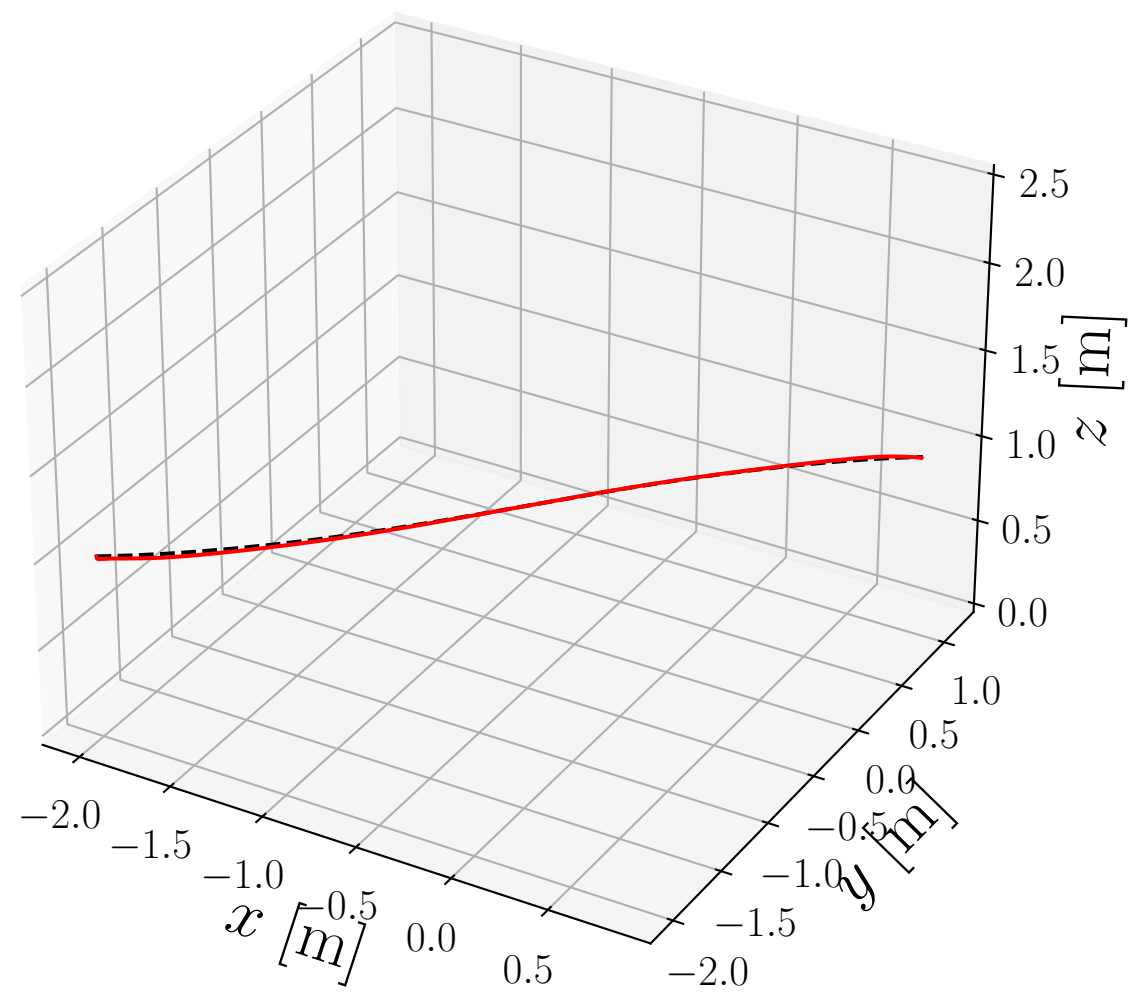
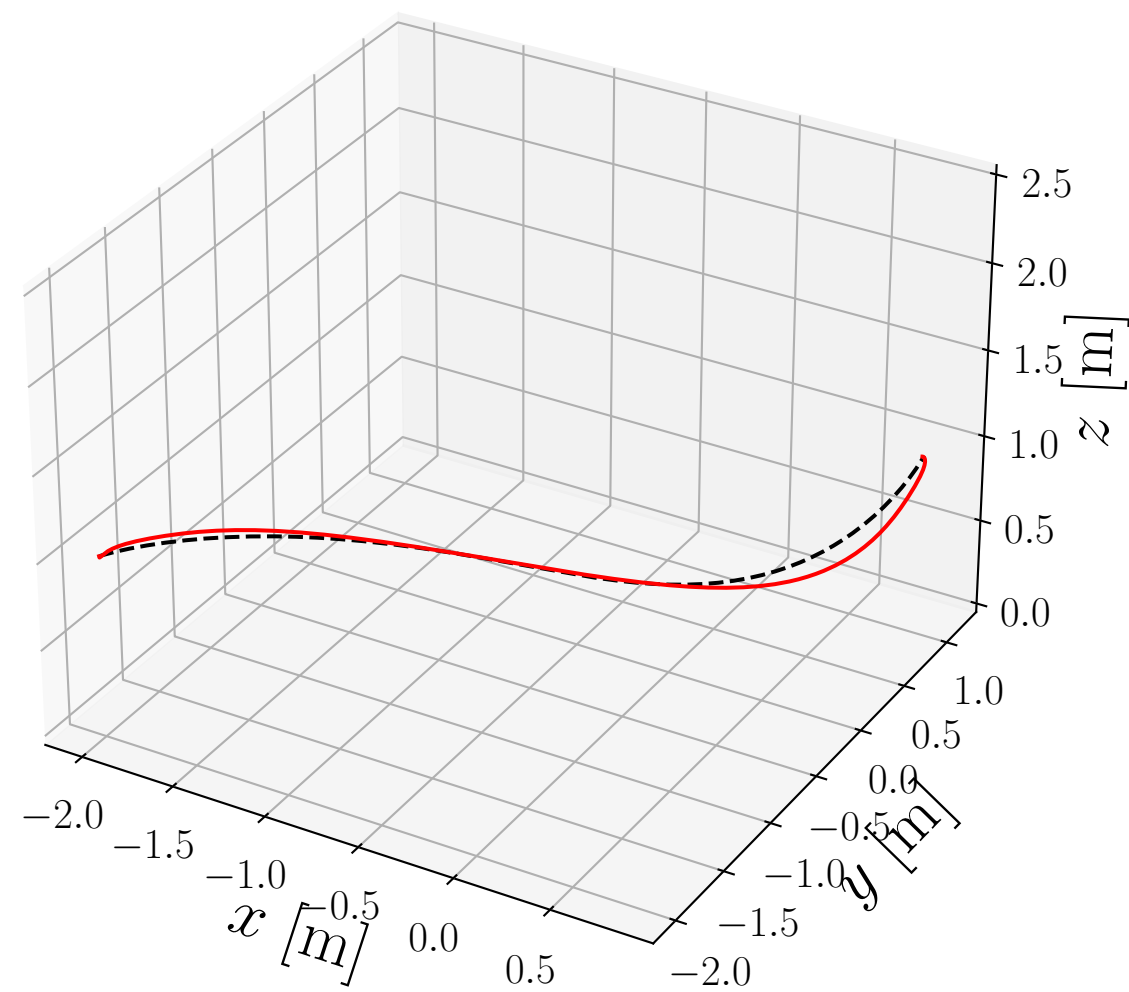


INIT



--- Reference Signal — PD Controller Behavior

PI



--- Reference Signal — PD Controller Behavior