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A Review of Ensemble Learning Based Feature Selection

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A Review of Ensemble Learning Based Feature Selection

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ABSTRACT

Feature selection is an important topic in machine learning. In recent years, via integrating ensemble learning, the ensemble learning based feature selection approach has been proposed and studied. The general idea is to generate multiple diverse feature selectors and combine their outputs. This approach is superior to conventional feature selection methods in many aspects. Among them, its most prominent advantage is the ability to handle stability issue that is usually poor in existing feature selection methods. This review covers different issues related to ensemble learning based feature selection, which include the main modules, the stability measurement, etc. To the best of our knowledge, this is the first review that focuses on ensemble feature selection. It can be a useful reference in the literature of feature selection.

Keywords:

Feature selection, Ensemble learning, Stability.

1. INTRODUCTION

Machine learning techniques are widely used to analyse different types of data [1–5]. However, with the proliferation of large-scale data-sets, many machine learning techniques suffer from intractability problems. Although diverse factors cause intractability, the number of attributes, or dimensionality, is one of the major factors. Data dimensionality affects both the training and run-time phases of a learning system. Meanwhile, high dimensionality may cause dimensionality problems.

Feature selection is the technique to solve the dimensionality problem [6-13]. It retains only useful features via removing irrelevant and redundant features. It produces multiple benefits including improving classification performance, speeding up the data mining algorithm, and good insight of the problem through interpretation of the most relevant features.

The various feature selection algorithms differ mainly from two aspects: searching strategy and evaluation criterion. Based on these aspects, they can be divided into three categories: filter, wrapper, and embedded models. Although with diversity, in most existing feature selection methods, usually only a single feature selection process is involved.

In recent years, a new type of feature selection, called ensemble learning based feature selection, has been proposed and studied [14–35]. This approach

integrates feature selection and ensemble learning. As shown in Figure 1, to integrate feature selection and ensemble learning, there exist two ways. One is to use ensemble learning for feature selection (FS_{en}). The other one is to utilize feature selection for ensemble learning (EN_{fs}) [36–38]. These two approaches look similar, but their goals are completely different. EN_{fs} is to use different feature subsets to construct an ensemble of diverse-based classifiers. The main research issue is to incorporate diversity into the objective function that supervises the search for the best features. But FS_{en} is designed to generate a good feature subset by combining multiple feature subsets based on the idea of ensemble learning.

This review focuses on the left branch of Figure 1, FS_{en}. The idea of FS_{en} is inspired due to the good performance of ensemble learning for supervised learning. In supervised learning, ensemble learning will generate multiple classifiers and then aggregate their classification results. It shows that this aggregated result is usually more accurate than the results from each individual classifier.

Similarly, the general idea of $FS_{\rm en}$ is to repeat the feature selection process for several times to generate diverse feature selectors, and aggregate their outputs. $FS_{\rm en}$ is expected to utilize the idea of ensemble learning to overcome the potential local optima problem of conventional single learning based feature selection. Various studies have proved that via integrating ensemble learning, $FS_{\rm en}$ is superior to conventional feature

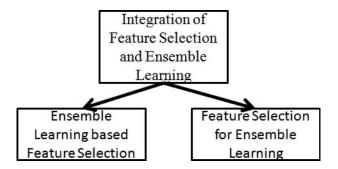


Figure 1: Two ways to integrate feature selection with ensemble learning.

selection from many aspects. Especially, it can improve the "stability" of feature selection, which usually cannot be satisfied by conventional feature selection.

This paper reviews the existing FS_{en} methods from different aspects, including the ways to generate diverse feature selectors, the ways to aggregate these selectors, and the ways to define the stability measurement.

Note that the reviews of feature selection already exist (e.g. [39–42]). This work differs from the existing review papers in the following aspects:

- 1. Existing reviews are aimed to cover all the different algorithms in feature selection. But because the idea of ensemble learning based feature selection is mainly studied in recent years, they are not covered by the most existing reviews.
- To the best of our knowledge, this is the first review of ensemble learning based feature selection approaches.

The remaining of this paper is organized as follows. Section 2 introduces the concept and motivation of ensemble learning based feature selection. Subsequently, the various methods are presented in Section 3. In Section 4, we discuss some other topics that are related to FS_{en}. We finally conclude this review in Section 5.

2. ENSEMBLE LEARNING BASED FEATURE SELECTION

Feature selection chooses a subset of features among original feature spaces according to strategies that remove unrelated and redundant features. When fewer dimensions are obtained, the exploration of results is facilitated. Therefore, feature selection is widely used in many different data analysis tasks.

There are three kinds of feature selection methods: wrapper, filter, and embedded methods. Wrappers [43] choose features with high classification

accuracies, as estimated by specified learning algorithms. Unlike wrappers, filters [44] evaluate the goodness of the proposed feature subset looking only at the intrinsic characteristics of the data, based on the relation of each single feature with the class label by the calculation of simple statistics computed from the empirical distribution. By taking classification accuracy into account, wrappers usually achieve better results than filters. Meanwhile, wrapper methods require more searching time, and are inefficient for large-scale problems. Finally, embedded methods [45] use internal information of the classification model to perform feature selection. Thus, they often provide a good trade-off between performance and computational cost.

The functions and usages of feature selection are diverse [46–47]. Because it is generally used as a preprocessing step for classification, classification accuracy is usually treated as the main goal of feature selection. For example, wrapper methods directly use classification accuracy to evaluate the goodness of features.

In addition to high accuracy, in recent years, the stability of feature selection has been recognized as another important issue [14–18, 20, 23, 27–28]. Stability is the measure to reflect the insensitivity of the feature selection algorithm to the variations of the training set. This issue is particularly important when using feature selection for knowledge discovery. Let us take the example of microarray analysis, wherein there are a big number of features. Feature selection is used to retain only important features and remove others. Finally, these selected features will be used by the biologists to explain the behaviours of microarray samples. Suppose we conduct feature selection for several times, if the training data are with variations, then the feature selection results with each time are also different. In terms of classification performance, all of the different feature subsets might be good. But such instability will result in the confidence drops to the domain experts. It is therefore necessary that the selected features are common to variations of training samples. Moreover, it also shows that usually the good stability can lead to the good classification/generalization accuracy.

 FS_{en} is mainly proposed to improve the stability of feature selection. The role of ensemble learning in FS_{en} is similar with that for supervised learning [48]. For supervised learning, multiple predictors are generated and their predictions are fused to make the final decision. In FS_{en} , based on the training data, feature selection processes will run for several times to generate several diverse feature selectors. Later, these diverse feature selectors are aggregated into the final feature subset. It has been proved that FS_{en} is extremely

important for the small sample size domains. For such domains, stability is more serious as usually several different feature subsets may yield equally optimal results, and ensemble feature selection may reduce the risk of choosing an unstable subset.

Furthermore, feature selection can be regarded as a searching process of the best features from the complete searching space. A single feature selection algorithm tends to select the local optima, while the ensemble feature selection has more chance to find the better features through aggregation of multiple feature selection processes. Finally, compared to single feature selection, the searching space of ensemble feature selection is enlarged so that the representation ability is also improved.

COMPONENTS IN ENSEMBLE LEARNING BASED FEATURE SELECTION

There are two essential steps in creating a feature selection ensemble. The first step is to generate a set of diverse feature selectors. Then, the second step is to aggregate the results of these feature selectors.

In this section, the two steps in Figure 2 will be introduced in detail. Moreover, as the main goal of ensemble feature selection is to improve the stability of feature selection, different stability measures will be discussed in this section. In essence, the two steps in Figure 2 and the stability measurements are dependent on each other. For example, the aggregation function can influence the stability of feature selection. Meanwhile, the stability measure can also limit the choices of aggregation functions.

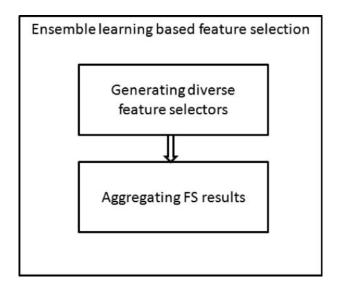


Figure 2: Components in ensemble learning based feature selection.

Table 1: The general scheme of ensemble feature selection based on data variation

```
Input: E (training set), A (feature selection algorithm)
Parameters: n (number of feature selectors)
Output: F2S (features to select)
(1) Form n different training sets (E_1, E_2, ..., E_n) based on E
(2) For i = 1, ..., n do
(3) FS_i = A(E_i)
(4) End for
(5) F2S = Aggregation (FS_1, FS_2, ..., FS_n)
```

3.1 Generating Diverse Feature Selectors

Assume that n feature selectors are used in FS_{en}. Each feature selector $fs^i = FS Function^i(Training Data^i)$. Here FSFunction¹ and TrainingData¹ are the feature selection function and training data used for the ith feature selector.

In ensemble learning based feature selection, it is important to have enough diversity among different feature selectors. This is because if the feature selectors are very similar or identical, their combination will be similar to each feature selector and nothing can be achieved through their combination. As shown in the above equation, to make fs¹ different, there are three approaches: making FS function different, making training data different, or making both of them different. Accordingly, these three methods are called data variation, function variation, and hybrid variation, respectively.

3.1.1 Data Variation Methods

The general scheme of data variation based FS_{en} is shown in Table 1.

The works in this category differ in the way to form different training sets (step (1) of Table 1). In the literature of ensemble learning, the popular methods include using different sample subsets (e.g. bagging [49], boosting [50]) or different feature subspaces (e.g. random subspace [51]). In the literature of FS_{en}, bagging is mainly used. Its algorithm is shown in Table 2.

```
Table 2: The bagging algorithm
Input: E (training set)
Parameters: n (number of feature selectors), m (number of training instances)
Output: The generated training subsets (E_1, E_2, ..., E_n)
(1) Set E_1 = E_2 = ... E_n = \emptyset
(2) For i = 1, ..., n do
(3) For j = 1, ..., m
(4)Index = m^* rand()
(5) E_i = E_i \cup E^{index}
(6) End for
(7) End for
```

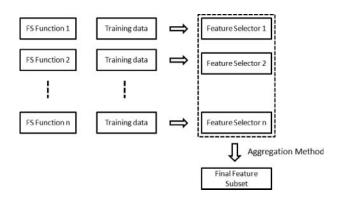


Figure 3: Function aggregation methods.

3.1.2 Function Variation Methods

For function variation methods, as shown in Figure 3, the training data are identical for each feature selector. The diversity of feature selectors is due to the diversity of feature selection functions.

Table 3 shows that for function variation methods, usually filters are employed. Recall that in addition to filter, wrapper is the other popular feature selection approach. Compared to filters, wrappers need much more computational costs. In function variation, as the feature selection process will run for several times. Therefore, filter is more suitable than wrapper.

The filter methods for function variation mainly include document frequency thresholding, chi-squared, information gain, ReliefF, mutual information, Kolmogorov–Smirnov statistic, deviance, geometric mean, area under the receiver operator characteristic (ROC) curve, area under the precision recall curve, signal to-noise (S2N), etc.

3.1.3 Hybrid Variation Methods

Hybrid variation methods believe that the diversity of individual data variation or function variation is not enough. Therefore, they combine these two variation methods. The recent studies of hybrid variation are shown in Table 4.

Dittman et al. [27] shows that the similarity between function variation and hybrid variation is much higher than their similarity between data diversity. In addition to have the highest similarity, function and hybrid variation methods show greater classification performance than data variation.

Because the size of training data is small, function and hybrid variation show outstanding performances. With small size, the diversity via data manipulation is very limited. Subsequently, the performance of data diversity is not satisfied. On the other hand, due to the relative large number of features, the function and hybrid variation can make more diversity for each feature selectors. This suggests that the size of training data is an important factor to choose the suitable method to generate multiple feature selectors.

3.2 Aggregation Functions

Considering there are n feature selectors in the FS_{en}. FS_{en} = {FS₁, FS₂, ..., FS_n}. According to the outcome in FS_i, feature selection algorithms can be divided into the following types:

- 1. Feature weighting algorithms. Each FS_i provides the weight for each feature. Therefore, each feature selection result, FS_i (i = 1, 2, ..., n), is a feature weighting vector. For feature weighting algorithms, the most common method is average the weights of each feature selector for a certain feature. Let FS_i represent the weight values of *j*th feature assigned by the *i*th feature selector. Then, the aggregated weight of *j*th feature is FS^j = $\frac{1}{n}\sum_{i=1:n}$ FS^j_i.
- 2. Feature ranking algorithms. Each FS_i provides the rank for the features. Therefore, each feature

Table 3: The representative works that use function variation methods

Reference	Function variation	Domain	Aggregation method
Olsson et al. [35]	3 filter-based methods	Text data	Highest rank, Lowest rank, Average rank
Wang et al. [33]	18 filter-based methods	Software data-sets	Arithmetic mean
Wang et al. [52]	6 filter-based methods	Software data-sets	Arithmetic mean
Dittman et al. [27]	10 filter-based methods	Bioinformatics	Arithmetic mean

Table 4: The representative works that use hybrid variation methods

Reference	Function variation	Data variation	Aggregation method
Awada et al. [30]	10 filter-based methods	Bagging	Arithmetic mean
Dittman et al. [27]	10 filter-based methods	Bagging	Arithmetic mean

selection result, FS_i (i = 1, 2, ..., n) is a feature ranking vector. For feature ranking algorithms, the most common method is average the ranks of each feature selector for a certain feature. Let FS_i^j represent the rank values of *j*th feature assigned by the *i*th feature selector. Then, the aggregated rank of *j*th feature is FS^j = $\frac{1}{n}\sum_{i=1:n}$ FS^j_i. Finally, the features can be ranked based on the aggregate value of each feature.

3. Feature subset selection algorithms. Each FS_i (i = 1, 2, ..., n) can be regarded as a vector of boolean values. If the jth feature is selected by FS_i , then the value of FS_i^j equals to 1. Otherwise, this value equals to 0. The aggregated weight of jth feature can still use the average aggregation method. Finally, the features can be ranked based on the aggregate weight of each feature.

In essence, the methods mentioned here can be generalized to the linear aggregation. In linear aggregation, the final rank of feature j is $FS^j = \sum_{i=1:n} w(FS^j_i)$. Here $w(\cdot)$ denotes a weighting function. If a linear aggregation is performed using $w(FS^j_i) = \frac{FS^j_i}{n}$, this means the arithmetic average of each ranking. By modifying $w(FS^j_i)$, more complex aggregation methods can be proposed. For example, we can use a function such that more weight can be assigned to the feature selectors which have more reliability.

In addition to linear aggregation, other aggregation methods also can be used. Most of these methods are heuristic and show good performance in some applications. For example, in [35], the highest rank combination has been proposed for the feature ranking algorithm. In the highest rank combination, each feature's combined score is the highest rank achieved in any of the lists. This approach is suitable if different feature selectors place different sets of informative features near the top of their lists. This method can discount the negative information provided by the input. Similarly, the lowest and average rank can also be used [35].

3.3 Stability Measurements

Stability is the major goal of ensemble learning based feature selection. To evaluate it, subsampling-based methods have been proposed. The key idea of these methods is to see how the feature selection results will change due to the variation of training data. Suppose the training data-set $E = \{e_1, \ldots, e_m\}$ consists of m instances and N features. Then, a partial subset can be randomly drawn from data-set E. We define x as the ratio of data to choose from E. The subsampling process will be repeated for k times and thus k data-sets

will be generated. Subsequently, feature selection is performed on each of the k data-sets, and a measure of stability is calculated. The calculation of stability is measured by comparing the outputs of the k feature selectors. The highest stability is achieved if the k feature selection results are completely identical. The total stability is the average over all pairwise similarity comparisons between the different feature selectors:

$$S_{\text{tot}} = \frac{2\sum_{i=1}^{k} \sum_{j=i+1}^{k} S(FS_i, FS_j)}{k(k-1)}$$

where FS_i represents the feature selection result based on subsample i (1 $\leq i \leq k$), and $S(FS_i, FS_i)$ represents a similarity measure between FS_i and FS_j. Obviously, the total similarity depends on how to define the similarity measure. In the literature, the similarity measure is defined according to the outcomes of FS that include feature weighting, feature ranking, and feature subset selection. Note that the similarity measure can only be applied to two feature selection results with the same type. Let us define the number of features as N. Then, FS_i is a vector whose length is N. FS_i denotes (1) the weight of *j*th feature for feature weighting, (2) the rank of jth feature for feature ranking (1 for the worst rank and *N* for the best rank), and (3) 1 if the *j*th feature is selected (0 otherwise) for feature subset selection. The widely used definition of similarity measure is presented as follows:.

1. Feature weighting algorithms. Pearson correlation coefficient can be used as

$$S(FS_i, FS_j) = \frac{\sum_{l} (FS_i^l - \mu_{f_i}) (FS_j^l - \mu_{f_j})}{\sqrt{\sum_{l} (FS_i^l - \mu_{f_i})^2 \sum_{l} (FS_j^l - \mu_{f_j})^2}}$$

2. Feature ranking algorithms. The Spearman rank correlation coefficient can be used as

$$S(FS_i, FS_j) = 1 - 6\sum_{l} \frac{(FS_i^l - FS_j^l)^2}{N(N^2 - 1)}$$

3. Feature subset selection algorithms. The Jaccard index can be used as

$$S(FS_i, FS_j) = \frac{|FS_i \cap FS_j|}{|FS_i \cup FS_j|} = \frac{\sum_l I(FS_i^l = FS_j^l = 1)}{\sum_l I(FS_i^l + FS_i^l > 0)}$$

In addition to the above stability measures, a number of other stability measurements have also been used. Dunne et al. [53] present an approach based on Hamming distance:

$$H(FS_i, FS_j) = \sum_{x=1}^{l} |FS_i^l - FS_j^l|$$

Given a set k of feature selectors, the total Hamming distance (H_{tot}) is computed as follows:

$$H_{\text{tot}} = \sum_{i=1}^{k-1} \sum_{j=i+1}^{k} H(FS_i, FS_j)$$

Kuncheva [54] developed the idea of consistency index to measure similarity for feature subset selection algorithms. In this method, the consistency index is obtained as follows:

$$I_C(FS_i, FS_j) = \frac{dp - t^2}{t(p - t)}$$

where d is the cardinality of the intersection between FS_i and FS_j. The length of FS_i is t. This consistency index is between -1 and +1. If the two feature selectors are more similar, the consistency index will become greater.

4. DISCUSSIONS

This paper reviews the existing work of ensemble learning based feature selection. According to the usage of class labels of training data, feature selection can be divided into supervised and unsupervised. Supervised feature selection usually aims to maximize the predictive accuracy though selecting the relevant subset of features.

But in unsupervised learning, as the class labels are unknown, it becomes more challengeable to know which features should be selected. The general idea of unsupervised feature selection is to find relevant subsets of features that produce natural groupings by grouping similar objects together based on some similarity measure.

Although in the literature, the research of ensemble feature selection mainly focuses on supervised FS, the study on unsupervised feature selection also exists. Haytham et al. [19] proposed a method called random cluster ensemble, which estimates the out-of-bag feature importance from an ensemble of partitions. Each partition is constructed using a different bootstrap sample and a random subset of the features. The good performance of this method suggests that the study of unsupervised ensemble feature selection should get more attention.

Another topic to discuss is EN_{fs} . It has been proved that EN_{fs} is an effective approach to generate an ensemble of accurate and diverse base classifiers. The general idea of EN_{fs} is to vary the feature subsets and use them to generate diverse classifiers. For traditional feature selection, the goal is to find the best feature subset that needs considering both the learning task and the selected inductive learning algorithm. But for EN_{fs} , one additional goal is to find a set of feature subsets that can promote diversities among the base classifiers.

Similar to traditional feature selection, there are two factors when designing EN_{fs} : (1) search strategy and (2) fitness function. The search strategy searches for the feature subset which maximizes the output of fitness function. In traditional feature selection, the classification accuracy is mainly considered in the fitness function. But for EN_{fs} , the fitness function should reflect both the classification accuracy and the diversity. One of the fitness functions, proposed by Opitz [36], defines the fitness value as follows: Fitness_i = $accu_i + \alpha \cdot diversity_i$, where α reflects the influence of diversity. diversity_i is the contribution of the *i*th classifier to the total ensemble diversity, which can be measured as the average pairwise diversity for all the pairs of classifiers including *i*.

 $\mathrm{EN}_{\mathrm{fs}}$ and $\mathrm{FS}_{\mathrm{en}}$ are compared in Table 5. Through this table, the similarity and difference between them are summarized.

Table 5: Comparison between two ways of integrating feature selection and ensemble learning

Similarity		Feature selection for ensemble learning (EN_{fs})	Ensemble learning for feature selection (FS _{en}) Integration of feature selection and ensemble learning	
		Integration of feature selection and ensemble learning		
Difference	Goal	(1) Use feature selection to generate different feature subsets; these different feature subsets are used to construct an ensemble of diverse classifiers	(1) Generates a good feature subset by combining multiple feature subsets based on the idea of ensemble learning.	
		(2) To achieve more accurate ensemble classifiers	(2) To obtain more stable feature subset	
	Main research issues	(1) How to define search strategy	(1) How to generate diverse feature selectors	
		(2) How to define fitness function	(2) How to aggregate these feature selectors	

5. CONCLUSIONS

In this paper, the idea of ensemble learning based feature selection is reviewed. This is a relatively new idea and gets attention in recent years. Compared to traditional feature selection, ensemble feature selection has several advantages. It can overcome the potential local optima, enlarge the search space, and improve the generalization accuracy and stability. Although stability is usually neglected before, but in fact it is extremely important for knowledge discovery. Regarding to stability, ensemble feature selection has shown significant improvement.

Moreover, we also discuss the other two topics that are related to ensemble feature selection. One is ensemble feature selection for unsupervised learning. The other topic is feature selection for ensemble learning. We believe that the knowledge in these two topics can also contribute to the promotion of ensemble feature selection.

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