Alisina Bayati

Ph.D. Candidate — Optimization, Control, and Learning for Dynamical Systems

♦ 348 CSL, Urbana, IL 61801 **→** (+1) 949 522 0972 github.com/alisina75

in linkedin.com/in/alisina-bayati alisina75.github.io

➤ abayati2@illinois.edu

Citizenship: United States | Iran

Profile

Applied mathematics & control/optimization researcher specializing in scalable algorithms for constrained optimization, safety-aware coordination, and sparse learning under evolving data. Proficient in Python, C, statistical modeling, control theory, and high-dimensional numerical methods.

Education

University of Illinois at Urbana-Champaign

Aug 2020- Dec 2026 (expected)

Ph.D. in Mechanical Science & Engineering

Advisor: Prof. Srinivasa Salapaka

University of Illinois at Urbana-Champaign

M.S. in Mathematics

Aug 2023 - Aug 2025 GPA 3.90/4.00

Sharif University of Technology

B.S. in Mechanical Engineering

Advisor: Prof. Hamed Moradi

Aug 2015- Aug 2019 GPA 18.10/20 (3.89/4.00)

Publications

Peer-Reviewed

- [1] A. Srivastava[†], A. Bayati[†]. "Sparse linear regression with constraints: A flexible entropy-based framework." IEEE ECC 2024. [IEEE Xplore]
- [2] A. Bayati, A. Srivastava, A. Malvandi, H. Feng, S. Salapaka. "Towards efficient modularity in industrial drying: A combinatorial optimization viewpoint." IEEE ACC 2023. [IEEE Xplore]
- [3] A. Bayati[†], D. Tiwary[†], S. Salapaka. "A Control Barrier Function Approach to Constrained Resource Allocation Problems in a Maximum Entropy Principle Framework." IEEE CDC 2025 (to appear). [arXiv], **?** Code
- [4] S. Basiri, A. Bayati, S. Salapaka. "Orthogonal non-negative matrix factorization with sparsity constraints." IEEE CDC 2025 (to appear). [arXiv], • Code
- [5] A. Bayati, A. Srivastava, V. Mundada, S. Salapaka, H. Feng, A. Malvandi. "Energy efficiency in industrial drying: A hybrid ultrasonic system with a novel dynamic optimization framework." Energy Conversion & Management. (in press) [DOI]

In Preparation

[6] A. Bayati, A. Srivastava, S. Salapaka. "Dynamic Resource Allocation under Safety and Mobility Constraints: A Maximum Entropy Framework for Multi-Agent Systems."

Experience & Projects

Graduate Research Assistant, SENSIC Lab, UIUC

Sep 2020 - Present

- Control-Theoretic Approaches to Combinatorial Optimization
- Oct 2024 Present
- Designed a dynamic feedback strategy for general constrained optimization problems that provably drives decision variables toward KKT stationarity, with guarantees on asymptotic convergence and feasibility.
- Applied to capacitated facility location problems, achieving up to 20× and 240× speedups over Safe Gradient Flow (Cortés et al.) and SciPy's SLSQP. Paper • Code
- Also applied to orthogonal non-negative matrix factorization with feature sparsity.
- Ongoing work extends to dynamic settings, where the objective and constraints evolve over time (e.g., collision-avoidance constraints in multi-agent systems), and the goal is to continuously track the moving optimizer in real time.
- Energy-Efficient Optimization for Hybrid Drying Systems

Sep 2020 - Present

- Developed a mixed-integer, multi-stage optimization framework for ultrasonic/convective drying, reducing energy consumption by 13% relative to the static single-stage baseline while satisfying key product quality constraints (e.g., color, moisture). Results under review at the *Journal of Energy Conversion and Management*.
- Currently extending to a smart drying setup involving multiple drying technologies, jointly optimizing the sequence of operations and their conditions.
- Also integrating mesh-based GNNs trained offline to replace CFD/statistical models and support fast, differentiable inference.

• Routing Optimization in Residential Wi-Fi Mesh Networks

Sep 2021 - Sep 2023

- Built a real-time digital twin for Wi-Fi mesh networks using permutation-invariant DNNs; solved large-scale placement and routing problems.
- Achieved latency in the lowest 3rd percentile across 50,000 uniformly sampled brute-force configurations.
- Funded by Foxconn Interconnect Technology (FIT).

Graduate Teaching Assistant, UIUC

Spring 2023, 2024

- Courses: ME 340 (Dynamics), TAM 210/211 (Statics and Intro to Dynamics)
 - Ranked as "Excellent Teaching Assistant" based on campus-wide student evaluations for Spring 2024.

Undergraduate Researcher, Sharif University of Technology

Sep 2018 - Jun 2019

- Optimal Control of Drug Delivery in Nonlinear Cancer Models
 - Designed optimal PID controllers for nonlinear cancer-tumor drug-delivery models in MATLAB/Simulink, minimizing side effects while reaching the target tumor volume.
 - Conducted as part of the Process Control Lab under Prof. Hamed Moradi

Selected Graduate Coursework

Mathematics

- Real Analysis
- Functional Analysis
- Random Processes
- Vector-Space Optimization
- Abstract Linear Algebra
- Abstract Algebra

Machine Learning & Statistics

- Statistical RL
- Machine Learning
- Computer Vision
- Statistics & Probability

Control & Systems

- Optimal Control Theory
- Nonlinear Systems
- Linear Control Systems
- Dynamic Programming

Honors & Awards

• CDC Student Travel Award, IEEE Conference on Decision and Control

2025 Spring 2024

• Teachers Ranked as Excellent, University of Illinois Urbana-Champaign

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• ACC Student Travel Award, American Control Conference

2023

• First-Year Fellowship, Department of Mechanical Science and Engineering, UIUC

2020

• Top 0.2% National Rank among 182,000 participants in Iran's Nationwide University Entrance Exam (Math & Physics)

Technical Skills

Programming Python (NumPy, pandas, PyTorch, SciPy, CVXPY, scikit-learn), MATLAB, C/C++,

Git, LATEX

Quantitative Stochastic processes, Optimal control, Convex/non-convex optimization, Monte Carlo

simulation, Time-series analysis

Tools Jupyter, Simulink, OpenCV

Languages Persian (native), English (fluent), Arabic (elementary)

Service

• Peer Reviewer, ACC, ECC, CDC

2023-Present

References

Prof. Srinivasa M. Salapaka

Dept. of Mechanical Science & Engineering & Coordinated Science Lab, UIUC salapaka@illinois.edu

 ${\bf Additional\ references\ available\ upon\ request.}$