

Feel free to work with other students, but make sure you write up the homework and code on your own (no copying homework *or* code; no pair programming). Feel free to ask students or instructors for help debugging code or whatever else, though. The starter code for problem 2 part c and d can be found under the Resource tab on course website.

*Note:* You need to create a Github account for submission of the coding part of the homework. Please create a repository on Github to hold all your code and include your Github account username as part of the answer to problem 2.

**1 (Linear Transformation)** Let  $\mathbf{y} = A\mathbf{x} + \mathbf{b}$  be a random vector. show that expectation is linear:

$$a) \mathbb{E}[\mathbf{y}] = \mathbb{E}[A\mathbf{x} + \mathbf{b}] = A\mathbb{E}[\mathbf{x}] + \mathbf{b}.$$

Also show that

$$b) \text{cov}[\mathbf{y}] = \text{cov}[A\mathbf{x} + \mathbf{b}] = A\text{cov}[\mathbf{x}]A^T = A\Sigma A^T.$$

a) By definition:

$$\mathbb{E}[\vec{y}] = \int_S (A\vec{x} + \vec{b}) P(x) dx$$

Distribute & pull out constants:

$$\mathbb{E}[\vec{y}] = A \int_S \vec{x} P(x) dx + \vec{b} \int_S P(x) dx$$

Notice that  
this is the  
definition for  
 $\mathbb{E}[\vec{x}]$

Thus:

$$\mathbb{E}[\vec{y}] = A \mathbb{E}[\vec{x}] + \vec{b} \quad \blacksquare$$

b) By definition:

$$\text{cov}[\vec{y}] = E[(\vec{y} - E[\vec{y}])(\vec{y} - E[\vec{y}])^T] = \vec{\Sigma}$$

Plug in for  $\vec{y}$ :

$$\text{cov}[\vec{y}] = E[(A\vec{x} + \vec{b} - E[A\vec{x} + \vec{b}])(A\vec{x} + \vec{b} - E[A\vec{x} + \vec{b}])^T]$$

Distribute & pull out constants as we did in part (a):

$$\text{cov}[\vec{y}] = E[(A\vec{x} + \cancel{\vec{b}} - AE[\vec{x}] - \cancel{\vec{b}})(A\vec{x} + \cancel{\vec{b}} - AE[\vec{x}] - \cancel{\vec{b}})^T]$$

Pull out A's:

$$\text{cov}[\vec{y}] = E[A(\underbrace{\vec{x} - E[\vec{x}]}_{\text{definition of cov}[\vec{x}]})A^T(\underbrace{\vec{x} - E[\vec{x}]}_{\text{definition of cov}[\vec{x}]})^T]$$

$$\text{cov}[\vec{y}] = A \text{cov}[\vec{x}] A^T$$

$$\text{cov}[\vec{y}] = A \vec{\Sigma} A^T$$

□

2 Given the dataset  $\mathcal{D} = \{(x, y)\} = \{(0, 1), (2, 3), (3, 6), (4, 8)\}$

- Find the least squares estimate  $y = \theta^\top x$  by hand using Cramer's Rule.
- Use the normal equations to find the same solution and verify it is the same as part (a).
- Plot the data and the optimal linear fit you found.
- Find randomly generate 100 points near the line with white Gaussian noise and then compute the least squares estimate (using a computer). Verify that this new line is close to the original and plot the new dataset, the old line, and the new line.

$$a) X = \begin{bmatrix} 1 & 0 \\ 1 & 2 \\ 1 & 3 \\ 1 & 4 \end{bmatrix} \quad \vec{y} = \begin{bmatrix} 1 \\ 3 \\ 6 \\ 8 \end{bmatrix}$$

$$y = \theta_0 + \theta_1 x \quad \text{where}$$

$$\theta_0^* = \frac{\begin{vmatrix} x^T \vec{y} & x^T X[2] \end{vmatrix}}{\begin{vmatrix} x^T X \end{vmatrix}} = \frac{\begin{vmatrix} 18 & 9 \\ 56 & 29 \end{vmatrix}}{\begin{vmatrix} 4 & 9 \\ 9 & 29 \end{vmatrix}} = \frac{18}{35}$$

$$\theta_1^* = \frac{\begin{vmatrix} X^T X[1] & x^T \vec{y} \end{vmatrix}}{\begin{vmatrix} X^T X \end{vmatrix}} = \frac{\begin{vmatrix} 4 & 18 \\ 9 & 56 \end{vmatrix}}{\begin{vmatrix} 4 & 9 \\ 9 & 29 \end{vmatrix}} = \frac{62}{35}$$

$$b) \theta^* = (X^T X)^{-1} X^T \vec{y}$$

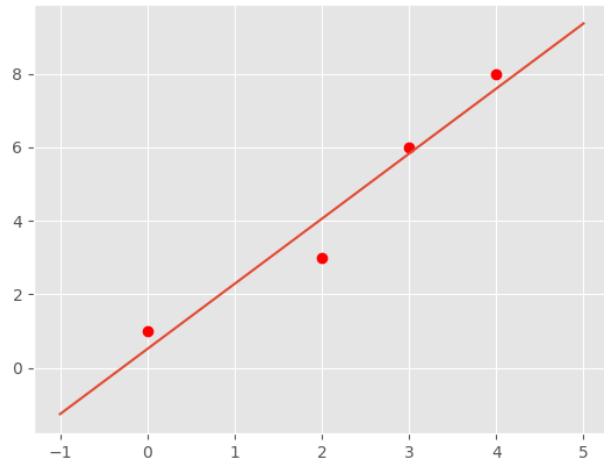
$$= \begin{bmatrix} 4 & 9 \\ 9 & 29 \end{bmatrix}^{-1} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 2 & 3 & 4 \end{bmatrix} \begin{bmatrix} 1 \\ 3 \\ 6 \\ 8 \end{bmatrix}$$

$$= \frac{1}{35} \begin{bmatrix} 29 & -9 \\ -9 & 4 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 2 & 3 & 4 \end{bmatrix} \begin{bmatrix} 1 \\ 3 \\ 6 \\ 8 \end{bmatrix}$$

$$= \frac{1}{35} \begin{bmatrix} 18 \\ 62 \end{bmatrix}$$

$$= \begin{bmatrix} \frac{18}{35} \\ \frac{62}{35} \end{bmatrix} \rightarrow \text{same as (a)} \quad 2$$

c)



d)

