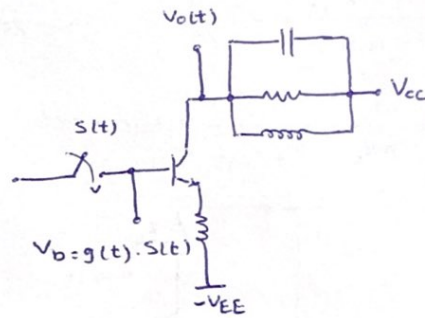
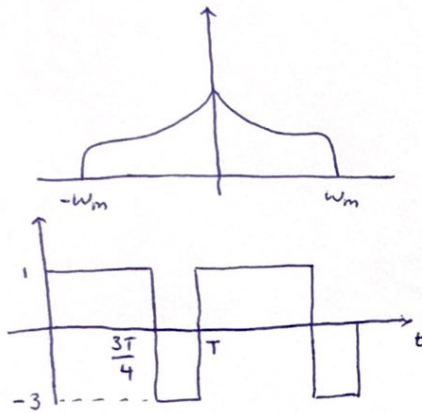


#3

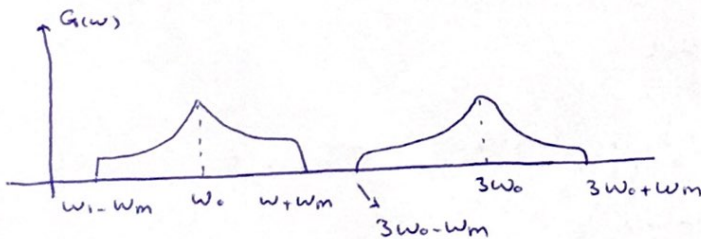


$$s(t) = \frac{a_0}{2} + \sum_{n=1}^{\infty} a_n \cos n\omega_0 t + b_n \sin n\omega_0 t \Rightarrow a_0 = \frac{1}{T} \int_0^T s(t) dt = \frac{1}{T} \int_0^{3T/4} 1 dt - 3 \int_{3T/4}^T dt = 0$$

$$b_n = \frac{2}{T} \int_0^T s(t) \sin n\omega_0 t dt = 0$$

$$a_n = \frac{2}{T} \int_0^T s(t) \cos n\omega_0 t dt = \frac{2}{T} \left(\int_0^{3T/4} \cos n\omega_0 t dt - 3 \int_{3T/4}^T \cos n\omega_0 t dt \right) = \frac{-1}{n\pi}$$

$$\Rightarrow s(t) = \sum_{n=1}^{\infty} a_n \cos n\omega_0 t \Rightarrow V_b(t) = g(t) s(t) = \frac{-1}{n\pi} g(t) \cos n\omega_0 t + \frac{-1}{8\pi} g(t) \cos n\omega_0 t$$



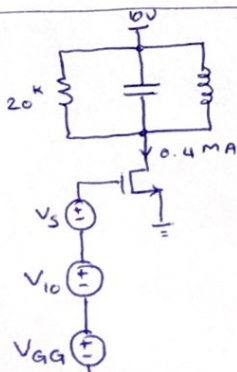
$$BW = w_0 - w_m - (w_0 - w_m) = 2w_m$$

$$3w_0 - w_m > w_0 + w_m$$

$$\Rightarrow 2w_0 > 2w_m$$

$$\Rightarrow \boxed{w_0 > w_m}$$

#5



$$\alpha = 25$$

$$\begin{cases} \mu' = 30 \frac{\mu A}{V^2} \\ V_T = 0.6 V \\ \frac{W}{L} = 20 \\ \lambda = \gamma = 0 \end{cases}$$

$$g_{oss} = \frac{2 I_{oss}}{|V_p|} \left(1 - \frac{V_{GS}}{V_p}\right) = \frac{2 I_{oss}}{|V_p|} = g_{m0}$$

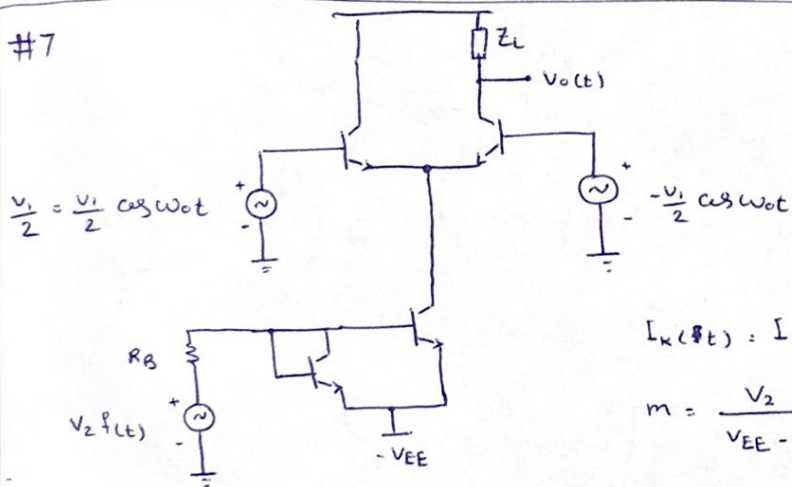
$$V_{oss} = \frac{1}{g_{m0}}, \quad V_{GS} = 0, \quad |V_{os}| = |V_A| \leq 100 \text{ mV}$$

$$V_a(t) = V_{os}(t) = \frac{V_{oss}}{R + r_{oss}} g(t) \quad \text{: شأبء ءءل ءءءل ءءء}$$

$$R > r_{oss} \left(\frac{|g(t)|_{\max}}{100 \text{ mV}} - 1 \right) \quad \text{: ءءء ءءءء ءءءء ءءء}$$

$$V_a(t) = V_{ce} + \frac{2}{\pi R_E} \cdot \frac{R}{R + r_{oss}} g(t) \cos \omega_c t$$

#7



$$I_K(t) = I_{K0} (1 + m f(t)), \quad I_{K0} = \frac{\beta}{\beta + 2} \times \frac{V_{EE} - V_{BE}}{R_B}$$

$$m = \frac{V_2}{V_{EE} - V_{BE}}$$

$$\cancel{i_{c2}(t) = -\alpha I_{K0}(t) a_1(x) (1 + m f(t)) \cos \omega_c t}$$

$$\Rightarrow i_{c2}(t) = \alpha \frac{I_{K0}(t)}{2} - \alpha I_{K0}(t) \sum_{n=1}^{\infty} a_{2n-1}(x) \cos((2n+1)\omega_c t), \quad x = \frac{V_2}{V_T}$$

$$i_{c2}(t) = -\alpha I_{K0}(t) a_1(x) (1 + m f(t)) \cos \omega_c t$$

$$\Rightarrow V_o(t) = V_{cc} + \alpha I_{K0} a_1(x) \cdot \left(1 + m f(t) + \frac{h_{L}(t)}{Z_L}\right) \cos \omega_c t$$

ءءءء ءءءءءل ءءءء ءءءء ءءءء (Z_L) ءءء