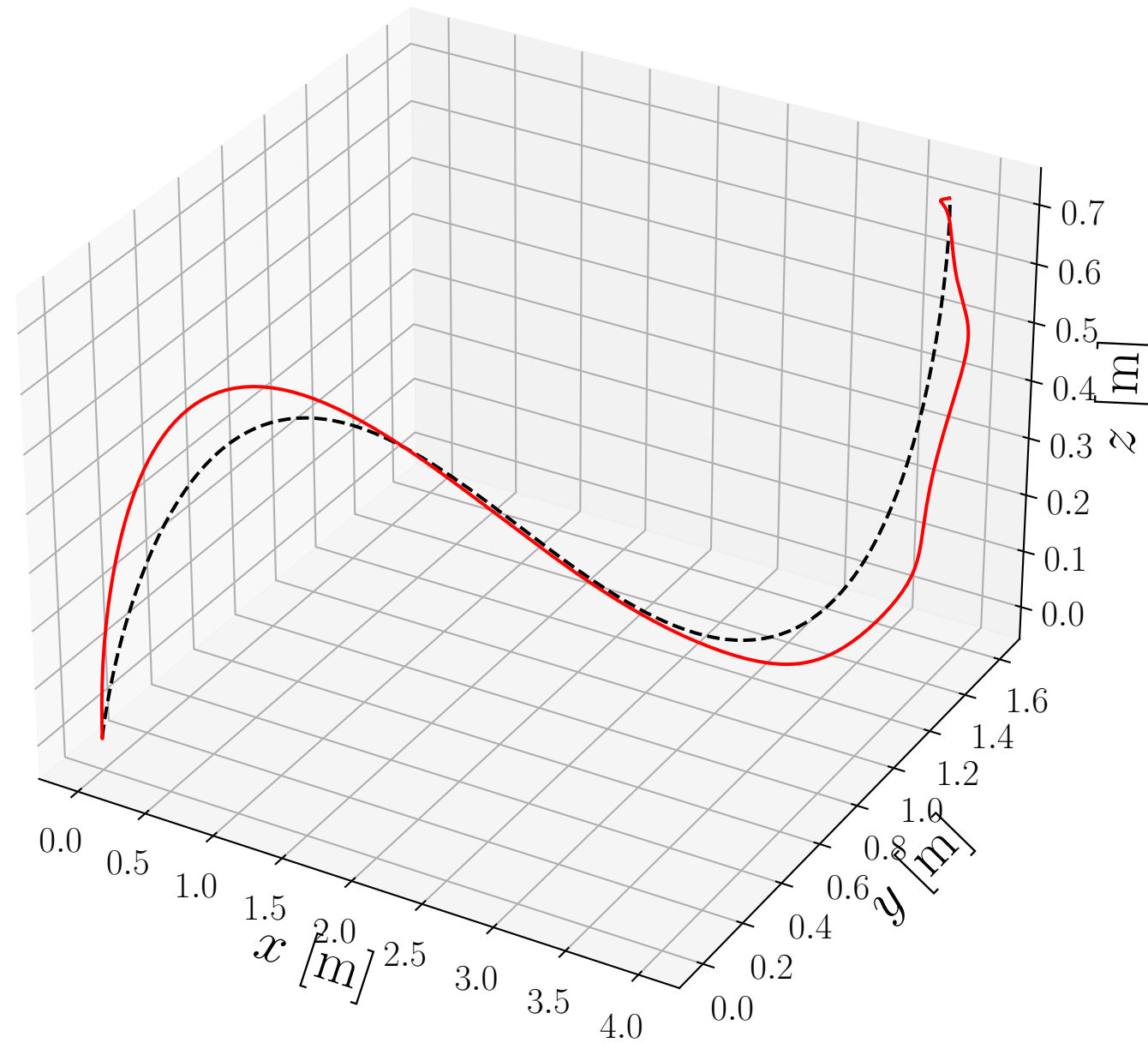


3D Trajectory PD



--- Reference Signal — PD Controller Behavior