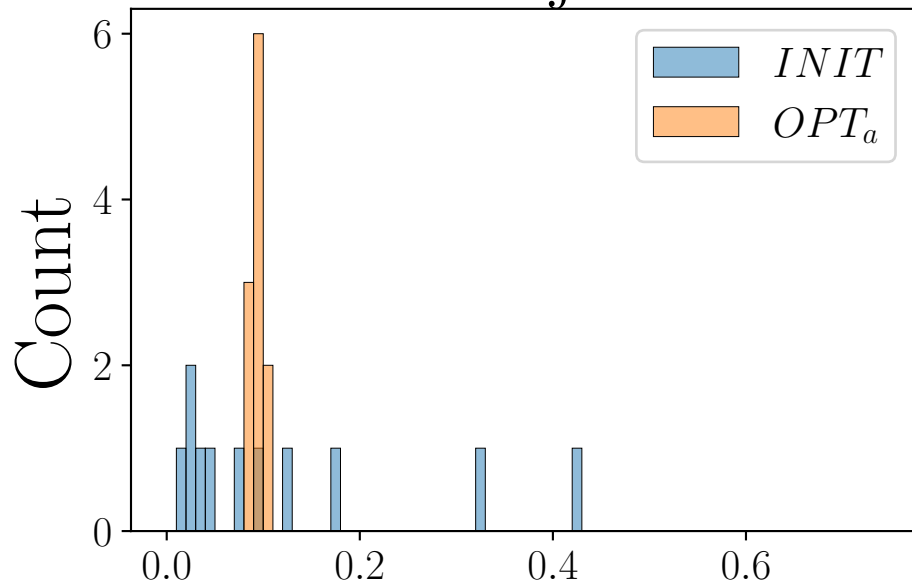
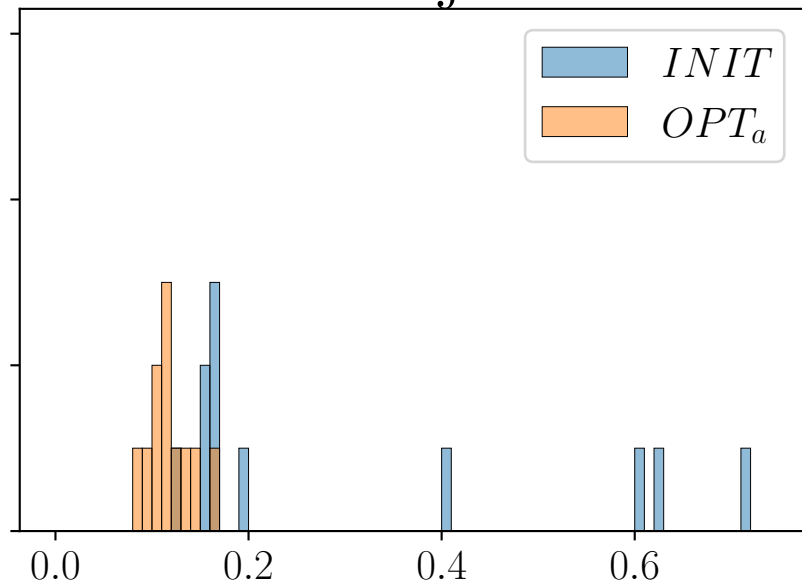


# Traj1 Gazebo



# Gazebo

# Traj2



Distance to the desired target  $r_d(t_w)$