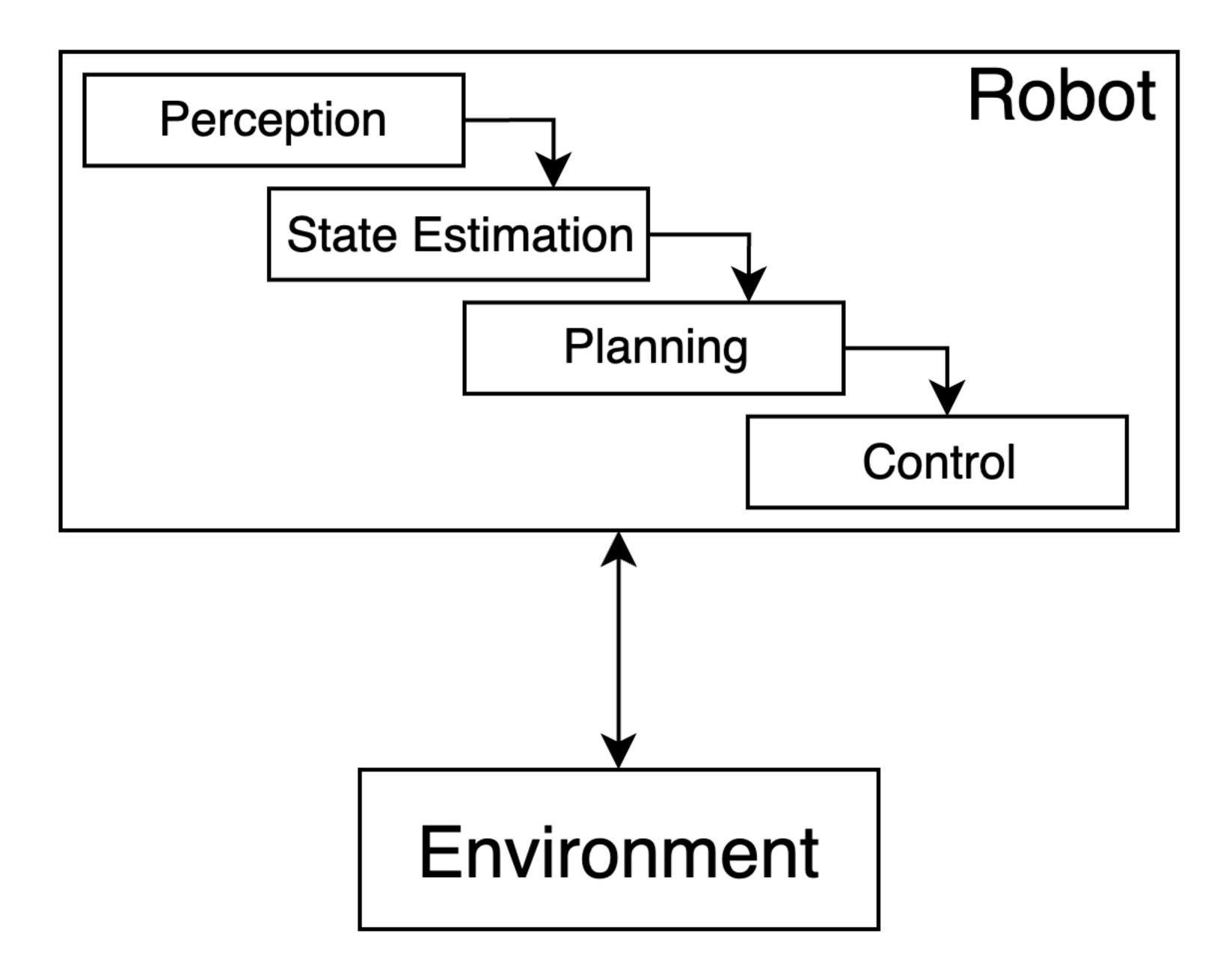
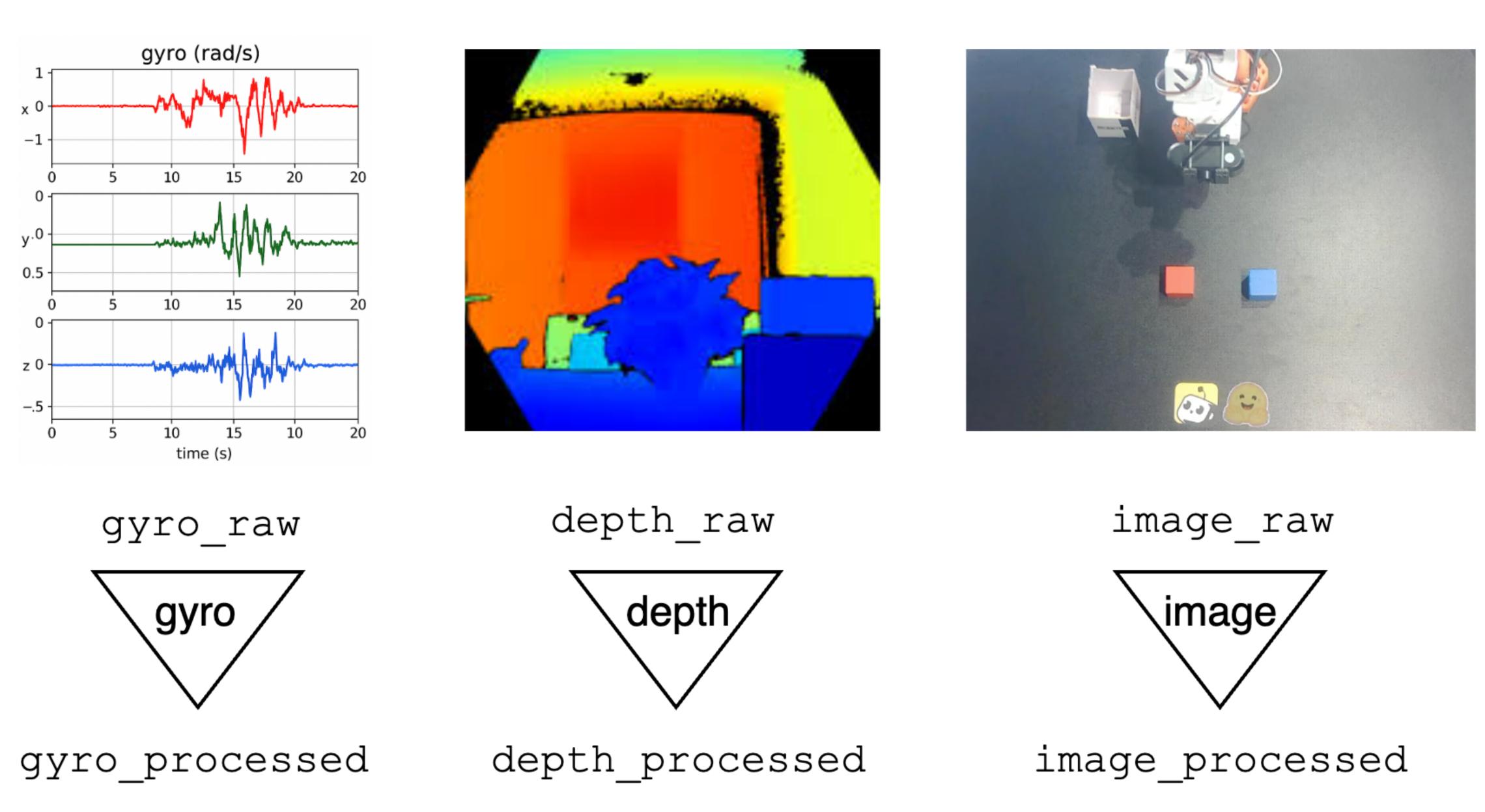
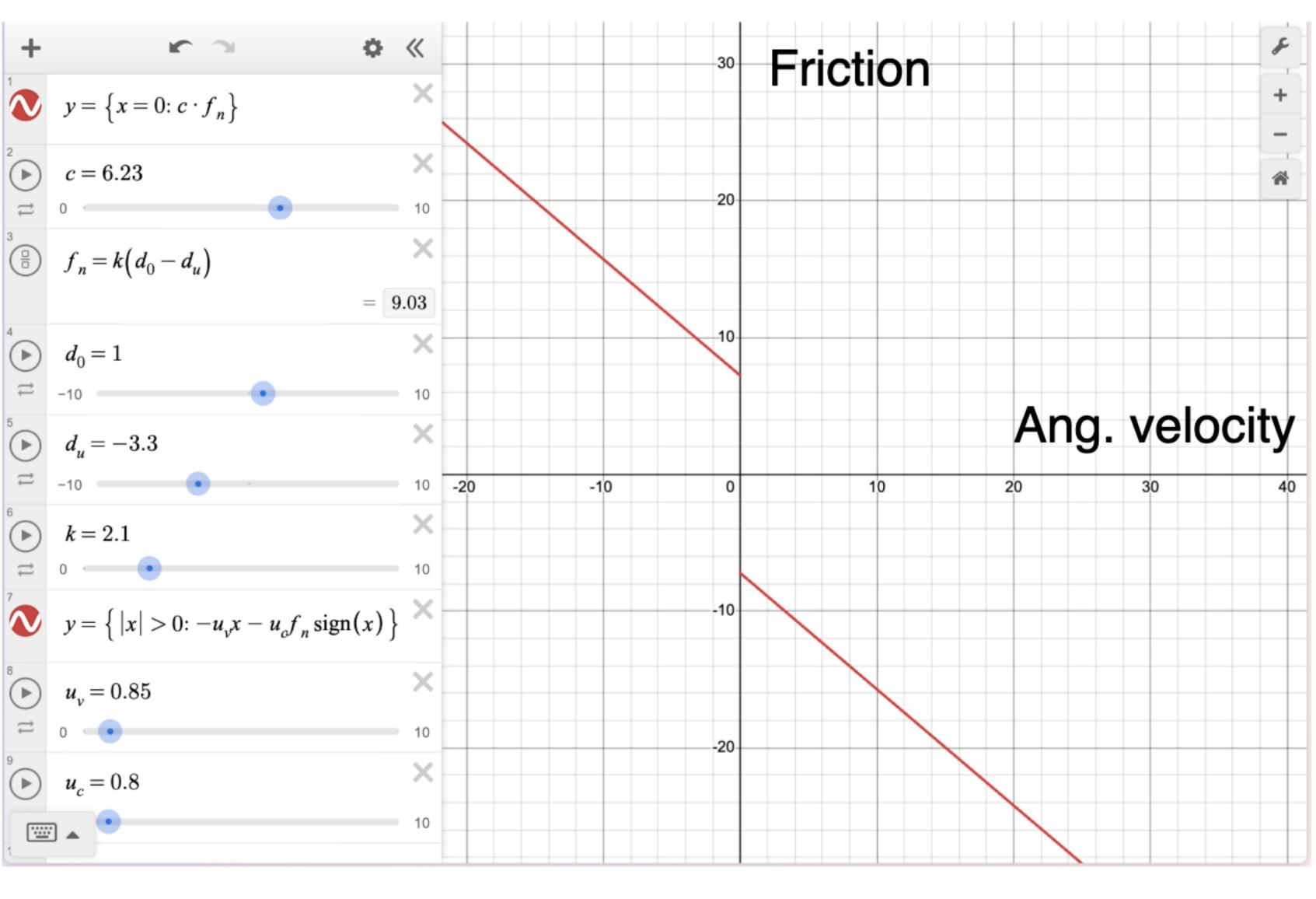
1) Integration challenges



2) Multimodality challenges



3 Undermodeling issues



Friction model for a manipulation task

4) Ignoring open-data growth

