

# Popular CNNs and Novel Concepts

**AlexNet (2012) and VGG (2014):**

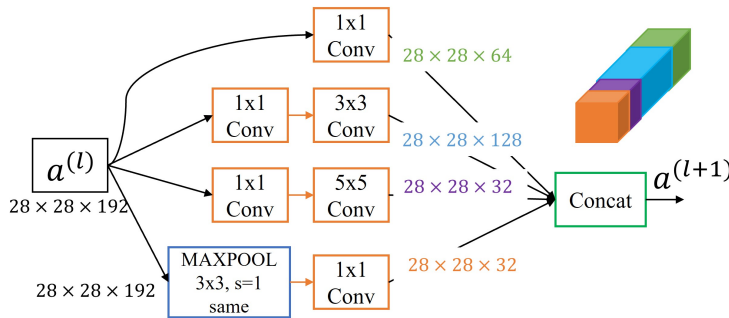
**AlexNet** has 8 layers with 60M parameters. Alexnet has used ReLU activations and **local response normalization** technique. **VGG-16** is designed to use the **deeper network** with 16 layers and 138M parameters.

**Inception-v1 (2014):**

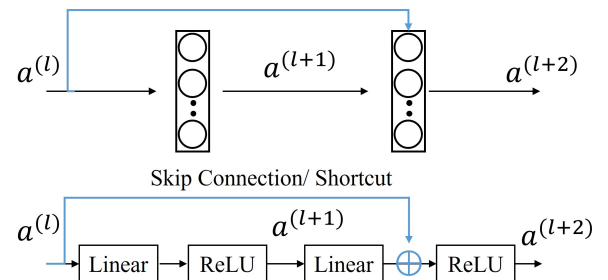
**Inception-v1** has introduced  **$1 \times 1$  convolutional layer** to decrease the depth size of the feature map which significantly reduces the computational time. **Auxiliary classifiers** are also used to increase the gradient signal in the backpropagation stage. **Inception modules**, having  $1 \times 1$ ,  $3 \times 3$ , and  $5 \times 5$  parallel filters, are used to learn global and area specific features from the input.

**ResNet (2015):**

**ResNet** has introduced the concept of **skip connections** in order to address the issue of vanishing gradient in deep neural networks. It also uses **batch normalization** to solve the internal covariate shift problem.



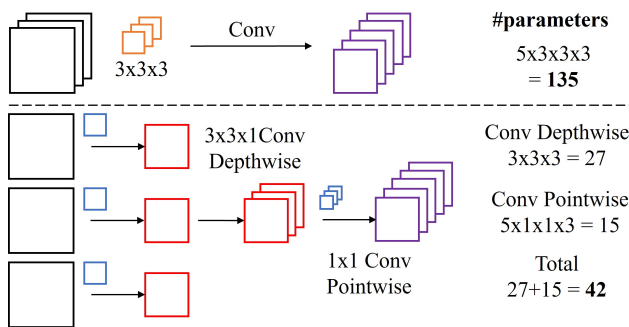
(a) Inception module



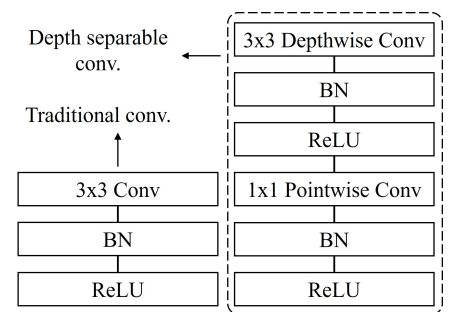
(b) ResNet residual module

**MobileNet(2017):**

**MobileNet** has utilized the concept of **depthwise separable convolution** (depthwise convolution +  $1 \times 1$  pointwise convolution) to replace the traditional convolution technique. It greatly reduces network parameters and makes MobilenNet, a lightweight and efficient network.



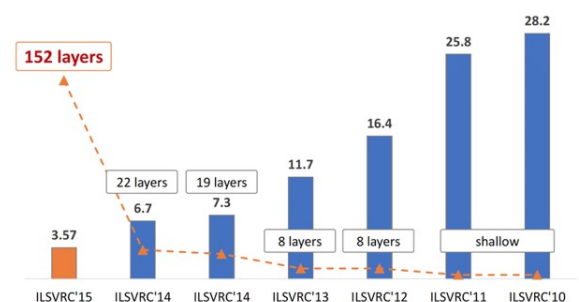
(a) Traditional and depth separable convolution parameters



(b) Difference in convolutions

**Summary:**

CNN Architecture	#Layers	#Weights	Activation Function	New Concepts
AlexNet	8	60M	ReLU	Local Response Normalization
VGG-16	16	138M	ReLU	Deep network
Inception-v1	22	7M	ReLU	Inception Modules and auxiliary classifiers
ResNet-50	50	26M	ReLU	Residual Blocks and Batch Normalization
MobileNet-v1	28	4.2M	ReLU	Depth wise separable Convolution



(a) Image source