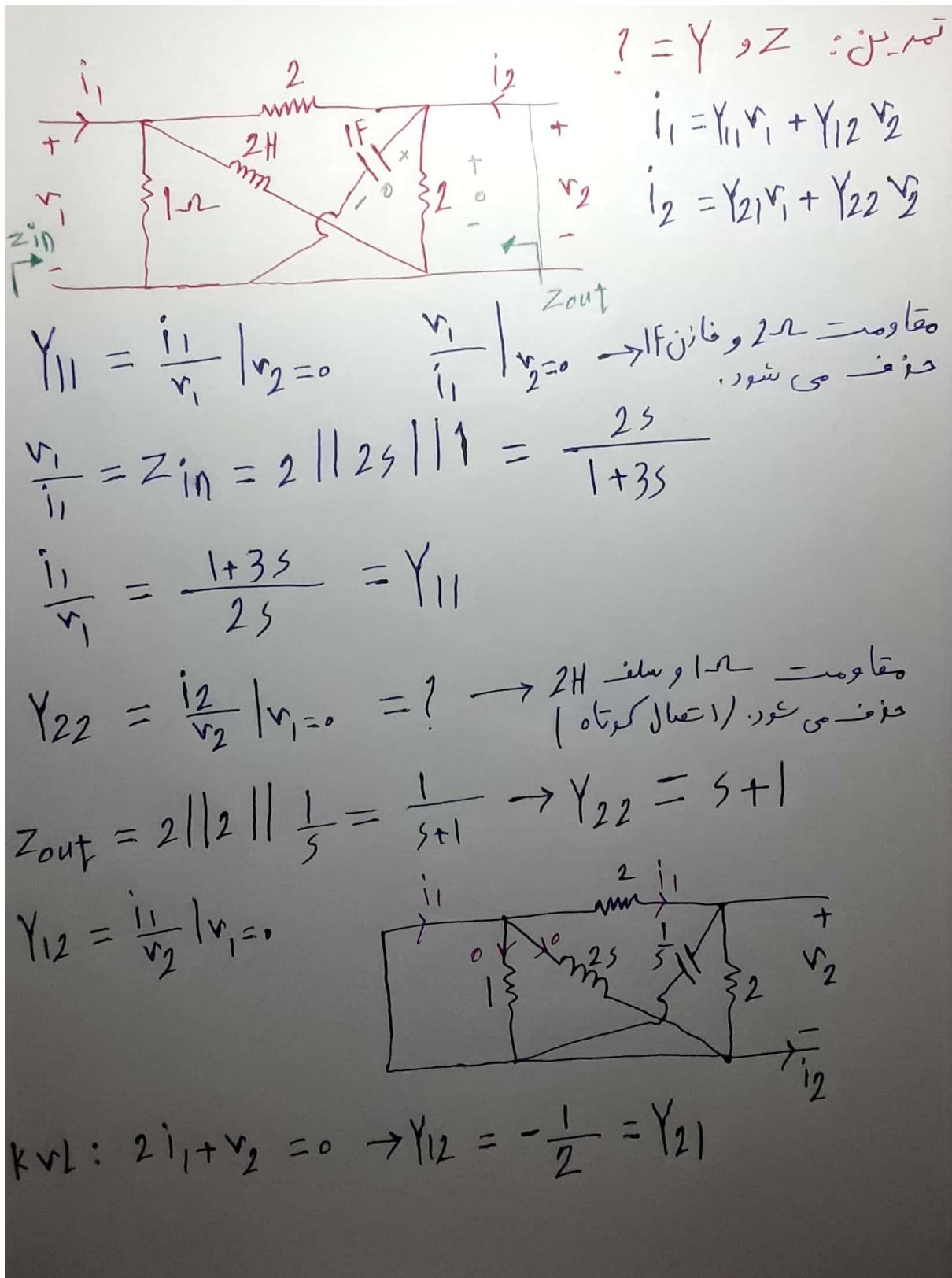
$$(0.3 + 0.1j)v_1 - 0.35v_2 = i_1 \quad (I)$$

$$KCL @ v_2: i_2 = \frac{v_2}{8} + 0.5v_1 + \frac{v_2 - v_1}{4}$$

$$0.25v_1 + 0.375v_2 = i_2 \quad (II)$$

$$v_1 = \frac{\begin{vmatrix} i_1 & -0.35 \\ i_2 & +0.375 \end{vmatrix}}{\begin{vmatrix} 0.3 + 0.1j & -0.35 \\ 0.25 & 0.375 \end{vmatrix}} = \underbrace{(1.8 - 0.34j)}_{Z_{11}} i_1 + \underbrace{(1.7 - 0.3j)}_{Z_{12}} i_2$$

$$v_2 = \frac{\begin{vmatrix} 0.3 + 0.1j & i_1 \\ 0.25 & i_2 \end{vmatrix}}{\begin{vmatrix} 1.8 - 0.34j & 1.7 - 0.3j \\ 1.2 + 0.22j & 1.54 + 0.2j \end{vmatrix}} = \underbrace{(-1.2 + 0.22j)}_{Z_{21}} i_1 + \underbrace{(1.54 + 0.2j)}_{Z_{22}} i_2$$



$$Y = \begin{bmatrix} \frac{3s+1}{2s} & -\frac{1}{2} \\ -\frac{1}{2} & s+1 \end{bmatrix} \rightarrow Z = \begin{bmatrix} s+1 & \frac{1}{2} \\ \frac{1}{2} & \frac{3s+1}{2s} \end{bmatrix} \times \frac{1}{(s+1)(3s+1)} = \frac{1}{2s} - \frac{1}{4}$$

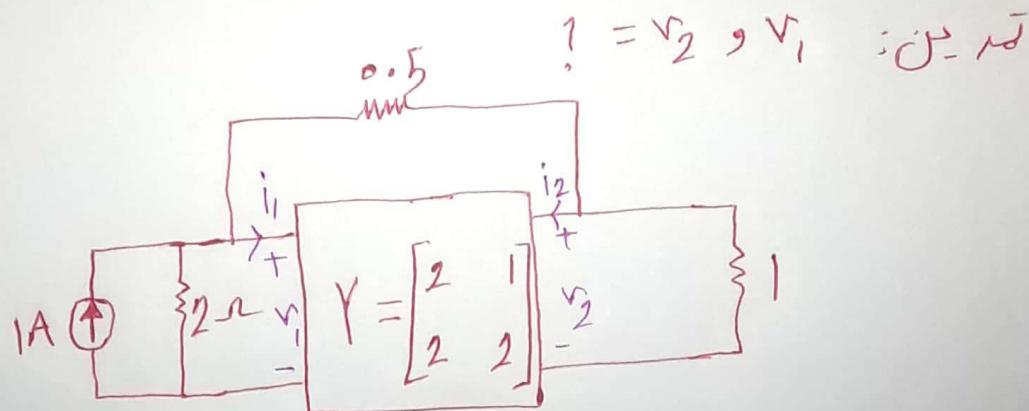
KCL @ v₁: i₁ = (1 + $\frac{1}{2s}$)v₁ + $\frac{v_1}{2}$ - $\frac{v_2}{2}$

$$\frac{3}{2}v_1 + \frac{1}{2s}v_1 - \frac{v_2}{2}$$

KCL @ v₂: i₂ = $\frac{v_2}{2}$ + s v₂ + $\frac{v_2 - v_1}{2} \rightarrow$

$$i_2 = -\frac{v_1}{2} + (s+1)v_2$$

$$Y = \begin{bmatrix} \frac{3s+1}{2s} & -\frac{1}{2} \\ -\frac{1}{2} & s+1 \end{bmatrix}$$



$$i_1 = 2v_1 + v_2 \quad i_2 = 2v_1 + 2v_2$$

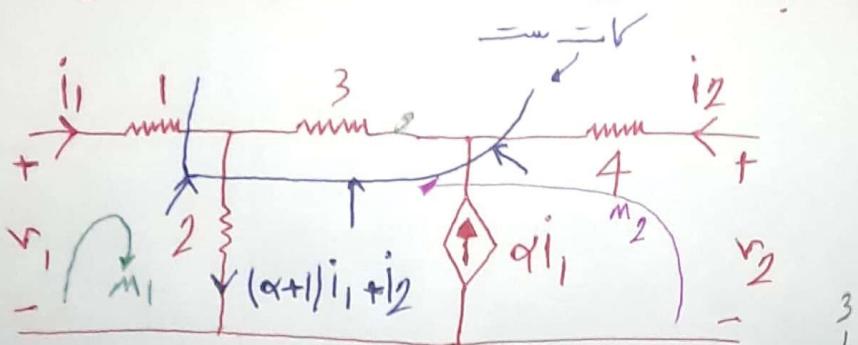
$$\text{KCL at } v_1: 1 = \frac{v_1 - 0}{\frac{1}{2}} + 2(v_1 - v_2) + i_1$$

$$(4 \cdot 5)v_1 - v_2 = 1$$

$$\text{KCL at } v_2: (v_2 - v_1) \frac{1}{2} + i_2 + v_2 = 0 \rightarrow v_2 = 0 \checkmark$$

$$v_1 = \frac{1}{4 \cdot 5} \checkmark$$

ما هي قيم α و m_1, m_2 التي تؤدي إلى انتقال مترافق؟



$$KVL @ M_1: v_1 = i_1 + 2(\alpha+1)i_1 + 2i_2 \rightarrow v_1 = (2\alpha+3)i_1 + 2i_2 \neq$$

$$KVL @ M_2: v_2 = 4i_2 + 3(\alpha i_1 + i_2) + 2(\alpha+1)i_1 + 2i_2$$

$$v_2 = (5\alpha+2)i_1 + 9i_2 \neq$$

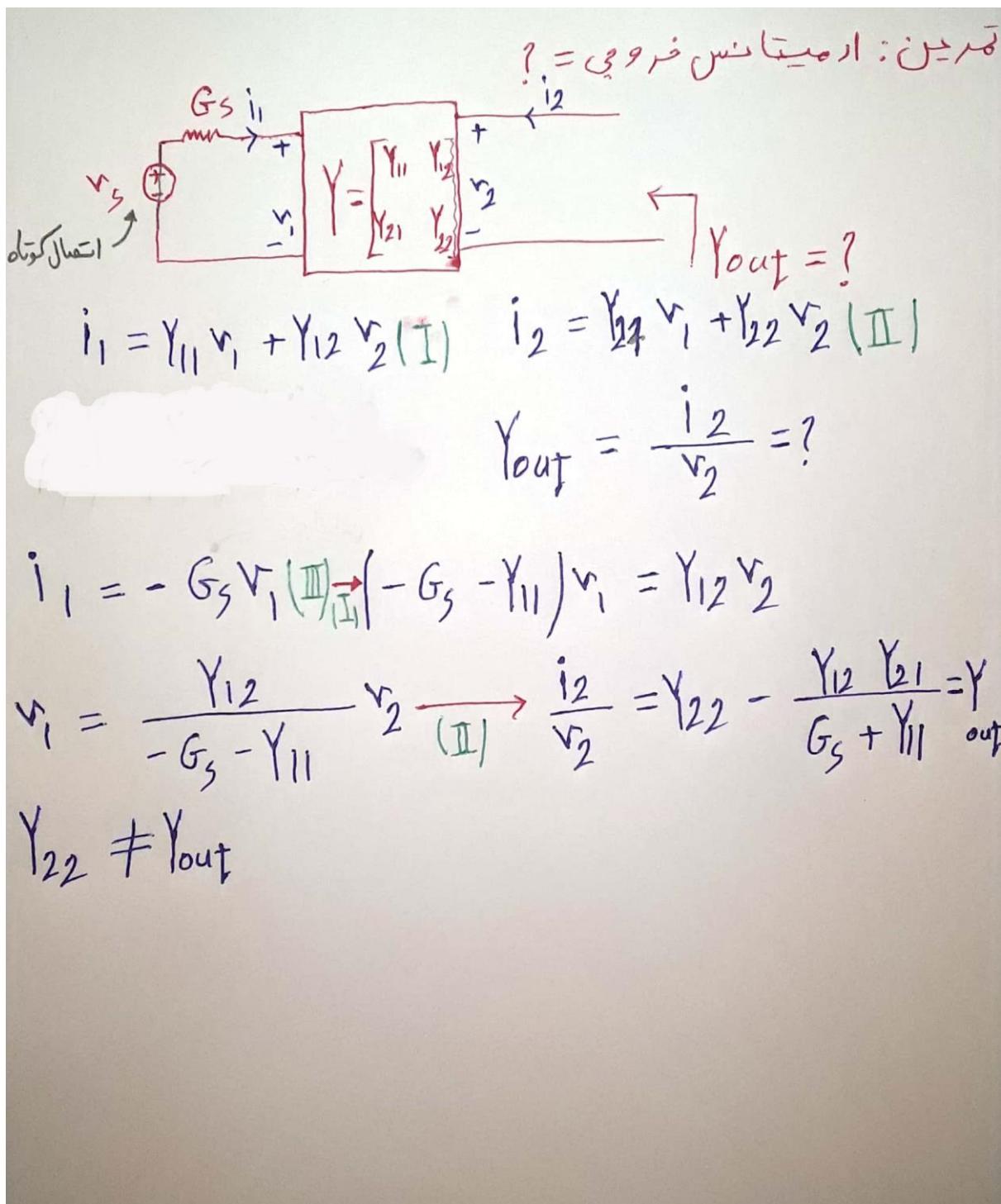
$$Z = \begin{bmatrix} 2\alpha+3 & 2 \\ 5\alpha+2 & 9 \end{bmatrix} \quad \det|z| = 0 \rightarrow Y \text{ مترافق} \rightarrow \text{وجود نسبات جذرية.}$$

$$\det|z| = (2\alpha+3)9 - 2(5\alpha+2)^2 = 8\alpha^2 + 23 = 0 \rightarrow \alpha = -\frac{23}{8}$$

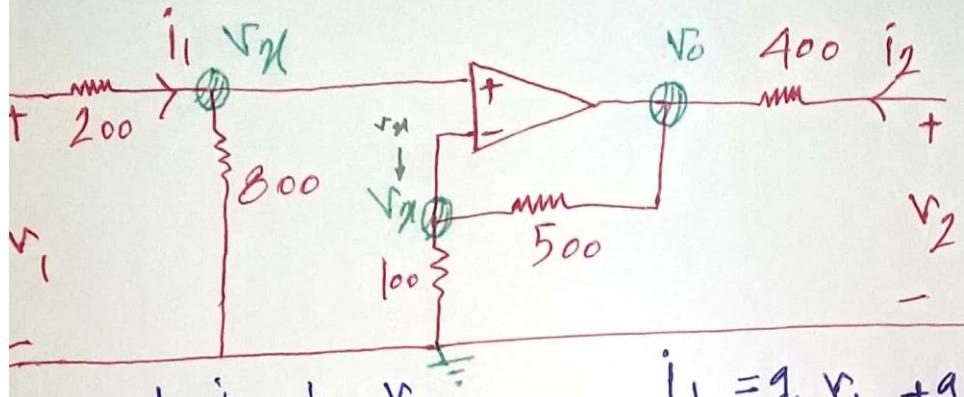
ما هي قيم α التي تؤدي إلى انتقال مترافق؟ $\alpha = -\frac{23}{8}$

$$inv(z) = \begin{bmatrix} \frac{9}{8\alpha+23} & \frac{-2}{8\alpha+23} \\ \frac{-(5\alpha+2)}{8\alpha+23} & \frac{2\alpha+3}{8\alpha+23} \end{bmatrix} = Y \rightarrow \det|y| = \frac{1}{8\alpha+23}$$

يتحقق المترافق $\alpha = -\frac{23}{8}$ في حين $8\alpha+23 = 0$ $\rightarrow |y| = 0$ \rightarrow صفر المترافق.



متریس G و H و فیلتر قطبی 2 همراه با



$$\left. \begin{array}{l} v_1 = h_{11}i_1 + h_{12}v_2 \\ i_2 = h_{21}i_1 + h_{22}v_2 \end{array} \right\} H \quad \left. \begin{array}{l} i_1 = g_{11}v_1 + g_{12}i_2 \\ v_2 = g_{21}v_1 + g_{22}i_2 \end{array} \right\} G$$

$$v_{pi} = \frac{800}{200+800} v_1 \rightarrow v_{pi} = \frac{4}{5} v_1 \quad (I)$$

$$v_{pi} = \frac{100 v_o}{100+500} \rightarrow v_{pi} = \frac{v_o}{6} \quad (II) \xrightarrow{(I, II)} v_o = \frac{24}{5} v_1$$

$$\frac{v_2 - \frac{24}{5} v_1}{400} = i_2 \rightarrow v_2 = 4.8 v_1 + 400 i_2 \quad (III)$$

$$i_1 = \frac{v_1 - \frac{4}{5} v_1}{200} \rightarrow i_1 = \frac{1}{1000} v_1 \quad (IV)$$

$$\xrightarrow{(III, IV)} G = \begin{bmatrix} \frac{1}{1000} & 0 \\ 4.8 & 400 \end{bmatrix}$$

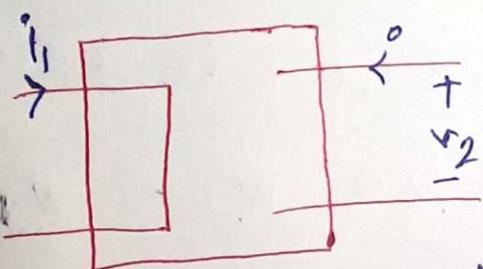
$$\xrightarrow{(IV)} v_1 = 1000 i_1 \quad (vI)$$

$$\xrightarrow[\text{(vI)}]{(III)} v_2 = 4.8(1000 i_1) + 400 i_2 \rightarrow i_2 = -12 i_1 + \frac{1}{400} v_2$$

$$H = \begin{bmatrix} 1000 & 0 \\ -12 & \frac{1}{400} \end{bmatrix}$$

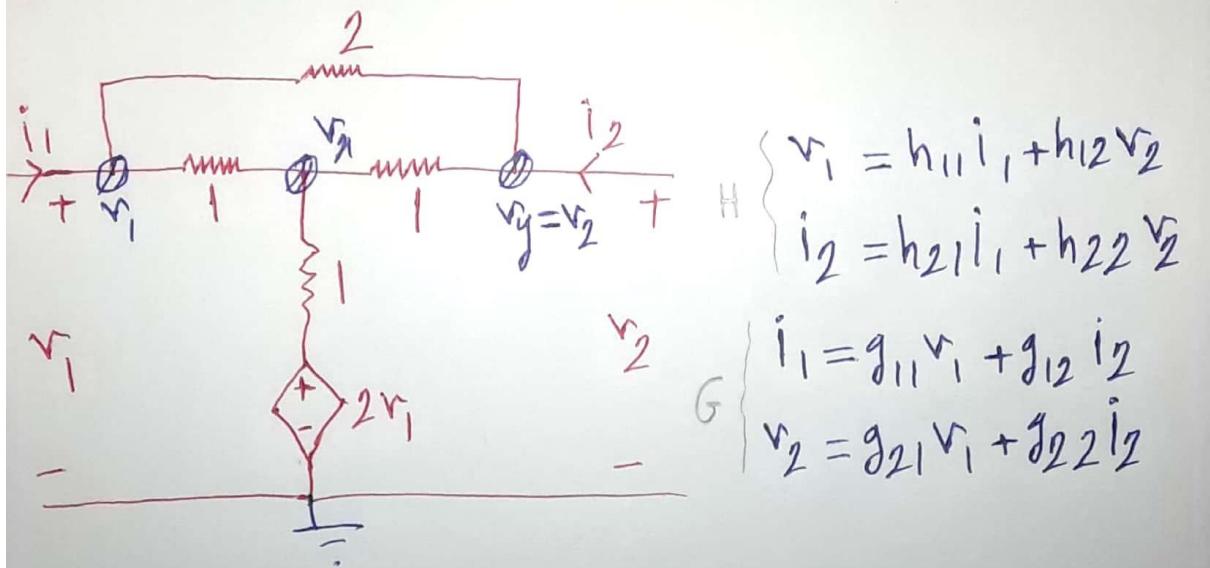
$$\bar{G}^{-1} = \frac{1000}{400} \begin{bmatrix} 400 & 0 \\ -4.8 & \frac{1}{1000} \end{bmatrix} \leftarrow H = \bar{G}^{-1} \quad \text{رسانیده شد}$$

$$= H \checkmark$$



$$\left. \begin{array}{l} v_1 = 0 \\ i_2 = 0 \end{array} \right\} \rightarrow H = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$\det(H) = 0 \rightarrow \text{موجي G}$$



$$KCL @ v_1 : v_1 - v_n + \frac{v_1 - v_2}{2} = i_1 \quad (I)$$

$$KCL @ v_n : v_n - v_1 + v_n - 2v_1 + v_n - v_2 = 0 \rightarrow v_n = v_1 + \frac{v_2}{3}$$

$$(I) \rightarrow \left(\frac{3}{2}\right)v_1 - \frac{v_2}{2} - \left(v_1 + \frac{v_2}{3}\right) = i_1 \rightarrow i_1 = \frac{1}{2}v_1 - \frac{5}{6}v_2 \quad (II)$$

$$KCL @ v_2 : i_2 = \frac{v_2 - \left(v_1 + \frac{v_2}{3}\right)}{1} + \frac{v_2 - v_1}{2}$$

$$i_2 = -\frac{3}{2}v_1 + \frac{7}{6}v_2 \quad (III)$$

$$(II) \rightarrow v_1 = 2i_1 + \frac{5}{3}v_2 \quad (IV) \xrightarrow{(III), (IV)} i_2 = -\frac{3}{2}(2i_1 + \frac{5}{3}v_2) + \frac{7}{6}v_2$$

$$i_2 = -3i_1 - \frac{4}{3}v_2 \quad (V) \xrightarrow{(IV), (V)} H = \begin{bmatrix} 2 & \frac{5}{3} \\ -3 & -\frac{4}{3} \end{bmatrix}$$

$$\xrightarrow{(V)} v_2 = -\frac{9}{4}i_1 - \frac{3}{4}i_2 \quad (VI)$$

$$\xrightarrow{(II)} i_1 = \frac{1}{2}v_1 - \frac{5}{6}(-\frac{9}{4}i_1 - \frac{3}{4}i_2)$$

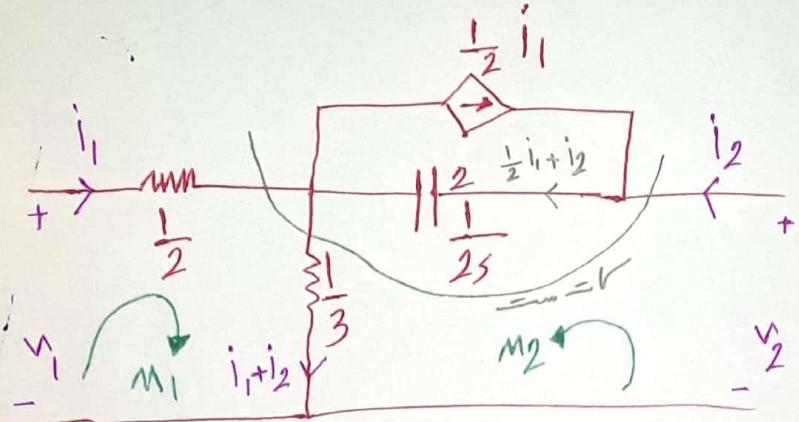
$$\rightarrow i_1 = -\frac{8}{7} \left(\frac{1}{2}v_1 + \frac{5}{8}i_2 \right) \rightarrow i_1 = -\frac{4}{7}v_1 - \frac{5}{7}i_2 \quad (VII)$$

$$\xrightarrow{(VI), (VII)} v_2 = -\frac{9}{4} \left(-\frac{4}{7}v_1 - \frac{5}{7}i_2 \right) - \frac{3}{4}i_2$$

$$v_2 = \frac{9}{7}v_1 + \frac{6}{7}i_2 \quad (VIII)$$

$$\xrightarrow{(VII), (VIII)} G = \begin{bmatrix} -\frac{4}{7} & -\frac{5}{7} \\ \frac{9}{7} & \frac{6}{7} \end{bmatrix}$$

برای کسری ماتریس H از این رابطه استفاده کنید.



$$\left. \begin{array}{l} v_1 = h_{11} i_1 + h_{12} v_2 \\ i_2 = h_{21} i_1 + h_{22} v_2 \end{array} \right\} \quad \left. \begin{array}{l} i_1 = g_{11} v_1 + g_{12} i_2 \\ v_2 = g_{21} v_1 + g_{22} i_2 \end{array} \right\} G$$

$$KVL @ M_1: v_1 = \frac{1}{2} i_1 + \frac{1}{3} (i_1 + i_2) \rightarrow v_1 = \frac{5}{6} i_1 + \frac{1}{3} i_2 \quad (I)$$

$$KVL @ M_2: v_2 = \frac{1}{2s} \left(\frac{1}{2} i_1 + i_2 \right) + \frac{1}{3} (i_1 + i_2)$$

$$v_2 = \left(\frac{1}{3} + \frac{1}{4s} \right) i_1 + \left(\frac{1}{3} + \frac{1}{2s} \right) i_2 \quad (II)$$

$$(I) \rightarrow i_1 = (v_1 - \frac{1}{3} i_2) \frac{6}{5} = \frac{6}{5} v_1 - \frac{2}{5} i_2$$

$$v_2 = \left(\frac{1}{3} + \frac{1}{4s} \right) \left(\frac{6}{5} v_1 - \frac{2}{5} i_2 \right) + \left(\frac{1}{3} + \frac{1}{2s} \right) i_2$$

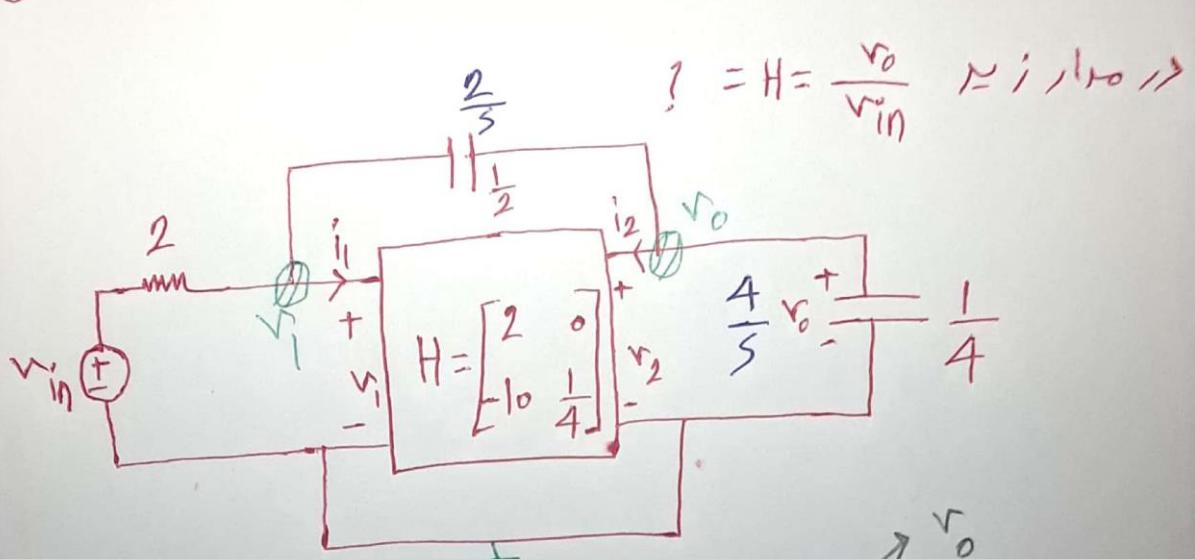
$$v_2 = \frac{6}{5} \left(\frac{1}{3} + \frac{1}{4s} \right) v_1 + \underbrace{\left[\left(\frac{1}{3} + \frac{1}{4s} \right) \left(-\frac{2}{5} \right) + \frac{1}{3} + \frac{1}{2s} \right]}_{\frac{1}{5} + \frac{2}{5s}} i_2 \quad (II)$$

$$G = \begin{bmatrix} \frac{6}{5} & -\frac{2}{5} \\ \frac{4s+3}{10s} & \frac{s+12}{5s} \end{bmatrix}$$

$$\xrightarrow{\text{III}} i_2 = \frac{v_2 - (\frac{1}{3} + \frac{1}{45})i_1}{\frac{1}{3} + \frac{1}{25}} \rightarrow i_2 = -\frac{(\frac{1}{3} + \frac{1}{45})i_1 + \frac{v_2}{\frac{1}{3} + \frac{1}{25}}}{\frac{1}{3} + \frac{1}{25}}$$

$$\xrightarrow{(II)} v_1 = \begin{pmatrix} \frac{5}{6} & -\frac{1}{3}\left(\frac{1}{3} + \frac{1}{4s}\right) \\ 0 & \frac{1}{3} + \frac{1}{2s} \end{pmatrix} i_1 + \frac{1}{3\left(\frac{1}{3} + \frac{1}{2s}\right)} v_2$$

$$H = \begin{bmatrix} \frac{s+2}{2s+3} & \frac{2s}{2s+3} \\ -\frac{(4s+3)}{4s+6} & \frac{6s}{2s+3} \end{bmatrix}$$



$$v_1 = 2i_1 \quad i_2 = -10i_1 + \frac{1}{4}v_2 \quad v_0$$

$$i_1 = \frac{v_1}{2}$$

$$\text{KCL at } v_1: \frac{v_1 - v_{in}}{2} + \frac{v_1}{2} + \frac{(v_1 - v_0)s}{2} = 0$$

$$v_1 = \frac{sv_0 + v_{in}}{s+2}$$

$$\text{KCL at } v_0: -10i_1 + \frac{1}{4}v_0 + \frac{v_0 s}{4} + \frac{(v_0 - v_1)s}{2} = 0$$

$$\left(\frac{1}{4} + \frac{s}{4} + \frac{s}{2}\right)v_0 = \left(5 + \frac{s}{2}\right)v_1$$

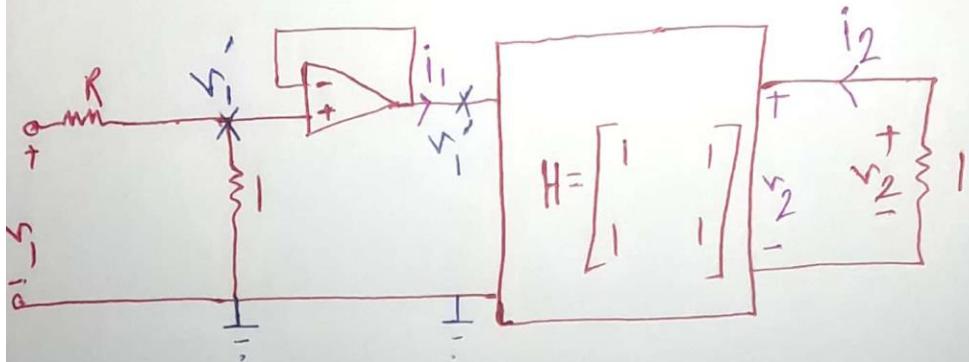
$$\frac{3s+1}{s+2}v_0 = \frac{s+10}{21} \times \frac{sv_0 + v_{in}}{s+2}$$

$$\left(\frac{3s+1}{2} - \frac{s^2 + 10s}{s+2} \right) v_o = \frac{s+10}{s+2} v_{in}$$

$$\frac{3s^2 + 6s + s + 2 - 2s^2 - 20s}{2(s+2)} v_o = \frac{10+s}{s+2} v_{in}$$

$$\frac{v_o}{v_{in}} = \frac{2(s+10)}{s^2 - 13s + 2} = \frac{2s + 20}{s^2 - 13s + 2} \checkmark$$

$$j = R \quad \leftarrow \frac{v_2}{v_1} = -\frac{1}{2} \text{ Nj} \rightarrow \text{to } j = 0$$



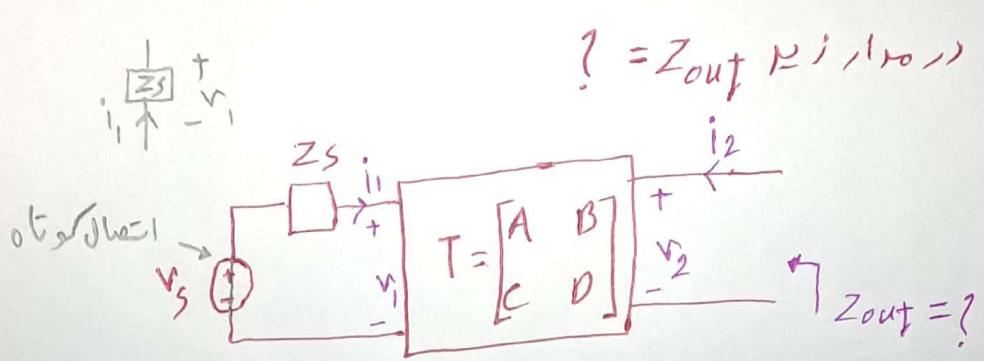
$$v_1' = i_1 + v_2 \text{ (I)}, \quad i_2 = i_1 + v_2 \text{ (II)}$$

$$v_1' = \frac{v_1}{R+1} \text{ (III)}, \quad i_2 = -v_2 \text{ (IV)}$$

$$\xrightarrow{(I, III)} \frac{v_1}{R+1} = i_1 + v_2 \rightarrow i_1 = \frac{v_1}{R+1} - v_2$$

$$\xrightarrow[\text{(IV)}]{(II)} -v_2 = \frac{v_1}{R+1} - v_2 + v_2 \rightarrow \frac{v_2}{v_1} = -\frac{1}{R+1}$$

$$-\frac{1}{R+1} = -\frac{1}{2} \rightarrow R+1=2 \rightarrow R=1 \quad \checkmark$$



$$v_1 = A v_2 - B i_2$$

$$i_1 = C v_2 - D i_2$$

$$v_1 = -Z_s i_1$$

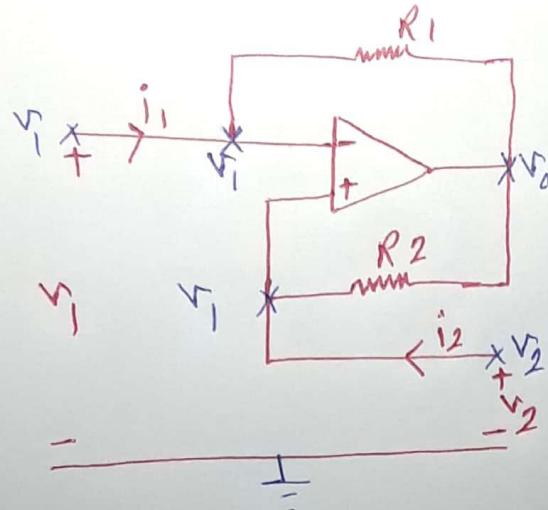
$$\frac{v_2}{i_2} = ?$$

$$-Z_s i_1 = A v_2 - B i_2 \rightarrow i_1 = \frac{-B i_2 - A v_2}{Z_s}$$

$$\frac{B i_2 - A v_2}{Z_s} = C v_2 - D i_2 \rightarrow \left(\frac{B}{Z_s} + D \right) i_2 = \left(\frac{A}{Z_s} + C \right) v_2$$

$$Z_{out} = \frac{v_2}{i_2} = \frac{D + \frac{B}{Z_s}}{\frac{A}{Z_s} + C} = \frac{B + D Z_s}{A + C Z_s}$$

$v_{out} = T' v_2$, $T \rightarrow \bar{T}$ ($\bar{v} = v$)



$$\begin{cases} v_1 = A v_2 - B i_2 \\ i_1 = C v_2 - D i_2 \end{cases} \quad T$$

$$\begin{cases} v_2 = A' v_1 - B' i_1 \\ i_2 = C' v_1 - D' i_1 \end{cases} \quad T'$$

$$v_1 = v_2 \quad KCL @ v_{1-} : i_1 = \frac{v_1 - v_0}{R_1} \rightarrow v_0 = v_1 - R_1 i_1 \quad (I)$$

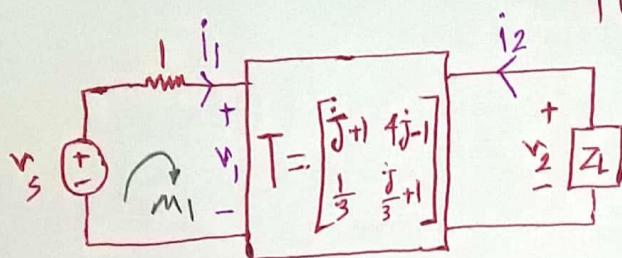
$$KCL @ v_{1+} : i_2 = \frac{v_1 - v_0}{R_2} \rightarrow v_1 - v_1 + R_1 i_1 = R_2 i_2 \rightarrow i_1 = \frac{R_2}{R_1} i_2$$

$$\begin{cases} v_1 = v_2 - o i_2 \\ i_1 = o v_2 - \left(\frac{R_2}{R_1}\right) i_2 \end{cases} \rightarrow T = \begin{bmatrix} 1 & 0 \\ 0 & -\frac{R_2}{R_1} \end{bmatrix}$$

$$\begin{cases} v_2 = v_1 - o i_1 \\ i_2 = o v_1 - \left(-\frac{R_1}{R_2}\right) i_1 \end{cases} \rightarrow T' = \begin{bmatrix} 1 & 0 \\ 0 & \frac{R_1}{R_2} \end{bmatrix}$$

$$T = (T')^{-1} = \text{مترافق مع طور متنفس}$$

جذب شرایطی حد اکثر توان Z_L متنقل می‌شود



$$(نحوه) i_1 = v_2 \leftarrow v_s = 156$$

$$A = j + 1$$

$$B = 4j - 1$$

$$C = \frac{1}{3}$$

$$D = 1 + \frac{j}{3}$$

جذب شرایطی حد اکثر توان Z_L متنقل می‌شود

..... مسأله 30

$$Z_{out} = \frac{B + D Z_s}{A + C Z_s} \quad \underline{Z_s = 1} \quad \frac{4j - 1 + j/3 + 1}{j + 1 + \frac{1}{3}}$$

$$Z_{out} = \frac{\frac{13j}{3}}{\frac{3j+4}{3}} \rightarrow Z_{out} = \frac{13j}{3j+4} \times \frac{(-3j+4)}{(-3j+4)}$$

$$Z_{out} = \frac{39 + 52j}{25} = 1.56 + 2.08j = Z_{out}$$

$Z_L = 1.56 - 2.08j \leftarrow Z_L = Z_{out}^*$

$$v_1 = (j+1)v_2 - (4j-1)i_2 \quad (I) \quad v_s = 15.6$$

$$i_1 = \frac{1}{3}v_2 - (1 + \frac{j}{3})i_2 \quad (II)$$

$$KVL @ M_1: v_s = i_1 + v_1 = 15.6 \quad (III)$$

$$v_2 = -Z_L i_2 \rightarrow i_2 = \frac{v_2}{-1.56 + 2.08j} \rightarrow i_2 = \left(-0.2308 - 0.3077j \right) v_2$$

$$i_2 = (-0.2308 - 0.3077j)v_2$$

$$\xrightarrow{(I)} v_1 = (j+1)v_2 - (4j-1)(-0.2308 - 0.3077j)v_2$$

$$v_1 = (-0.4616 + 1.0155j)v_2$$

$$\xrightarrow{(II), (III)} i_1 + v_1 = 15.6$$

$$\leftarrow \frac{1}{3}v_2 - \left(1 + \frac{j}{3} \right) (-0.2308 - 0.3077j)v_2 + (-0.4616 + 1.0155j)v_2 = 15.6$$

$$\rightarrow 2jv_2 = 15.6 \rightarrow v_2 = -7.8j = 7.8 \angle -90^\circ = v_2$$