

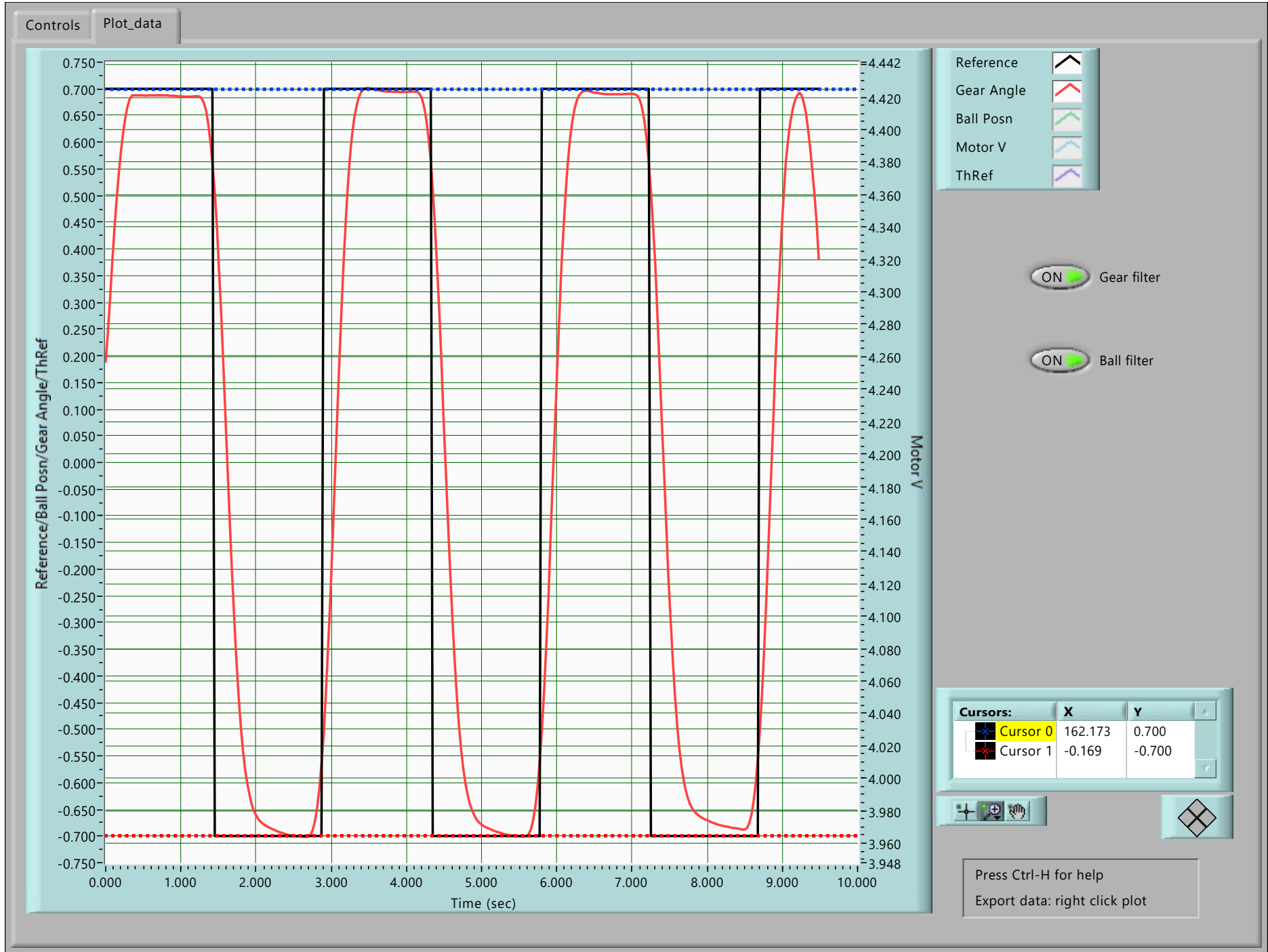


cRIO-9076_RT.vi
N:\GWizFiles\cRIO-9076_RT.vi
Last modified on 2019-10-27 at 5:24 AM
Printed on 2019-10-27 at 5:25 AM

cRIO-9076_RT.vi



This VI shows an example of how to implement a closed loop position move using the NI 9505. The position loop is implemented using PID. The output of the loop is used as the command for the current loop, which then sets the PWM duty cycle for the motor. This example assumes that an encoder is connected for position and velocity feedback. This example does not implement advanced motion features such as trajectory generation and splining.



cRIO-9076_RT.vi

N:\GWizFiles\cRIO-9076_RT.vi

Last modified on 2019-10-27 at 5:24 AM

Printed on 2019-10-27 at 5:25 AM

