

CPSC 532W Assignment 4

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Here is the link to the repository:

https://github.com/aliseyfi75/Probabilistic-Programming/tree/master/Assignment_4

write a black-box variational inference (VI) evaluator following section 4.4 of the book.

1 Code

Show code snippets that demonstrate the completeness and correctness of your BBVI implementation.

1.1 primitives

```
1 baseprimitives = {
2     '+': lambda x: x[0] + x[1],
3     '-': lambda x: x[0] - x[1],
4     '*': lambda x: x[0] * x[1],
5     '/': lambda x: x[0] / x[1],
6     '>': lambda x: x[0] > x[1],
7     '>=': lambda x: x[0] >= x[1],
8     '<': lambda x: x[0] < x[1],
9     '<=': lambda x: x[0] <= x[1],
10    '==': lambda x: x[0] == x[1],
11    '!=': lambda x: torch.tensor([1]) if x[0] != x[1] else torch.tensor([0]),
12    'and': lambda x: x[0] and x[1],
13    'or': lambda x: x[0] or x[1],
14    'sqrt': lambda x: torch.sqrt(x[0]),
15    'exp': lambda x: torch.exp(x[0]),
16    'log': lambda x: torch.log(x[0]),
17    'abs': lambda x: torch.abs(x[0]),
18    'vector': vector,
19    'list': list,
20    'get': get,
21    'put': put,
22    'hash-map': hash_map,
23    'first': lambda x: x[0][0],
24    'last': lambda x: x[0][-1],
25    'nth': lambda x: x[0][int(x[1].item())],
26    'second': lambda x: x[0][1],
27    'rest': lambda x: x[0][1:],
28    'append': append,
29    'cons': lambda x: append([x[1], x[0]]),
30    'conj': append,
31    'mat-add': lambda x: x[0] + x[1],
32    'mat-mul': lambda x: torch.matmul(x[0], x[1]),
33    'mat-transpose': lambda x: x[0].T,
34    'mat-tanh': lambda x: x[0].tanh(),
35    'mat-repmat': lambda x: x[0].repeat((int(x[1].item()), int(x[2].item())))
36 }
```

Listing 1: primitives.py - Base primitives

```

1 def vector(x):
2     try:
3         vector = torch.stack(x)
4     except:
5         vector = x
6     return vector
7
8 def list(x):
9     try:
10        list = torch.stack(x)
11    except:
12        list = x
13    return list
14
15 def get(x):
16     if type(x[0]) == dict:
17         value = x[0][x[1].item()]
18     else:
19         value = x[0][x[1].long()]
20     return value
21
22 def put(x):
23     if type(x[0]) == dict:
24         x[0][x[1].item()] = x[2]
25     else:
26         x[0][x[1].long()] = x[2]
27     return x[0]
28
29 def hash_map(x):
30     keys = x[:, :2]
31     value = x[:, 2:]
32     new_keys = []
33     for key in keys:
34         try:
35             new_keys.append(key.item())
36         except:
37             new_keys.append(key)
38     result = dict(zip(new_keys, value))
39     return result
40
41 def append(x):
42     first = x[0]
43     second = x[1]
44
45     if first == 'vector':
46         first = torch.tensor([])
47     elif first.dim() == 0:
48         first = first.unsqueeze(0)
49     if second == 'vector':
50         second = torch.tensor([])
51     if second.dim() == 0:
52         second = second.unsqueeze(0)
53     return torch.cat((first, second))

```

Listing 2: primitives.py - Functions

```

1 import distributions as dist
2
3 class Dist:
4     def __init__(self, name, distribution, num_par, *par):
5         self.name = name
6         self.distribution = distribution
7         self.num_par = num_par
8         self.pars = []
9         for i in range(num_par):
10             self.pars.append(par[i])
11
12     def sample(self):
13         return self.distribution.sample()
14
15     def log_prob(self, c):
16         return self.distribution.log_prob(c)
17
18     def parameters(self):
19         return self.distribution.Parameters()
20
21     def make_copy_with_grads(self):
22         temp_dist = self.distribution
23         self.distribution = None
24         dist_copy = copy.deepcopy(self)
25         self.distribution = temp_dist
26         dist_copy.distribution = temp_dist.make_copy_with_grads()
27         return dist_copy
28
29 class normal(Dist):
30     def __init__(self, pars):
31         mean = pars[0]
32         var = pars[1]
33         normal_dist = dist.Normal(mean, var)
34         super().__init__('normal', normal_dist, 2, mean, var)
35
36 class beta(Dist):
37     def __init__(self, pars):
38         alpha = pars[0]
39         betta = pars[1]
40         super().__init__('beta', distributions.Beta(alpha, betta), 2, alpha, betta)
41
42 class exponential(Dist):
43     def __init__(self, par):
44         lamda = par[0]
45         super().__init__('exponential', distributions.Exponential(lamda), 1, lamda)
46
47 class uniform(Dist):
48     def __init__(self, pars):
49         a, b = pars[0], pars[1]
50         if a > b:
51             b = 5
52         uniform_dist = dist.Uniform(a, b)
53         super().__init__('uniform', uniform_dist, 2, a, b)
54
55 class discrete(Dist):
56     def __init__(self, pars):
57         prob = pars[0]
58         discrete_dist = dist.Categorical(prob)
59         super().__init__('discrete', discrete_dist, 0)
60
61 class bernoulli(Dist):
62     def __init__(self, pars):
63         p = pars[0]
64         bernoulli_dist = dist.Bernoulli(p)

```

```

65         super().__init__('bernoulli', bernoulli_dist, 1, p)
66
67 class gamma(Dist):
68     def __init__(self, pars):
69         alpha, betta = pars[0], pars[1]
70         gamma_dist = dist.Gamma(alpha, betta)
71         super().__init__('gamma', gamma_dist, 2, alpha, betta)
72
73 class dirichlet(Dist):
74     def __init__(self, pars):
75         dirichlet_dist = dist.Dirichlet(pars[0])
76         super().__init__('dirichlet', dirichlet_dist, len(pars), *pars)
77
78 class dirac(Dist):
79     def __init__(self, value):
80         mean = value[0]
81         mean = torch.clip(mean, -1e5, 1e5)
82         var = torch.tensor(1e-5)
83         super().__init__('normal', distributions.Normal(mean, var), 2, mean, var)

```

Listing 3: primitives.py - Distributions

```

1 distlist = {
2     'normal' : normal,
3     'beta' : beta,
4     'exponential' : exponential,
5     'uniform' : uniform,
6     'discrete' : discrete,
7     'bernoulli': bernoulli,
8     'gamma': gamma,
9     'dirichlet': dirichlet,
10    'flip': bernoulli,
11    'dirac': dirac,
12    'uniform-continuous': uniform
13 }

```

Listing 4: primitives.py - distlist

1.2 evaluation based sampling

This part is same as last assignment.

1.3 topological sort

This part is same as last assignment.

1.4 BBVI evaluator

```
1 def BBVI_evaluator(order_node, graph, sigma):
2     P = graph[1]['P']
3     Y = graph[1]['Y']
4     Q = sigma['Q']
5     G = sigma['G']
6     optimizer = sigma['optimizer']
7     results = {}
8
9     for node in order_node:
10         link_function = P[node][0]
11
12         if link_function == 'sample*':
13             d = deterministic_eval(value_subs(P[node][1], results))
14             if node not in Q:
15                 Q[node] = d.make_copy_with_grads()
16                 optimizer[node] = torch.optim.Adam(Q[node].parameters(), lr=0.01)
17             result = Q[node].sample()
18             G[node] = grad_log_prob(Q[node], result)
19             try:
20                 sigma_temp = d.log_prob(result) - Q[node].log_prob(result)
21                 sigma['logW'] += sigma_temp
22             except:
23                 sigma['logW'] += 0
24
25         elif link_function == 'observe*':
26             result = torch.tensor(Y[node])
27             d = deterministic_eval(value_subs(P[node][1], results))
28             sigma_temp = d.log_prob(result)
29             sigma['logW'] += sigma_temp
30
31         results[node] = result
32
33     return results, sigma
```

Listing 5: graph_based_sampling.py - BBVIEvaluator

1.5 grad log prob

```
1 def grad_log_prob(dist, value):
2     for param in dist.parameters():
3         param = param.clone().detach()
4         param.requires_grad = True
5     log_prob = dist.log_prob(value)
6     log_prob.backward()
7     grad = [param.grad for param in dist.parameters()]
8     return grad
```

Listing 6: graph_based_sampling.py - grad_log_prob

1.6 BBVI

```
1 def BBVI(graph, T, L):
2     sigma = {'Q': {}, 'optimizer': {}}
3     order_node = topological_sort(graph)
4
5     results = []
6     log_weights = []
7     posteriors = []
8
9     for t in range(T):
10         sigma['G'] = {}
11         gradients = []
12         log_ws = []
13
14         for l in range(L):
15             sigma['logW'] = 0
16             result, sigma = BBVI_evaluator(order_node, graph, sigma)
17             gradients.append(copy.deepcopy(sigma['G']))
18             log_ws.append(sigma['logW'])
19
20         if t==0:
21             posteriors.append(copy.deepcopy(sigma['Q']['sample2'].parameters()))
22
23         ELBO_gradients(gradients, log_ws, sigma['Q'])
24
25         for optimizer in sigma['optimizer'].values():
26             optimizer.step()
27             optimizer.zero_grad()
28
29         post_temp = {}
30         for q in sigma['Q']:
31             post_temp[q] = sigma['Q'][q].parameters().copy()
32
33         posteriors.append(post_temp)
34         result_temp = deterministic_eval(value_subs(graph[2], result))
35         results.append(result_temp)
36         log_weights.append(log_ws[-1])
37         wandb.log({'ELBO': torch.mean(torch.stack(log_weights)).detach().numpy()})
38
39     return results, log_weights, posteriors
```

Listing 7: graph_based_sampling.py - BBVI

1.7 infinity skipper

```
1 def inf_skipper(gradients, log_ws):
2     temp_gradients = []
3     temp_log_ws = []
4
5     for i in range(len(log_ws)):
6         if log_ws[i] == float('-inf'):
7             continue
8         temp_gradients.append(gradients[i])
9         temp_log_ws.append(log_ws[i])
10
11     return temp_gradients, temp_log_ws
```

Listing 8: graph_based_sampling.py - inf_skipper

1.8 ELBO gradient

```
1 def ELBO_gradients(gradients, log_ws, posteriors):
2
3     gradients, log_ws = inf_skipper(gradients, log_ws)
4     len_grads = len(gradients)
5
6     var_union = list(set([var for grad in gradients for var in grad]))
7
8     Fs = []
9     Gs = []
10    stack = {}
11
12    for var in var_union:
13        gradient_var = gradients[0][var]
14        if len(gradient_var[0].shape) > 0 and len(gradient_var[0]) > 1:
15            gradient_var = [grad.clone().detach().requires_grad_(True) for grad in
16            gradient_var[0]]
17            stack[var] = len(gradient_var)
18
19            len_vars = len(gradient_var)
20
21            G_var = torch.zeros((len_grads, len_vars))
22            F_var = torch.zeros((len_grads, len_vars))
23
24            for lg in range(len_grads):
25                G_var[lg, :] = torch.stack(gradients[lg][var])
26                F_var[lg, :] = G_var[lg, :] * log_ws[lg]
27            Gs.append(G_var.detach().numpy())
28            Fs.append(F_var.detach().numpy())
29
30    Gs = np.column_stack(Gs)
31    Fs = np.column_stack(Fs)
32
33    num = np.sum([np.cov(Fs[:, v], Gs[:, v])[0, 1] for v in range(Gs.shape[1])])
34    denum = np.sum([np.var(Gs[:, v]) for v in range(Gs.shape[1])])
35    b_hat = 0.
36    if not denum == 0. and not np.isnan(num):
37        b_hat = num/denum
38
39    counter_1 = 0
40    for var in var_union:
41        gradient_var = gradients[0][var]
42        counter_2 = len(gradient_var)
43        if var in stack:
44            counter_2 = stack[var]
45        g_hat = np.array([np.sum(Fs[:, v] - b_hat * Gs[:, v]) / len_grads for v in range(
46        counter_1, counter_1+counter_2)])
47        if var in stack:
48            g_hat = [g_hat]
49        for i, parameter in enumerate(posteriors[var].parameters()):
50            parameter.grad = torch.tensor(-g_hat[i], dtype=parameter.grad.dtype)
51        counter_1 += counter_2
52    return
```

Listing 9: graph_based_sampling.py - ELBO_gradient

2 Results

2.1 Task 1

$T = 10^4$ and $L = 50$ for this task.

Time of drawing samples: **410.81 seconds**

Posterior expected value of μ is: **7.3007**

Parameters of the posterior distribution of μ : $\mu = 7.2742$ and $\sigma = 0.4931$.

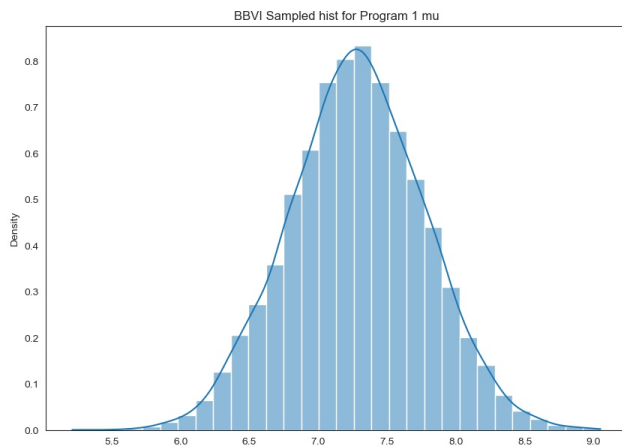


Figure 1: Histogram of posterior distribution of μ

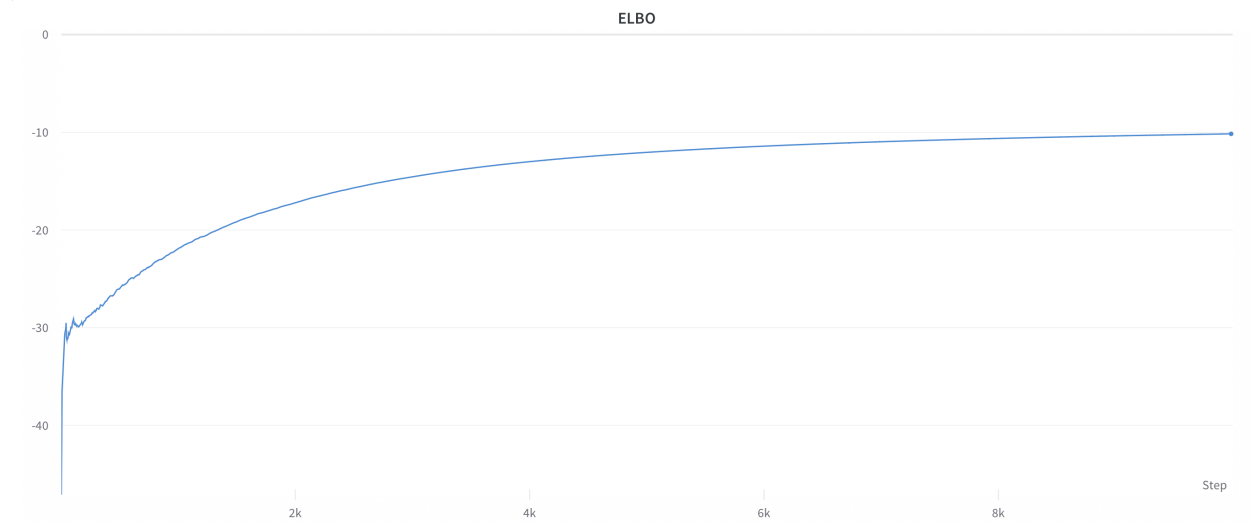


Figure 2: ELBO in task 1

2.2 Task 2

$T = 5 * 10^3$ and $L = 50$ for this task.

Time of drawing samples: **510.36 seconds**

Posterior mean of slope is: **2.1169**

Posterior mean of bias is: **-0.4039**

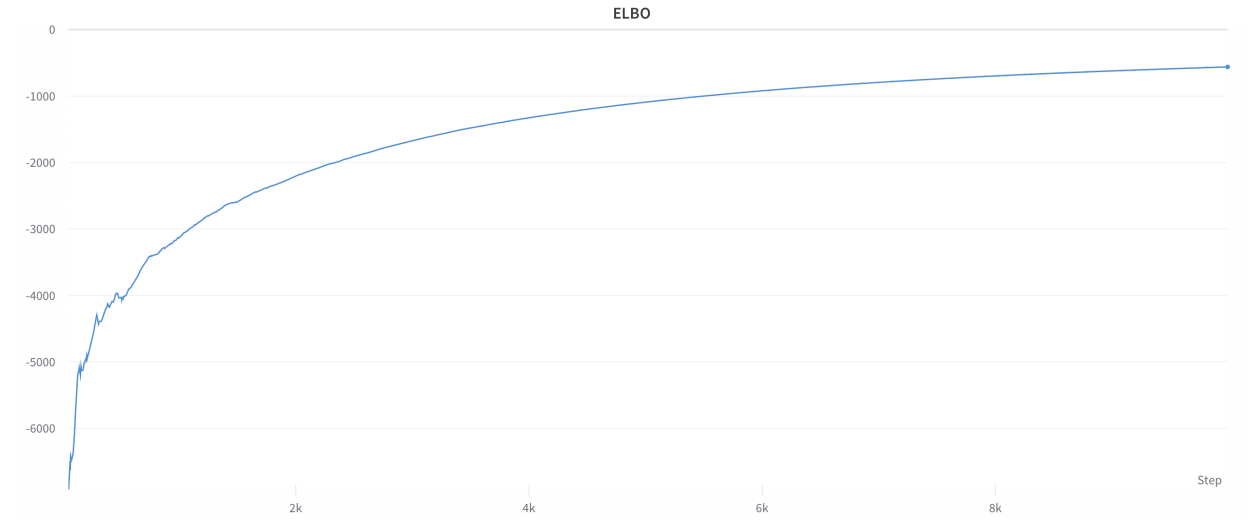


Figure 3: ELBO in task 2

2.3 Task 3

$T = 2 * 10^3$ and $L = 50$ for this task.

Time of drawing samples: **581.53 seconds**

Posterior mean of probability that the first and second datapoint are in the same cluster is: **0.7743**

Should talk about the mode-seeking behaviour of VI

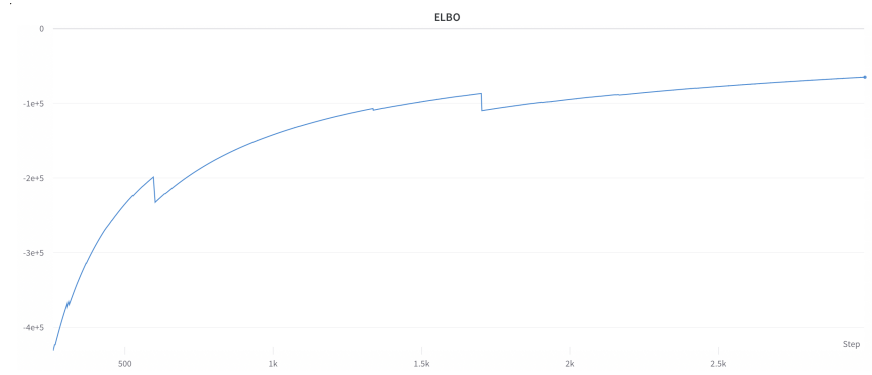


Figure 4: ELBO in task 3

2.4 Task 4

Time of drawing samples: **595.87 seconds**

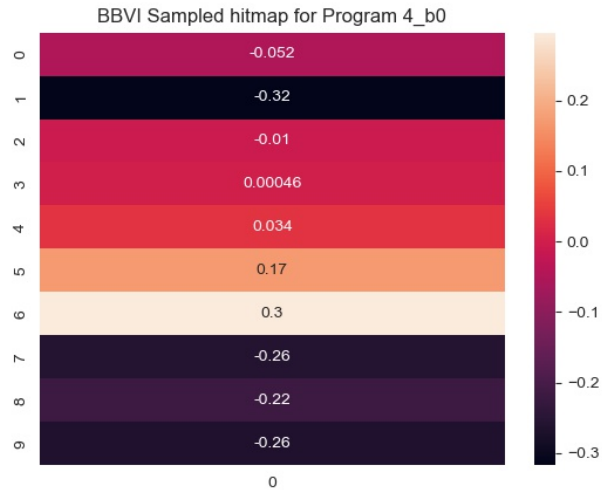


Figure 5: Posterior distribution of b_0

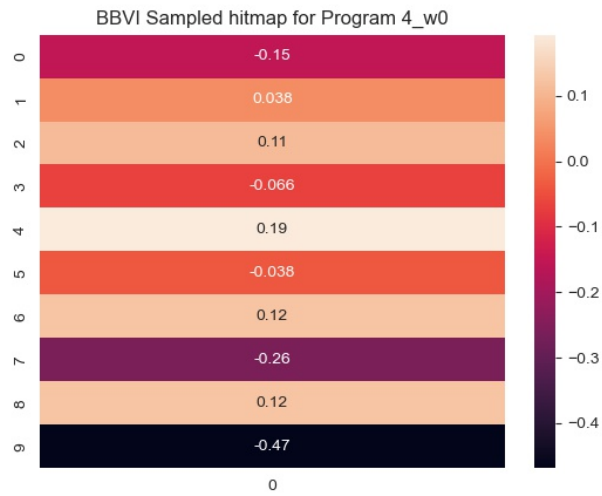


Figure 6: Posterior distribution of w_0

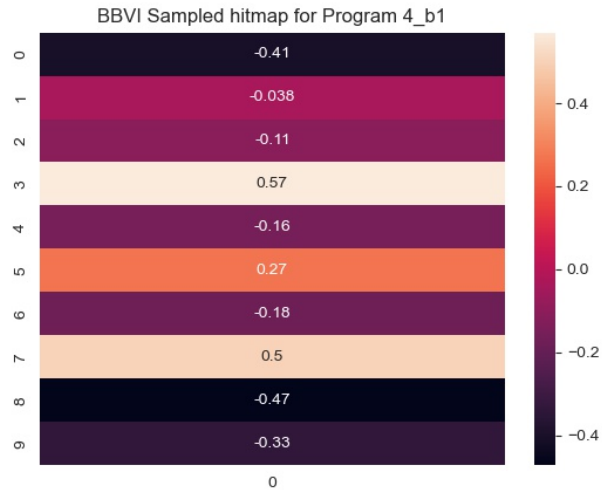


Figure 7: Posterior distribution of b_1

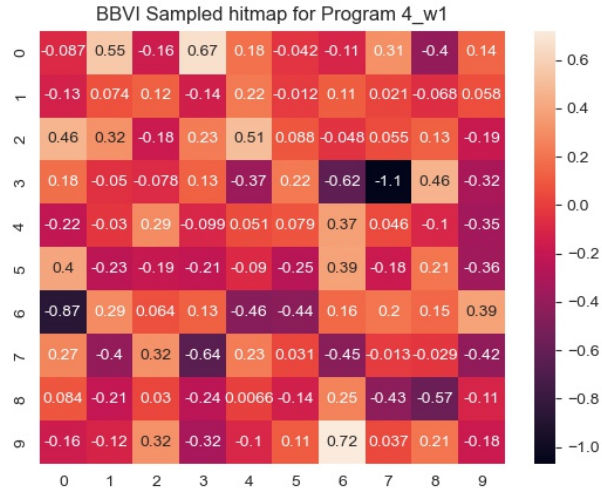


Figure 8: Posterior distribution of w_1

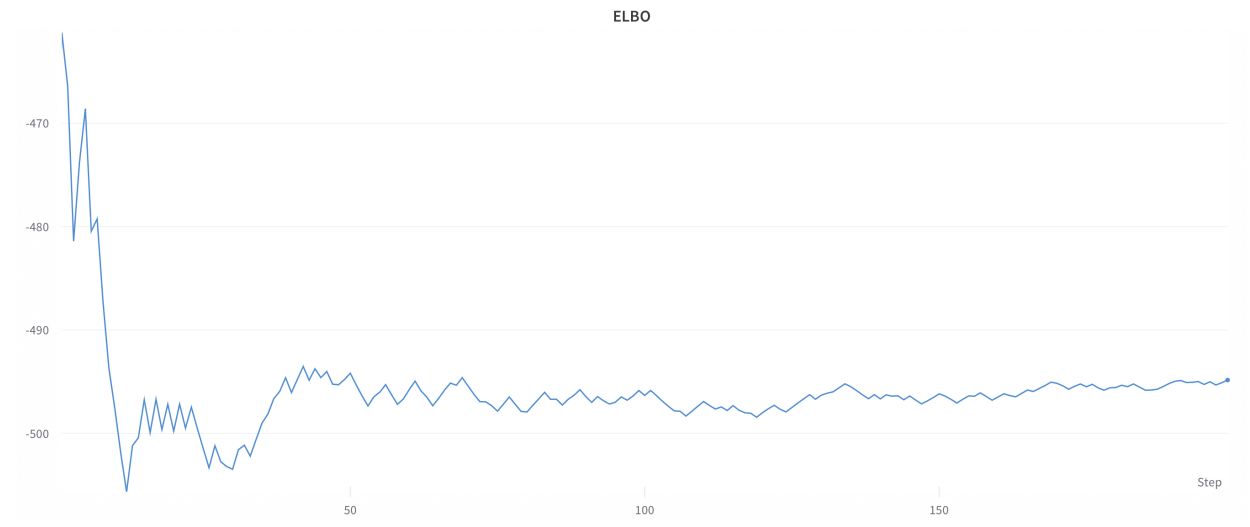


Figure 9: ELBO in task 4

should compare and contrast mean-field BBVI to parameter estimation via gradient descent.

2.5 Task 5

$T = 2 * 10^3$ and $L = 25$ for this task.

Time of drawing samples: **45.19 seconds**

learned variational distribution for s: **Uniform(0.9024, 1.7703)**

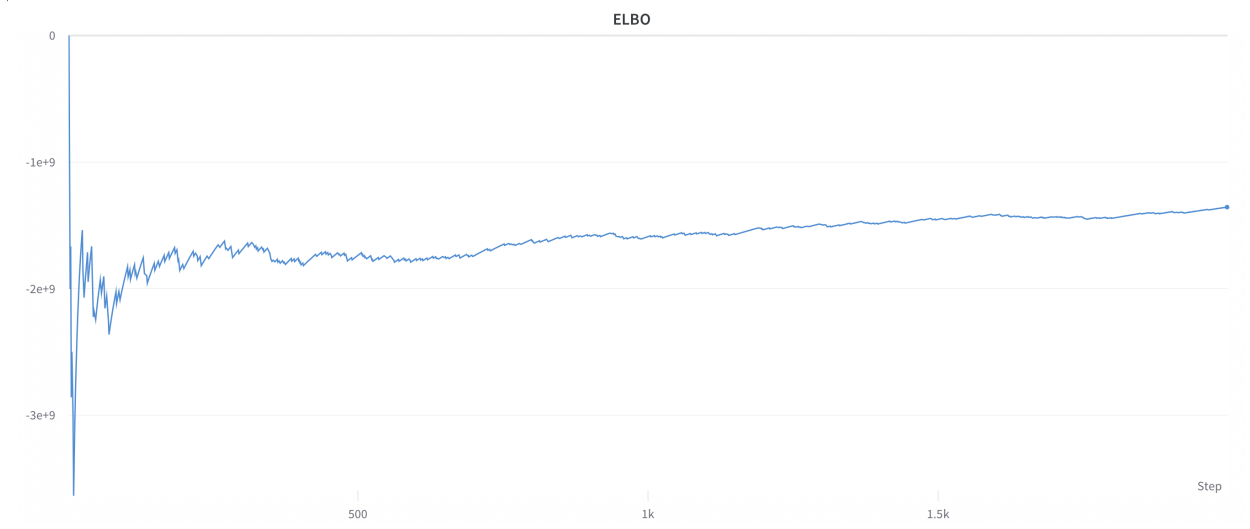


Figure 10: ELBO in task 5