1 Column Space and Nullspace (L6)

1.1 Column Space

Given a 4×3 matrix A whose columns are in \mathbb{R}^4 space:

$$A = \begin{pmatrix} 1 & 1 & 2 \\ 2 & 1 & 3 \\ 3 & 1 & 4 \\ 4 & 1 & 5 \end{pmatrix}$$

Column space C(A) is the linear combination of A's columns, which forms a subspace of R^4 .

$$C(A) = c_1 \begin{pmatrix} 1 \\ 2 \\ 3 \\ 4 \end{pmatrix} + c_2 \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} + c_3 \begin{pmatrix} 2 \\ 3 \\ 4 \\ 5 \end{pmatrix}$$

Does Ax = b have a solution for every b?

$$Ax = \begin{pmatrix} 1 & 1 & 2 \\ 2 & 1 & 3 \\ 3 & 1 & 4 \\ 4 & 1 & 5 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \end{pmatrix} = b$$

No, because there are 4 equations and 3 unknowns.

Which b allows the system to be solved?

e.g.
$$b = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \Rightarrow x = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \quad b = \begin{pmatrix} 1 \\ 2 \\ 3 \\ 4 \end{pmatrix} \Rightarrow x = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

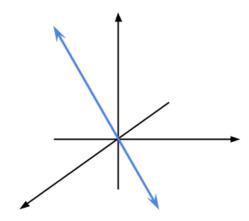
Ax = b is solvable if b is the linear combination of A's columns i.e. C(A)

1.2 Null Space

$$Ax = \begin{pmatrix} 1 & 1 & 2 \\ 2 & 1 & 3 \\ 3 & 1 & 4 \\ 4 & 1 & 5 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

Null space N(A) is all the solutions x to Ax = 0, which forms a subspace of R^3 .





If Av = 0 and Aw = 0, then $A(c_1v + c_2w) = c_1Av + c_2Aw = 0$, therefore solutions to Ax = 0 always give a subspace.

2 Ax = 0, Special Solutions, Reduced Row Form (L7)

2.1 Example: Solving Ax = 0

Given a matrix A for 3 equations and 4 unknowns:

$$A = \begin{pmatrix} 1 & 2 & 2 & 2 \\ 2 & 4 & 6 & 8 \\ 3 & 6 & 8 & 10 \end{pmatrix}$$

Third row of A is dependent on the first and second i.e. $r_3 = r_1 + r_2$. Second column of A is dependent on the first i.e. $c_2 = 2c_1$.

Run eliminations to derive U in an echelon (staircase) form:

$$\begin{pmatrix}
\boxed{1} & 2 & 2 & 2 \\
2 & 4 & 6 & 8 \\
3 & 6 & 8 & 10
\end{pmatrix}
\Rightarrow
\begin{pmatrix}
\boxed{1} & 2 & 2 & 2 \\
2 - 2 * 1 & 4 - 2 * 2 & 6 - 2 * 2 & 8 - 2 * 2 \\
3 - 3 * 1 & 6 - 3 * 2 & 8 - 3 * 2 & 10 - 3 * 2
\end{pmatrix}
=
\begin{pmatrix}
\boxed{1} & 2 & 2 & 2 \\
0 & 0 & 2 & 4 \\
0 & 0 & 2 & 4
\end{pmatrix}$$

$$\begin{pmatrix} \boxed{1} & 2 & 2 & 2 \\ 0 & 0 & \boxed{2} & 4 \\ 0 & 0 & 2 & 4 \end{pmatrix} \Rightarrow \begin{pmatrix} \boxed{1} & 2 & 2 & 2 \\ 0 & 0 & \boxed{2} & 4 \\ 0 - 0 & 0 - 0 & 2 - 2 & 4 - 4 \end{pmatrix} = \begin{pmatrix} \boxed{1} & 2 & 2 & 2 \\ \hline 0 & 0 & \boxed{2} & 4 \\ 0 & 0 & 0 & 0 \end{pmatrix} = U$$

• Pivot Column: c_1 and c_3

• Pivot Rows: r_1 and r_2

• Free Columns: c_2 and $c_4 \Rightarrow$ Any values can be assigned to x_2 and x_4

• Rank r: Number of pivots = 2 (1 at U_{11} and 2 at U_{23})

• Number of free variables: n - r = 4 - 2 = 2 (x_2 and x_4)

Equations we have are:

$$\begin{cases} x_1 +2x_2 +2x_3 +2x_4 = 0 \\ 2x_3 +4x_4 = 0 \end{cases}$$

We can assign specific values to x_2 and x_4 and solve equations to derive x_1 and x_3 . We'll call these special solutions:

$$\begin{cases} x_2 = 1 \\ x_4 = 0 \end{cases} \Rightarrow \begin{cases} x_1 = -2 \\ x_3 = 0 \end{cases} \begin{cases} x_2 = 0 \\ x_4 = 1 \end{cases} \Rightarrow \begin{cases} x_1 = 2 \\ x_3 = -2 \end{cases}$$

Null space (all solutions to Ax = 0) is the linear combination of the special solutions:

$$N(A) = c \begin{pmatrix} -2\\1\\0\\0 \end{pmatrix} + d \begin{pmatrix} 2\\0\\-2\\1 \end{pmatrix}$$

2.2 Reduced Row Echelon Form (RREF)

Matrix is in a RREF when all pivots are 1s and there are all 0s below and above the pivots. For example, starting with U from the previous section:

$$U = \begin{pmatrix} \boxed{1} & 2 & 2 & 2 \\ 0 & 0 & \boxed{2} & 4 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} 1 - 0 = 1 & 2 - 0 = 2 & 2 - 2 = 0 & 2 - 4 = -2 \\ 0 & 0 & 2 & 4 \\ 0 & 0 & 0 & 0 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & 2 & 0 & -2 \\ 0/2 = 0 & 0 = 0 & 2/2 = 1 & 4/2 = 2 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$R = RREF(A) = \begin{pmatrix} \boxed{1} & 2 & 0 & -2 \\ 0 & 0 & \boxed{1} & 2 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

Notice how the pivot columns and rows of R forms an identity matrix I:

$$\left(\begin{array}{c|c}
1 & 2 & 0 & -2 \\
0 & 0 & 1 & 2 \\
0 & 0 & 0 & 0
\end{array}\right) \Rightarrow \left[\begin{array}{c|c}
1 & 0 \\
0 & 1
\end{array}\right] = I$$

Similarly the free columns and rows of R forms a matrix F:

$$\begin{pmatrix} 1 & 2 & 0 & -2 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{pmatrix} \Rightarrow \begin{bmatrix} 2 & -2 \\ 0 & 2 \end{bmatrix} = F$$

Those matrices I and F form the special solutions from the previous section:

$$\begin{pmatrix} -2 \\ \boxed{1} \\ 0 \\ \boxed{0} \end{pmatrix} \begin{pmatrix} 2 \\ \boxed{0} \\ -2 \\ \boxed{1} \end{pmatrix} \Rightarrow \boxed{1 \quad 0} \\ \boxed{0 \quad 1} = I \quad \begin{pmatrix} \boxed{-2} \\ 1 \\ \boxed{0} \\ 0 \end{pmatrix} \begin{pmatrix} \boxed{2} \\ 0 \\ \boxed{-2} \\ 1 \end{pmatrix} \Rightarrow \boxed{-2 \quad 2} \\ \boxed{0 \quad -2} = -F$$

In general, R (A in RREF) can be broken down into I, F, and zeros. I and F form the null space matrix N i.e. the columns of I and F form special solutions.

$$Rx = \begin{pmatrix} I & F \end{pmatrix} \begin{pmatrix} x_{pivot} \\ x_{free} \end{pmatrix} = 0$$

$$x_{pivot} = -Fx_{free} \Rightarrow \begin{cases} x_{pivot} & = & -F \\ x_{free} & = & I \end{cases}$$

$$RN = 0 \Rightarrow N = x = \begin{pmatrix} -F \\ I \end{pmatrix}$$

2.3 Additional Example

Eliminations from A to U:

$$A = \begin{pmatrix} \boxed{1} & 2 & 3 \\ 2 & 4 & 6 \\ 2 & 6 & 8 \\ 2 & 8 & 10 \end{pmatrix} \Rightarrow \begin{pmatrix} \boxed{1} & 2 & 3 \\ 0 & \boxed{0} & 0 \\ 0 & 2 & 2 \\ 0 & 4 & 4 \end{pmatrix} \Rightarrow \begin{pmatrix} \boxed{1} & 2 & 3 \\ 0 & \boxed{2} & 2 \\ 0 & 0 & 0 \\ 0 & 4 & 4 \end{pmatrix} \Rightarrow \begin{pmatrix} \boxed{1} & 2 & 3 \\ 0 & \boxed{2} & 2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = U$$

- Pivot columns: c_1 and $c_2 \Rightarrow \text{Rank} = 2$
- Free columns: c_3

Assign $x_3 = 1$:

$$\begin{cases} x_1 & +2x_2 & +3x_3 & = 0 \\ 2x_2 & +2x_3 & = 0 \end{cases} \Rightarrow \begin{cases} x_1 & = -1 \\ x_2 & = -1 \end{cases} \Rightarrow x = c \begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix} = N(A)$$

Eliminations from U to R:

$$U = \begin{pmatrix} \boxed{1} & 2 & 3 \\ 0 & \boxed{2} & 2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \Rightarrow \begin{pmatrix} \boxed{1} & 0 & 1 \\ 0 & \boxed{2} & 2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \Rightarrow \begin{pmatrix} \boxed{1} & 0 & 1 \\ 0 & \boxed{1} & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = R$$

3 Solving Ax = b (L8)

Is there a solution? Is the solution unique?

$$\begin{cases} x_1 & +2x_2 & +2x_3 & +2x_4 & = b_1 \\ 2x_1 & +4x_2 & +6x_3 & +8x_4 & = b_2 \\ 3x_1 & +6x_2 & +8x_3 & +10x_4 & = b_3 \end{cases} \Rightarrow Ax = \begin{pmatrix} 1 & 2 & 2 & 2 \\ 2 & 4 & 6 & 8 \\ 3 & 6 & 8 & 10 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}$$

Run eliminations on an augmented matrix $(A \mid b)$ until the left side is in an echelon form:

$$\begin{pmatrix} \boxed{1} & 2 & 2 & 2 & b_1 \\ 2 & 4 & 6 & 8 & b_2 \\ 3 & 6 & 8 & 10 & b_3 \end{pmatrix} \Rightarrow \begin{pmatrix} \boxed{1} & 2 & 2 & 2 & b_1 \\ 0 & 0 & \boxed{2} & 4 & b_2 - 2b_1 \\ 0 & 0 & 2 & 4 & b_3 - 3b_1 \end{pmatrix} \Rightarrow \begin{pmatrix} \boxed{1} & 2 & 2 & 2 & b_1 \\ 0 & 0 & \boxed{2} & 4 & b_2 - 2b_1 \\ 0 & 0 & 0 & 0 & b_3 - b_2 - b_1 \end{pmatrix}$$

The third row shows the equations are solvable if $b_3 - b_2 - b_1 = 0$ e.g. $b = \begin{pmatrix} 1 \\ 5 \\ 6 \end{pmatrix}$

Solvability

Ax = b is solvable when b is in C(A). If a combination of A's rows give a zero row, some combination of b's entries must also give zero.

3.1 Complete Solution for Ax = b

Find the particular solution x_p by setting all free variables to 0s and solving Ax = b for pivot variables:

$$\begin{cases} x_1 + 2x_2 + 2x_3 + 2x_4 &= b_1 \\ +2x_3 + 4x_4 &= b_2 - 2b_1 \end{cases} b = \begin{pmatrix} 1 \\ 5 \\ 6 \end{pmatrix}$$
$$\begin{cases} x_2 = 0 \\ x_4 = 0 \end{cases} \Rightarrow \begin{cases} x_1 = -2 \\ x_3 = \frac{3}{2} \end{cases}$$
$$x_p = \begin{pmatrix} -2 \\ 0 \\ \frac{3}{2} \\ 0 \end{pmatrix}$$

Complete solution for Ax = b is a combination of x_p and the null space x_n :

$$Ax_p = b$$
 $Ax_n = 0$ \Rightarrow $A(x_p + x_n) = b$

$$x_{complete} = x_p + x_n = \begin{pmatrix} -2\\0\\\frac{3}{2}\\0 \end{pmatrix} + c_1 \begin{pmatrix} -2\\1\\0\\0 \end{pmatrix} + c_2 \begin{pmatrix} 2\\0\\-2\\1 \end{pmatrix}$$

3.2 Full Ranks

A is a $m\times n$ matrix with rank $r\Rightarrow r\leq m, r\leq n$

Full Column Rank: r = n < m

$$A = \begin{pmatrix} 1 & 3 \\ 2 & 1 \\ 6 & 1 \\ 5 & 1 \end{pmatrix} \Rightarrow R = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{pmatrix}$$

- Every column is a pivot column. No free columns.
- Null space N(A) contains only the zero vector.
- $Ax = b \ 0$ or 1 solutions, depending on b.
- If Ax = b has a solution, $x = x_p$ i.e. unique solution.

Full Row Rank: r = m < n

$$A = \begin{pmatrix} 1 & 2 & 6 & 5 \\ 3 & 1 & 1 & 1 \end{pmatrix} \Rightarrow R = \begin{pmatrix} 1 & 0 & - & - \\ 0 & 1 & - & - \end{pmatrix}$$

- m pivot columns, n-m free columns.
- Ax = b has ∞ solutions for any b.

Square Full Rank: r = m = n

$$A = \begin{pmatrix} 1 & 2 \\ 3 & 1 \end{pmatrix} \Rightarrow R = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

 \bullet R is an identity matrix.

• Ax = b has 1 solution for any given b.

r, m, n	Number of Solutions	R
r = n = m	1	(I)
r = n < m	0 or 1	$\begin{pmatrix} I \\ 0 \end{pmatrix}$
r = m < n	∞	(I F)
r < m, n	0 or ∞	$ \left(\begin{pmatrix} I & F \\ 0 & 0 \end{pmatrix} \right) $

4 Independence, Basis, Dimension (L9)

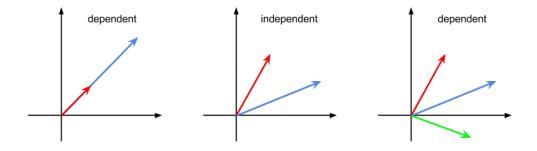
Suppose m < n for a $m \times n$ matrix A, there are non-zero solutions to Ax = 0. Why?

- More unknowns than equations.
- There will be free variables.

4.1 Independence

Vectors $x_1, x_2, ..., x_n$ are <u>independent</u> if no combination gives a zero vector except when all coefficients are zeros:

$$c_1x_1 + c_2x_2 + \dots + c_nx_n \neq 0$$
 if $c_i \neq 0$ for some i



Given A's columns consist of $x_1, x_2, ..., x_n$:

$$A = \begin{pmatrix} x_1 & x_2 & \dots & x_n \\ x_1 & x_2 & \dots & x_n \end{pmatrix}$$

If $x_1, x_2, ..., x_n$ are independent:

$$\begin{pmatrix} x_1 & x_2 & \dots & x_n \\ x_1 & x_2 & \dots & x_n \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad \text{only if} \quad \begin{cases} c_1 & = 0 \\ c_2 & = 0 \\ c_3 & = 0 \end{cases}$$

In other words, they are independent if N(A) contains only the zero vector i.e. rank(A) < n and there are no free variables. They're dependent if Ac = 0 for some non-zero c.

4.2 Span

Vectors $x_1, x_2, ..., x_n$ span a space when the space consists of all combinations of those vectors.

4.3 Basis

Vectors $x_1, x_2, ..., x_n$ are <u>basis</u> for a space when they are independent *and* span the space. Standard basis for space R^3 is:

$$\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \quad \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \quad \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

Another example of basis for space R^3 is:

$$\begin{pmatrix} 1\\1\\2 \end{pmatrix} \qquad \begin{pmatrix} 2\\2\\5 \end{pmatrix} \qquad \begin{pmatrix} 3\\8\\1 \end{pmatrix}$$

- Basis of \mathbb{R}^n : n vectors give basis of \mathbb{R}^n if $n \times n$ matrix with those columns is invertable.
- Given a space, every basis for the space has the same number of vectors. This number is the <u>dimension</u> of the space.

4.4 Example

$$A = \begin{pmatrix} 1 & 2 & 3 & 1 \\ 1 & 1 & 2 & 1 \\ 1 & 2 & 3 & 1 \end{pmatrix} \quad N(A) = \begin{pmatrix} -1 \\ -1 \\ 1 \\ 0 \end{pmatrix}$$

Given the space C(A): Column vectors of A span the space.

There are 2 pivot columns because only the first and second columns are independent. Therefore rank of A i.e. dimension of C(A) is 2.

One example of basis for C(A):

$$2\begin{pmatrix}1\\1\\1\end{pmatrix} \qquad \begin{pmatrix}1\\1\\1\end{pmatrix} + 2\begin{pmatrix}3\\2\\3\end{pmatrix} \quad \Rightarrow \quad \begin{pmatrix}2\\2\\2\end{pmatrix} \quad \begin{pmatrix}7\\5\\7\end{pmatrix}$$

They are independent, both in C(A). We need two vectors since the dimension is 2.

Now given the space N(A) instead, the dimension of N(A) i.e. number of free variables is 2.

One example of basis for
$$N(A)$$
: $\begin{pmatrix} -1 \\ -1 \\ 1 \\ 0 \end{pmatrix}$ $\begin{pmatrix} -1 \\ 0 \\ 0 \\ 1 \end{pmatrix}$

5 The Four Fundamental Subspaces (L10)

Given a $m \times n$ matrix A:

- Column space C(A) in R^m
- Null space N(A) in \mathbb{R}^n
- Row space = All combinations of A's rows i.e. A^T 's columns = $C(A^T)$ in R^n
- Null space of $A^T = N(A^T)$ in \mathbb{R}^m

	Space	Basis	Dimension
C(A)	R^m	pivot columns	rank(A) = r
$N(A^T)$	R^m		m-r
Row space	R^n		r
N(A)	R^n	special solutions	n-r

5.1 Row Space Example

$$A = \begin{pmatrix} 1 & 2 & 3 & 1 \\ 1 & 1 & 2 & 1 \\ 1 & 2 & 3 & 1 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & 2 & 3 & 1 \\ 0 & -1 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & 2 & 3 & 1 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \Rightarrow \begin{pmatrix} \boxed{1} & 0 & 1 & 1 \\ 0 & \boxed{1} & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} = R$$

- Different column spaces: $C(A) \neq C(R)$
- Same row spaces: R(A) = R(R)
- \bullet Basis for row space is the first r rows of R

5.2 Null Space of A^T

$$A^T y = 0 \quad \Rightarrow \quad y^T A^{TT} = y^T A = 0^T$$

$$rref((A_{m\times n} \mid I_{m\times m})) = E(A_{m\times n} \mid I_{m\times m}) = (R_{m\times n} \mid E_{m\times m})$$

e.g.
$$EA = \begin{pmatrix} -1 & 2 & 0 \\ 1 & -1 & 0 \\ \hline -1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 2 & 3 & 1 \\ 1 & 1 & 2 & 1 \\ 1 & 2 & 3 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & 0 \\ \hline 0 & 0 & 0 & 0 \end{pmatrix} = R$$

Third row of E is the combination of rows that gives zeros i.e. y^T