

The EFSM is the tuple  $S = (Q, \Sigma_1, \Sigma_2, q_0, V, \Lambda)$ ,

where

$Q = \{\text{dormant, init, idle, monitoring, safe\_shutdown, error\_diagnosis, final}\}$

$\Sigma_1 = \{\text{kill, start, init\_ok, begin\_monitoring, moni\_crash, init\_crash, idle\_crash, retry\_init, idle\_rescue, moni\_rescue, shutdown, sleep}\}$

$\Sigma_2 = \{\text{retry++}, \text{moni\_err\_msg}, \text{idle\_err\_msg}, \text{init\_err\_msg}, \text{retry}=0\}$

$q_0 : \text{dormant}$

$V : \text{retry} = \{0, 1, 2, 3\}$

$\Lambda_{\text{unrefined}} = \{$

1.  $\rightarrow \text{dormant}$

2.  $\text{dormant} \xrightarrow{\text{kill}} \text{final}$

3.  $\text{dormant} \xrightarrow{\text{start}} \text{init}$

4.  $\text{init} \xrightarrow{\text{init\_ok}} \text{idle}$

5.  $\text{init} \xrightarrow{\text{init\_crash} / \text{init\_err\_msg}} \text{error\_diagnosis}$

6.  $\text{init} \xrightarrow{\text{kill}} \text{final}$

7.  $\text{idle} \xrightarrow{\text{begin\_monitoring}} \text{monitoring}$

8.  $\text{idle} \xrightarrow{\text{idle\_crash} / \text{idle\_err\_msg}} \text{error\_diagnosis}$

9.  $\text{idle} \xrightarrow{\text{kill}} \text{final}$

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10. monitoring  $\xrightarrow{kill}$  final
11. monitoring  $\xrightarrow{moni\_crash/moni\_err\_msg}$  error_diagnosis
12. error_diagnosis  $\xrightarrow{kill}$  final
13. error_diagnosis  $\xrightarrow{moni\_rescue}$  monitoring
14. error_diagnosis  $\xrightarrow{retry\_init[retry \leq 3]/retry++}$  init
15. error_diagnosis  $\xrightarrow{idle\_rescue}$  idle
16. error_diagnosis  $\xrightarrow{shutdown[retry > 3]/retry=0}$  safe_shutdown
17. safe_shutdown  $\xrightarrow{kill}$  final
18. safe_shutdown  $\xrightarrow{sleep}$  dormant
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The EFSM of the init state is the tuple  $S = (Q, \Sigma_1, \Sigma_2, q_0, V, \wedge)$ ,

where

$Q = \{\text{boot\_hw}, \text{senchk}, \text{tchk}, \text{psichk}, \text{ready}\}$

$\Sigma_1 = \{\text{hw\_ok}, \text{sen\_ok}, \text{t\_ok}, \text{psi\_ok}\}$

$\Sigma_2 = \{\}$

$q_0 : \text{boot\_hw}$

$V = \{\}$

$\Lambda_{\text{refined}} = \{$

1.  $\rightarrow \text{boot\_hw}$

2.  $\text{boot\_hw} \xrightarrow{hw\_ok} \text{senchk}$

3.  $\text{senchk} \xrightarrow{sen\_ok} \text{tchk}$

4.  $\text{tchk} \xrightarrow{t\_ok} \text{psichk}$

5.  $\text{psichk} \xrightarrow{psi\_ok} \text{ready}$

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The EFSM of the refined monitoring state is the tuple  $S = (Q, \Sigma_1, \Sigma_2, q_0, V, \Lambda)$ ,

where

$Q = \{\text{monidle}, \text{regulate\_environment}, \text{lockdown}\}$

$\Sigma_1 = \{\text{verify\_contagion}, \text{contagion\_alert}, \text{\_no\_contagion}, \text{after\_100ms}, \text{purge\_succ}\}$

$\Sigma_2 = \{\text{inlockdown=false}, \text{inlockdown=true}, \text{set contagion}\}$

$q_0 : \text{monidle}$

$V = \{\text{inlockdown}\{\text{true}, \text{false}\}\}$

$\Lambda_{\text{refined}} = \{$

1.  $\rightarrow \text{monidle}$

2.  $\text{monidle} \xrightarrow{no\_contagion} \text{regulate\_environment}$

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3. monidle  $\xrightarrow{\text{contagion\_alert/FACILITY\_CRIT\_MSG, inlockdown=true}}$  lockdown
4. monidle  $\xrightarrow{\text{verify\_contagion/set contagion}}$  monidle
5. regulate_environment  $\xrightarrow{\text{after\_100ms}}$  monidle
6. lockdown  $\xrightarrow{\text{purge\_succ/inlockdown=false}}$  monidle
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