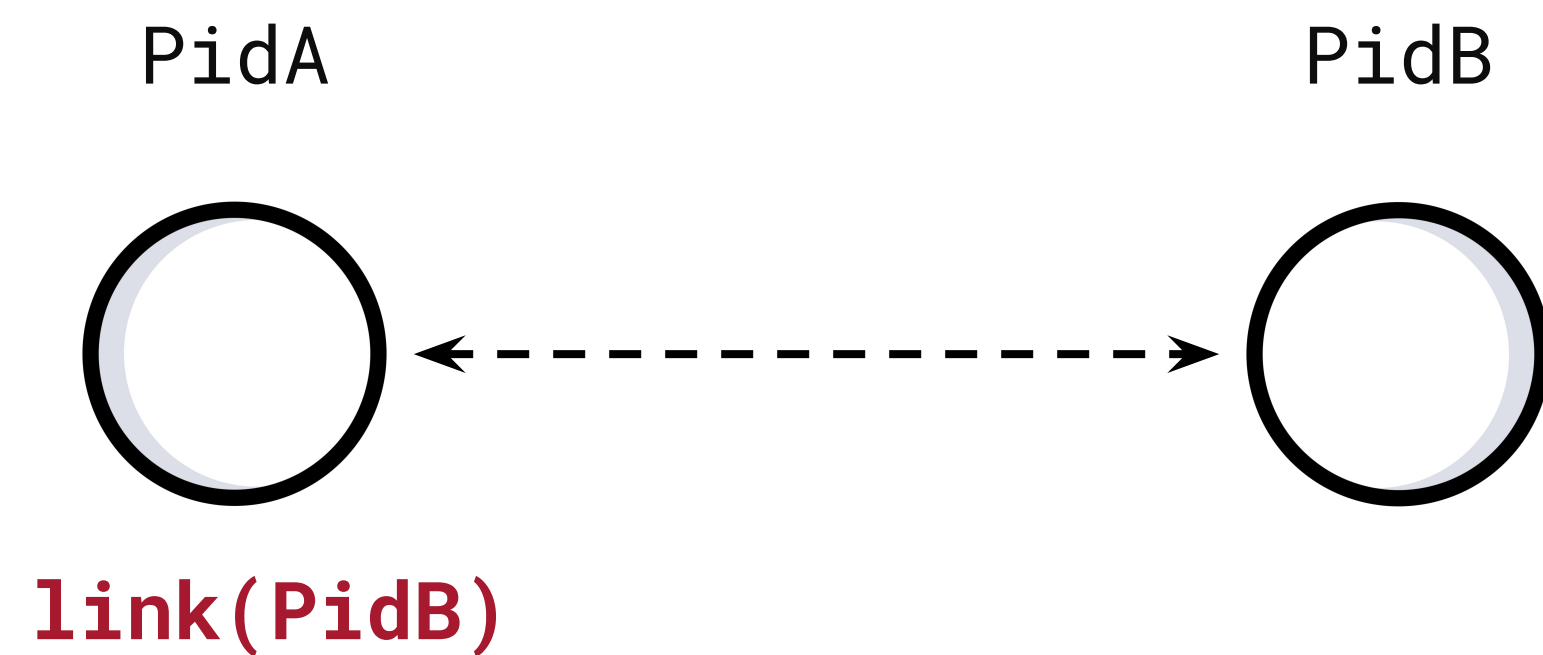


Concurrent Error Handling

Process Error Handling

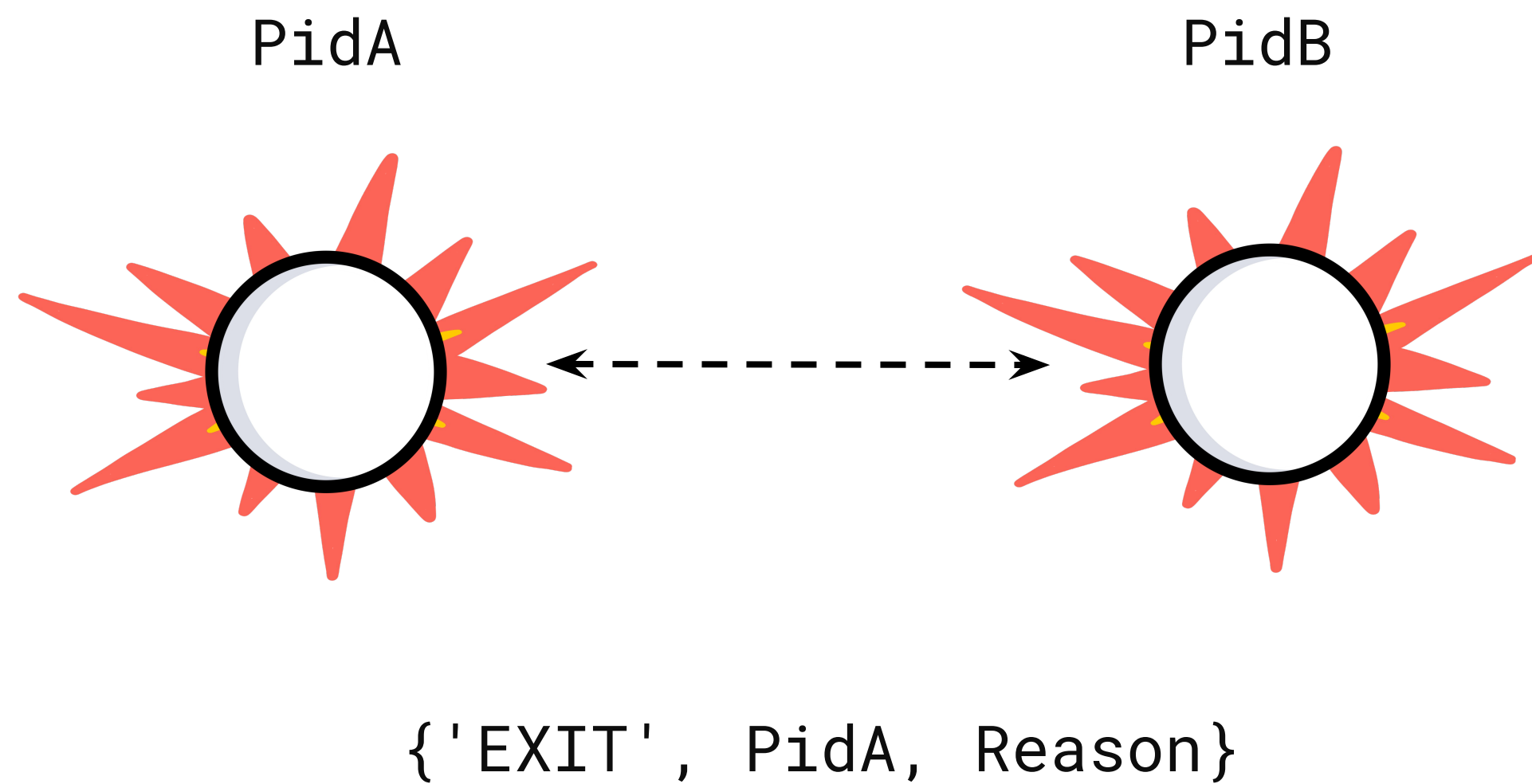
- ▶ Links
- ▶ Exit Signals
- ▶ Definitions
- ▶ Propagation Semantics
- ▶ Monitors
- ▶ Robust Systems
- ▶ Error Handling Example

Links



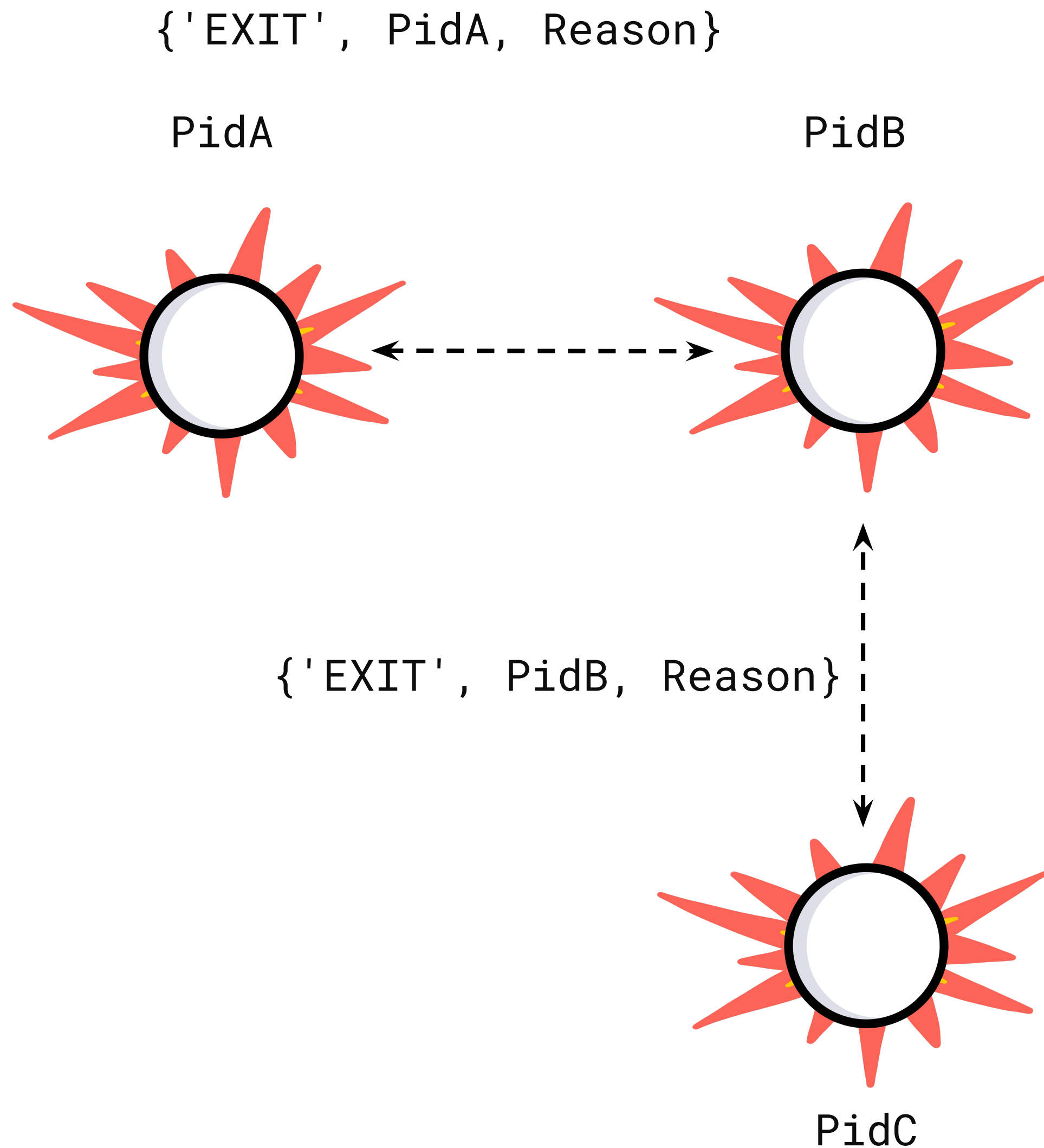
- ▶ **link/1** will create a bi-directional link between the process calling the BIF and the process **PidB**
- ▶ **spawn_link/3** will yield the same result as calling **spawn/3** followed by **link/1**, only that it will do it **atomically**

Exit Signals



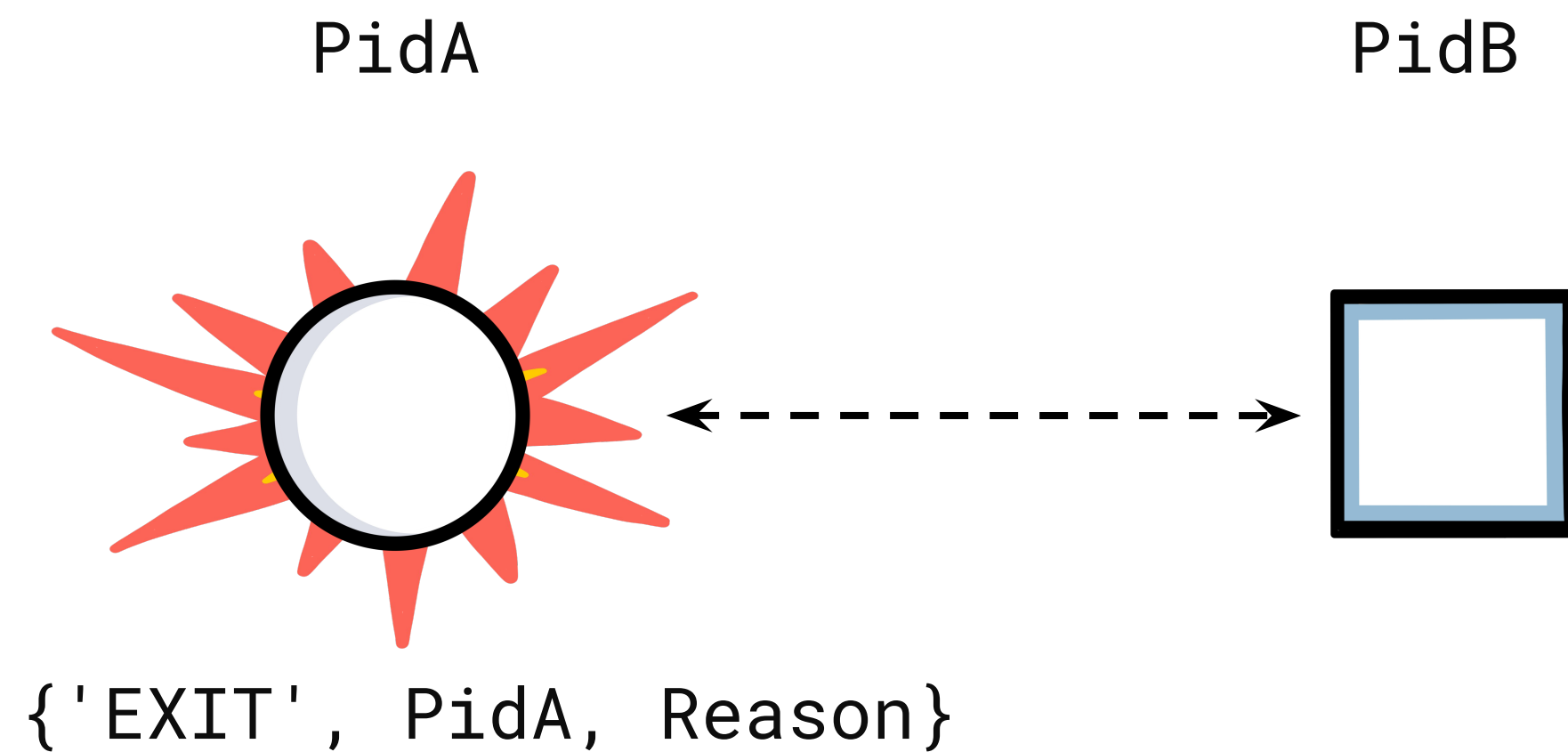
- ▶ **Exit Signals** are sent when processes terminate abnormally
- ▶ They are sent to all processes to which the failing process is currently linked to
- ▶ The process receiving the signal will exit, then propagate a new signal to the processes it is linked to

Exit Signals



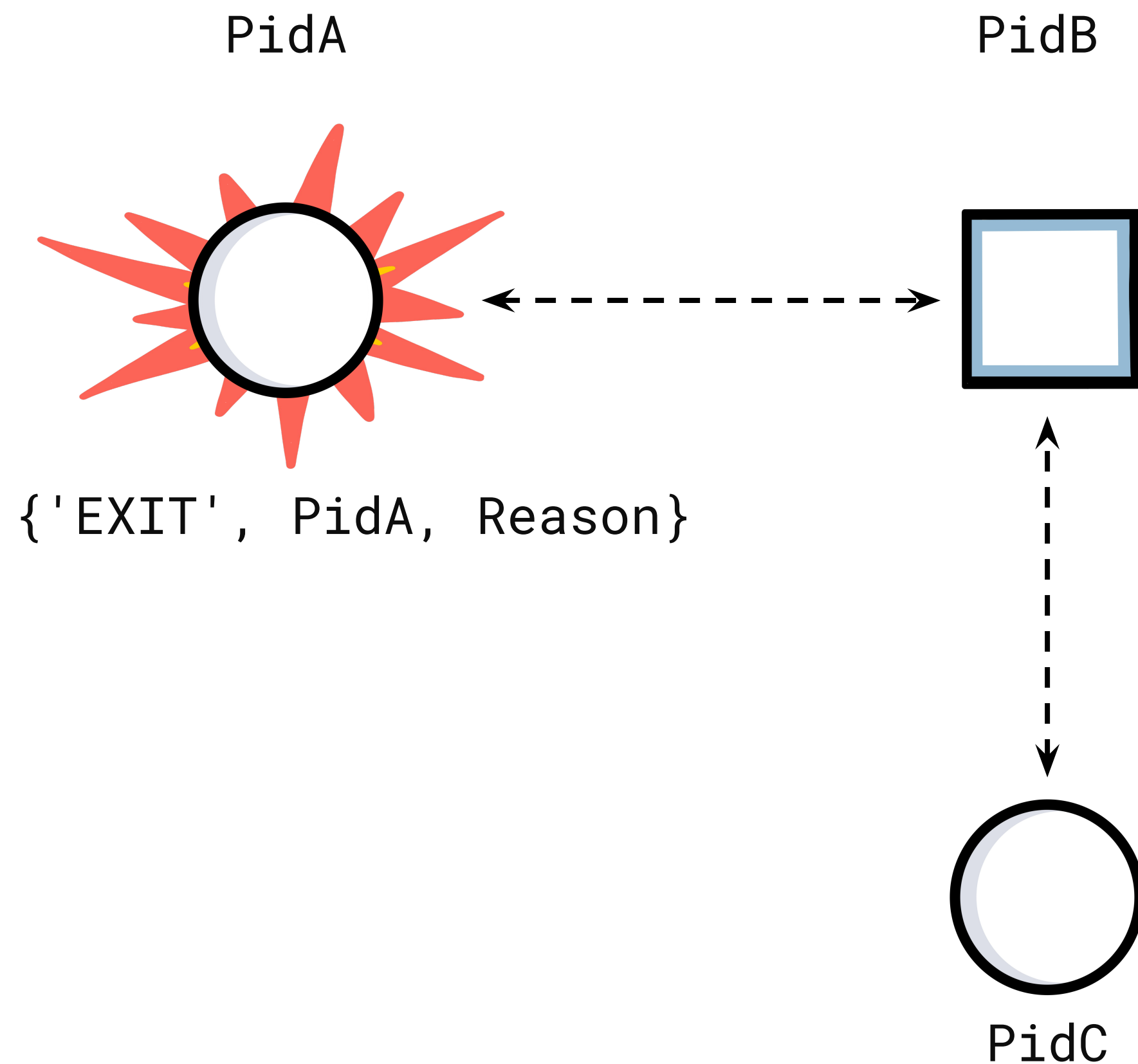
- ▶ When process **PidA** fails, the exit signals propagate to **PidB**
- ▶ From **PidB**, it propagates to **PidC**.

Exit Signals



- ▶ Processes can trap exit signals by calling the BIF **`process_flag(trap_exit, true)`**
- ▶ Exit signals will be converted to messages of the format **`{'EXIT', Pid, Reason}`**
- ▶ They are saved in the process mailbox
- ▶ If an exit signal is trapped, it does not propagate further

Exit Signals



- ▶ Process B marked with a double ring is trapping EXITs
- ▶ If an error occurs in A or C, then they will terminate.
- ▶ Process B will receive the **`{'EXIT', Pid, Reason}`** message
- ▶ The process that did not terminate will not be affected.

Definitions: **terminology**

Link

A bi-directional propagation path for exit signals set up between processes

Exit Signal

An asynchronous signal transmitted by a process upon exiting. It contains termination information

Error Trapping

The ability of a process to handle exit signals as if they were messages

Definitions: **built-in functions**

link(Pid)

Set a link between the calling process and Pid

unlink(Pid)

Removes a link to Pid

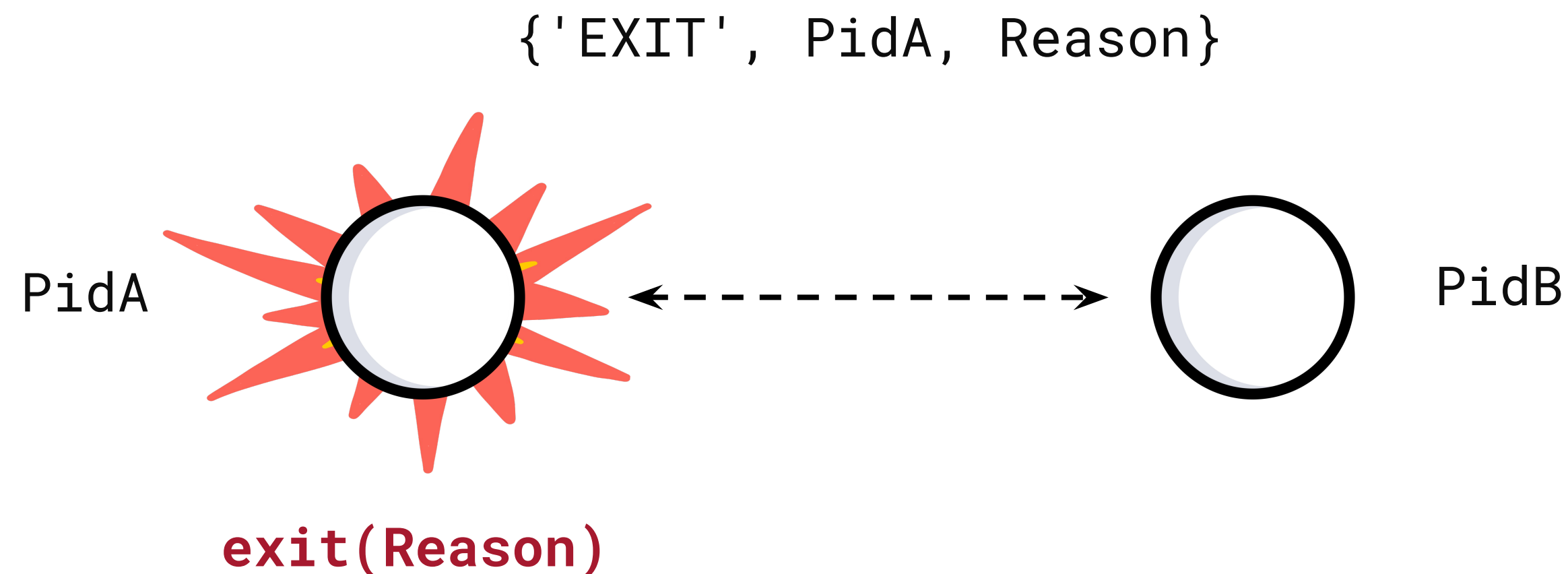
spawn_link(M, F, Args)

Atomically spawns and sets a link between the calling and the spawned processes.

process_flag(trap_exit, Bool)

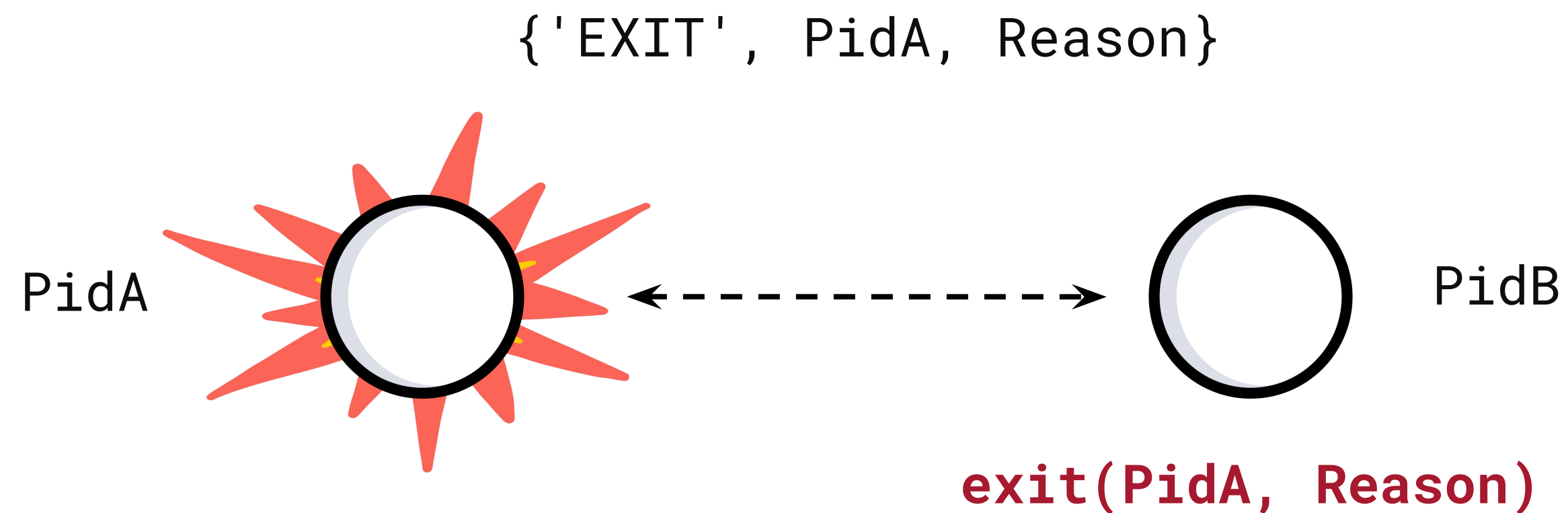
Sets the current process to convert exit signals into exit messages

Definitions: **built-in functions**



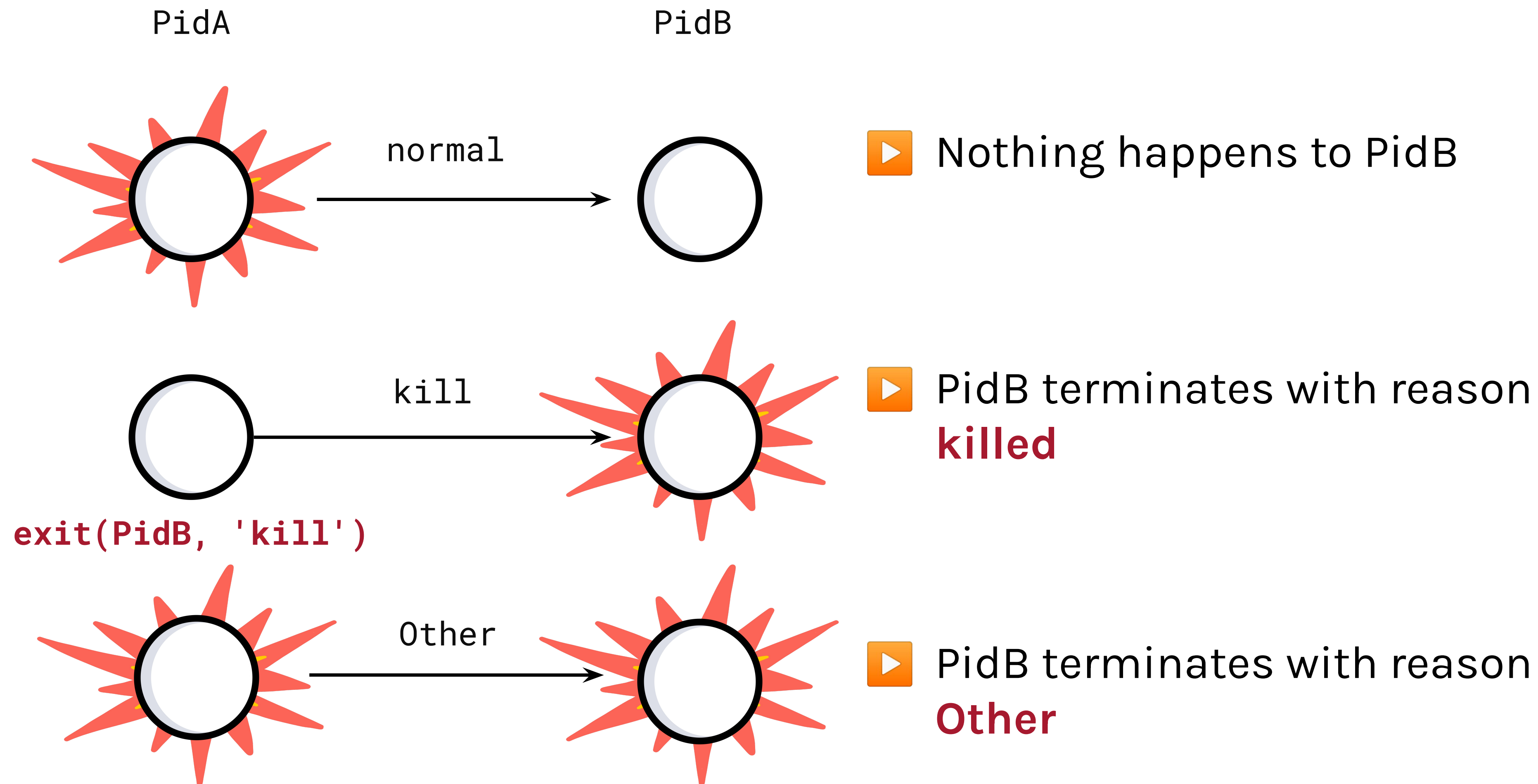
- ▶ The BIF **exit(Reason)** terminates the process which calls it
- ▶ It generates an exit signal sent to linked processes
- ▶ The BIF **exit/1** can be caught in a **try ... catch**.

Definitions: **built-in functions**

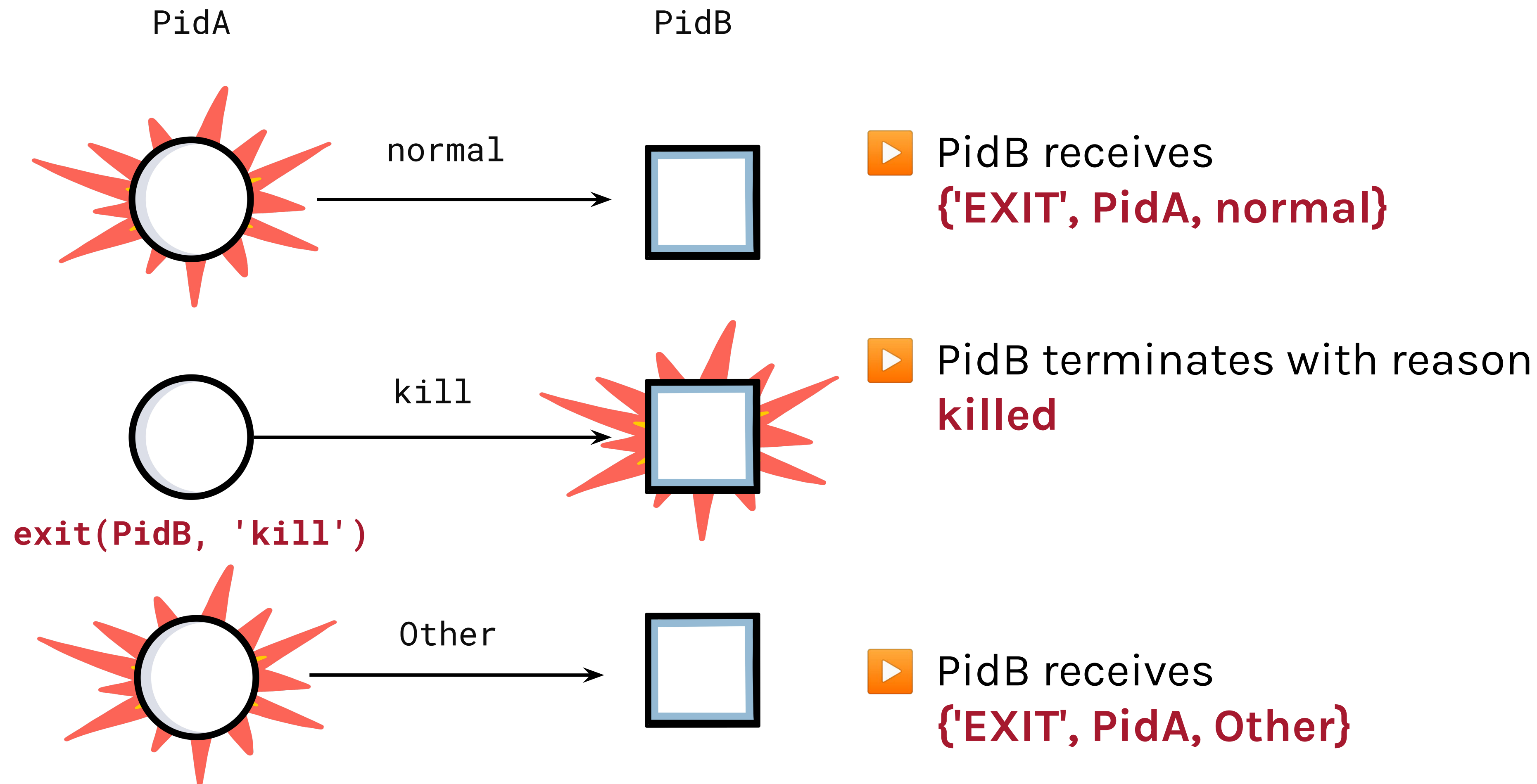


- ▶ **exit(Pid, Reason)** sends an exit signal containing **Reason** to the process **Pid**
- ▶ If PidA is trapping exits, the signal is converted to an exit message

Propagation Semantics: **no trapping**



Propagation Semantics: **trapping exits**



Propagation Semantics

- ▶ When a process terminates, it sends an exit signal to the processes in its link set
- ▶ Exit signals can be **normal** or **non-normal**
- ▶ A process not trapping exits dies if it receives a non-normal one. Normal signals are ignored.
- ▶ A process which is trapping exit signals converts all incoming exit signals to conventional messages handled in a receive statement
- ▶ If the reason is **kill**, the process is terminated unconditionally with reason **killed**

Monitors



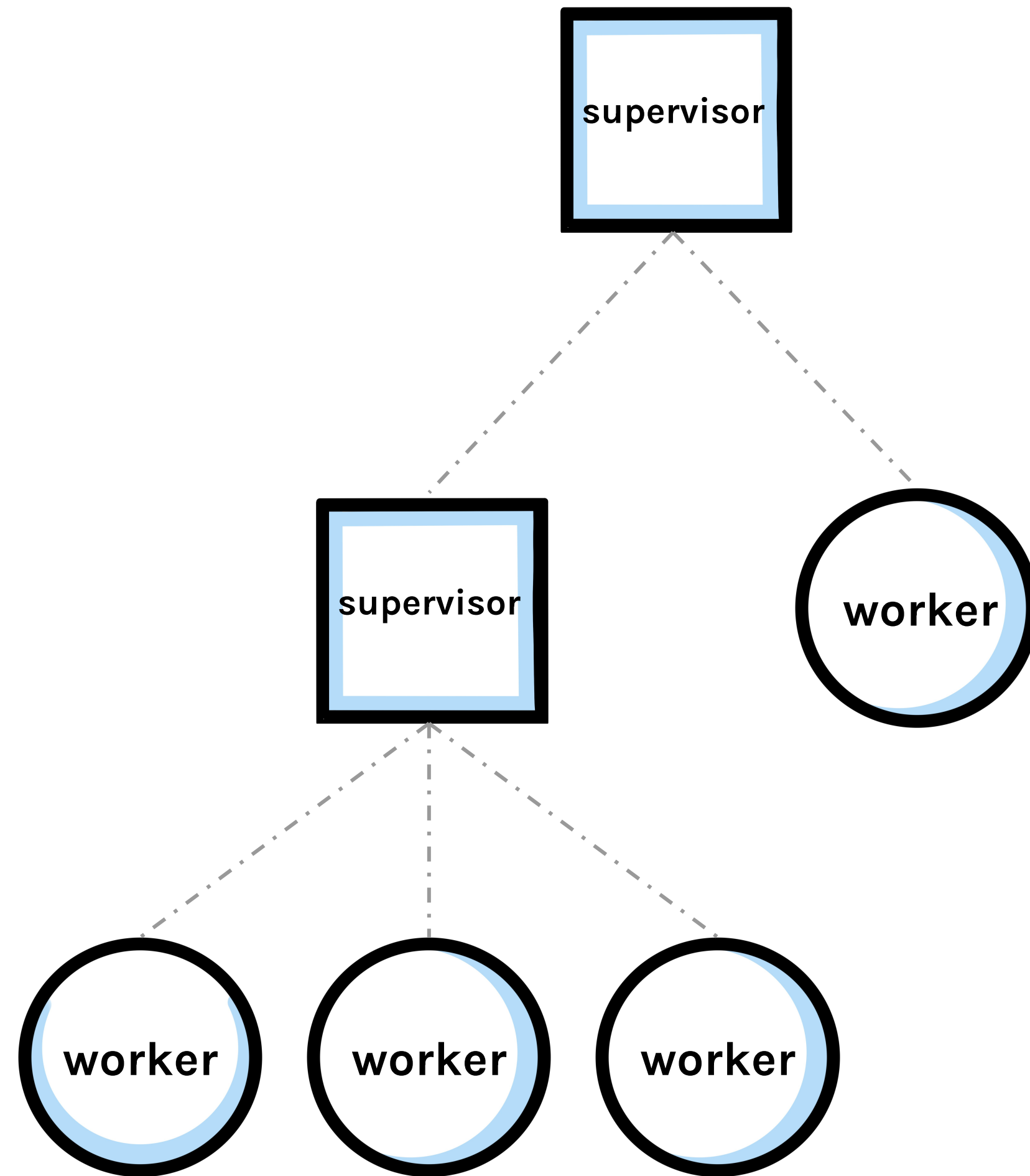
Ref = erlang:monitor(process, PidB)

- ▶ **erlang:monitor/2** will tell the process calling the BIF monitor the process **PidB**. The monitoring is uni-directional and stackable.
- ▶ When process PidB dies then PidA will be sent the message **{'DOWN', Ref, process, PidB, Reason}**
- ▶ A monitor can be turned by calling **erlang:demonitor(Ref)** and **erlang:demonitor(Ref, [flush])**

Robust Systems

- ▶ Building a system in layers can make it robust
 - Level N-1 traps and fixes errors occurring in level N
 - The leaves of the tree are workers
- ▶ In well designed systems, application programmers will not have to worry about error handling code
 - Error handling will be isolated by higher levels of the system, managed uniformly across processes
- ▶ Processes whose only task is to supervise children are called supervisors

Robust Systems



- Robust systems can be designed by layering

A Robust Server

Remember the server example in the process design patterns section? *The Server is unreliable!*

- ▶ Let's rewrite the server making it reliable by monitoring the clients
- ▶ Let's rewrite the clients making them reliable by monitoring the server

A Robust Server

```
-module(frequency).  
-export([start/0, stop/0, allocate/0, deallocate/1]).  
-export([init/0]).
```

```
start() ->  
    register(frequency, spawn(frequency, init, [])).
```

```
init() ->  
    process_flag(trap_exit, true),  
    Frequencies = {get_frequencies(), []},  
    loop(Frequencies).
```

```
get_frequencies() -> [10,11,12,13,14, 15].
```

A Server Example

```
stop()           -> call(stop).  
allocate()       -> call(allocate).  
deallocate(Freq) -> call({deallocate, Freq}).
```

```
%% We hide all message passing and the message protocol in  
%% functional interfaces.
```

```
call(Message) ->  
    Ref = erlang:monitor(process, frequency),  
    frequency ! {request, self(), Message},  
    receive  
        {reply, Reply} ->  
            erlang:demonitor(Ref, [flush]),  
            Reply;  
        {'DOWN', Ref, process, Pid, Reason} ->  
            exit(Reason)  
    end.
```

```
reply(Pid, Message) -> Pid ! {reply, Message}.
```

*Keep race conditions
in mind!*



A Server Example

```
%% The main server loop.

loop(Frequencies) ->
  receive
    {request, Pid, allocate} ->
      {NewFrequencies, Reply} = allocate(Frequencies, Pid),
      reply(Pid, Reply),
      loop(NewFrequencies);
    {request, Pid, {deallocate, Freq}} ->
      NewFrequencies = deallocate(Frequencies, Freq),
      reply(Pid, ok),
      loop(NewFrequencies);
    {request, Pid, stop} ->
      reply(Pid, ok);
    {'EXIT', Pid, Reason} ->
      NewFrequencies = exited(Frequencies, Pid),
      loop(NewFrequencies)
  end.

end.
```

A Robust Server

```
%% The Internal Functions
%% Functions used to allocate and deallocate frequencies.

allocate([], Allocated, Pid) ->
    {[], Allocated}, {error, no_frequencies}};
allocate([Freq|Frequencies], Allocated, Pid) ->
    link(Pid),
    {[Frequencies, [{Freq, Pid}|Allocated]}, {ok, Freq}}.


deallocate({Free, Allocated}, Freq) ->
    {Freq, Pid} = lists:keyfind(Freq, 1, Allocated),
    unlink(Pid),
    NewAllocated = lists:keydelete(Freq, 1, Allocated),
    {[Freq|Free], NewAllocated}.
```


A Robust Server

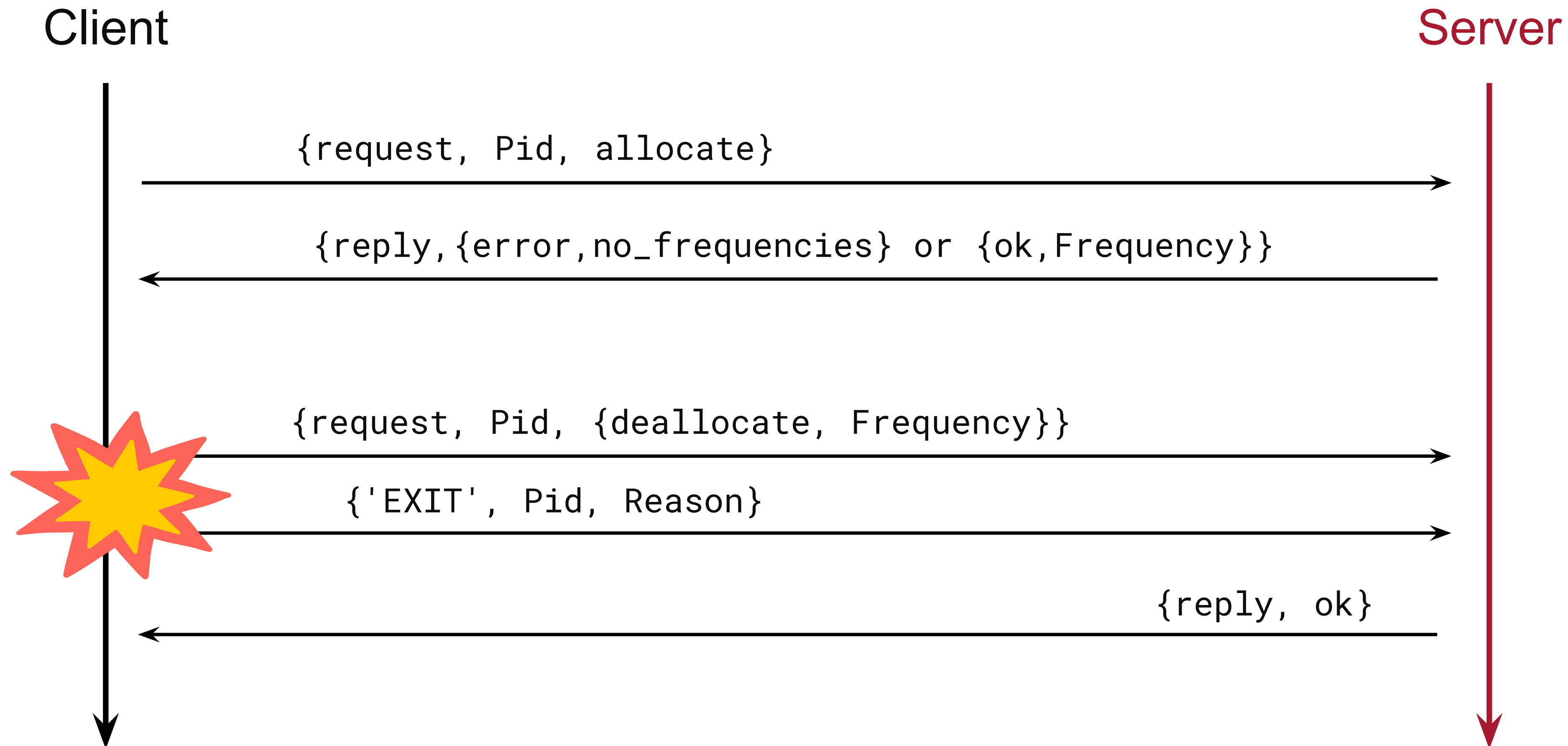
%% Help function used when a client crashes.

```
exited({Free, Allocated}, Pid) ->  
  case lists:keyfind(Pid, 2, Allocated) of  
    {Freq, Pid} ->  
      NewAllocated = lists:keydelete(Freq, 1, Allocated),  
      {[Freq|Free], NewAllocated};  
    false ->  
      {Free, Allocated}  
  end.
```

Keep race conditions in mind!



A Server Example



Process Error Handling

- ▶ Links
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