

حل تمارین فصل 2

ص 1

نمودارین: تبدیل لاپلاس توابع زیر به دست آورید:

$$x(t) = \sin t \times u(t-1) = \sin(t-1+1) u(t-1)$$

$$x(t) = \sin(t-1) \cos(1) u(t-1) + \sin(1) \cos(t-1) u(t-1)$$

← مقدار ثابت ←

$$X(s) = \cos(1) \times \left( \frac{1}{s^2 + 1} \right) \times e^{-s} + \sin(1) \times \left( \frac{s}{s^2 + 1} \right) \times e^{-s}$$

$$y(t) = \sin(t-1) u(t) = \sin t \times \cos 1 \times u(t) - \sin 1 \cos t \times u(t)$$

$$Y(s) = \cos 1 \times \left( \frac{1}{s^2 + 1} \right) - \sin(1) \times \left( \frac{s}{s^2 + 1} \right)$$

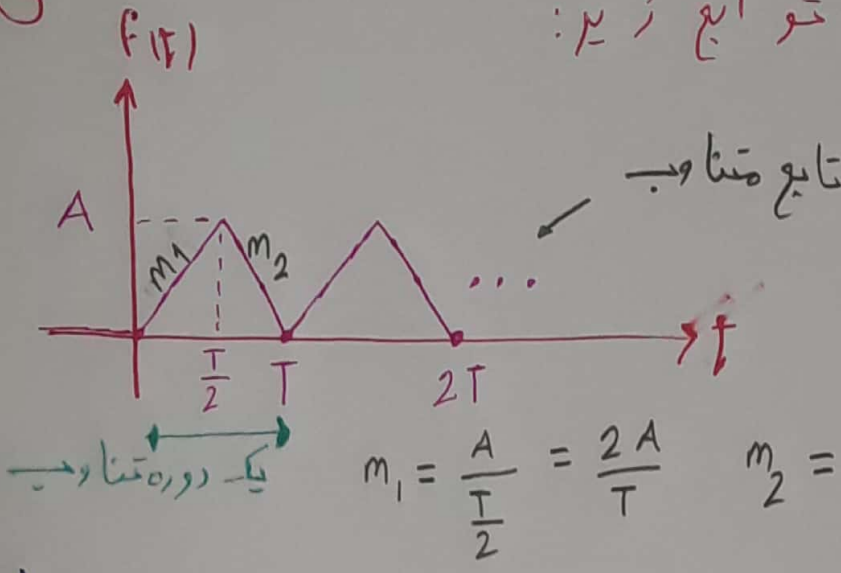
$$Z(t) = \sin(t-1) u(t-1)$$

اولاً سینوس  $\sin t u(t)$

$$Z(s) = \left( \frac{1}{s^2 + 1} \right) \times e^{-s}$$

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تبدیل: تبدیل لاپلاس توابع زیر:



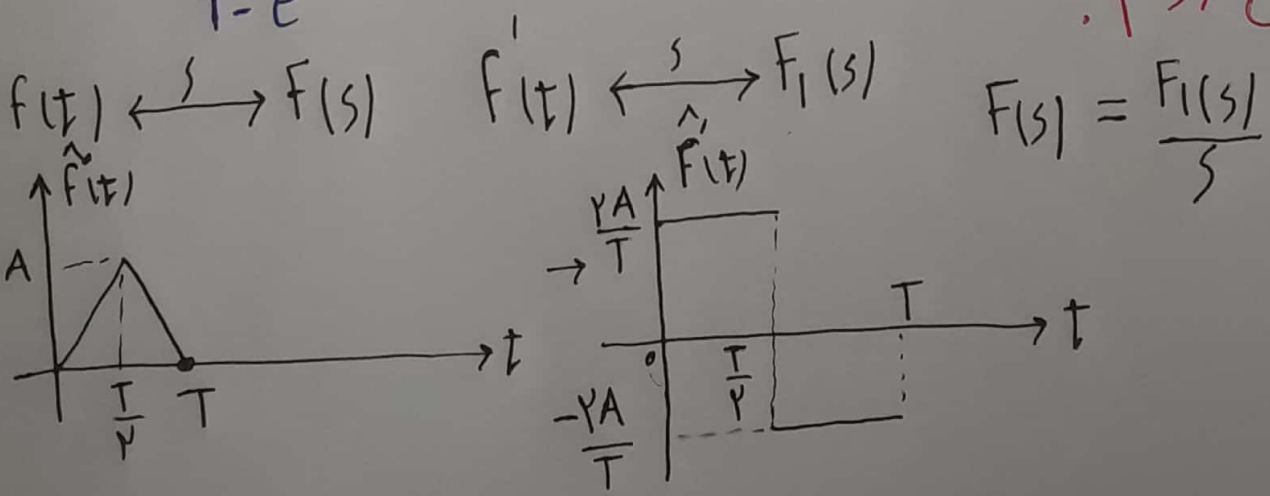
$$\hat{f}(t) = \frac{2A}{T} r(t) - \frac{2A}{T} r\left(t - \frac{T}{2}\right) + \frac{2A}{T} r(t-T)$$

$$\hat{f}(t) = \frac{2A}{T} \left( t u(t) - 2\left(t - \frac{T}{2}\right) u\left(t - \frac{T}{2}\right) + (t-T) u(t-T) \right)$$

$$\hat{F}(s) = \frac{2A}{T} \left( \frac{1}{s^2} - 2e^{-\frac{T}{2}s} \times \frac{1}{s^2} + e^{-Ts} \frac{1}{s^2} \right)$$

$$F(s) = \frac{\hat{F}(s)}{1 - e^{-Ts}} \quad T=T \rightarrow F(s) =$$

روش دوم:



$$\hat{f}'(t) = \frac{2A}{T} u(t) - \frac{2A}{T} u\left(t - \frac{T}{2}\right) + \frac{2A}{T} u(t-T)$$

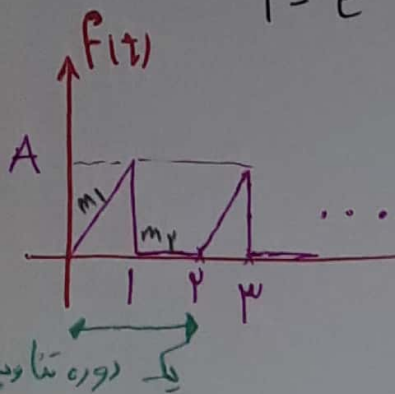
ادامه حل درص 3

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$$\hat{F}_1(s) = \frac{\gamma A}{T} \left( \frac{1}{s} - \gamma e^{-\frac{T}{\gamma}s} \times \frac{1}{s} + e^{-Ts} \times \frac{1}{s} \right)$$

$$\hat{F}(s) = \frac{\hat{F}_1(s)}{s} \rightarrow \hat{F}(s) = \frac{\gamma A}{T} \left( \frac{1}{s^2} - \frac{\gamma}{s^2} e^{-\frac{T}{\gamma}s} + \frac{1}{s^2} e^{-Ts} \right)$$

$$F(s) = \frac{\hat{F}(s)}{1 - e^{-Ts}}$$



$$m_1 = A$$

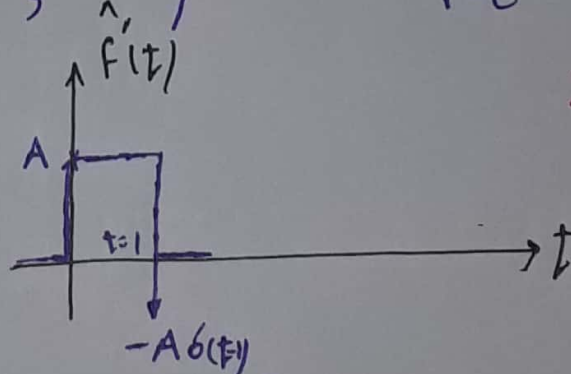
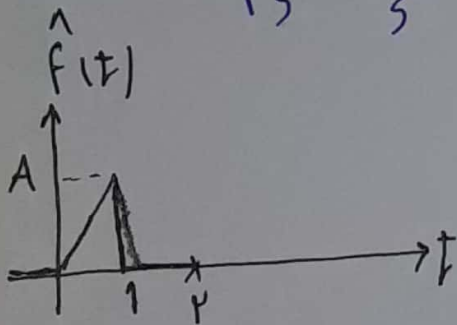
$$m_2 = 0$$

تکرار می‌شود:

$$\hat{f}(t) = A v(t) - A v(t-1) - A u(t-1)$$

$$\hat{f}(t) = A (t u(t) - (t-1) u(t-1) - u(t-1))$$

$$\hat{F}(s) = A \left( \frac{1}{s^2} - \frac{1}{s^2} e^{-s} - \frac{1}{s} e^{-s} \right) \rightarrow F(s) = \frac{\hat{F}(s)}{1 - e^{-Ts}}$$



روش دوم:

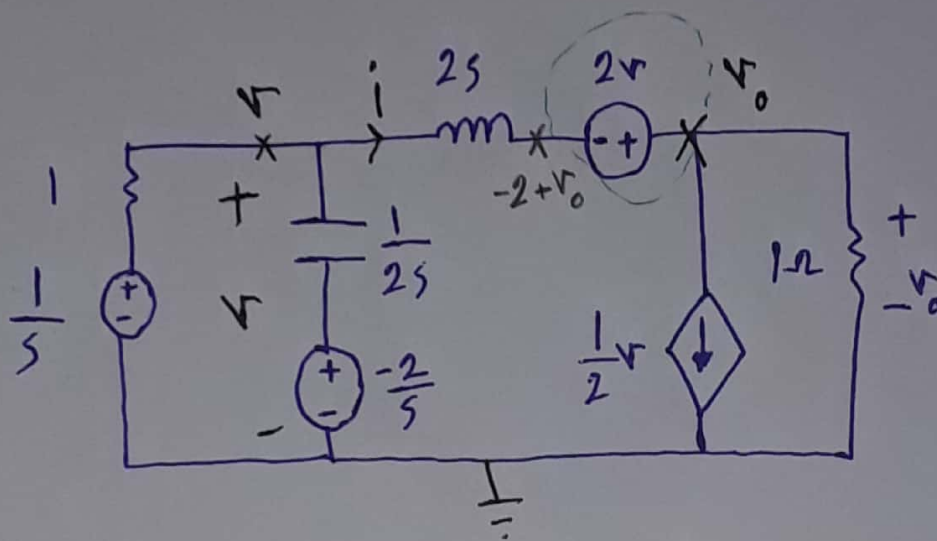
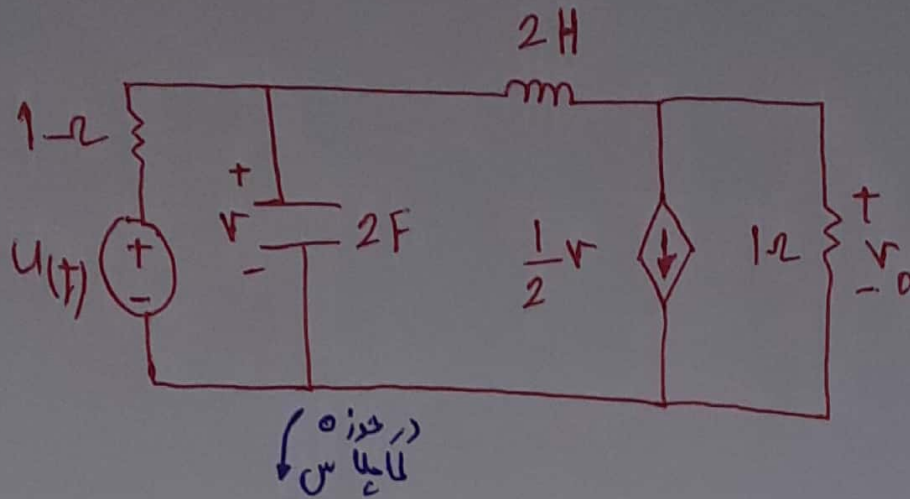
$$\hat{f}(t) = A u(t) - A u(t-1) - A b(t-1) \rightarrow \hat{F}(s) = A \left( \frac{1}{s} - \frac{1}{s} e^{-s} - e^{-s} \right)$$

$$\hat{F}(s) = \frac{\hat{F}_1(s)}{s} \rightarrow \hat{F}(s) = A \left( \frac{1}{s^2} - \frac{1}{s^2} e^{-s} - \frac{1}{s} e^{-s} \right)$$

$$F(s) = \frac{\hat{F}(s)}{1 - e^{-Ts}} = \frac{\hat{F}(s)}{1 - e^{-Ts}}$$

$$v_o(t) = ?$$

$$i_L(0^-) = 1A \text{ و } v_C(0^-) = -2v \text{ (تشرین 1)}$$



$$KCL @ v: \frac{v - \frac{1}{s}}{1} + \frac{v + \frac{2}{s}}{\frac{1}{2s}} + \frac{v - v_o + 2}{2s} = 0 \xrightarrow{\times 2s}$$

$$2sv - 2 + 4s^2(v) + 8s + v - v_o + 2 = 0 \rightarrow$$

$$-v_o + (4s^2 + 2s + 1)v = -8s \quad (I)$$

$$KCL @ v_o: \frac{v_o - 2 - v}{2s} + \frac{1}{2}v + \frac{v_o - 0}{1} = 0 \xrightarrow{\times 2s}$$

$$v_o - 2 - v + sv + 2sv_o = 0 \rightarrow (2s+1)v_o + (s-1)v = 2 \quad (II)$$

ادامه حل در ص 2



ادامہ حل تھوہ جی 1 -

$$\begin{bmatrix} v_0 \\ v_1 \end{bmatrix} \begin{matrix} * \\ \sim \\ \times \\ \div \end{matrix} \begin{bmatrix} -1 & 4s^2 + 2s + 1 \\ 2s + 1 & s - 1 \end{bmatrix} = \begin{bmatrix} -1s \\ 2 \end{bmatrix}$$

$$v_0 = \frac{\begin{vmatrix} -1s & 4s^2 + 2s + 1 \\ 2 & s - 1 \end{vmatrix}}{\begin{vmatrix} -1 & 4s^2 + 2s + 1 \\ 2s + 1 & s - 1 \end{vmatrix}} = \frac{-1s^2 + 1s - 1s^2 - 4s - 2}{-s + 1 - 8s^2 - 4s^2 - 2s - 4s^2 - 2s - 1} = \frac{-2s^2 - 7s - 2}{-8s^2 - 7s + 1}$$

$$v_0(s) = \frac{2(1s^2 - 2s + 1)}{s(1s^2 + 1s + 0)}$$

\* نکتہ \*  $s=0$  کا سبب لاپلا س مکتوب  $1s^2 + 1s + 0 = 0 \rightarrow \Delta < 0 \rightarrow$  قطب مفصل  
 0 زمانی کہ ریشہ مفصل داریم  
 قطب

$$F(s) = \frac{X(s)}{(s+a)^2 + b^2} = \frac{k_1 s + k_p}{(s+a)^2 + b^2} = \frac{k_1 (s+a)}{(s+a)^2 + b^2} + \frac{k_p - k_1 a}{(s+a)^2 + b^2}$$

$$f(t) = F^{-1}\{F(s)\} = k_1 e^{-at} \cos bt + \frac{k_p - k_1 a}{b} e^{-at} \sin bt$$

$$v_0(s) = \frac{1}{s} \frac{(1s^2 - 2s + 1)}{(s^2 + s + \frac{0}{1})} = \frac{A}{s} + \frac{\frac{b}{k_1(s + \frac{1}{p})} + k_p - \frac{1}{p} k_1}{\frac{(s + \frac{1}{p})^2 + \frac{q}{\lambda}}{s^2 + s + \frac{0}{1}}}$$

↑  
 مقاب  
 $A, k_1, k_2$

ادامہ حل درص 3

ادامہ حل تھریں ۱:

$$\frac{\frac{1}{\tau} (\lambda s^2 - \gamma s + 1)}{s (s^2 + s + \frac{\delta}{\lambda})} = \frac{A}{s} + \frac{K_1 (s + \frac{1}{\tau})}{(s + \frac{1}{\tau})^2 + \frac{\omega}{\lambda}} + \frac{K_2 - \frac{1}{\tau} K_1}{(s + \frac{1}{\tau})^2 + \frac{\omega}{\lambda}}$$

$$\xrightarrow{XS} \frac{\frac{1}{\tau} (\lambda s^2 - \gamma s + 1)}{(s^2 + s + \frac{\delta}{\lambda})} = A + \frac{K_1 s (s + \frac{1}{\tau})}{(s + \frac{1}{\tau})^2 + \frac{\omega}{\lambda}} + \frac{(K_2 - \frac{1}{\tau} K_1) s}{(s + \frac{1}{\tau})^2 + \frac{\omega}{\lambda}}$$

$$s=0: \frac{\frac{1}{\tau}}{\frac{\delta}{\lambda}} = A \rightarrow A = \frac{\gamma}{\delta}$$

$$s=\infty: \frac{\lambda}{\tau} = A + K_1 \rightarrow K_1 = \gamma - A = \frac{\lambda}{\delta}$$

$$s=-1: \frac{\frac{1}{\tau} (\lambda + \gamma + 1)}{(1+1)(1-1+\frac{\delta}{\lambda})} = +\frac{\gamma}{\delta} - \frac{\frac{\lambda}{\delta} (-1+\frac{1}{\tau})}{\frac{1}{\tau} + \frac{\omega}{\lambda}} + \frac{(K_2 - \frac{\gamma}{\delta})(-1)}{\frac{1}{\tau} + \frac{\omega}{\lambda}}$$

$$\rightarrow K_2 = -0.9, K_1 = 1.4, A = 0.4$$

$$r_o(t) = e^{-\frac{t}{\tau}} \left( \frac{\lambda}{\delta} \cos(0.412t) - \frac{17.5}{\delta} \sin(0.412t) \right) + \frac{\gamma}{\delta} u(t)$$

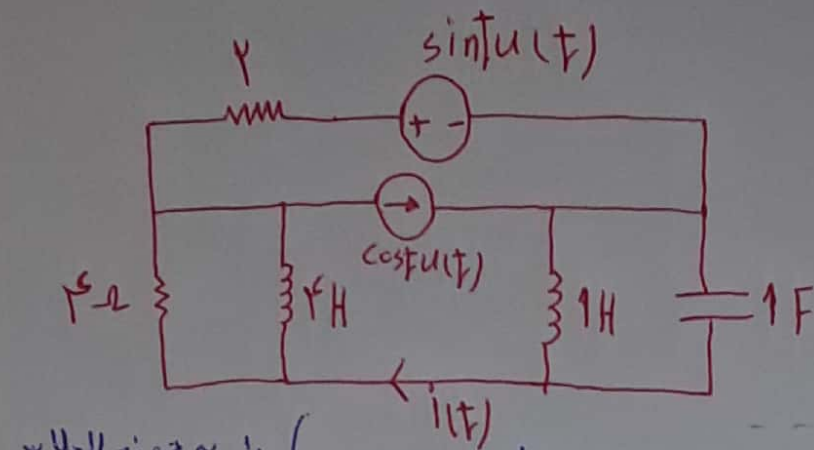
$$\text{matlab test: } \frac{\lambda}{5} e^{-\frac{t}{\tau}} \left[ \cos \frac{\sqrt{2} \times \sqrt{3}}{4} t - \frac{17}{24} \frac{\sqrt{2} \times \sqrt{3}}{4} \sin \frac{\sqrt{2} \times \sqrt{3}}{4} t \right] + \frac{2}{5}$$

تصريح 2:  $i(t) = ? ; t > 0$   
 شرایط اولیه صفر است.

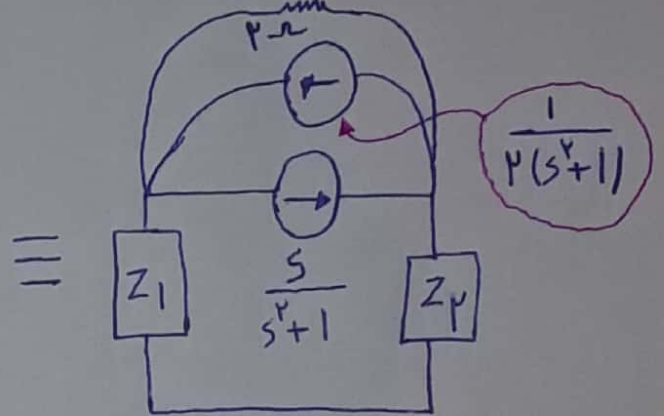
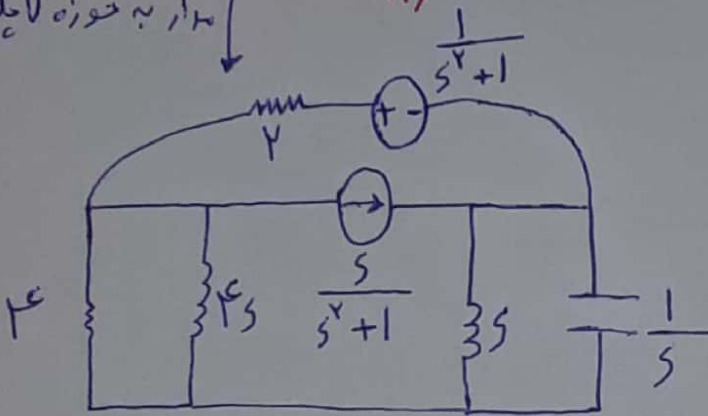
$$i_{L1}(t=0^-) = i_{L2}(t=0^-) = 0$$

$$v_C(0^-) = v_C(0^+) = 0$$

$$i_{L1}(t=0^+) = i_{L2}(t=0^+) = 0$$

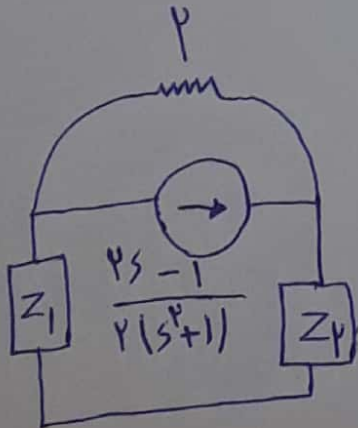


بدان به نحوه لاپلاس

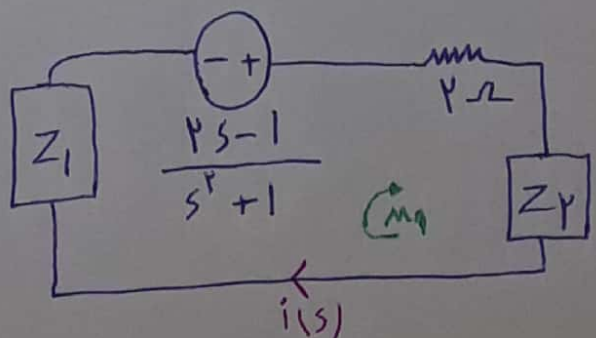


$$Z_{1(s)} = 2 \parallel 2s = \frac{2s}{s+1}$$

$$Z_{2(s)} = s \parallel \frac{1}{s} = \frac{s}{s^2+1}$$



$\approx$



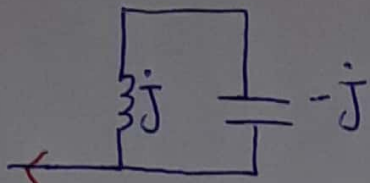
$$\text{KVL @ } M_1: i(s) = \frac{\frac{2s-1}{s^2+1}}{Z_1 + Z_2 + \frac{2}{s}}$$

$$Z_1 + Z_2 + \frac{2}{s} = \frac{4s^3 + 3s^2 + 5s + 2}{(s^2+1)(s+1)}$$

ادامه حل ص 13



ص 5  
 باکشی دقت متوجه می شویم در  $\omega=1$  سلف  $1H$  با خازن  $1F$  تشدید دارد.  
 پس پاسخ حالت دائمی  $i(t)$   $0 \neq i(t)$



پس  $i(t)$  تنها پاسخ حالت گذرا دارد که همان قطب پای (ک) می باشد.

$$i(s) = \frac{(2s-1)(s+1)}{4s^3 + 3s^2 + 7s + 2}$$

هدف اولیه  
 قطب پای (ک)

$$4s^3 + 3s^2 + 7s + 2 = 0$$

ریشه معادله (پاسی، خطا)  $s \approx -0.3$

$s + 0.3 = 0 \rightarrow$  ریشه معادله  $\rightarrow$

$$\begin{array}{r|l} 4s^3 + 3s^2 + 7s + 2 & s + 0.3 \\ \hline -4s^3 & -1.2s \\ \hline 1.2s^2 + 7s & \\ -1.2s^2 - 3.6s & \\ \hline 4.4s + 2 & \\ -4.4s - 1.32 & \\ \hline & \approx 0 \end{array}$$

$$(s + 0.3) \left( 4s^2 + 1.2s + 4.4 \right) = 0$$

$\Delta < 0$

$$4s^2 + 1.2s + 4.4 = 0 \rightarrow s^2 + 0.3s + 1.1 = 0$$

$2\alpha = 1 \rightarrow \alpha = 0.5$   
 $\omega_0 = \sqrt{1.1} \approx 1$

$\omega_0 > \alpha \rightarrow$  میرا ضعیف  $e^{(\alpha \cos \omega_d t + B \sin \omega_d t)}$   $\omega_d = \sqrt{\omega_0^2 - \alpha^2} = 0.84$

$$i(t) = 0 + Ae^{-0.3t} + e^{-0.1t} (B \cos \omega_d t + C \sin \omega_d t)$$

ادامه حل ص 6



$$i(t) = A e^{-0,13t} + e^{-0,10t} (B \cos 0,14t + C \sin 0,14t) + 0$$

$$i(s) = \frac{2s^2 + s - 1}{4s^3 + 3s^2 + 7s + 2}$$

اگر  $F(s)$  تبدیل لاپلاس  $f(t)$  باشد:

$$f(0^+) = \lim_{s \rightarrow \infty} s F(s) \quad \frac{df}{dt}(0^+) = \lim_{s \rightarrow \infty} [s^2 F(s) - s f(0^+)]$$

$$\frac{d^2 f}{dt^2}(0^+) = \lim_{s \rightarrow \infty} [s^3 F(s) - s^2 f(0^+) - s f'(0^+)]$$

$$i(0^+) = \lim_{s \rightarrow \infty} \frac{2s^2 + s - 1}{4s^3 + 3s^2 + 7s + 2} = \frac{1}{4} = i(t=0^+)$$

$$\frac{di}{dt}(0^+) = \lim_{s \rightarrow \infty} \left[ \frac{2s^2 + s - 1}{4s^3 + 3s^2 + 7s + 2} - \frac{s}{4} \right] = \frac{-10}{4}$$

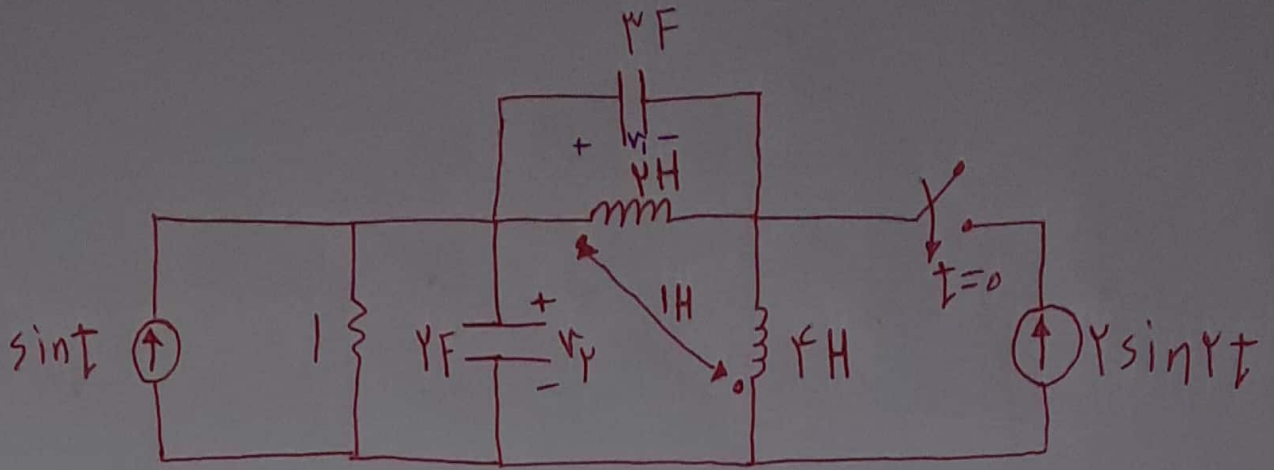
$$\frac{d^2 i}{dt^2}(0^+) = \lim_{s \rightarrow \infty} \left[ \frac{2s^2 + s - 1}{4s^3 + 3s^2 + 7s + 2} - \frac{s^2}{4} + \frac{10s}{4} \right] = \lim_{s \rightarrow \infty} \left[ \frac{2s^2}{4s^3} \right] = \frac{1}{2}$$

$$i(0) = A + B = \frac{1}{4} \quad (I) \quad \frac{di}{dt}(0) = -0,13A - 0,10B + 0,14C = -\frac{10}{4} \quad (II)$$

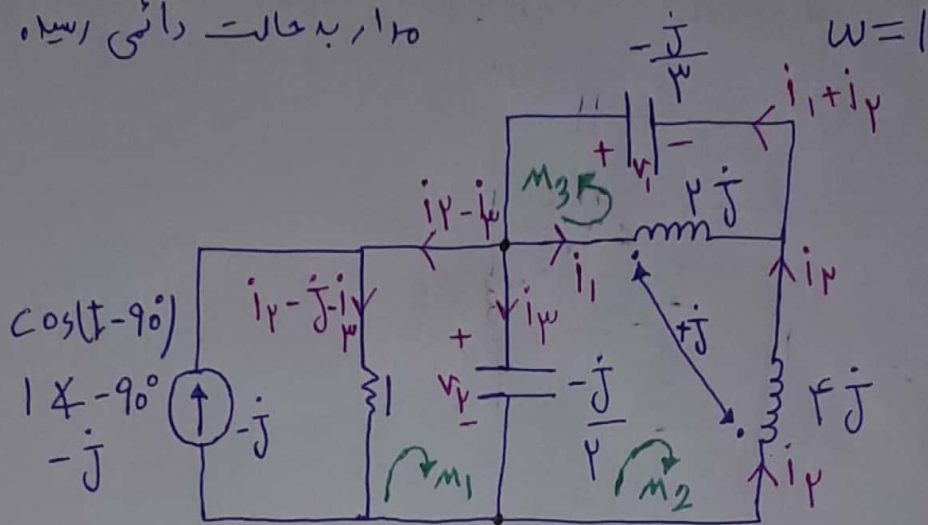
$$\frac{d^2 i}{dt^2}(0) = 0,09A + 0,12B - 0,10 \times 0,14C + 0,14^2 C = \frac{1}{2} \quad (III)$$

$$\begin{cases} A = 4 \\ B = -0,1 \\ C = -0,1 \end{cases}$$

$$i(t) = 4e^{-0,13t} + e^{-0,10t} (-0,1 \cos 0,14t - 0,1 \sin 0,14t) + 0$$



$t < 0$ : مدار به حالت دائمی رسیده



$$KVL @ m_1: -i_2 + j + i_3 - \frac{j}{2} i_3 = 0 \rightarrow -i_2 + (1 - \frac{j}{2}) i_3 = -j \quad (I)$$

$$KVL @ m_2: +\frac{j}{2} i_3 + 2j i_1 + j i_2 - (4j (i_2) + j i_1) = 0$$

$$\rightarrow j i_1 - 3j i_2 + \frac{j}{2} i_3 = 0 \rightarrow i_1 - 3i_2 + \frac{i_3}{2} = 0 \quad (II)$$

$$KVL @ m_3: 2j i_1 + j i_2 - \frac{j}{3} (i_1 + i_2) = 0 \rightarrow \frac{5}{3} j i_1 + \frac{2}{3} j i_2 = 0$$

$$\rightarrow 5i_1 = -2i_2 \rightarrow +2i_2 + 5i_1 = 0 \quad (III)$$

$$\begin{cases} i_1 = -0,103 + 0,108j = 0,104 \angle 120^\circ \\ i_2 = 0,107 - 0,113j = 0,158 \angle -41^\circ \\ i_3 = 0,181 - 0,117j \rightarrow v_1 = -\frac{j}{3} i_3 = -0,43 - 0,28j = 0,51 \angle 210^\circ \end{cases}$$

ادامه حل ص ۱۲

ادامہ حل تھریس: ۳

$$i_1(t) = 0.104 \angle 120^\circ = 0.104 \cos(t + 120^\circ) \rightarrow i_1(0) = -0.103$$

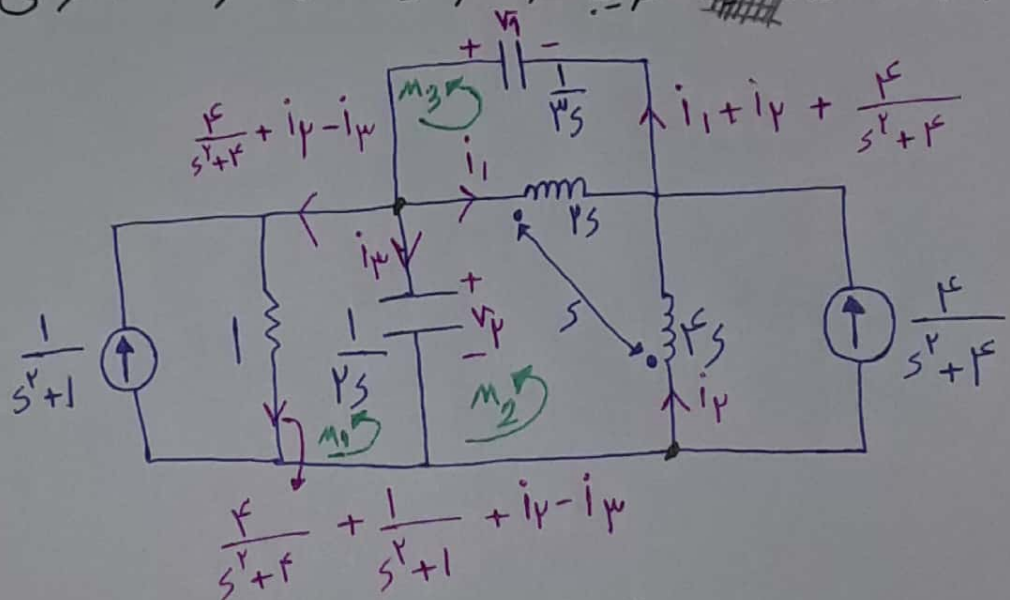
$$i_2(t) = 0.115 \angle -41^\circ = 0.115 \cos(t - 41^\circ) \rightarrow i_2(0) = 0.107$$

$$v_1(t) = 0.044 + 0.01j = 0.047 \angle 11^\circ \rightarrow v_1(0) = 0.047 \cos(11^\circ) = 0.046$$

$$v_2(t) = 0.15 \angle 210^\circ = 0.15 \cos(t + 210^\circ) \Rightarrow v_2(0) = -0.143$$

باقیہ بہ صفا دیر اولیہ تقریباً از شرایط اولیہ صرف نظر می کنیم.

$$t \gg 0$$



$$\text{KVL @ } m_1: -\frac{1}{s} i_w + \frac{4}{s^2+4} + \frac{1}{s^2+1} + i_2 - i_3 = 0$$

$$\rightarrow i_2 - \left(1 + \frac{1}{s}\right) i_3 = \frac{-4}{s^2+4} - \frac{1}{s^2+1} \quad (\text{I})$$

$$\text{KVL @ } m_2: 4s i_2 + s i_1 - (2s i_1 + s i_2) + \frac{i_3}{s} = 0$$

$$\rightarrow -s i_1 + 3s i_2 + \frac{1}{s} i_3 = 0 \quad (\text{II})$$

$$\text{KVL @ } m_3: 2s i_1 + s i_2 + \frac{1}{s} (i_1 + i_2 + \frac{4}{s^2+4}) = 0$$

$$\rightarrow \left(2s + \frac{1}{s}\right) i_1 + \left(s + \frac{1}{s}\right) i_2 = \frac{-4}{s(s^2+4)} \quad (\text{III})$$

مثلاً با حل ۳ معادله میسر می آید:

$$i_3 = \frac{2s^2(21s^2 + 4) \left[ \left( \frac{1}{s^2 + 1} \right) + \frac{4}{s^2 + 4} \right] - \frac{18s^2}{A}}{21s^5 + 42s^4 + 4s^3 + 14s^2 + 1}$$

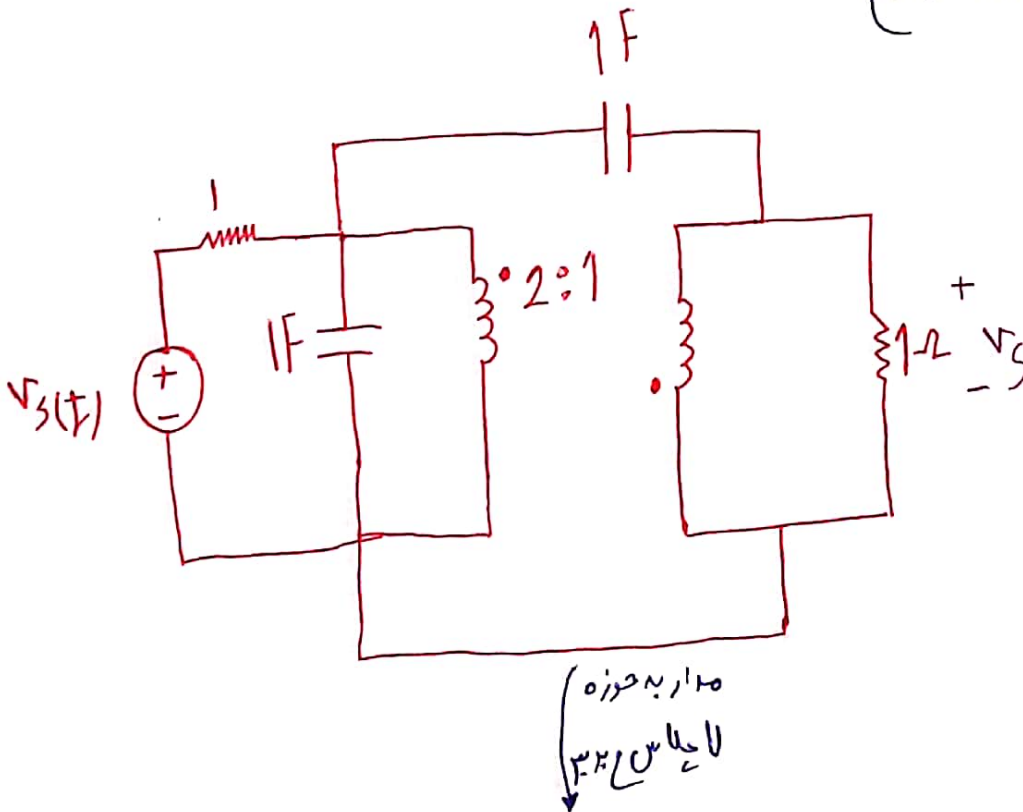
$$A = (s^2 + 4)(21s^5 + 42s^4 + 4s^3 + 14s^2 + 1)$$

$$v_2 = \frac{i_3}{2s} \rightarrow \text{با ضرایب لایه‌های معکوس} \\ \text{به دست می آید}$$

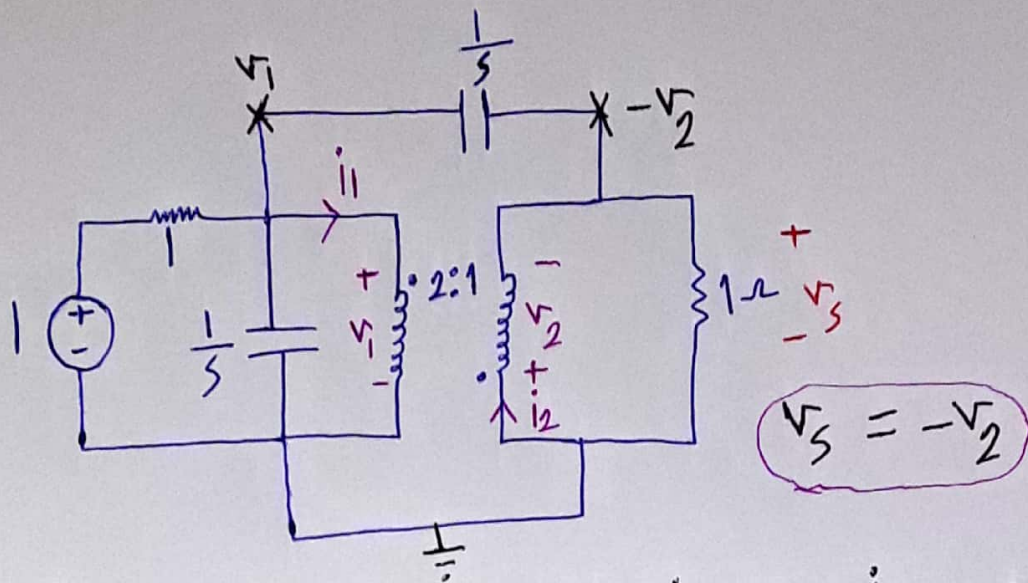
$$v_1 = -\frac{1}{3s} \left( i_1 + i_2 + \frac{4}{s^2 + 4} \right)$$

تبدیل: یا سطح ضربه مدار شکل زیر با فرض شرایط اولیه صفر

یا سطح ضربه  $\leftarrow v_s(t) = \delta(t)$  ورودی







$$\frac{v_1}{v_2} = \frac{2}{1} \rightarrow v_1 = 2v_2 \text{ (I)} \quad 2i_1 + i_2 = 0 \rightarrow i_2 = -2i_1 \text{ (II)}$$

$$\text{KCL @ } v_1: v_1 - 1 + s v_1 + i_1 + (v_1 + v_2)s = 0$$

$$\text{(I)} \rightarrow \cancel{v_1 - 1 + s v_1 + i_1 + s v_1} \quad (1 + 2s)v_1 + s v_2 = 1 - i_1 \quad (*)$$

$$\text{I} \rightarrow 2(2s + 1)v_2 + s v_2 = 1 - i_1 \rightarrow (5s + 2)v_2 + i_1 = 1 \quad (**)$$

$$\text{KCL @ } v_2: -v_2 - i_2 + (v_2 + v_1)s = 0 \rightarrow s v_1 + (s + 1)v_2 - i_2 = 0$$

$$\text{I, II} \rightarrow -2s v_2 - (s + 1)v_2 + 2i_1 = 0 \rightarrow -(3s + 1)v_2 + 2i_1 = 0$$

$$\rightarrow i_1 = \frac{(3s + 1)v_2}{2} \quad (***) \rightarrow (5s + 2)v_2 + \frac{3s + 1}{2}v_2 = 1 \rightarrow$$

$$v_2(s) = \frac{2}{13s + 5} \rightarrow v_2(t) = \frac{2}{13} \left( \frac{1}{s + \frac{5}{13}} \right) \rightarrow v_2(t) = \frac{2}{13} e^{-\frac{5}{13}t} u(t)$$

$$\rightarrow v_5(t) = -\frac{2}{13} e^{-\frac{5}{13}t} u(t)$$