

Concurrent Erlang

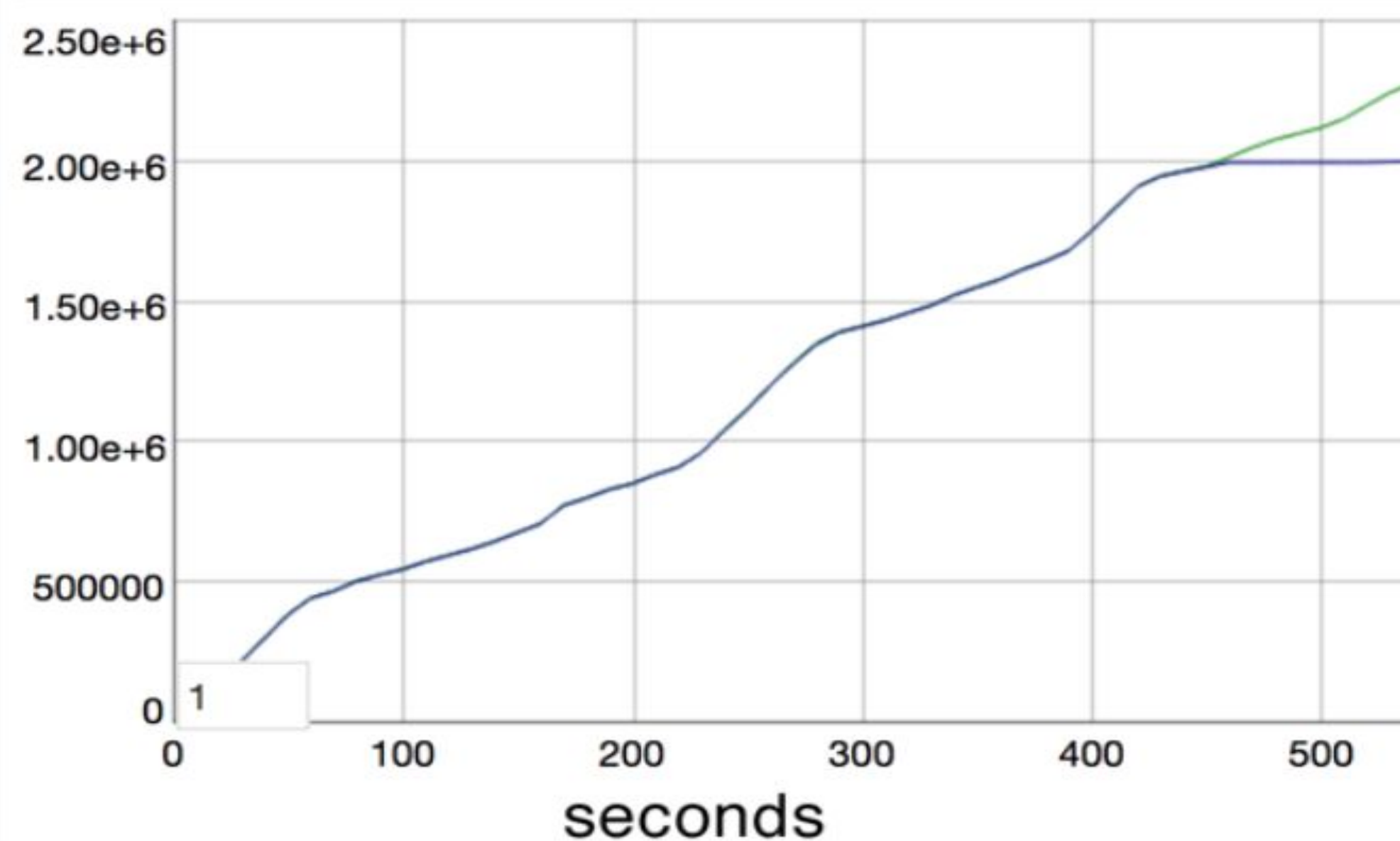
Overview: **concurrent Erlang**

- ▶ Creating Processes
- ▶ Message Passing
- ▶ Receiving Messages
- ▶ Data in Messages
- ▶ Registered Processes
- ▶ Timeouts
- ▶ More on Processes
- ▶ Observer Processes

The Road to 2 Million Websocket Connections in Phoenix

Posted on November 3rd, 2015 by Gary Rennie

Simultaneous Users

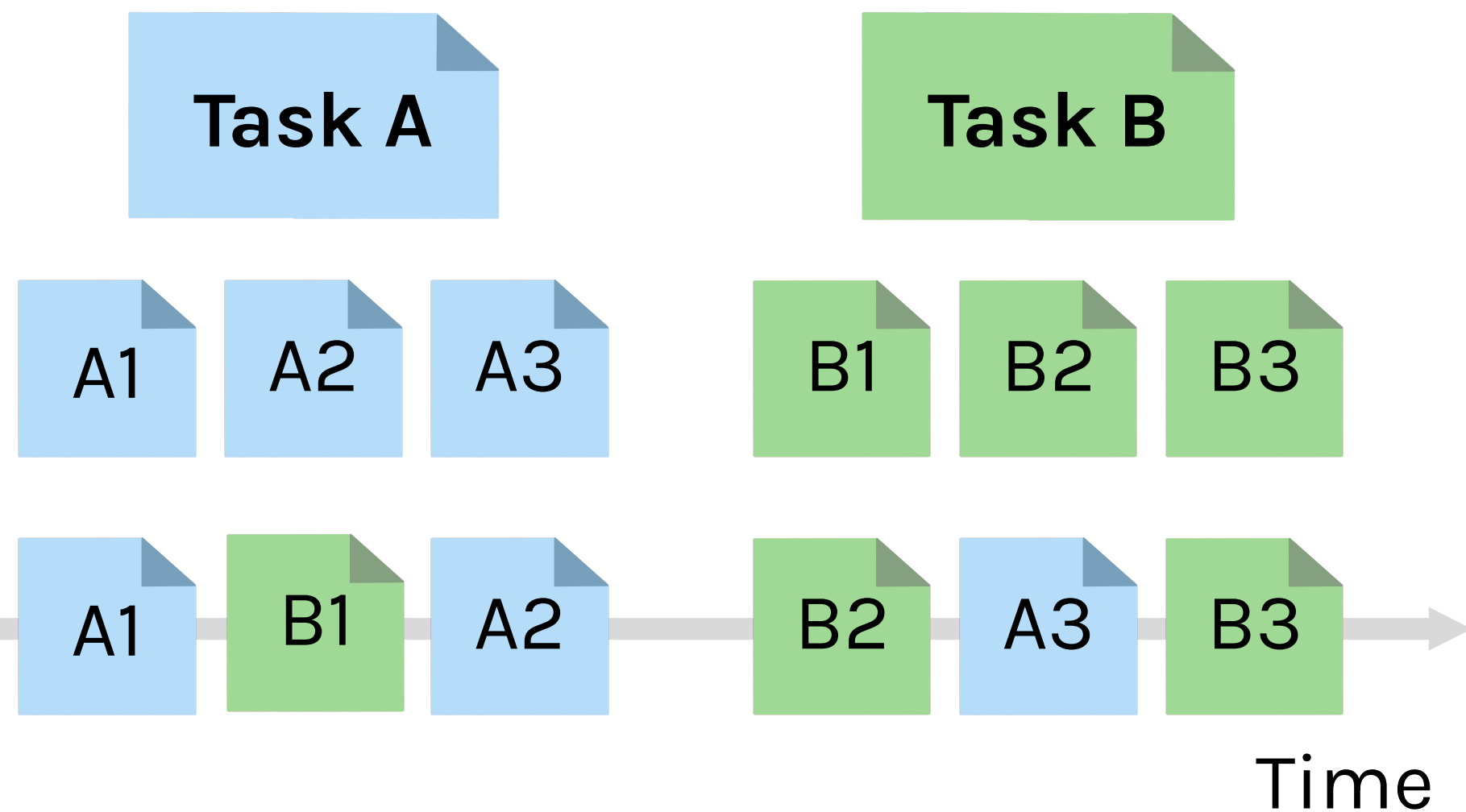


```
1700045
1763630
1999975
1999984
subscribers

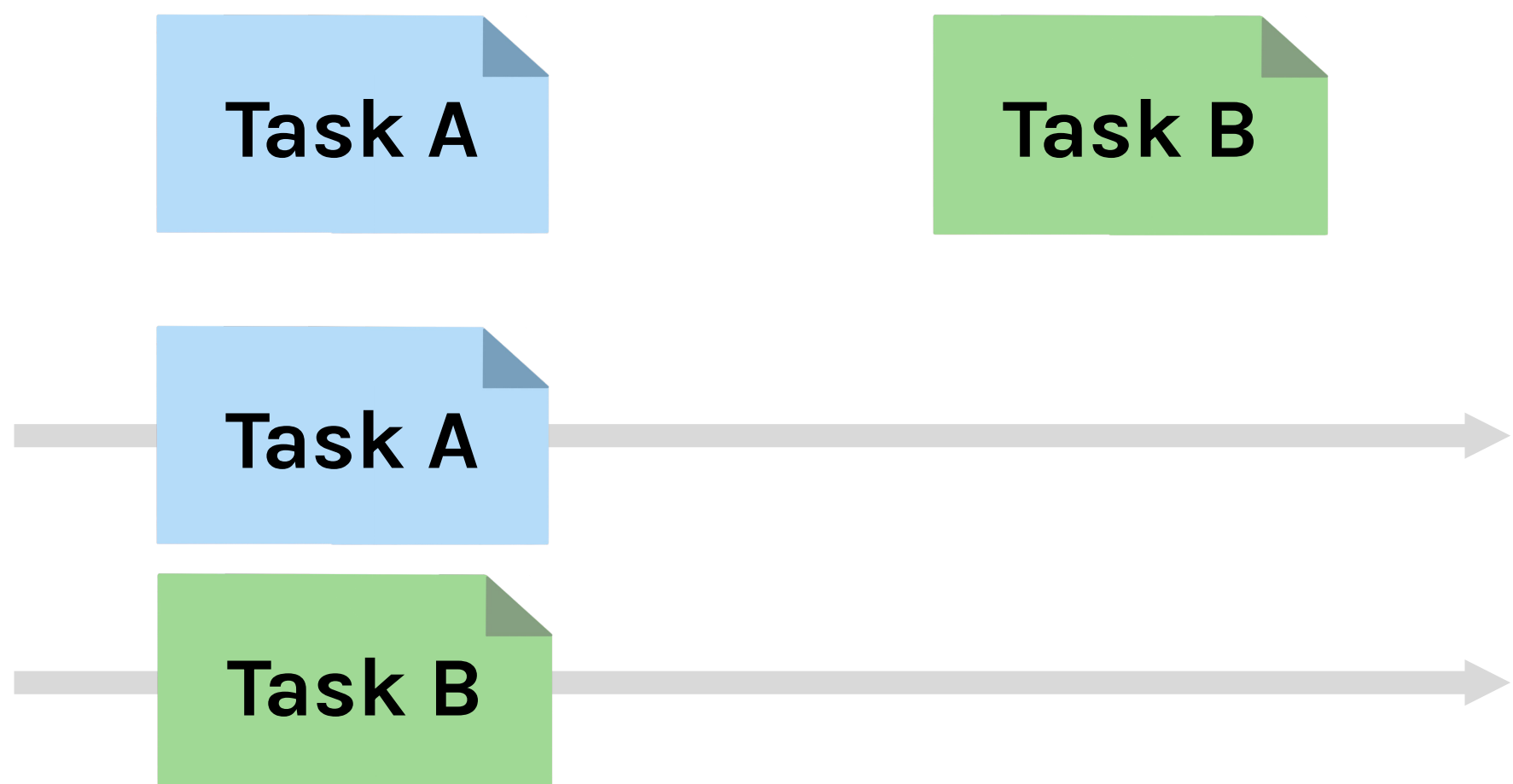
1 [ 0.0%] 11 [ 0.5%] 21 [ 0.0%] 31 [ 0.0%]
2 [ 0.0%] 12 [ 0.5%] 22 [ 0.0%] 32 [ 0.0%]
3 [ 0.0%] 13 [ 0.0%] 23 [ 0.0%] 33 [ 0.0%]
4 [ 1.0%] 14 [ 0.0%] 24 [ 0.5%] 34 [ 0.0%]
5 [ 0.5%] 15 [ 0.0%] 25 [ 0.0%] 35 [ 0.0%]
6 [ 0.5%] 16 [ 0.0%] 26 [ 0.0%] 36 [ 0.0%]
7 [ 0.0%] 17 [ 0.0%] 27 [ 0.0%] 37 [ 0.0%]
8 [ 1.0%] 18 [ 0.0%] 28 [ 0.5%] 38 [ 0.0%]
9 [ 0.0%] 19 [ 0.0%] 29 [ 0.0%] 39 [ 0.0%]
10 [ 0.0%] 20 [ 0.0%] 30 [ 0.0%] 40 [ 0.0%]
Mem[|||||||83765/128906MB] Tasks: 22, 150 thr; 2 running
Swp[ 0/0MB] Load average: 5.98 5.45 3.98
Uptime: 5 days, 11:17:13
```

If you have been paying attention on Twitter recently, you have likely seen some increasing numbers regarding the number of simultaneous connections the Phoenix web framework can handle. This post documents some of the techniques used to perform the benchmarks.

Concurrency vs Parallelism

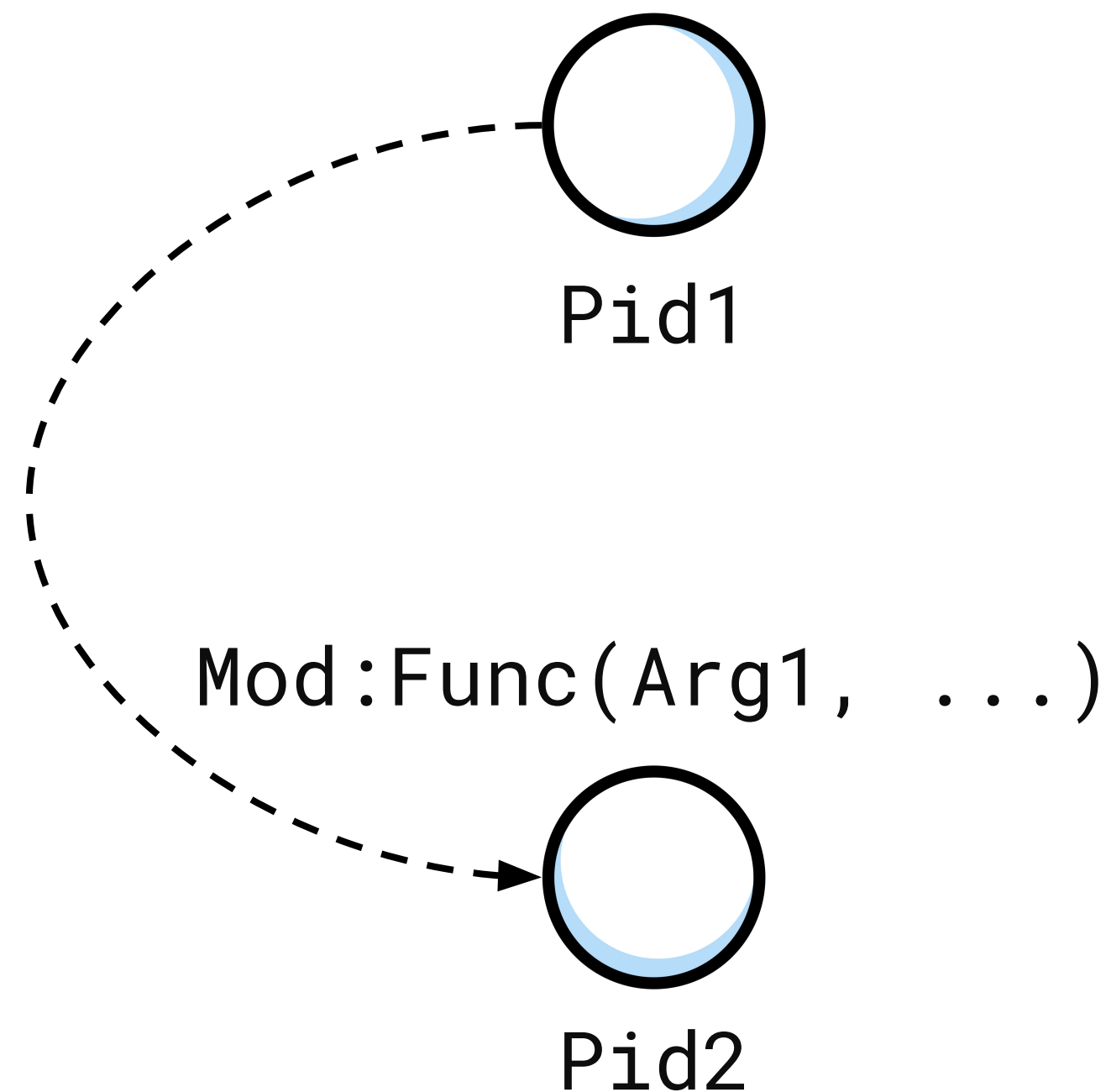


- ▶ Concurrency happens when your code is running in different processes
- ▶ Control of Concurrency is key to scale
- ▶ Concurrent solutions can exploit the underlying system's parallelism, if present
- ▶ Parallelism can speed up execution



Creating Processes

```
Pid2 = spawn(Mod, Func, Args)
```



Before

- Code executed by Process 1
- **process identifier** is Pid1
- `Pid2 = spawn(M, F, A)`



After

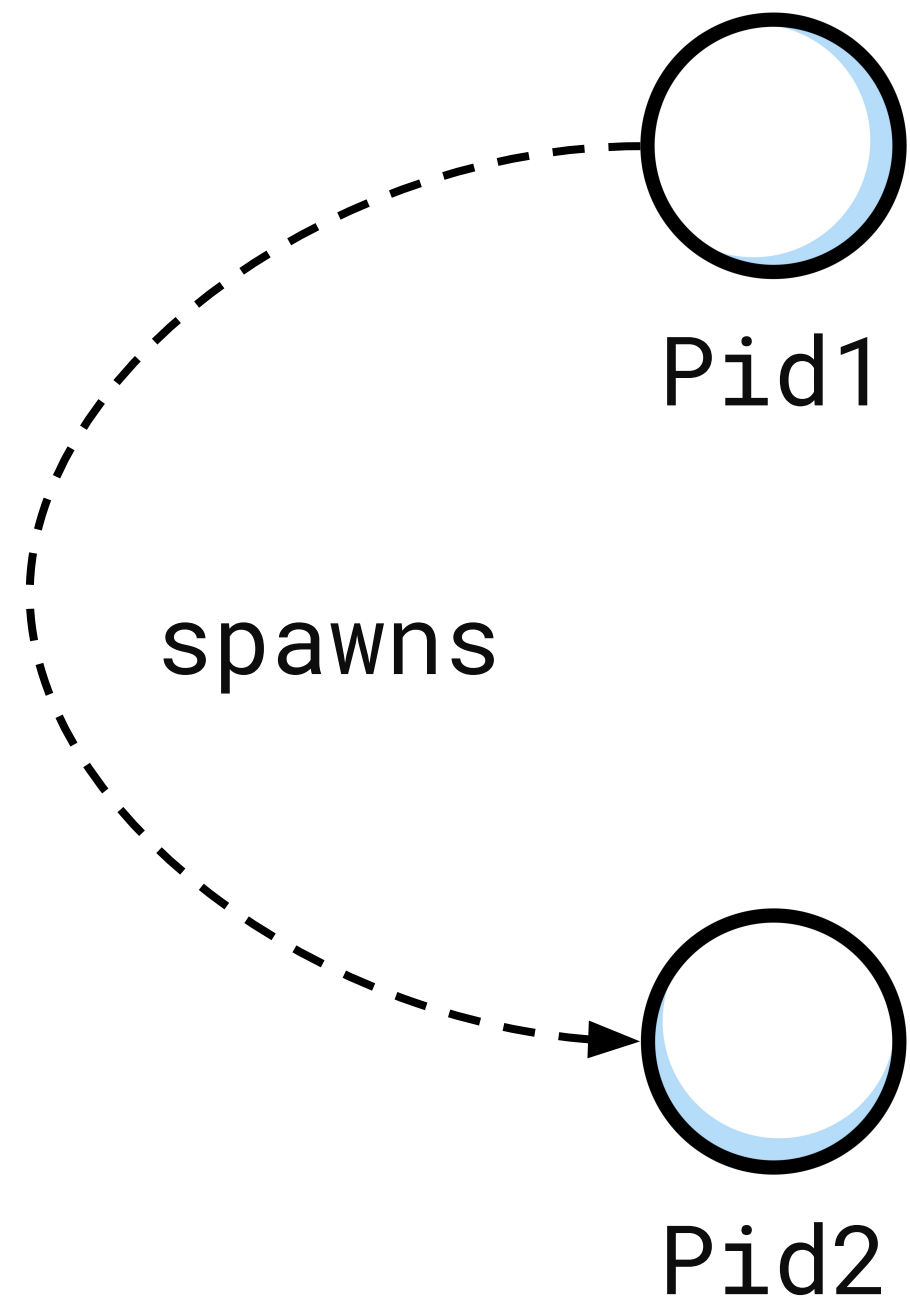
- A new process with Pid2 is created
- Pid2 is only known to Pid1
- Pid2 runs `M:F(A)`
- `M:F/Arity` must be exported



Convention: we identify processes by their process ids (pids)

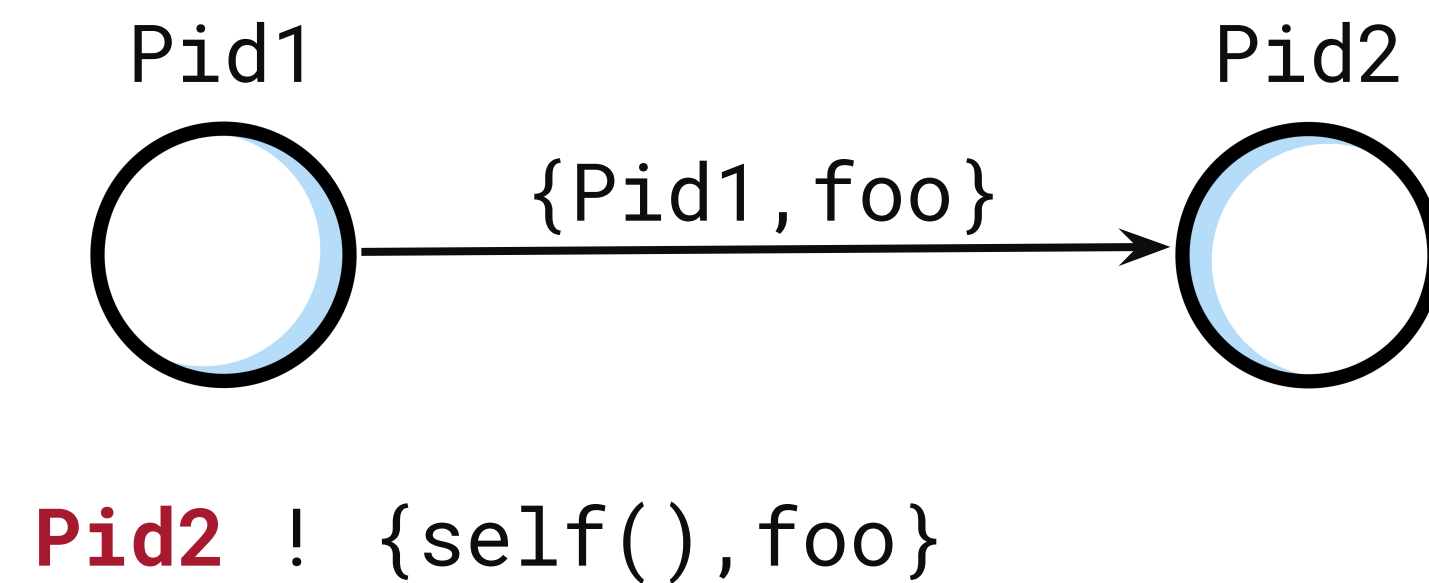
Creating Processes

```
Pid2 = spawn(Mod, Func, Args)
```



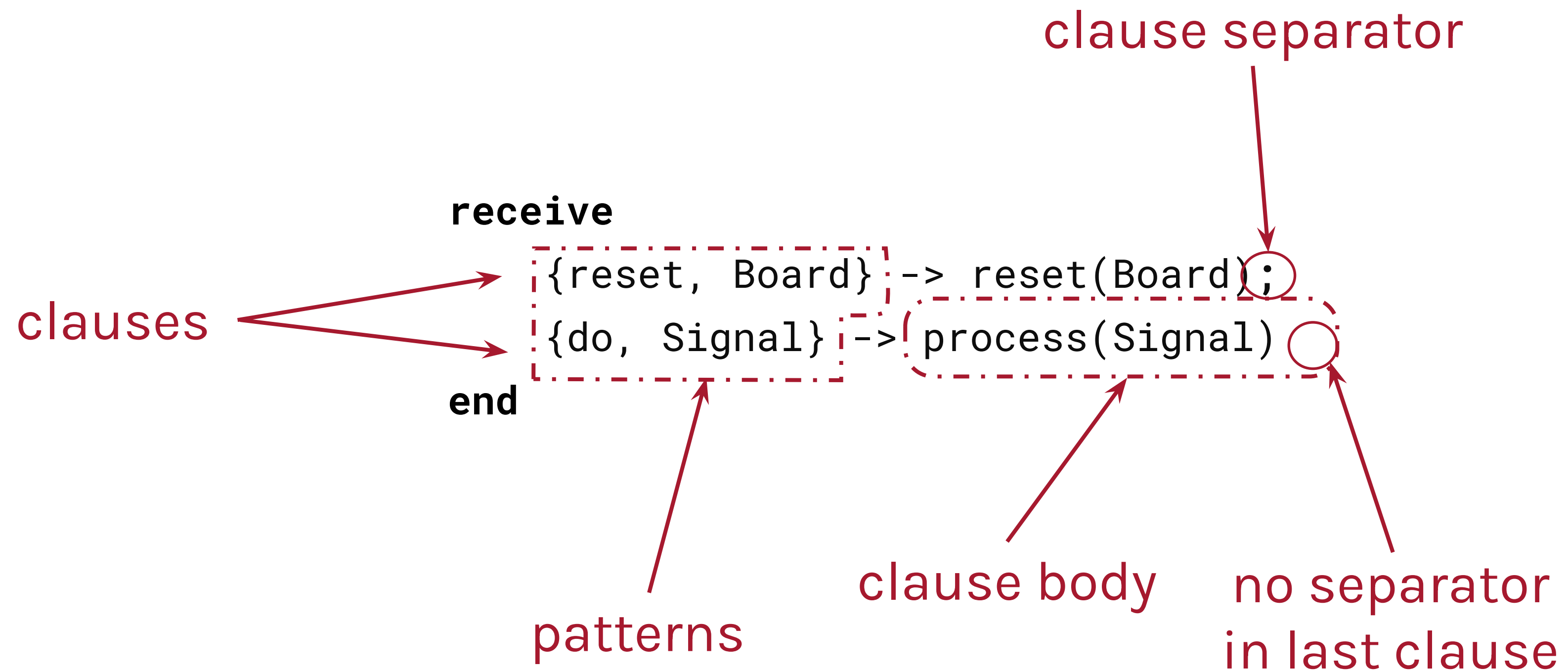
- ▶ The BIF **spawn** fails when max number of running processes reached
- ▶ A process terminates
 - **abnormally** when run-time errors occur
 - **normally** when there is no more code to execute

Message Passing



- ▶ Messages are sent using the **Pid ! Msg** expression
 - **Msg** is any valid Erlang data type
- ▶ Sending a message will never fail
- ▶ Messages sent to non-existing processes are thrown away
- ▶ Received messages are stored in the process' mailbox

Message Passing



Receiving Messages

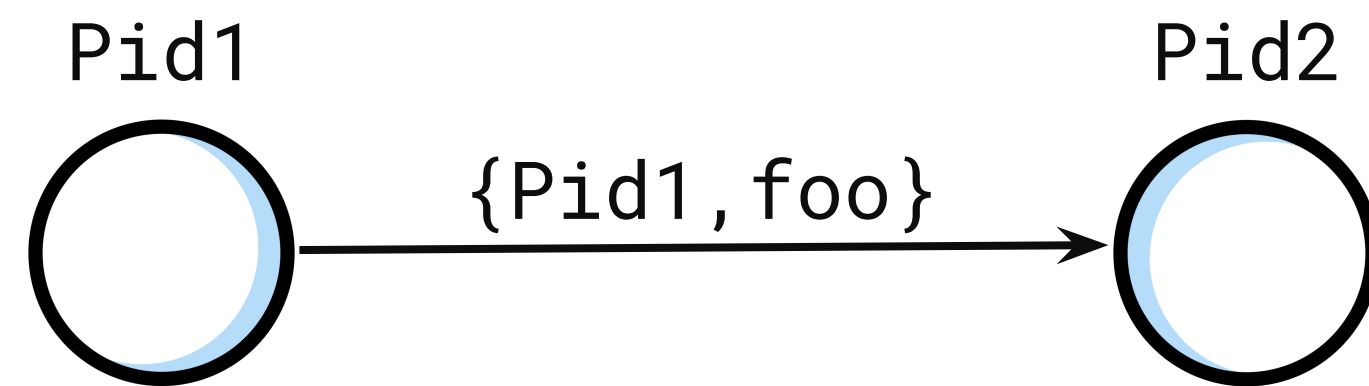
receive

```
Pattern1 ->
    <expression 1>,
    <expression 2>,
    ...
    <expression N>;
Pattern2 ->
    <expression 1>,
    ...
    <expression N>;
PatternN ->
    <expression 1>,
    ...
    <expression N>
```

end

- ▶ Messages are retrieved using a **receive** clause
- ▶ **receive** suspends the process until a matching message is received
- ▶ Message passing is asynchronous

Receiving Messages

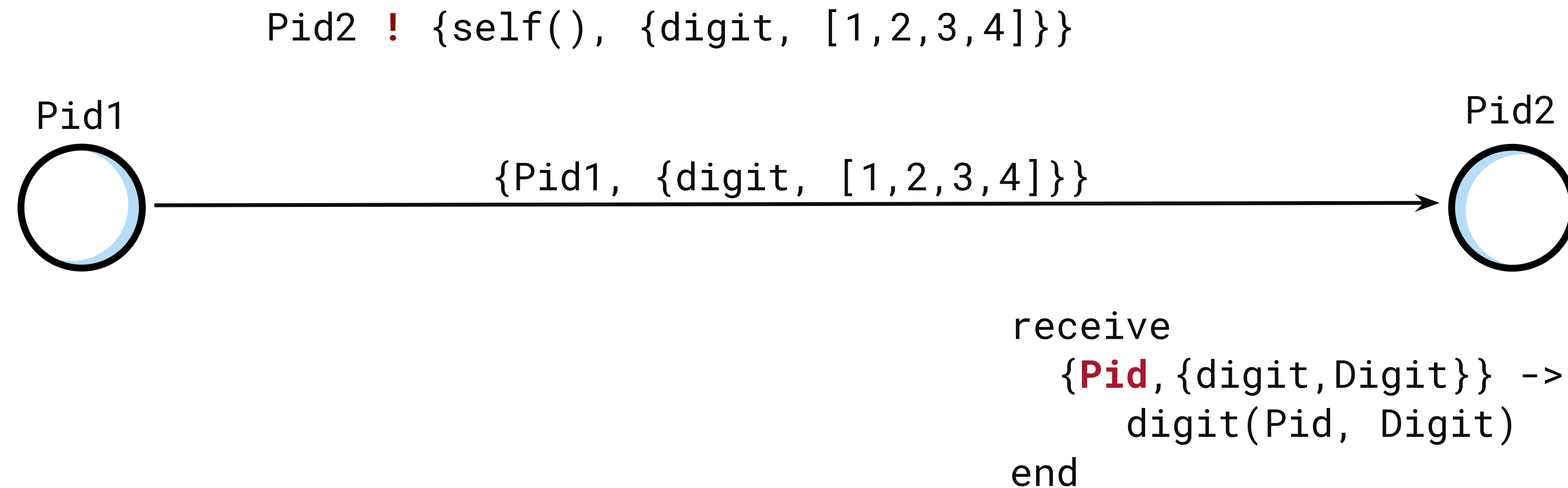


Pid2 ! {self(), foo}

```
receive
  start      -> start_it();
  stop       -> stop_it();
  {Pid, foo} -> foo(Pid)
end
```

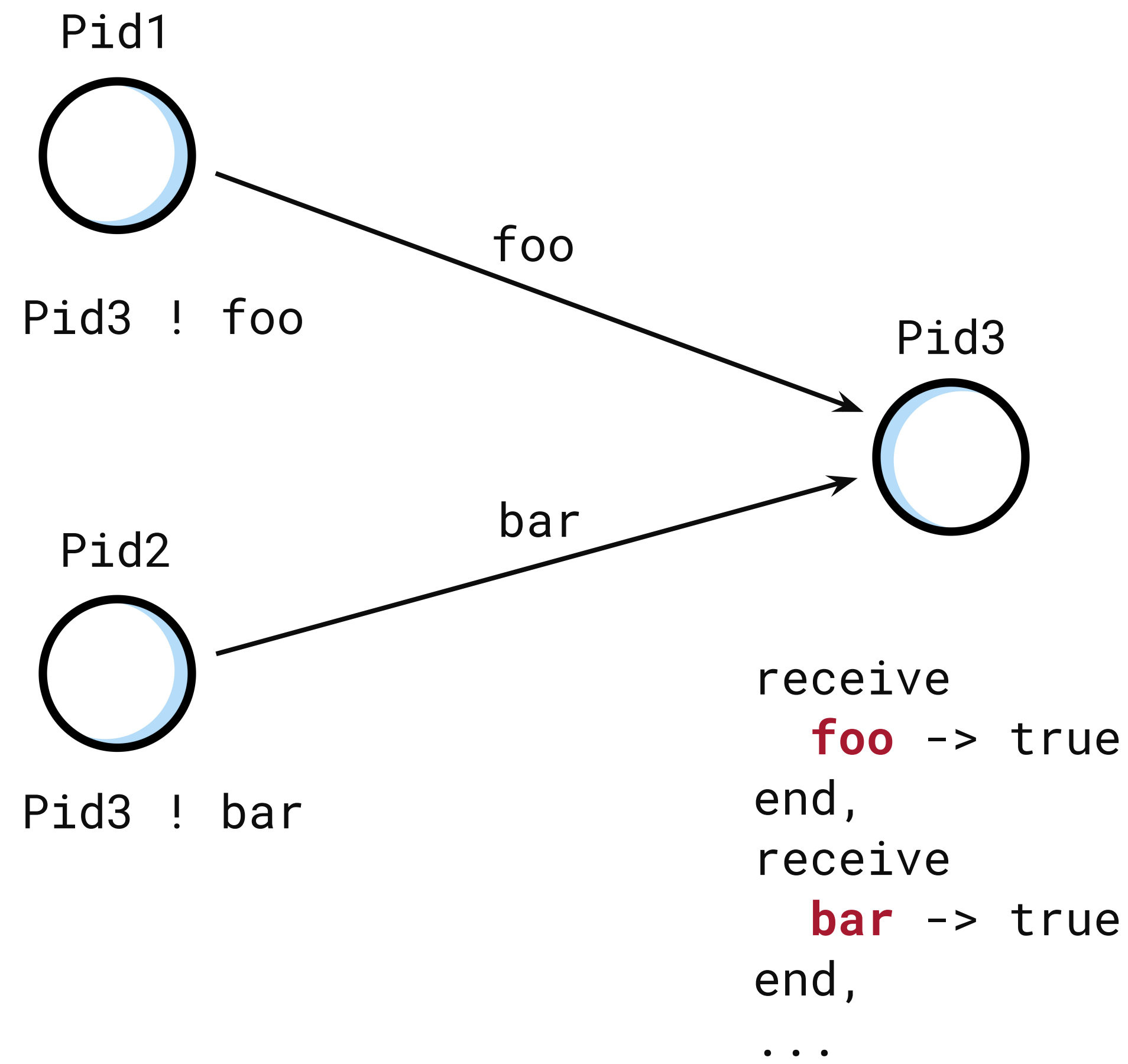
- ▶ Messages can be matched and selectively retrieved
- ▶ Messages are received when a message matches a clause
- ▶ Mailboxes are scanned sequentially.

Receiving Messages



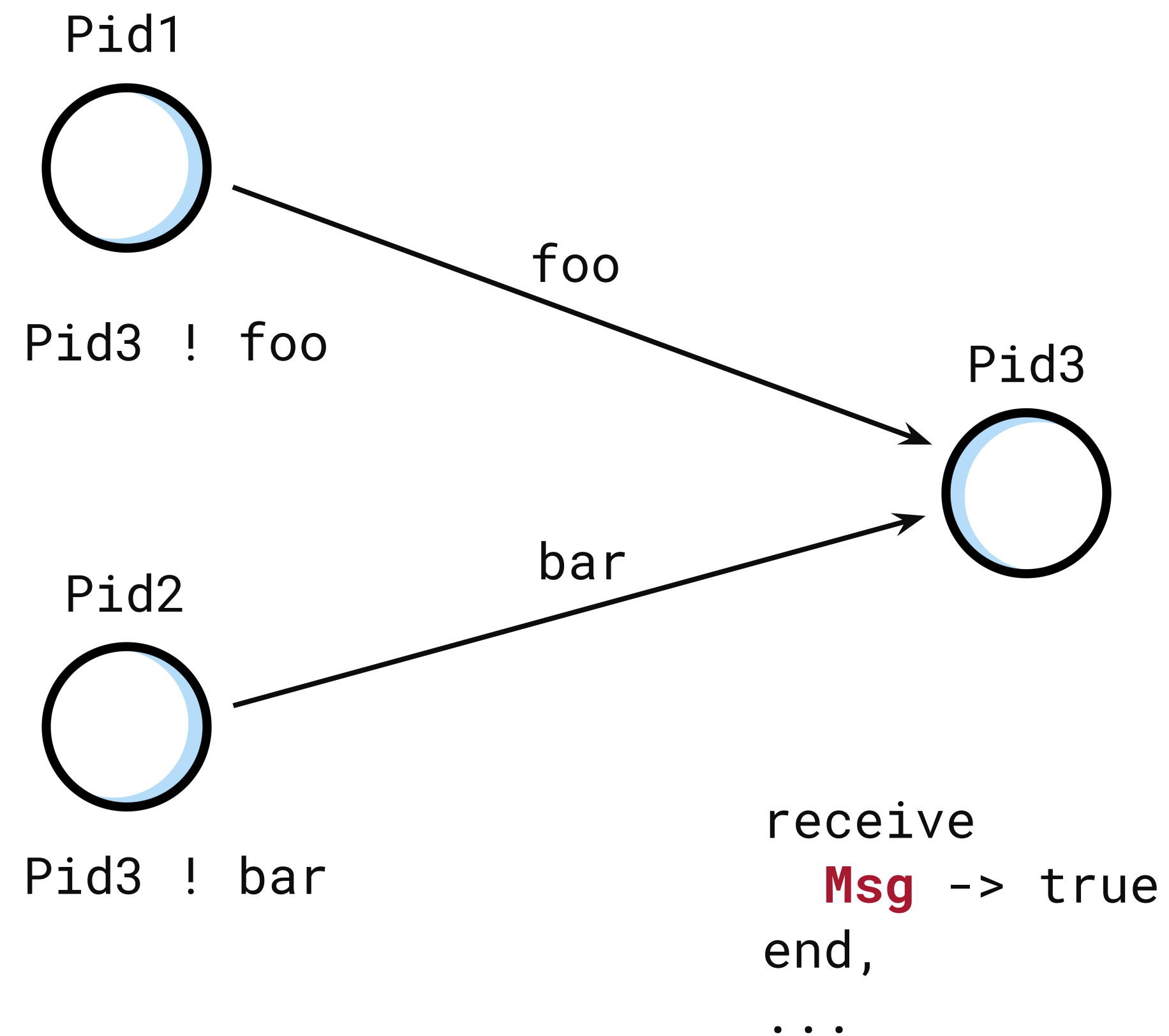
- ▶ If **Pid** is bound before receiving the message, then only data tagged with that pid can be pattern matched
- ▶ The variable **Digit** is bound when receiving the message

Receiving Messages: **selective**



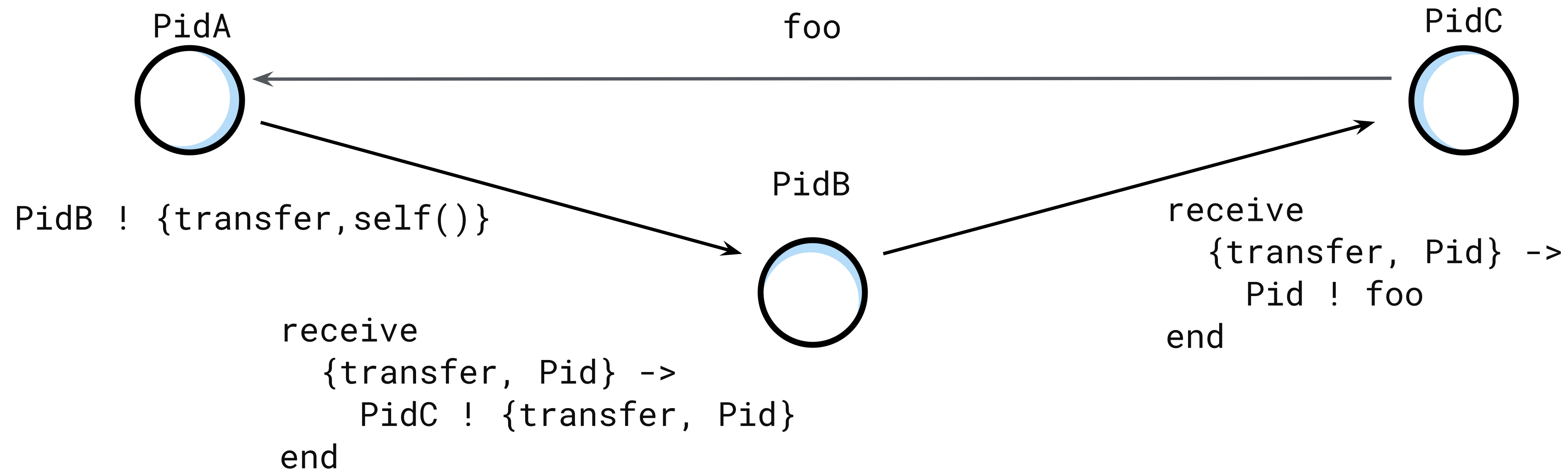
- ▶ The message **foo** is received, followed by the message **bar**
- ▶ This is irrespective of the order in which they were sent or stored in the mailbox

Receiving Messages: **non-selective**



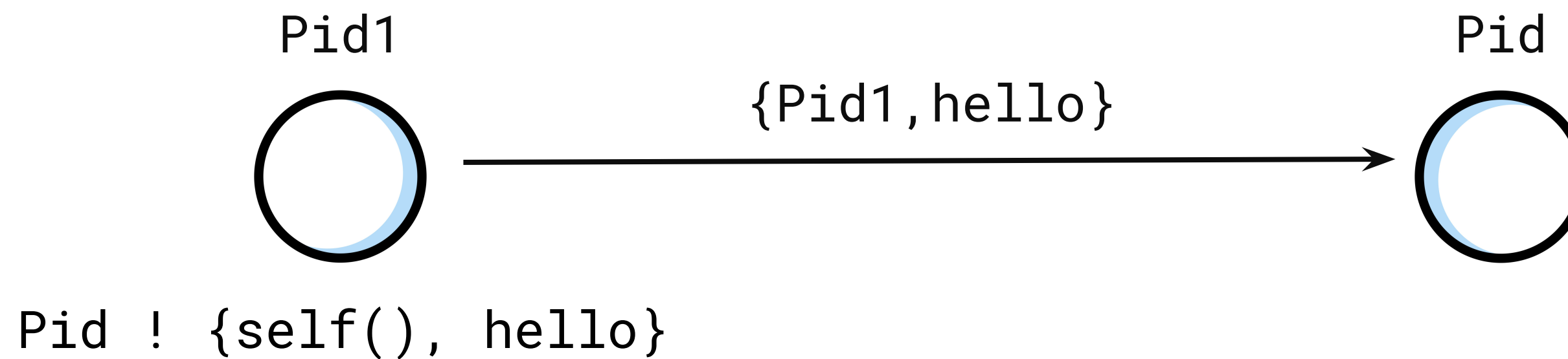
- ▶ The first message to arrive at the process **Pid3** will be processed
- ▶ The variable **Msg** in the process **Pid3** will be bound to one of the atoms **foo** or **bar** depending on which arrives first.

Receiving Messages



- ▶ PidA sends a message to PidB containing its own Pid
- ▶ PidB binds it to variable Pid and sends a message to PidC
- ▶ PidC receives the message and replies directly to PidA

Data in Messages: **example**



```
-module(echo).  
-export([go/0, loop/0]).  
  
go() ->  
    Pid = spawn(echo, loop, []),  
    Pid ! {self(), hello},  
    receive  
        {Pid, Msg} ->  
            io:format("~w~n", [Msg])  
    end,  
    Pid ! stop.
```

```
loop() ->  
    receive  
        {From, Msg} ->  
            From ! {self(), Msg},  
            loop();  
        stop ->  
            ok  
    end.
```

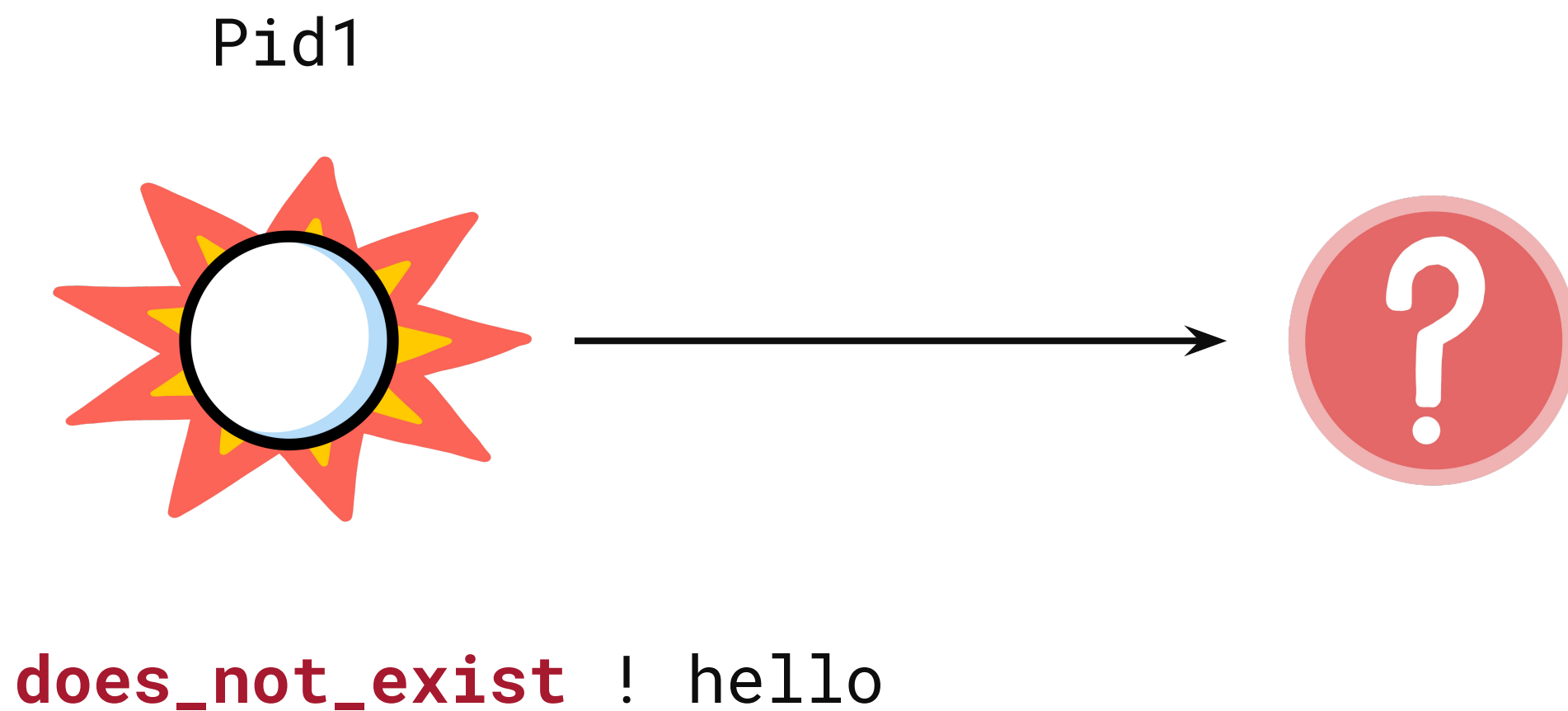
Registered Processes

```
register(Alias, Pid)  
Alias ! Message
```

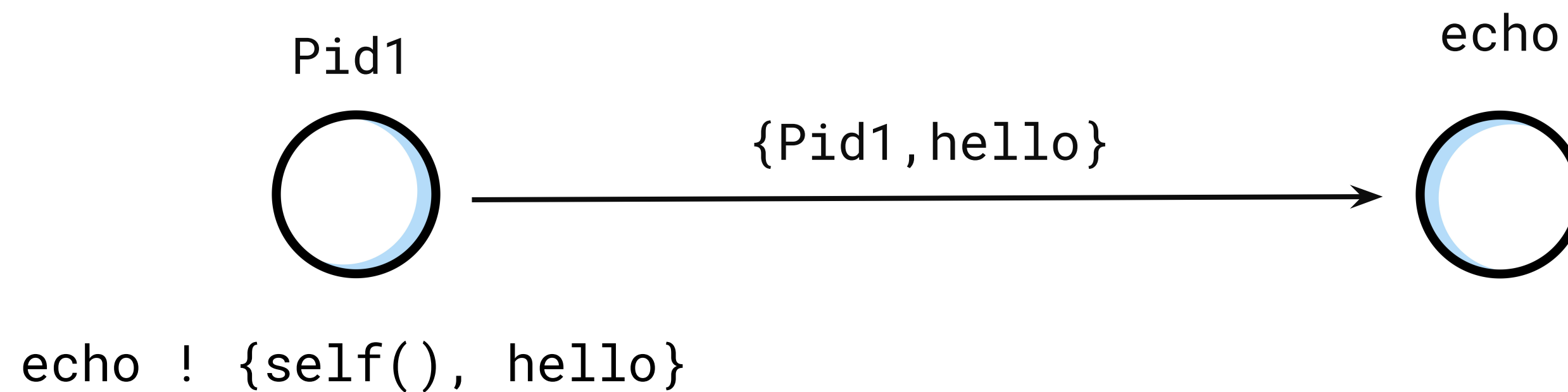
- ▶ Registers the process **Pid** with the name **Alias**, which has to be an atom
- ▶ Any process can send a message to a registered process
- ▶ The BIF **registered/0** returns all registered process names
- ▶ The BIF **whereis(Alias)** returns the Pid of the process with the name **Alias**.

Message Passing

- ▶ Sending messages to non-existing registered processes causes the calling process to terminate with a **badarg** error



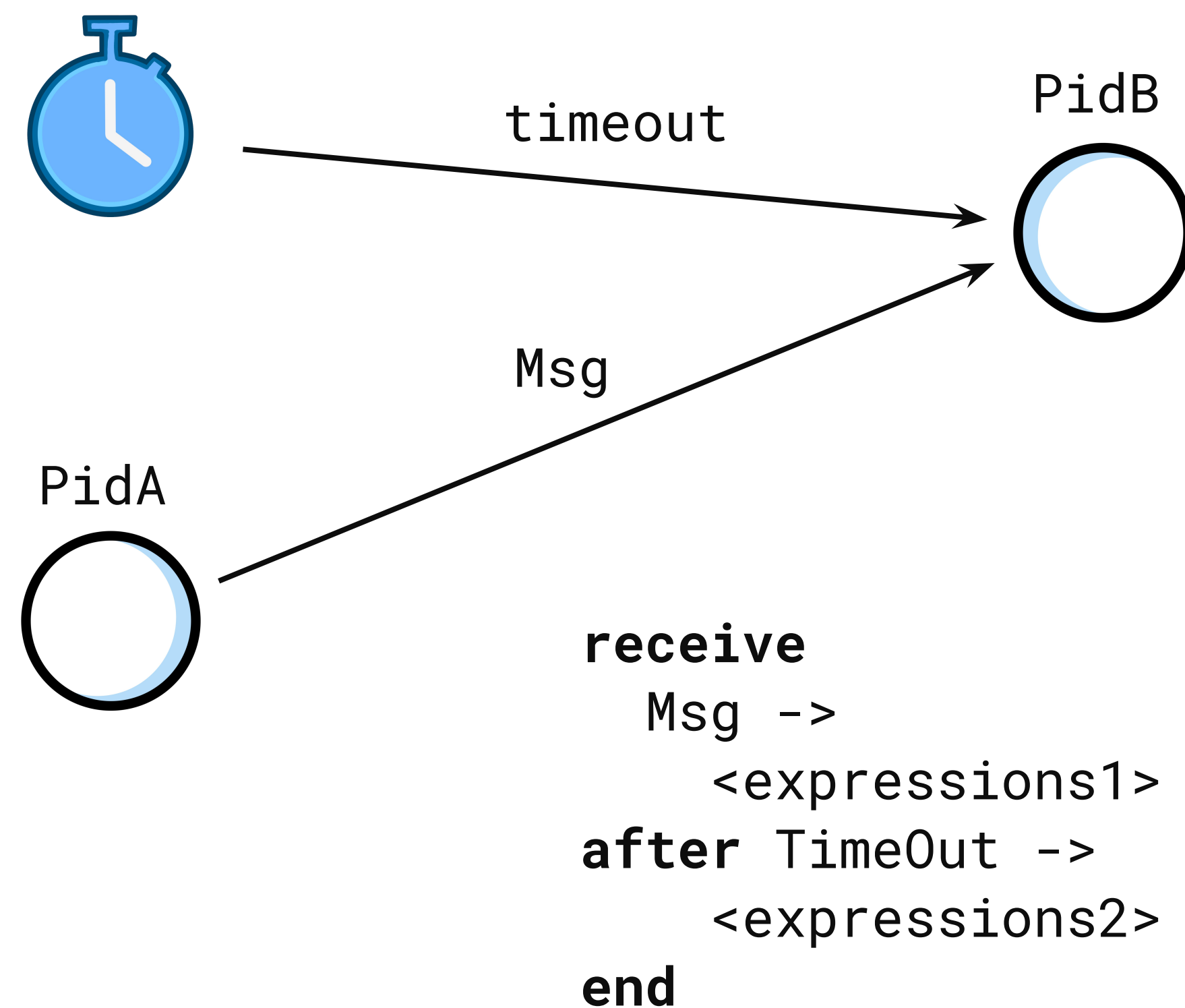
Registered Processes



```
-module(echo).  
-export([go/0, loop/0]).  
  
go() ->  
    Pid = spawn(echo, loop, []),  
    register(echo, Pid).
```

```
loop() ->  
    receive  
        {From, Msg} ->  
            From ! {self(), Msg},  
            loop();  
        stop ->  
            ok  
    end.
```

Timeouts



- ▶ If the message **Msg** is received within the time **TimeOut**, <expressions1> will be executed
- ▶ If not, <expressions2> will be executed
- ▶ TimeOut is an integer denoting the time in milliseconds or the atom **infinity**

Timeouts

```
read(Key) ->  
  db ! {self(), {read, Key}},  
  receive  
    {read, R} ->  
      {ok, R};  
    {error, Reason} ->  
      {error, Reason}  
  after 1000 ->  
    {error, timeout}  
end.
```

- ▶ If the server takes more than a second to handle the request, a timeout is generated
- ▶ Do not forget to handle messages received after a timeout

Timeouts

```
send_after(Time, Msg) ->  
    spawn(timer,  
          send,  
          [self(), Time, Msg]).
```

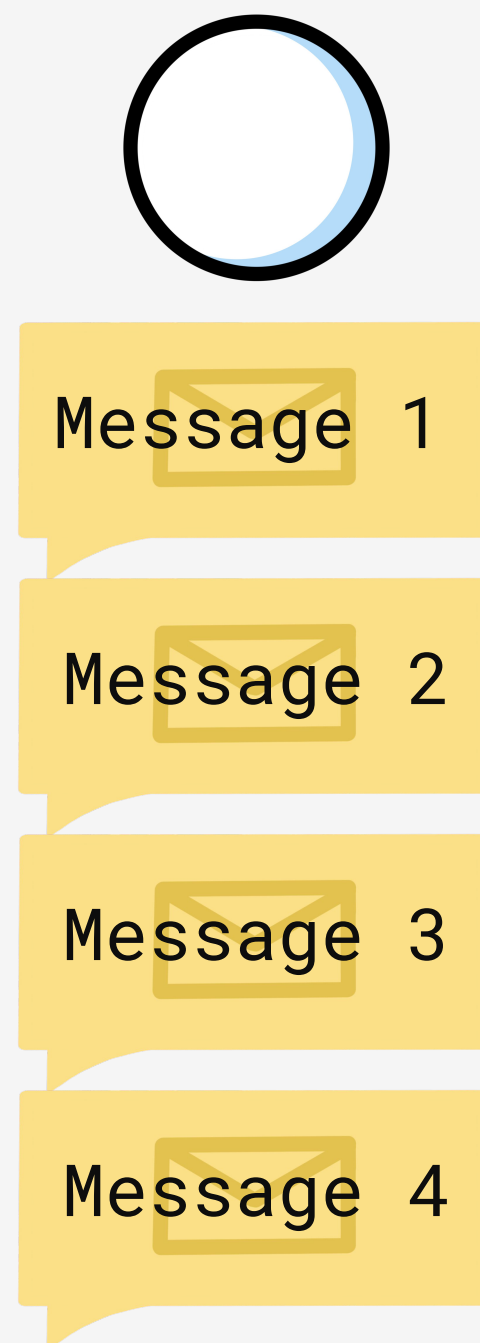
```
send(Pid, Time, Msg) ->  
    receive  
    after Time ->  
        Pid ! Msg  
    end.
```

```
sleep(T) ->  
    receive  
    after T ->  
        true  
    end.
```

- ▶ **send_after(T, What)** sends the message **What** to the current process after **T** milliseconds
- ▶ The **sleep(T)** function will suspend the calling process for **T** milliseconds

Timeouts

```
flush() ->  
  receive  
    _ -> flush()  
  after 0 ->  
    ok  
end.
```



- **flush()** will clear the mailbox from all messages, stopping when it is empty.

More on Processes: **definitions**

Process

A concurrent activity. The system may have many concurrent processes executing at the same time

Message

A method of communication and sharing data between processes

Timeout

A mechanism for waiting for a given period of time for an incoming message

More on Processes: **definitions**

Registered Processes

Processes which have been given a name with BIFs such as **register/2**.

Termination

A process is said to terminate **normally** when it has no more code to execute.

It terminates **abnormally** if a run time error occurs or if someone makes it exit with a non-normal reason.

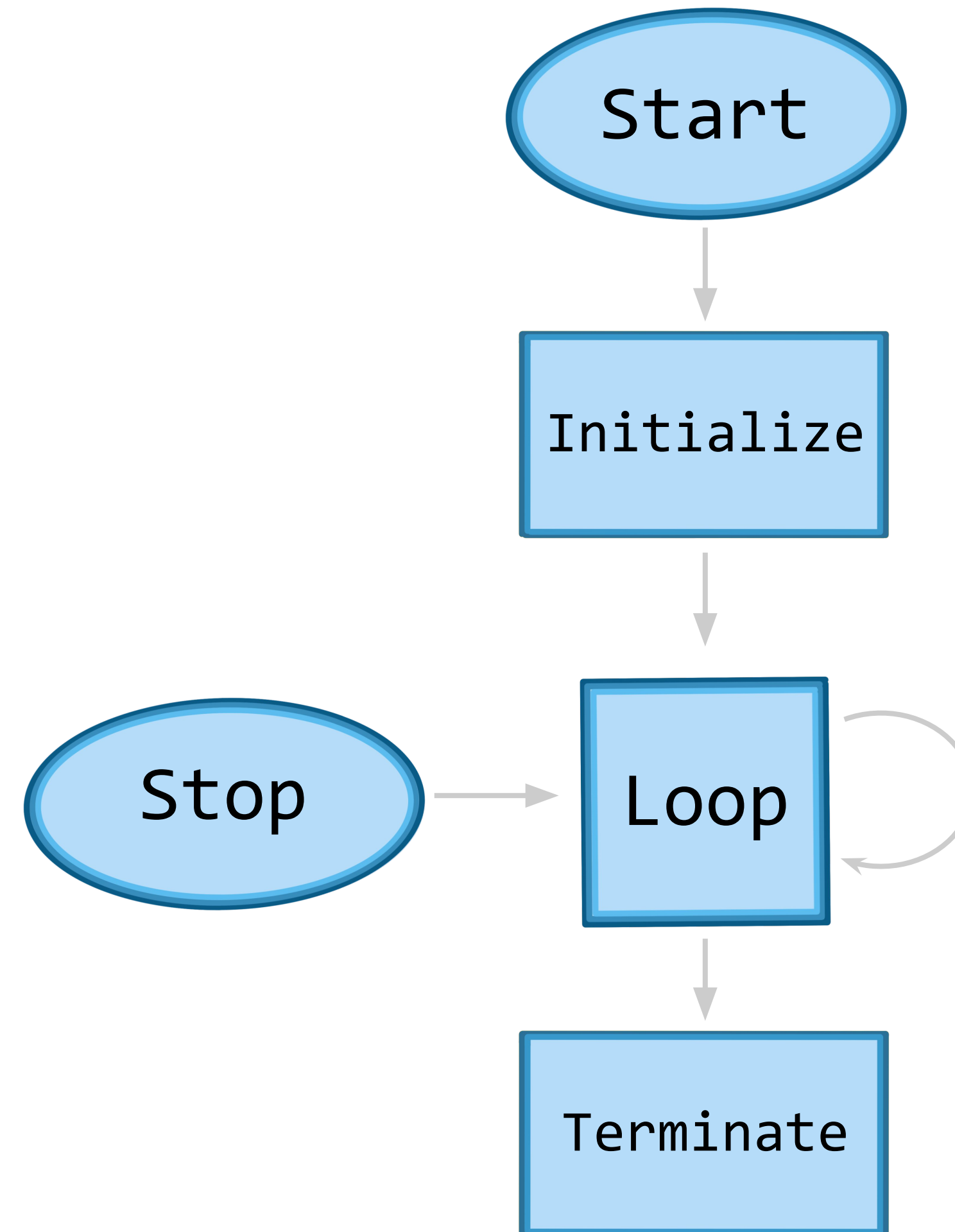
More on Processes: **process skeleton**

```
start(Args) ->
    spawn(server, init, [Args])

init(Args) ->
    State = initialize_state(Args),
    loop(State).

loop(State) ->
    receive
        {handle, Msg} ->
            NewState = handle(Msg, State),
            loop(NewState);
        stop -> terminate(State)
    end.

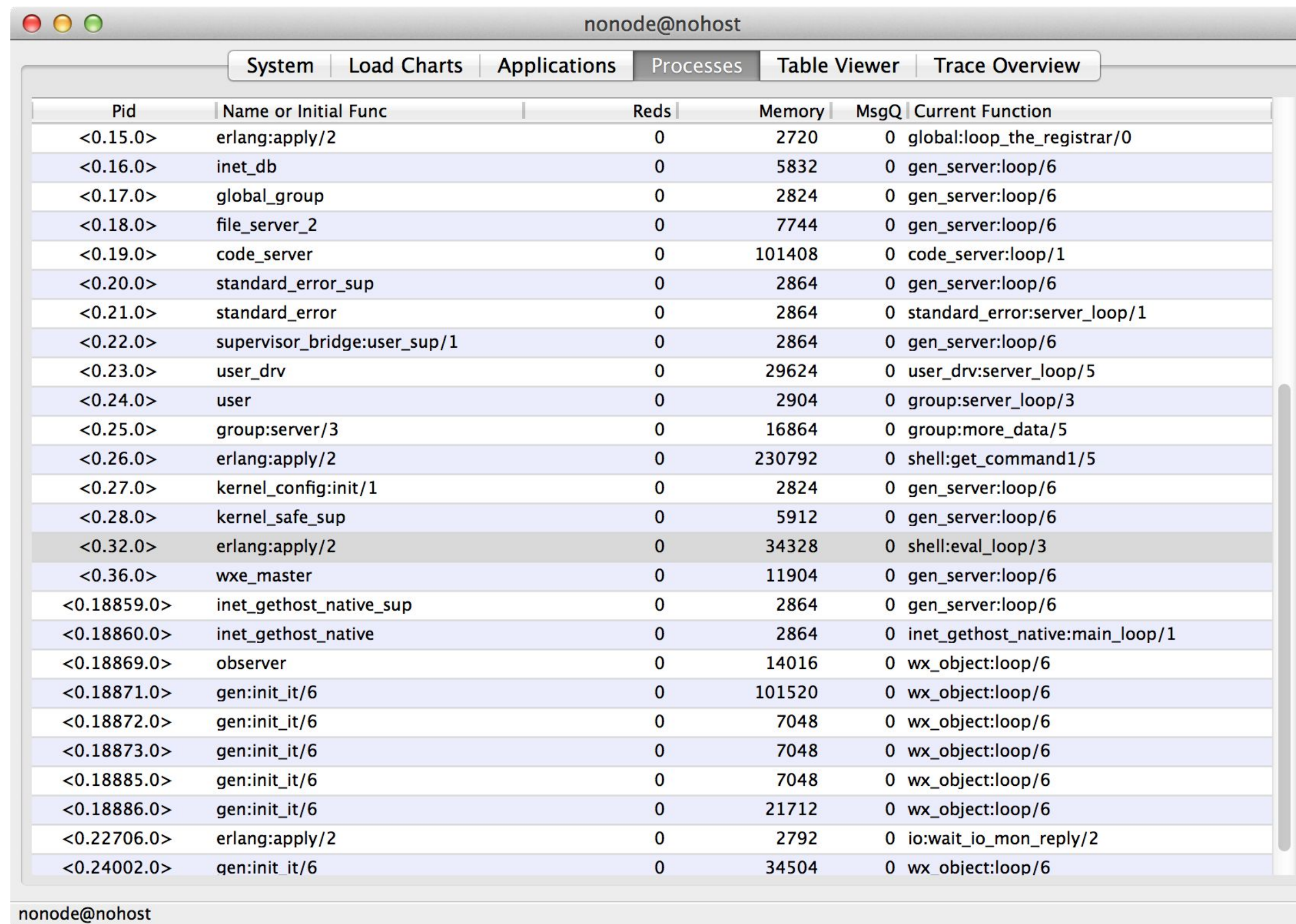
terminate(State) -> clean_up(State).
```



Observer Processes

- ▶ A component of the observer graphical tool used to inspect the state of processes
 - Including processes in connected nodes
- ▶ Trace output for messages sent & received
- ▶ Trace output for process events such as spawn, exit and link
- ▶ Trace output for BIF and function calls
- ▶ Replaces the **pman** tool which was discontinued after R16

Observer Processes

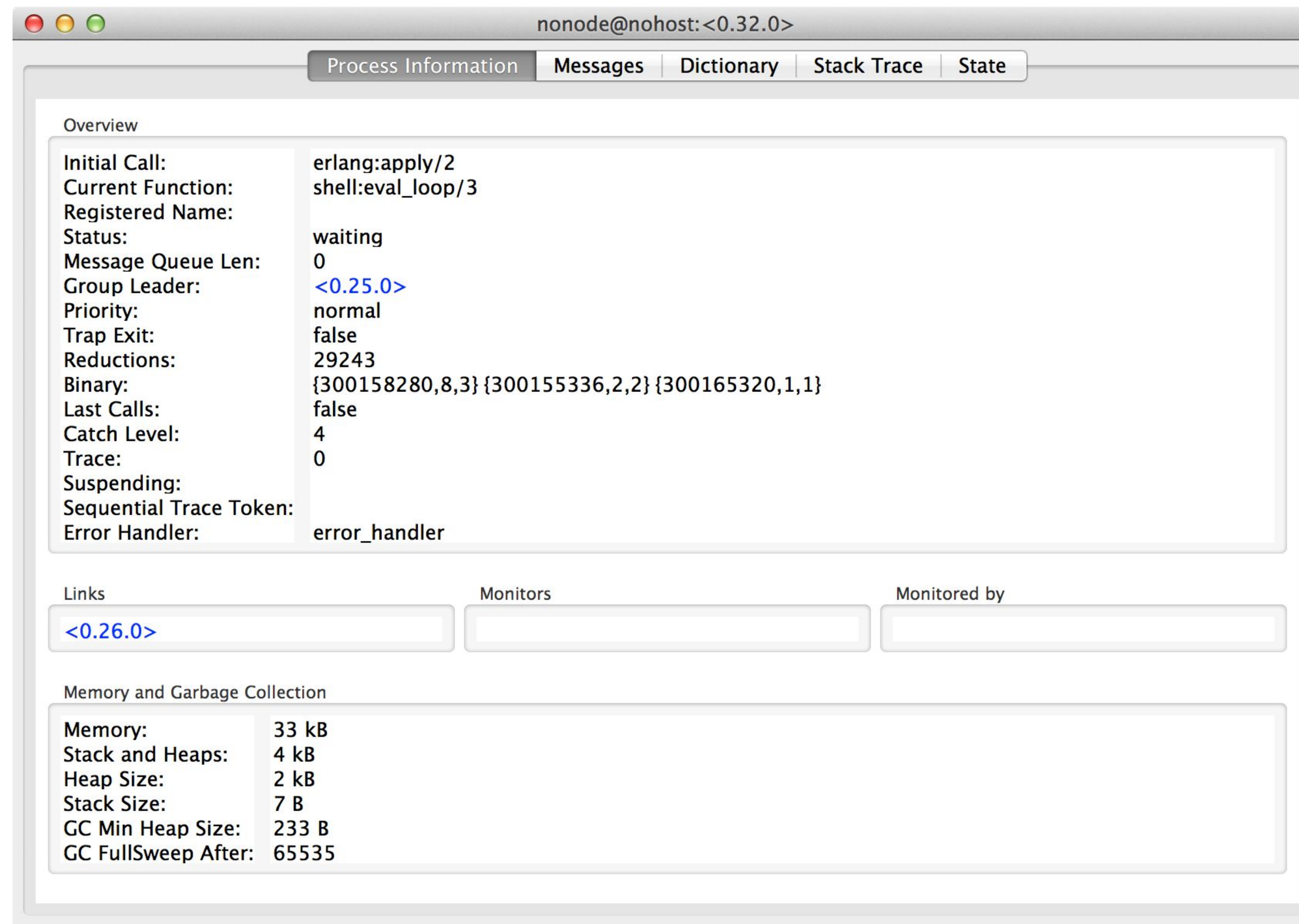


The screenshot shows the Erlang Observer GUI with the 'Processes' tab selected. The window title is 'nonode@nohost'. The table lists various system processes with columns for Pid, Name or Initial Func, Reds, Memory, MsgQ, and Current Function. The 'observer' process (Pid <0.18869.0>) is highlighted in blue.

Pid	Name or Initial Func	Reds	Memory	MsgQ	Current Function
<0.15.0>	erlang:apply/2	0	2720	0	global:loop_the_registrar/0
<0.16.0>	inet_db	0	5832	0	gen_server:loop/6
<0.17.0>	global_group	0	2824	0	gen_server:loop/6
<0.18.0>	file_server_2	0	7744	0	gen_server:loop/6
<0.19.0>	code_server	0	101408	0	code_server:loop/1
<0.20.0>	standard_error_sup	0	2864	0	gen_server:loop/6
<0.21.0>	standard_error	0	2864	0	standard_error:server_loop/1
<0.22.0>	supervisor_bridge:user_sup/1	0	2864	0	gen_server:loop/6
<0.23.0>	user_drv	0	29624	0	user_drv:server_loop/5
<0.24.0>	user	0	2904	0	group:server_loop/3
<0.25.0>	group:server/3	0	16864	0	group:more_data/5
<0.26.0>	erlang:apply/2	0	230792	0	shell:get_command1/5
<0.27.0>	kernel_config:init/1	0	2824	0	gen_server:loop/6
<0.28.0>	kernel_safe_sup	0	5912	0	gen_server:loop/6
<0.32.0>	erlang:apply/2	0	34328	0	shell:eval_loop/3
<0.36.0>	wxe_master	0	11904	0	gen_server:loop/6
<0.18859.0>	inet_gethost_native_sup	0	2864	0	gen_server:loop/6
<0.18860.0>	inet_gethost_native	0	2864	0	inet_gethost_native:main_loop/1
<0.18869.0>	observer	0	14016	0	wx_object:loop/6
<0.18871.0>	gen:init_it/6	0	101520	0	wx_object:loop/6
<0.18872.0>	gen:init_it/6	0	7048	0	wx_object:loop/6
<0.18873.0>	gen:init_it/6	0	7048	0	wx_object:loop/6
<0.18885.0>	gen:init_it/6	0	7048	0	wx_object:loop/6
<0.18886.0>	gen:init_it/6	0	21712	0	wx_object:loop/6
<0.22706.0>	erlang:apply/2	0	2792	0	io:wait_io_mon_reply/2
<0.24002.0>	qen:init_it/6	0	34504	0	wx_object:loop/6

➤ `observer:start()`

Observer Processes



➤ Prints process information

Observer Processes

The screenshot shows the Erlang Observer GUI with the 'Processes' tab selected. A 'Process Options' dialog is open, showing tracing and inheritance settings. The main table lists various processes with their Pids, Names, Redts, Memory, MsgQ, and Current Function.

Process Options Dialog:

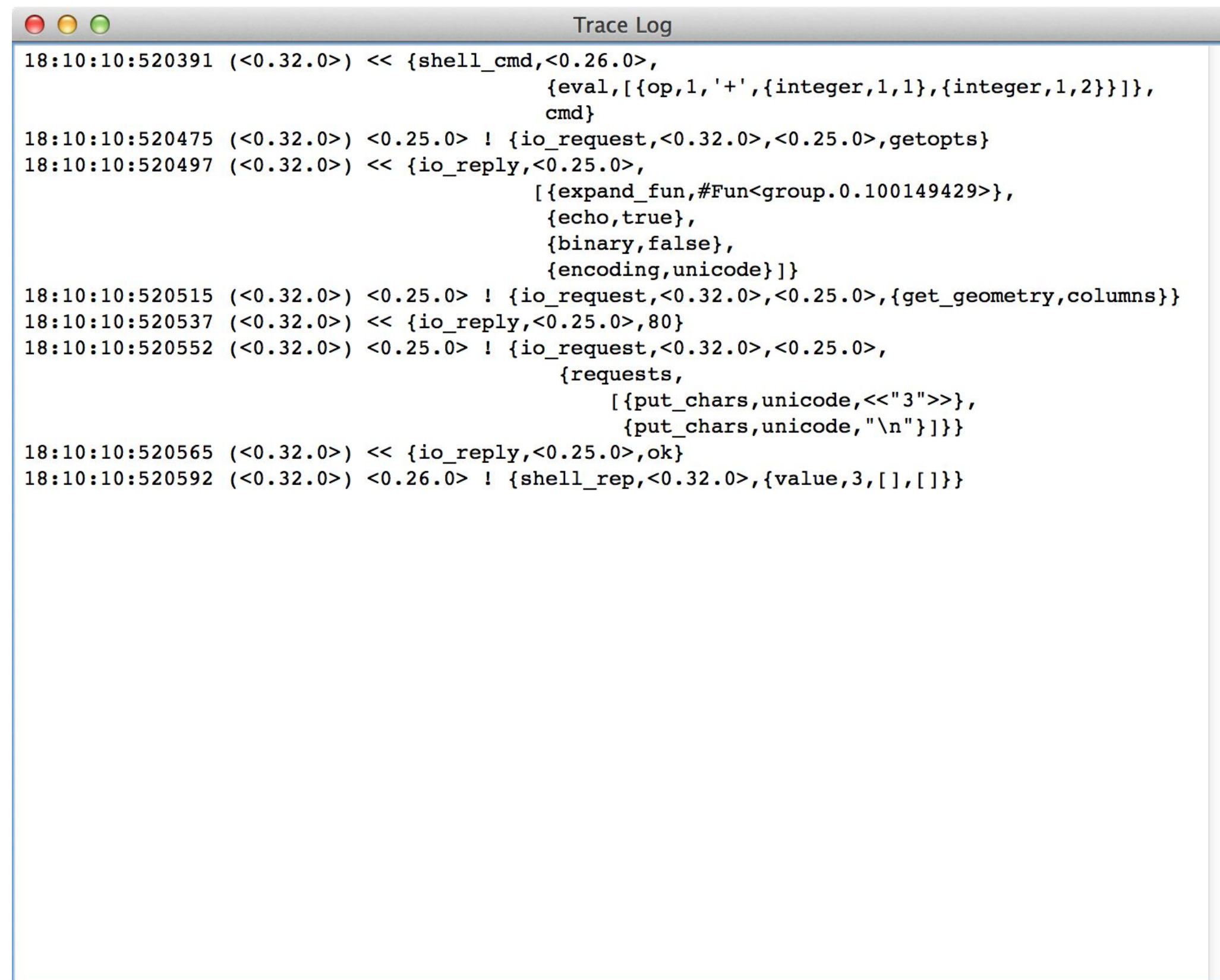
- Tracing options:
 - ☐ Trace function call
 - ☒ Trace send message
 - ☒ Trace receive message
 - ☐ Trace process events
- Inheritance options:
 - ☐ Inherit on spawn
 - ☐ All spawn
 - ☐ First spawn only
 - ☐ Inherit on link
 - ☐ All link
 - ☐ First link only

Processes Table:

Pid	Name or Initial Func	Redts	Memory	MsgQ	Current Function
<0.15.0>	erlang:apply/2	0	2720	0	global:loop_the_registrar/0
<0.16.0>	inet_db	0	5832	0	gen_server:loop/6
<0.17.0>	global_group	0	2824	0	gen_server:loop/6
<0.18.0>	le_server_2	0	7744	0	gen_server:loop/6
<0.19.0>	code_server	0	101408	0	code_server:loop/1
<0.20.0>	standard_error_sup	0	2864	0	gen_server:loop/6
<0.21.0>	standard_error	0	2864	0	standard_error:server_loop/1
<0.22.0>	supervisor_bridge:user_sup/1	0	2864	0	gen_server:loop/6
<0.23.0>	ser_drv	0	29624	0	user_drv:server_loop/5
<0.24.0>	ser	0	2904	0	group:server_loop/3
<0.25.0>	group:server/3	0	16864	0	group:more_data/5
<0.26.0>	erlang:apply/2	0	230792	0	shell:get_command1/5
<0.27.0>	kernel_config:init/1	0	2824	0	gen_server:loop/6
<0.28.0>	kernel_safe_sup	0	5912	0	gen_server:loop/6
<0.32.0>	erlang:apply/2	0	34328	0	shell:eval_loop/3
<0.36.0>	wxe_master	0	11904	0	gen_server:loop/6
<0.18859.0>	inet_gethost_native_sup	0	2864	0	gen_server:loop/6
<0.18860.0>	inet_gethost_native	0	2864	0	inet_gethost_native:main_loop/1
<0.18869.0>	observer	0	14016	0	wx_object:loop/6
<0.18871.0>	gen:init_it/6	0	101520	0	wx_object:loop/6
<0.18872.0>	gen:init_it/6	0	7048	0	wx_object:loop/6
<0.18873.0>	gen:init_it/6	0	7048	0	wx_object:loop/6
<0.18885.0>	gen:init_it/6	0	7048	0	wx_object:loop/6
<0.18886.0>	gen:init_it/6	0	21712	0	wx_object:loop/6
<0.22706.0>	erlang:apply/2	0	2792	0	io:wait_io_mon_reply/2
<0.24002.0>	gen:init_it/6	0	34504	0	wx_object:loop/6

- Pick what trace messages you want to view
- Pick the inheritance level when spawning

Observer Processes



```
Trace Log
18:10:10:520391 (<0.32.0>) << {shell_cmd,<0.26.0>,
                           {eval,[{op,1,'+',{integer,1,1},{integer,1,2}}]},
                           cmd}
18:10:10:520475 (<0.32.0>) <0.25.0> ! {io_request,<0.32.0>,<0.25.0>,getopts}
18:10:10:520497 (<0.32.0>) << {io_reply,<0.25.0>,
                           [{expand_fun,#Fun<group.0.100149429>},
                           {echo,true},
                           {binary,false},
                           {encoding,unicode}}]
18:10:10:520515 (<0.32.0>) <0.25.0> ! {io_request,<0.32.0>,<0.25.0>,{get_geometry,columns}}
18:10:10:520537 (<0.32.0>) << {io_reply,<0.25.0>,80}
18:10:10:520552 (<0.32.0>) <0.25.0> ! {io_request,<0.32.0>,<0.25.0>,
                           {requests,
                           [{put_chars,unicode,<<"3">>},
                           {put_chars,unicode,"\\n"}]}}
18:10:10:520565 (<0.32.0>) << {io_reply,<0.25.0>,ok}
18:10:10:520592 (<0.32.0>) <0.26.0> ! {shell_rep,<0.32.0>,{value,3,[],[]}}
```

- Start tracing in the Trace Overview
- Prints trace information

Summary: **concurrent Erlang**

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