3D Trajectory PD

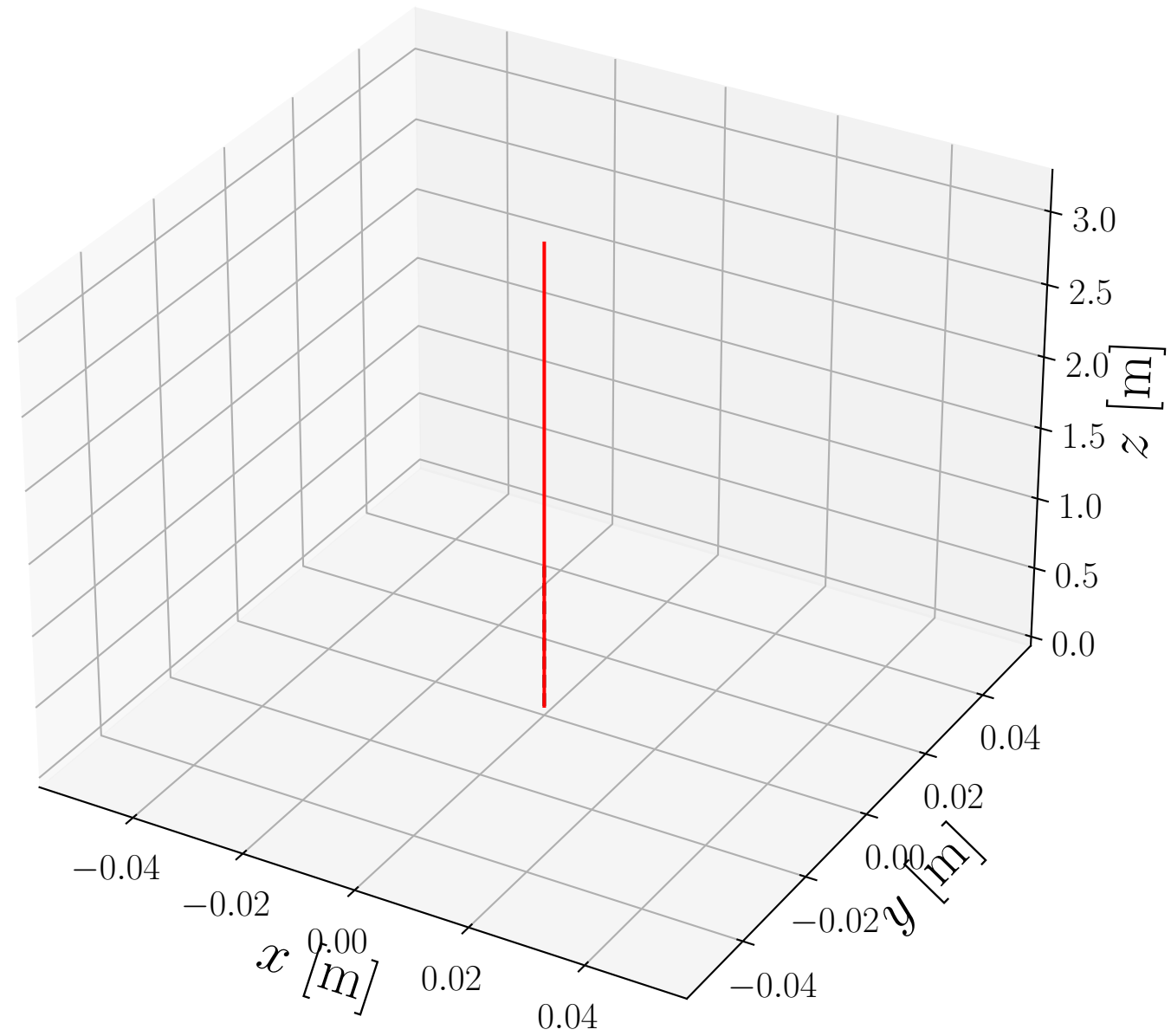---- Reference Signal — PD Controller Behavior