

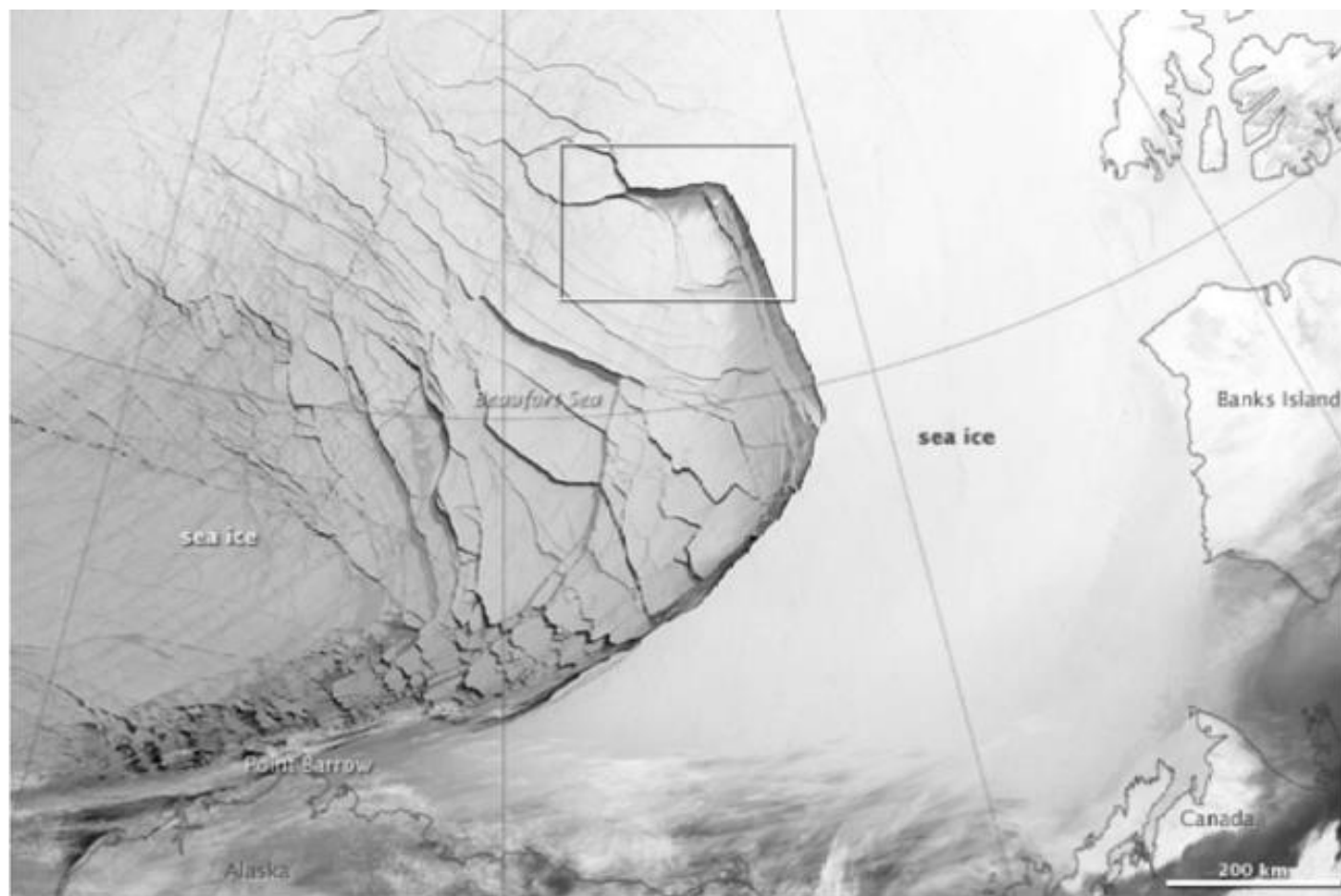
A Spatio-Temporal Model for Arctic Sea Ice

Alison Kleffner, Susan VanderPlas, Yawen Guan
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Introduction

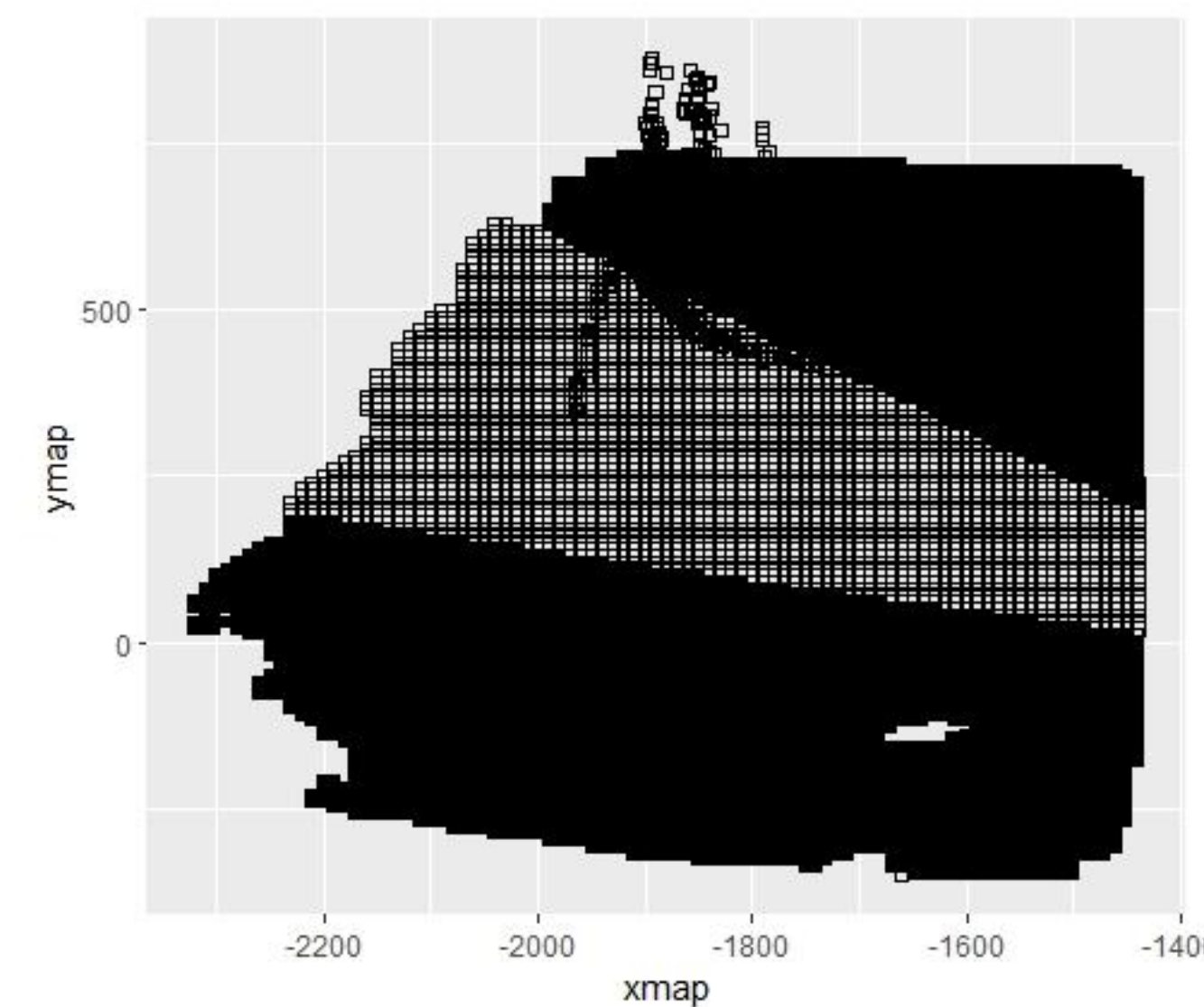
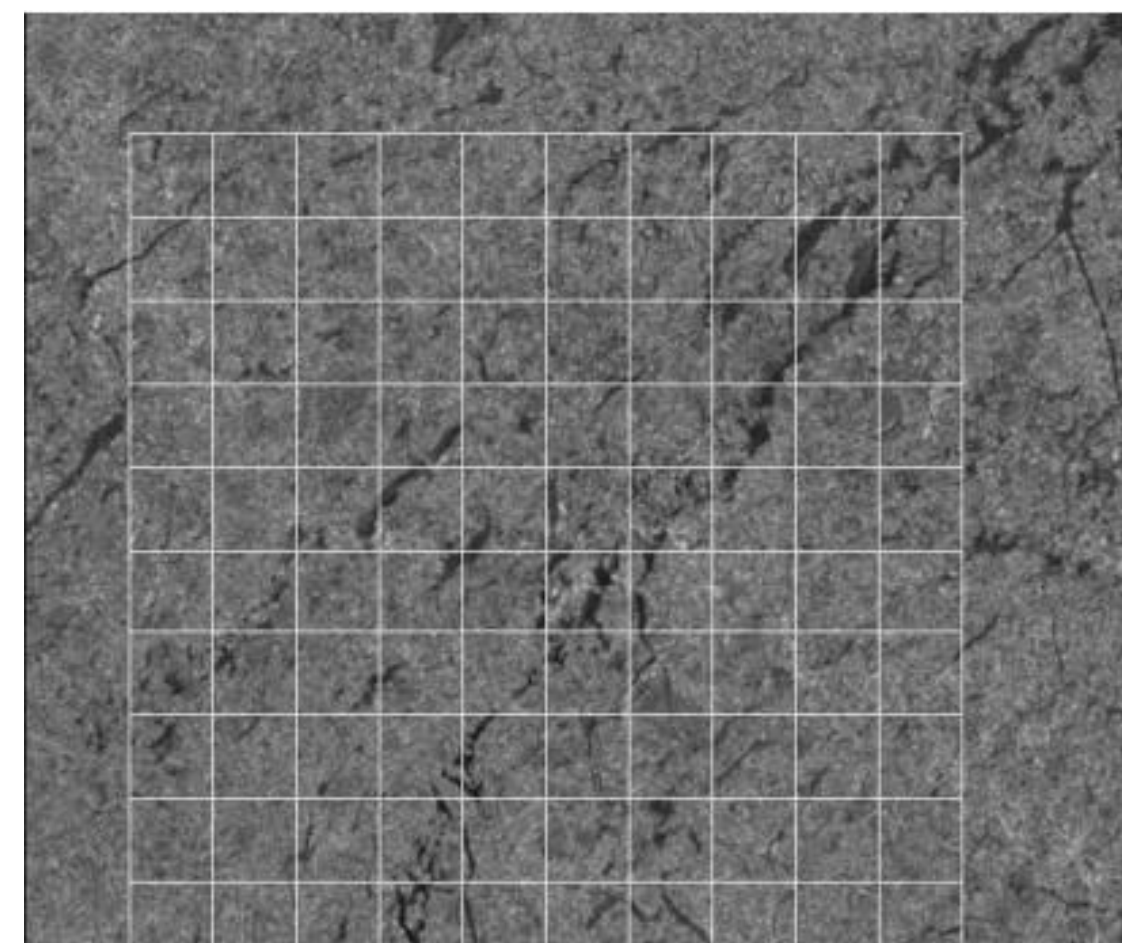
- Sea ice is frozen water in the Arctic Ocean that generally occurs as an ice pack which can drift over the oceans surface
- Cracks, or leads, may form in the ice pack due to dynamic processes
 - Allows for heat from the ocean to be transferred to the atmosphere



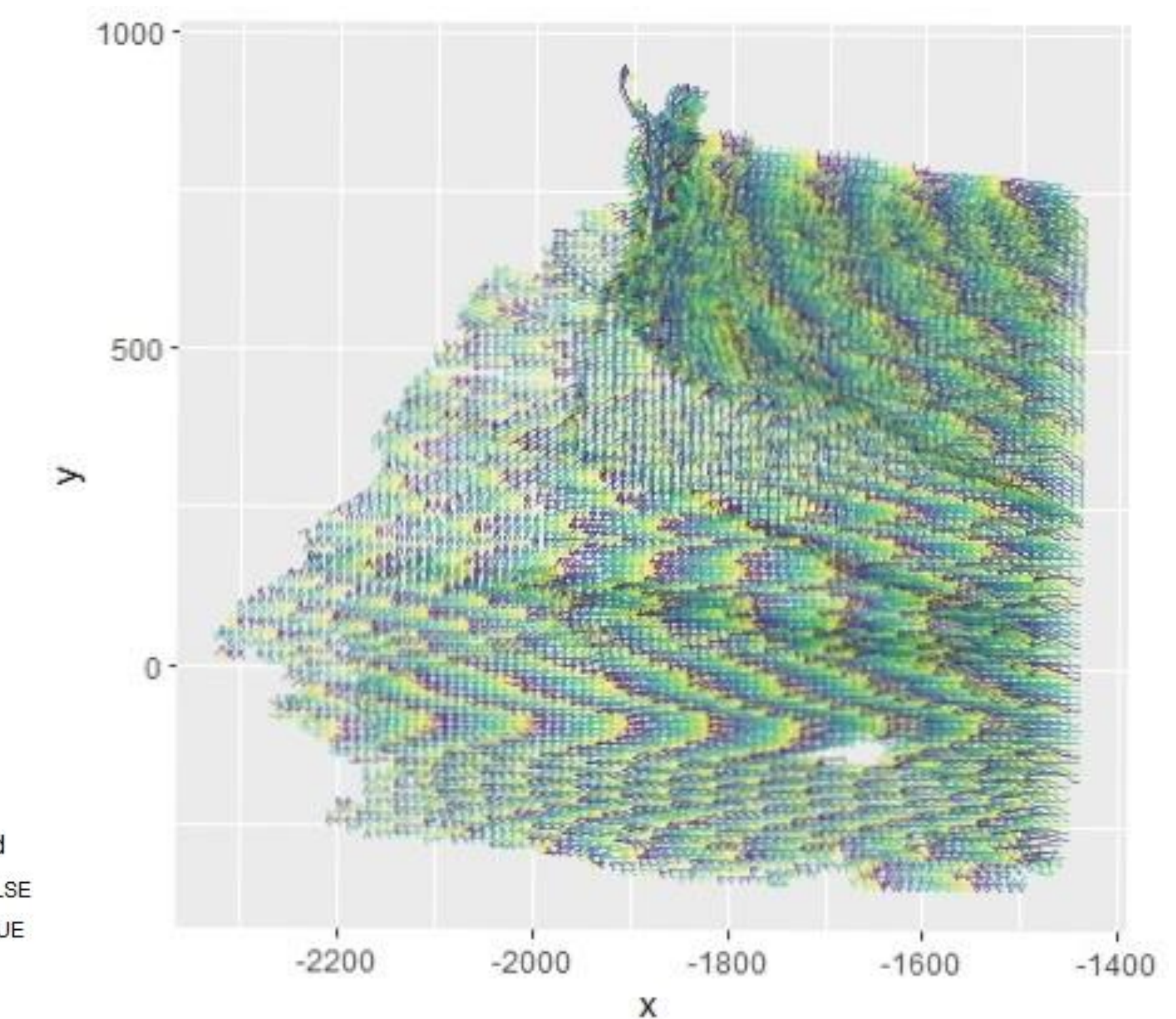
- Other Ice Lead detection methods through satellite images
 - Thermal Images
 - Deformation Calculations
- Satellite data can be low in resolution and are affected by atmospheric conditions (clouds, etc.)

Data

- Used motion data from the RADARSTAT Geophysical Processing System (RGPS)
- The movement of sea ice is tracked in sequential radar images
- Due to this data collection, data may be missing



Method Motivation



- Groups of movement patterns within the ice pack.
- Trajectories in the ice sheet can be grouped together when have similar movement.

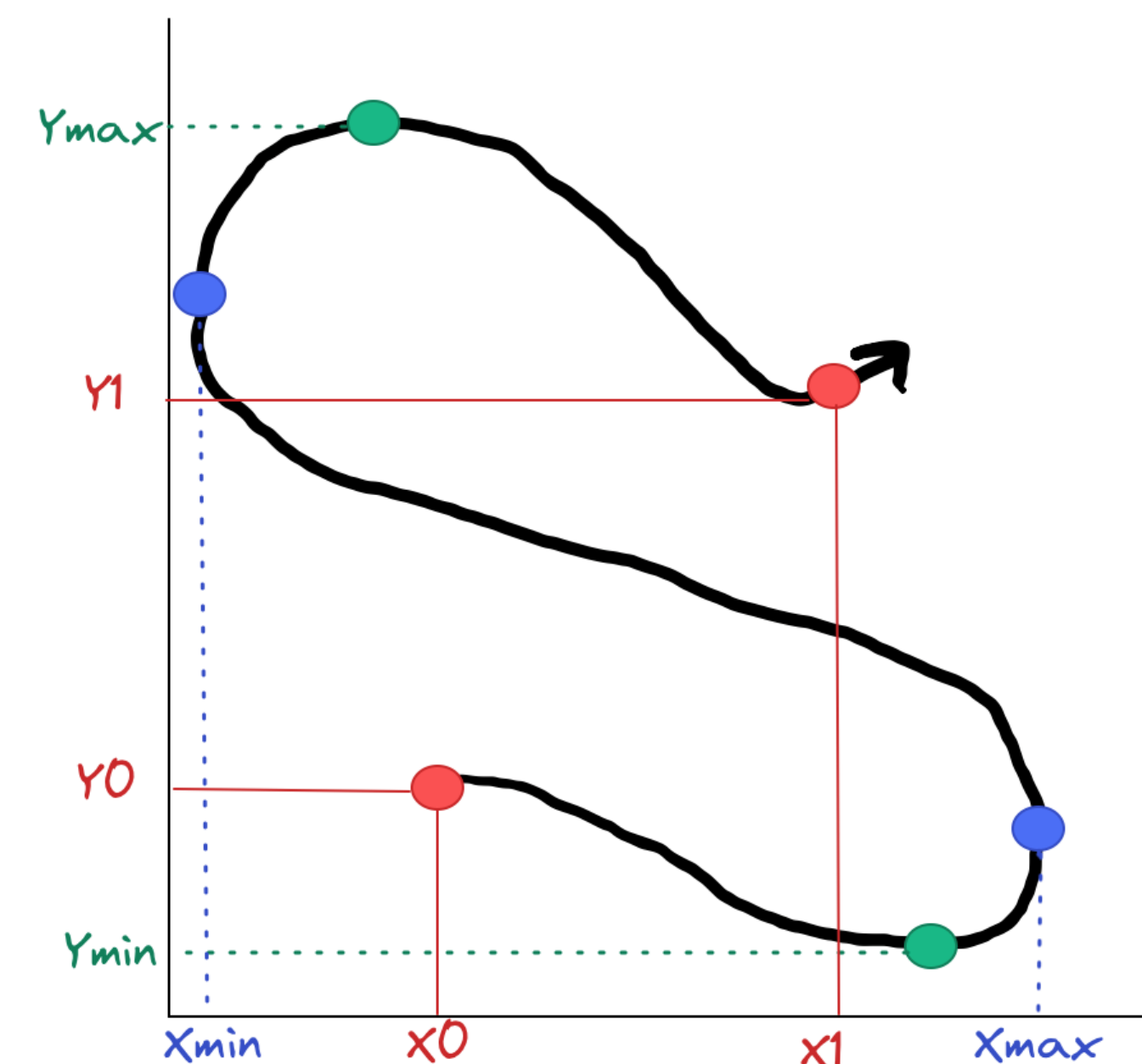
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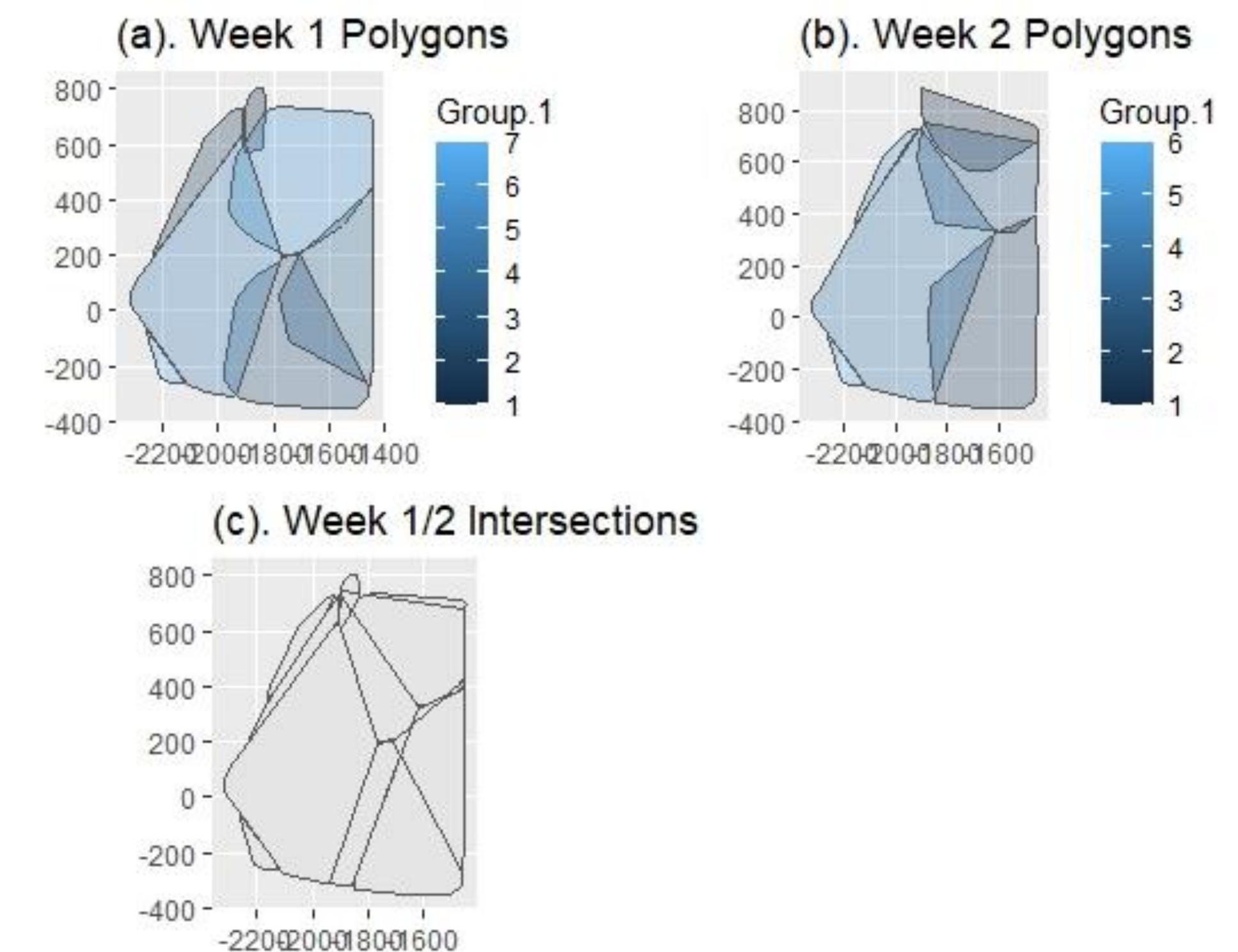
Clustering: Using Bounding Box

- Created a bounding box around each trajectory, to represent the movement of the trajectory over time.
- Features used:
 - Length of x/y traveled (between max and min location)
 - $x_{max} - x_{min}, y_{max} - y_{min}$
 - Difference in x/y from latest to earliest observation
 - $x_1 - x_0, y_1 - y_0$
 - Angle of movement
 - Average x/y value
 - Sub-trajectories – previous time information
- Then used K-means clustering
 - Number of clusters found using Silhouette Statistic



Spatio-Temporal Interpolation

- Define the spatio-temporal neighbors for each missing point, using our previously made clusters



- Member of an intersection are considered spatio-temporal neighbors, because in similar geographic region over time.
- Created univariate models for x and y using the GpGp package in R, which uses the Vecchia's approximation, using the exponential space-time covariance function. Output is the MLE of mean and covariance parameters.
- Use Model to predict missing locations and on the grid.

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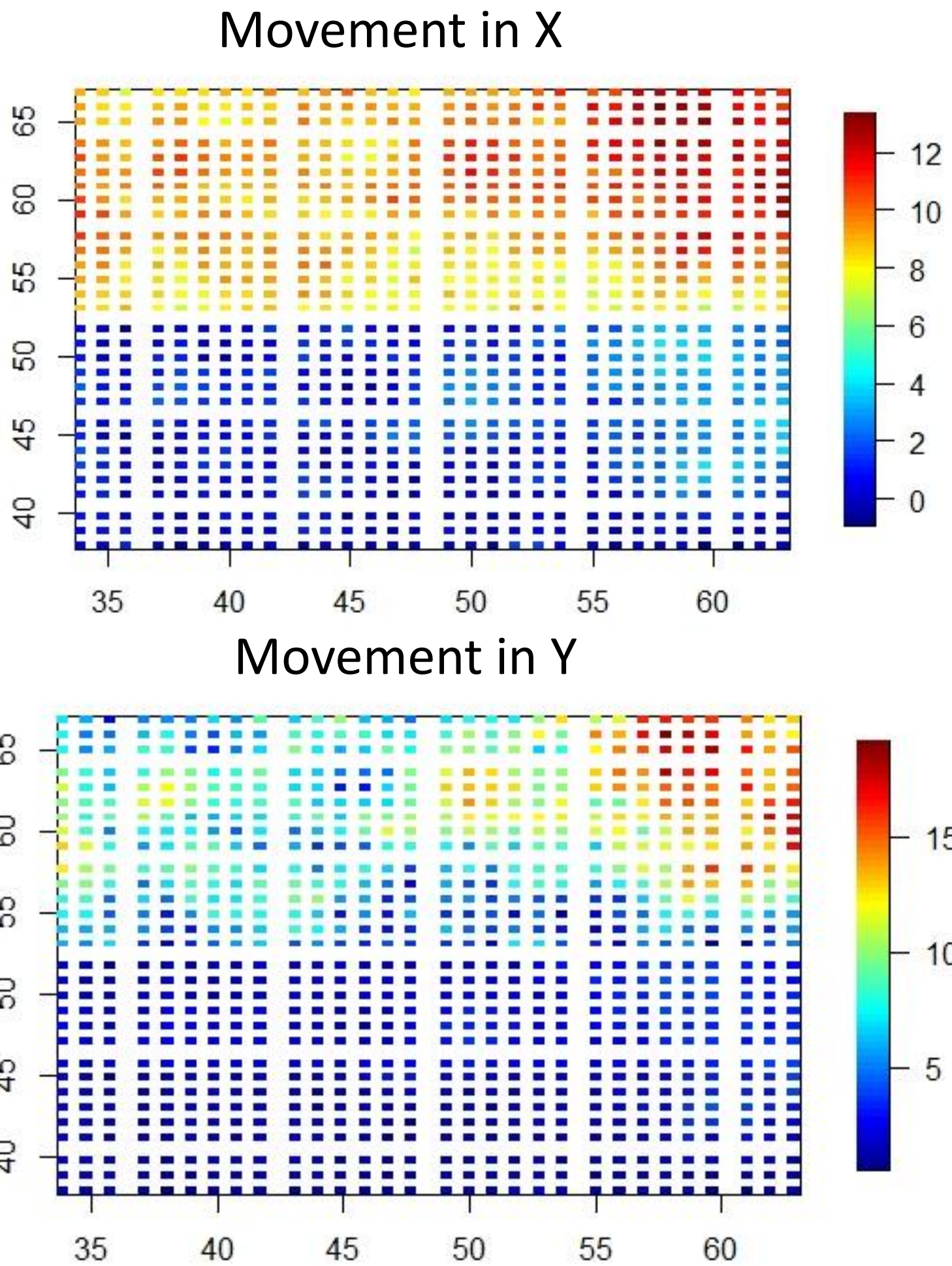


Simulation Study

1. Generate Underlying Process:

$$U_{d,c}(s,t) \sim GP(\mu_{d,c}, C_{d,c}(\theta)),$$
$$C_{d,c}(\theta) = \sigma^2 e^{-||D^{-1}(x-y)||},$$

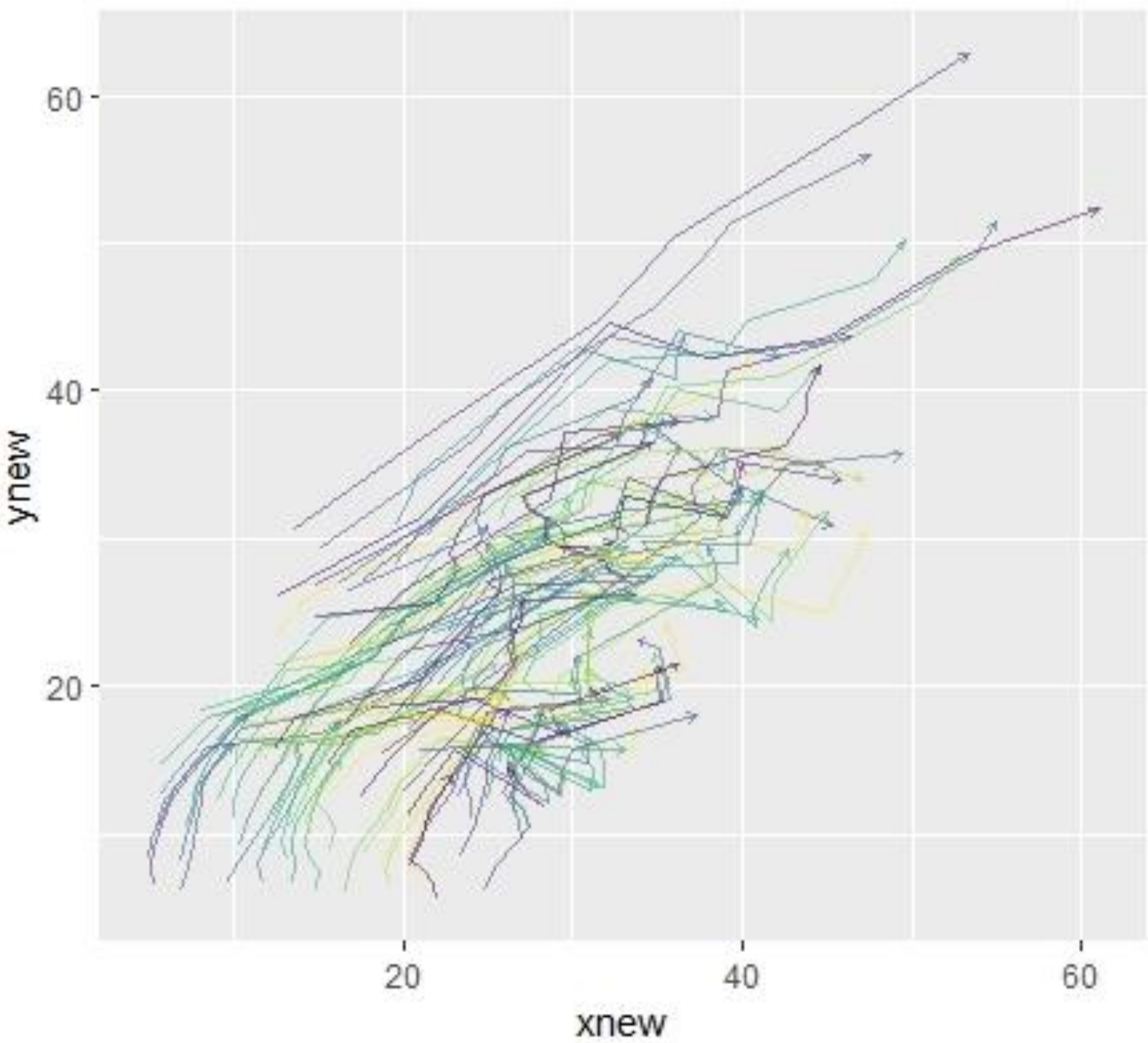
d=x,y c = 1,2



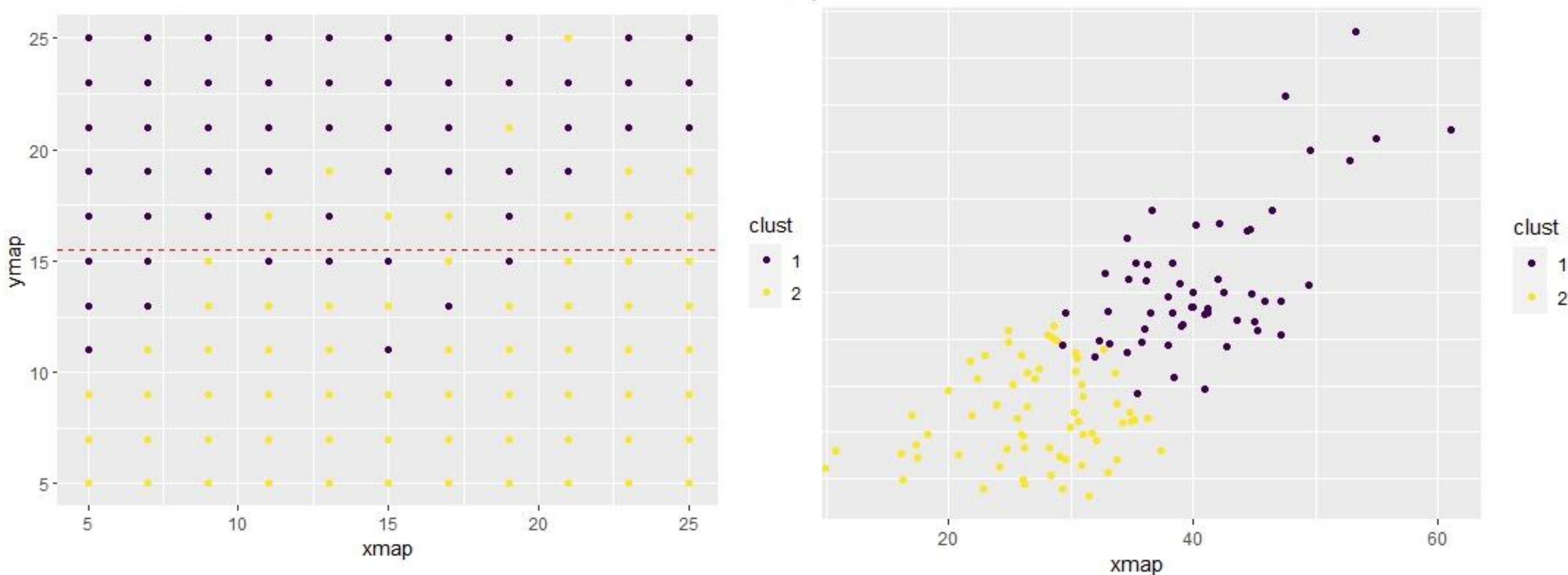
2. Generate Trajectories using Underlying Process

$$(x_{t,j}, y_{t,j}) = (U_{t-1,c,g}^X, U_{t-1,c,g}^Y) + (x_{t-1,j}, y_{t-1,j}),$$

j = 1,...,121 t = 1,...,7 g = 1,...,900



3. Results



RMSE for Interpolation Methods						
	Intersection Model		Linear Interpolation		No Intersection Model	
	X	Y	X	Y	X	Y
Overall	1.388	1.304	2.7	1.83	1.441	1.493
Cluster 1	1.38	1.16	3.1	2.18	1.457	1.664
Cluster 2	1.402	1.53	1.39	0.35	1.423	1.261

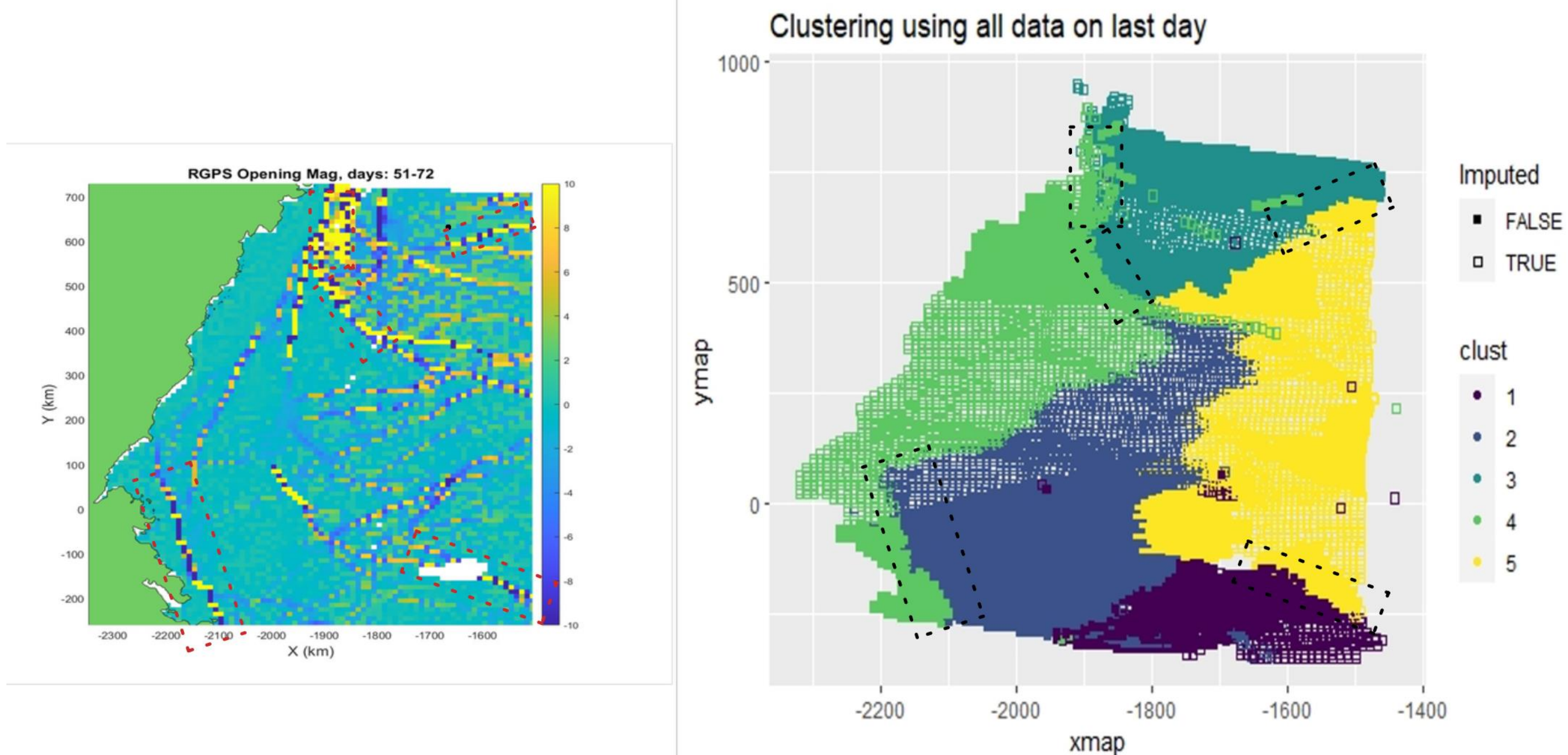
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Ice Data Results

- Clustering:



- Interpolation Cross Validation :
 - Used data in intersection from day before and day after to develop model
 - Compared to Linear Interpolation, and running the model using all the data from the week (no intersections)

RMSE for Interpolation Methods						
	Intersection Model		Linear Interpolation		No Intersection Model	
Week	X	Y	X	Y	X	Y
1	3.156	3.24	1.52	4.098	3.093	3.067
2	3.142	3.062	1.984	1.399	3.198	3.151
3	3.178	3.093	0.987	1.189	3.19	3.15

RMSE for Week 1 by Cluster						
	Intersection Model		Linear Interpolation		No Intersection Model	
Cluster	X	Y	X	Y	X	Y
1	3.018	4.333	3.199	13.042	2.515	3.41
2	4.376	4.633	0.187	0.359	4.258	4.106
3	2.641	3.144	1.314	3.066	2.163	2.883
4	3.024	2.873	1.396	2.442	2.46	2.777
5	3.925	3.586	0.74	3.036	3.895	3.241
6	3.143	3.08	1.876	5.459	2.597	3.098

Conclusion

- Bounding Box method is limited by pre-defined number of clusters, but seems to discover large ice leads. Should be used in conjunction with other ice lead detection methods
- Intersection Interpolation Method shows promise over linear interpolation when data is not linear. Some issues in model creation – like if not enough known data in that intersection for a given time, large temporal range, etc.

References

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