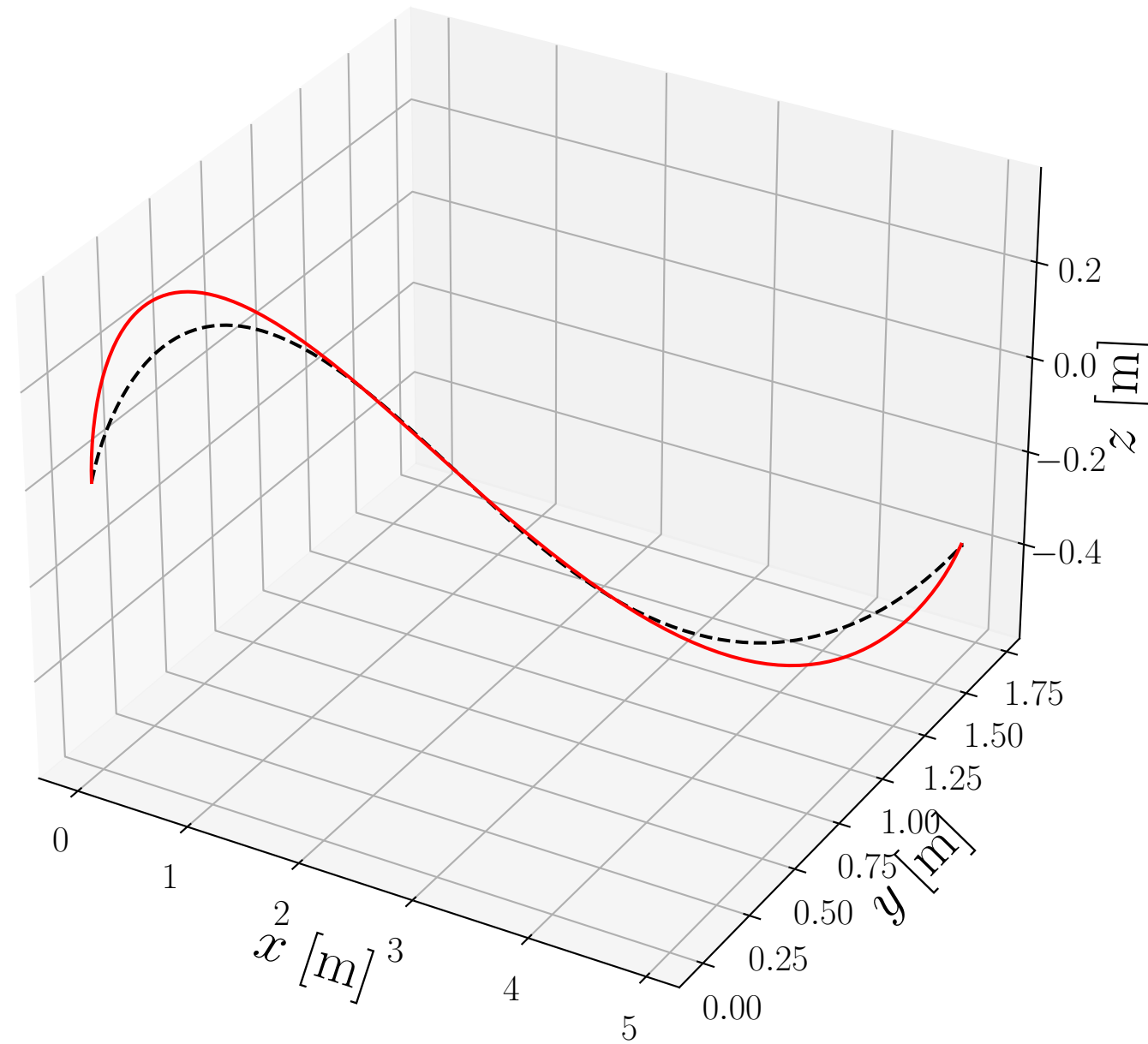


# 3D Trajectory PD



--- Reference Signal      — PD Controller Behavior