

Deep Learning from Scratch

Session #3: Feeding DNNs



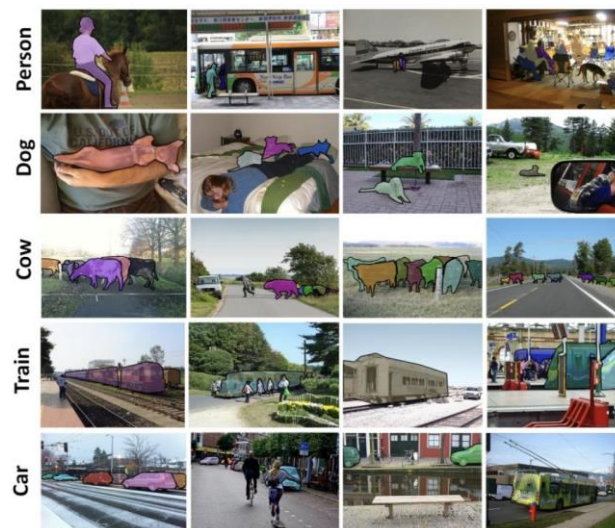
by: Ali Tourani – Summer 2021

Agenda

- ▶ Warm-up and Review
- ▶ Essential Concepts
- ▶ Hyperparameters
- ▶ Overfitting Problem
- ▶ Learning Paradigms
- ▶ Roadmap

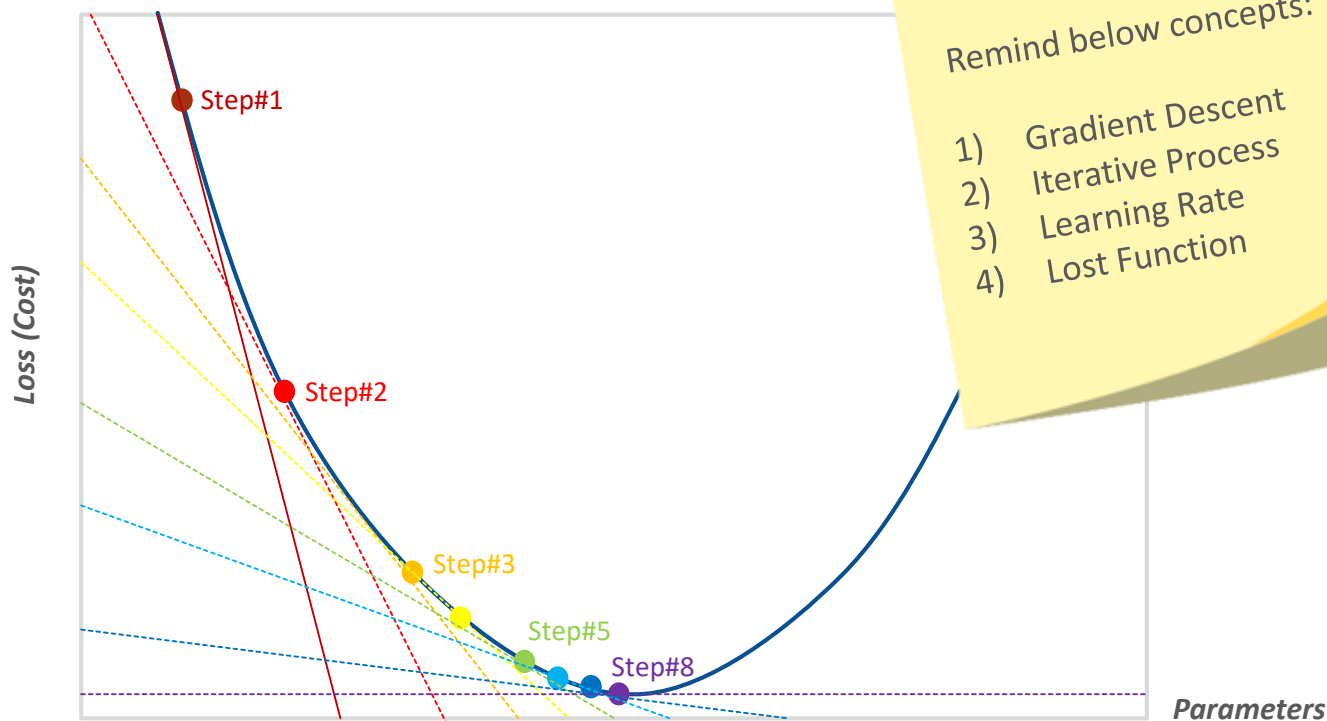
Warm-up and Review

- ▶ Types of data: image, video, sound, text, time series
- ▶ Datasets
- ▶ Standard vs. real-world data
- ▶ Generate datasets
- ▶ Data labeling/annotation
- ▶ Where to find data?
 - ▶ Google's dataset search engine, Kaggle, etc.
- ▶ Deep learning and data
 - ▶ Training-set, dev-set, test-set



Essential Concepts

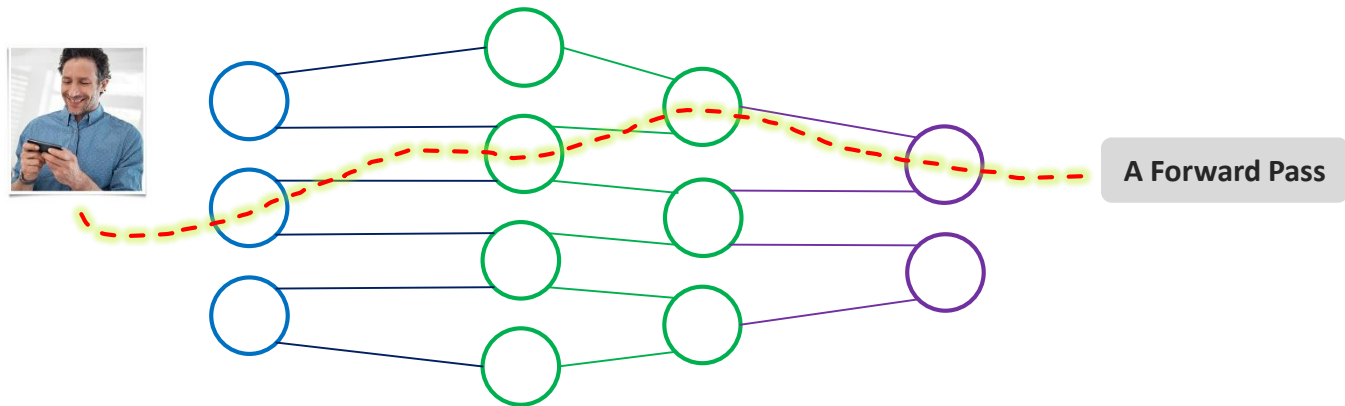
Take a look back at GDA



Essential Concepts

I. Pass

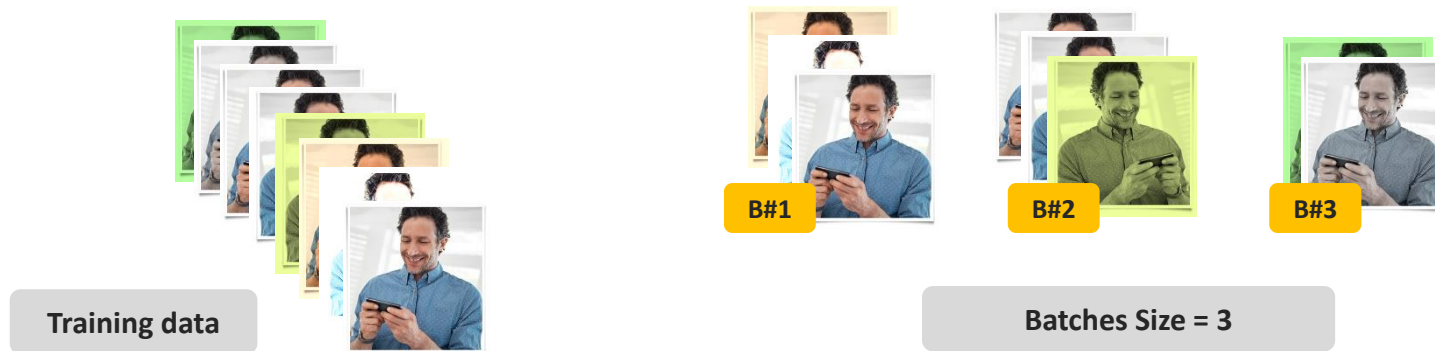
- ▶ A **forward pass (calculation)** or a **backward pass (learning)** in an ANN
- ▶ Traversing through all neurons of a neural network
- ▶ It might be time-consuming, considering the number of hidden layers



Essential Concepts

II. Batch

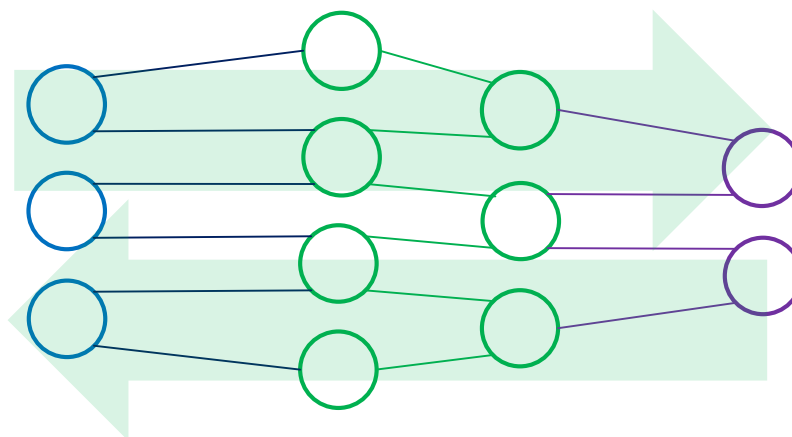
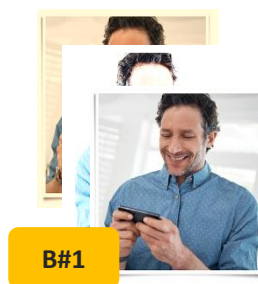
- ▶ A subset of the training-set, AKA a **Mini-Batch**
 - ▶ **Goal:** feeding the NN with a limited number of instances iteratively
- ▶ The number of data used in one forward/backward pass
- ▶ **Batch size:** the number of cases collected from the training-set



Essential Concepts

III. Iteration

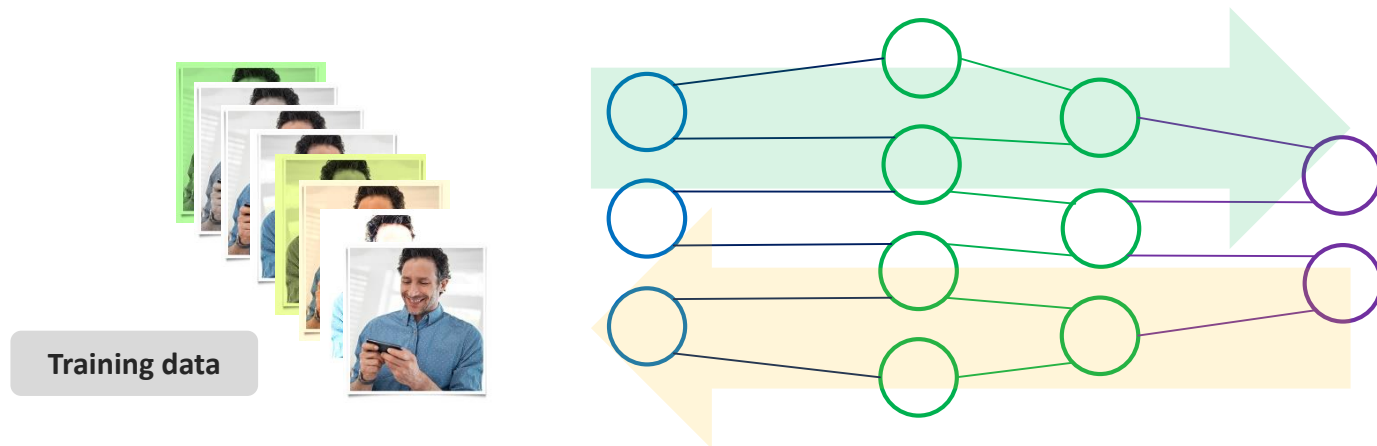
- ▶ A backward and forward pass of a batch of data
- ▶ *The number of iterations?*
 - ▶ Number of passes, each using a **[batch size]** number of instances
- ▶ We may need calculations for this!



Essential Concepts

IV. Epoch

- ▶ Passing the **entire dataset forward and backward ONLY ONCE**
- ▶ The number of times the algorithm works through the whole training-set
- ▶ One epoch contains $datasetSize / batchSize$ iterations



Essential Concepts



Important Notes

- ▶ Batch size and number of batches are not equal
- ▶ Setting a **batch size** is essential, as we cannot pass the whole training set into the ANN at once
- ▶ The final batch may contain fewer samples than the other batches
- ▶ The whole training set should be passed to the ANN **multiple times**
- ▶ The more **number of epochs**, the more learning processes
- ▶ There is no magic rule for choosing the right **number of epochs** and **batch size**

Essential Concepts

Let's see an example

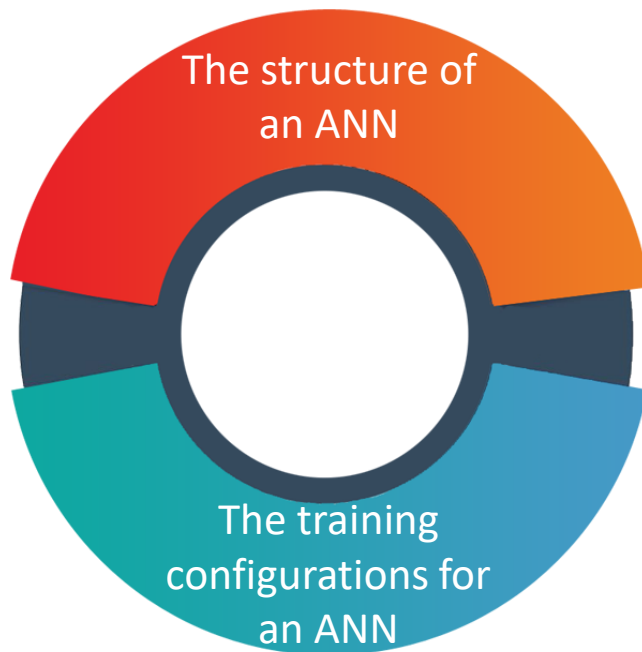
- ▶ **10,000 images** of human face (training data)
- ▶ *Batch-size:* **500**
- ▶ *# of iterations:* **20**



So, if we divide a dataset of **10,000 samples** into **batches of size 500**, we will have to wait for **20 iterations** to complete **one epoch**.

Hyperparameters

- ▶ Variables and parameters to define:



It is so important to set the hyperparameters **before training the network** (one of the main factors to gain magnificent results and accurate predictions).

Hyperparameters

I. Network Structure-related Hyperparameters

Hyperparameter	How to tune?	Notes
Number of Hidden Layers	Adding hidden layers until the error does not improve in the test	Having too many layers is as inefficient as too low layers
Network Weight Initialization	Using different weight initialization schemes according to the AFs	Uniform distribution might be a good idea in many cases
Activation Functions	Choosing proper AFs according to their functionality and usage	Using a particular type of AF on all layers will result in improper outcomes

Hyperparameters

II. Training Algorithm-related Hyperparameters

Hyperparameter	How to tune?	Notes
Learning Rate	Considering the effects of low and large LR's in the ANN's performance	Decaying or Adaptive LR's are usually preferred
Batch Size	Trying 32, 64, 128, 256, and so on	-
Number of Epochs	Increasing the number of epochs and checking the validation accuracy	-

Hyperparameters



Important Notes

- ▶ Hyperparameters values are used to control the overall learning process
- ▶ They cannot be directly trained from the data
 - ▶ So, Hyperparameters are not model parameters
- ▶ Model parameters (*e.g. weights, coefficients, etc.*) are fetched from data, and hyperparameters are manually used to estimate their values
- ▶ Tuning of HPs lead to minimized loss functions and optimized models
- ▶ A good practice for tuning them can be as follows:

Model Definition

Sampling possible hyperparameter values

Evaluation & cross-validation

Hyperparameters

How to tune them?

- ▶ We can simply build a model for each possible combination of the HPs
- ▶ **Grid Search**
 - ▶ Iterates on all different permutations of values to select the most appropriate one
 - ▶ Might be inefficient in some scenarios

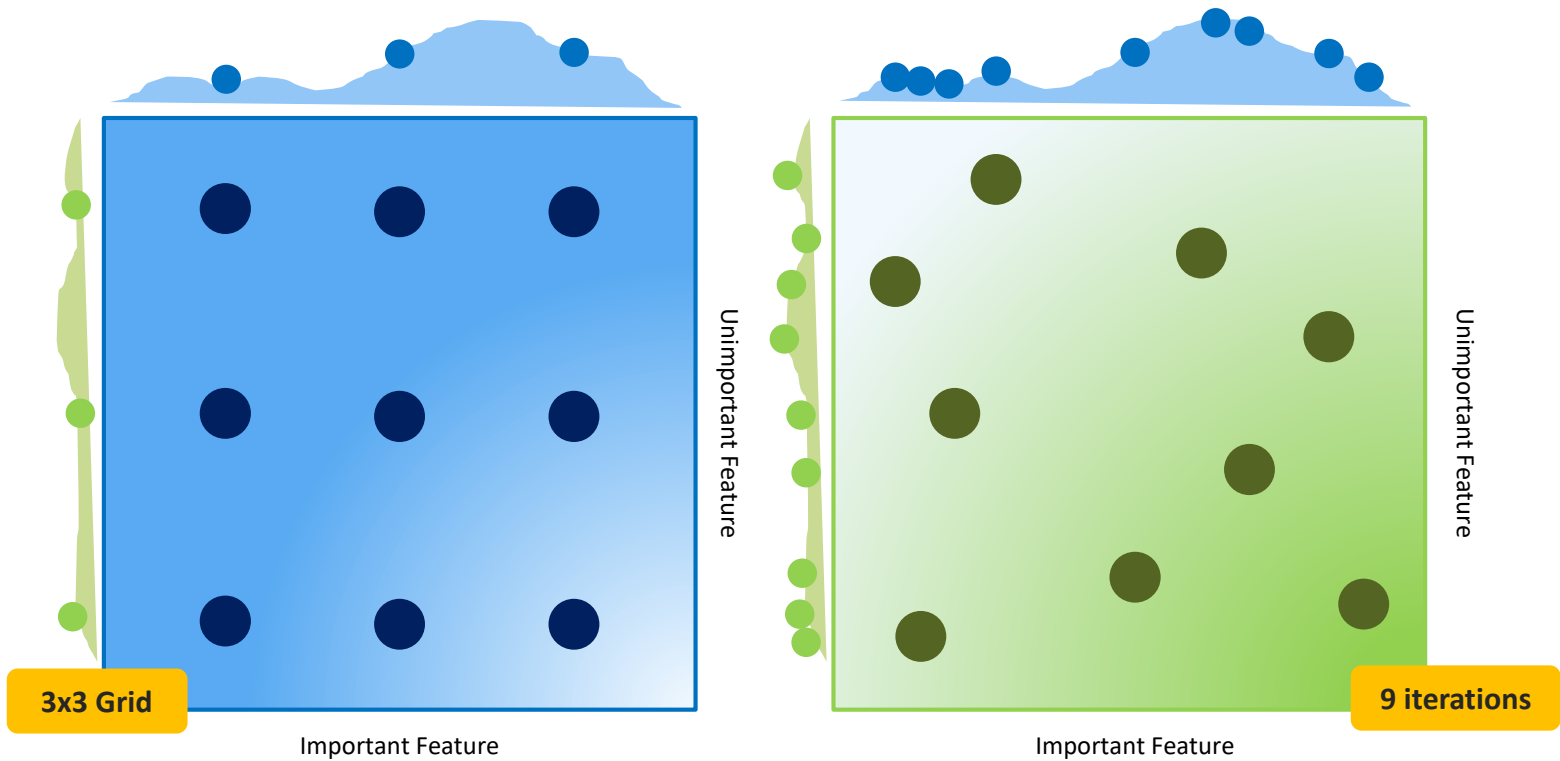
$HP1 = [1, 2, 3, 4, 5]$ $HP2 = [0, 9, 18, 27, 35]$ $Result = \{(1,0), (1,9) \dots (5, 35)\}$

- ▶ **Random Search**
 - ▶ Providing an statistical distribution for each hyperparameter (random sampling)

$HP1 = random(1, 5)$ $HP2 = random(0, 35)$

Hyperparameters

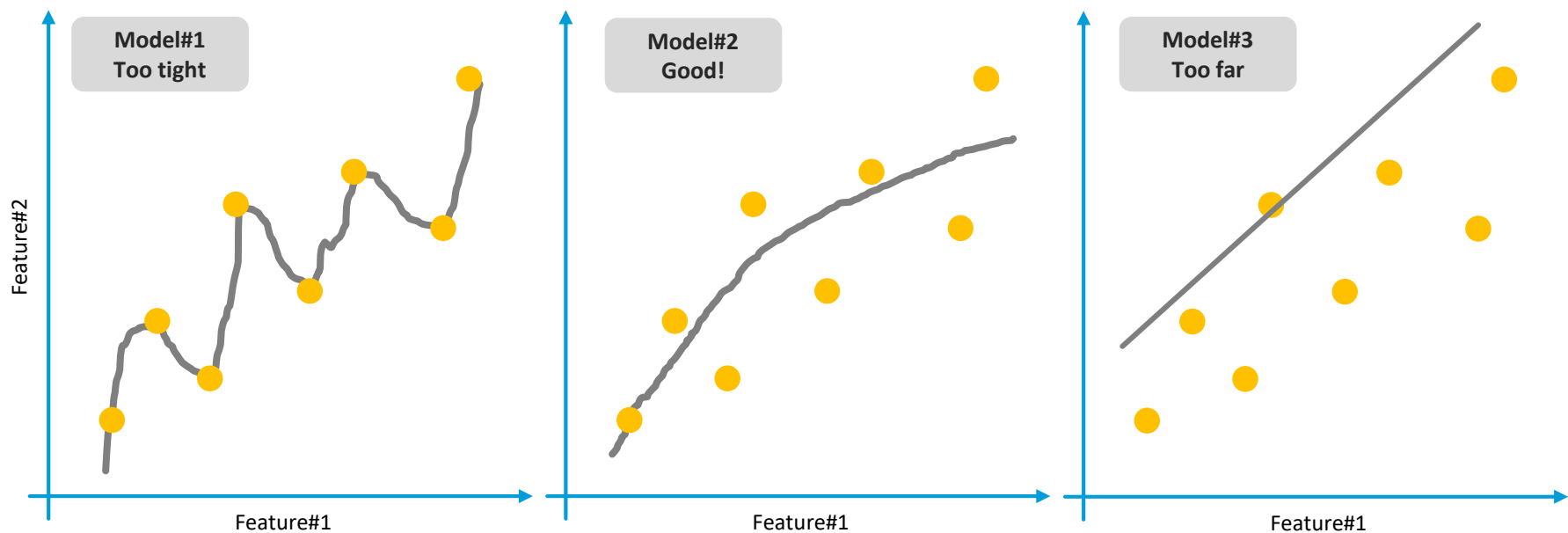
Grid Search vs. Random Search



Overfitting Problem

Consider the DNN model below:

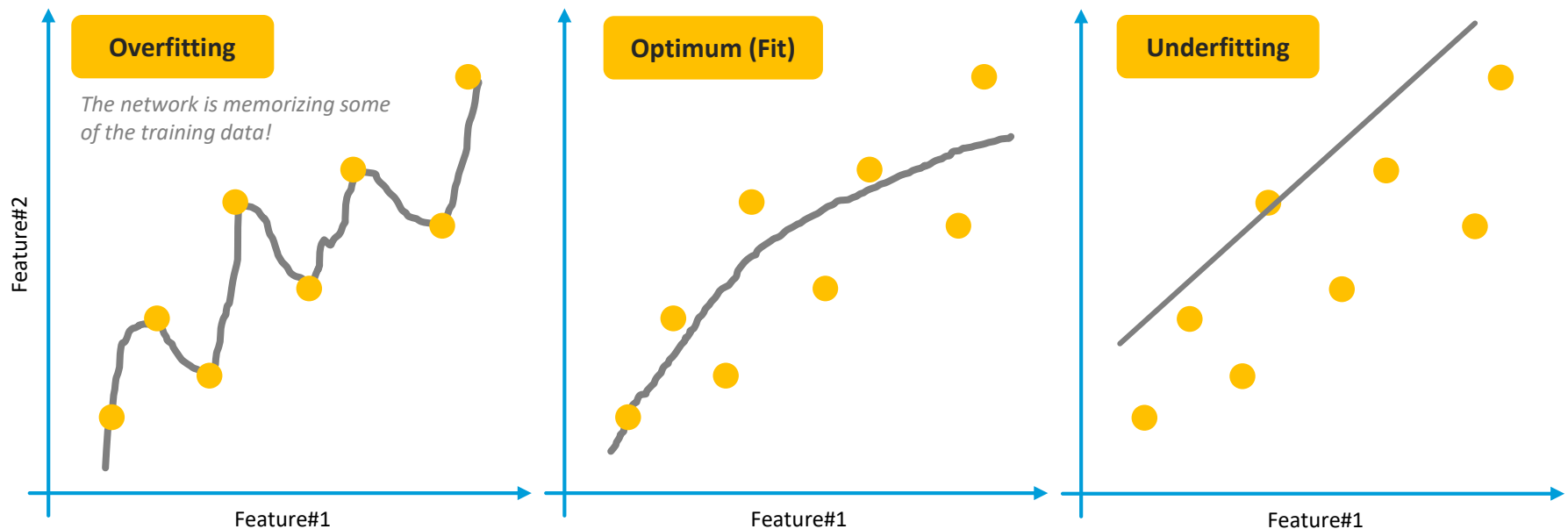
- **Goal:** finding a model that fits data samples with an acceptable error



Overfitting Problem

Consider the DNN model below:

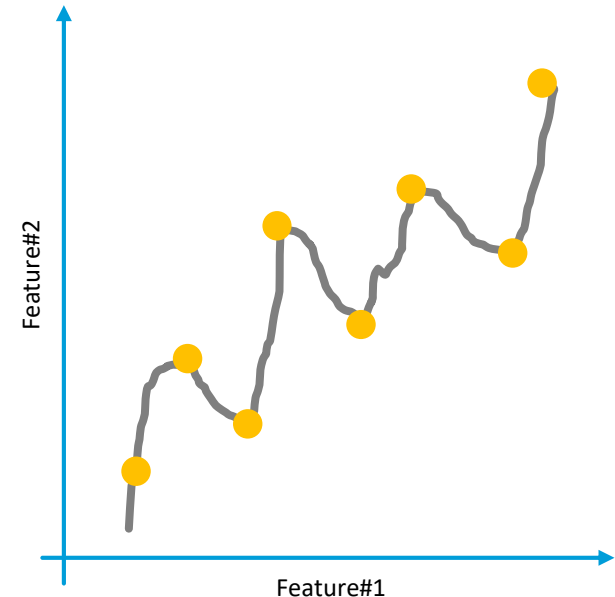
- **Goal:** finding a model that fits data samples with an acceptable error



Overfitting Problem

The Concept of Overfitting

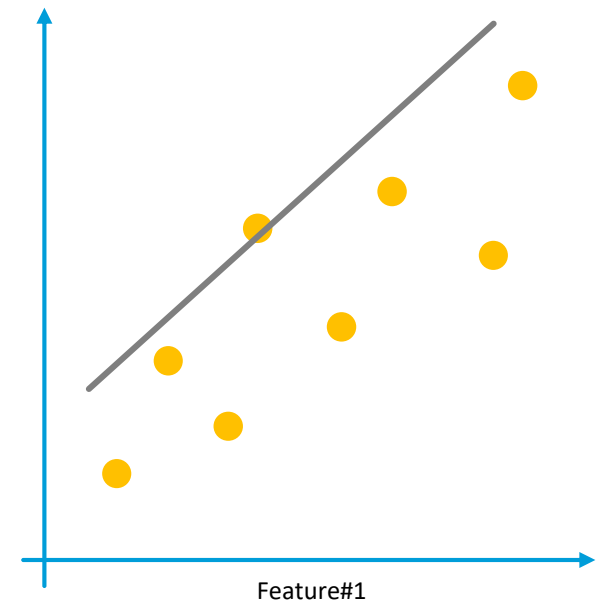
- ▶ Generalization Problem in ML?
 - ▶ The model is not trained to solve **General Problems**
 - ▶ Accurate predictions on the **training set** but inaccurate on **unseen data**
 - ▶ A complex model containing extra parameters and data
- ▶ Detecting the relationships in training data that are not held in **GENERAL**
- ▶ Fitting the line instead of finding the trend
- ▶ Might be called **“high variance”** in some cases
 - ▶ Real data are highly varied from what has been trained



Overfitting Problem

The Concept of Underfitting

- ▶ The model cannot provide accurate predictions even on the training set
- ▶ Unable to find a capacity to learn data fully
- ▶ The model could not:
 - ▶ Learn enough patterns from the training data
 - ▶ Capture the dominant trend
- ▶ Might be called ***“high bias”*** in some cases
 - ▶ The model is highly biased towards its assumptions



Overfitting Problem



Important Notes

- ▶ The primary purpose of all ML models is to generalize well
- ▶ As we want the error to become smaller with more iterations, the process of overfitting detection should be based on the errors
- ▶ We should always try to find the trend instead of fitting the line
- ▶ Training with one epoch will lead to an underfitted model
- ▶ The training flow changes as: **underfitted** → **optimum** → **overfitted**
- ▶ Underfitting is as bad for the generalization of the model as overfitting



Overfitting Problem

How to avoid Overfitting?

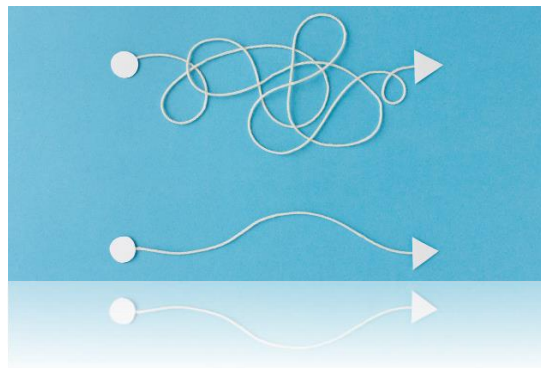
- ▶ *Method#1: Training the ANN with more data*
 - ▶ Reducing the capacity of the model to overfit a training set
 - ▶ Training the model with more data will increase the generalization
 - ▶ **Data augmentation** is a similar approach
- ▶ *Method#2: Multiple Neural Networks*
 - ▶ Running several ANNs in parallel on the same training set
 - ▶ Using different initial weights and configurations
 - ▶ Comparing their error with the error of their average

Overfitting Problem

How to avoid Overfitting?

▶ *Method#3: Constraining Model Complexity*

- ▶ Decreasing the complexity of the model and making the ANN smaller
 - ▶ Removing layers and reducing the number of neurons
- ▶ Avoiding the network to catch all data points
- ▶ Pruning it by removing nodes until it achieves a suitable performance
- ▶ Any *magic rule* for the amount of simplification? **Unfortunately not!**

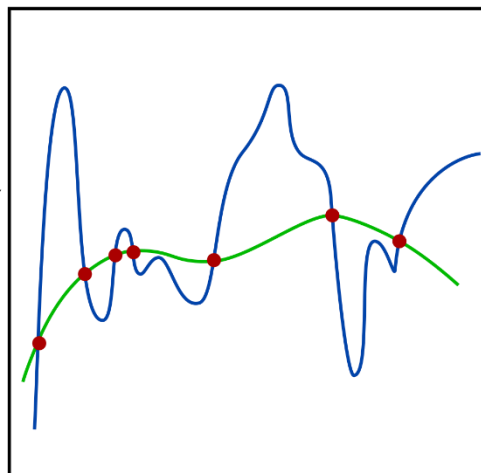


Overfitting Problem

How to avoid Overfitting?

► *Method#4: Early Stopping*

- A simple approach applicable to **all ANNs** (due to utilizing **GDA**)
- But before going further, what is **Regularization**?



Overfitting Problem

Regularization

- ▶ Simply, trying to **reduce the error** by **fitting a function** on the training set
- ▶ **Finding patterns** in the training data and generalize them as much as possible

How can it help?

- ▶ Preventing **complex information** from being learned (overfitting)
- ▶ Limiting the optimization problem to discourage complex models
- ▶ Improving generalization of our model on test data



Overfitting Problem

How to avoid Overfitting?

- ▶ *Method#4: Early Stopping – continued*
 - ▶ A simple approach applicable to **all ANNs** (due to utilizing **GDA**)
 - ▶ Stop training when the **Generalization Error** increases!
 - ▶ *The error measured with respect to dev set often shows a **decrease** followed by an **increase***
 - ▶ Stop when the training data starts to diverge from the test data
 - ▶ Do the mentioned check in each iteration

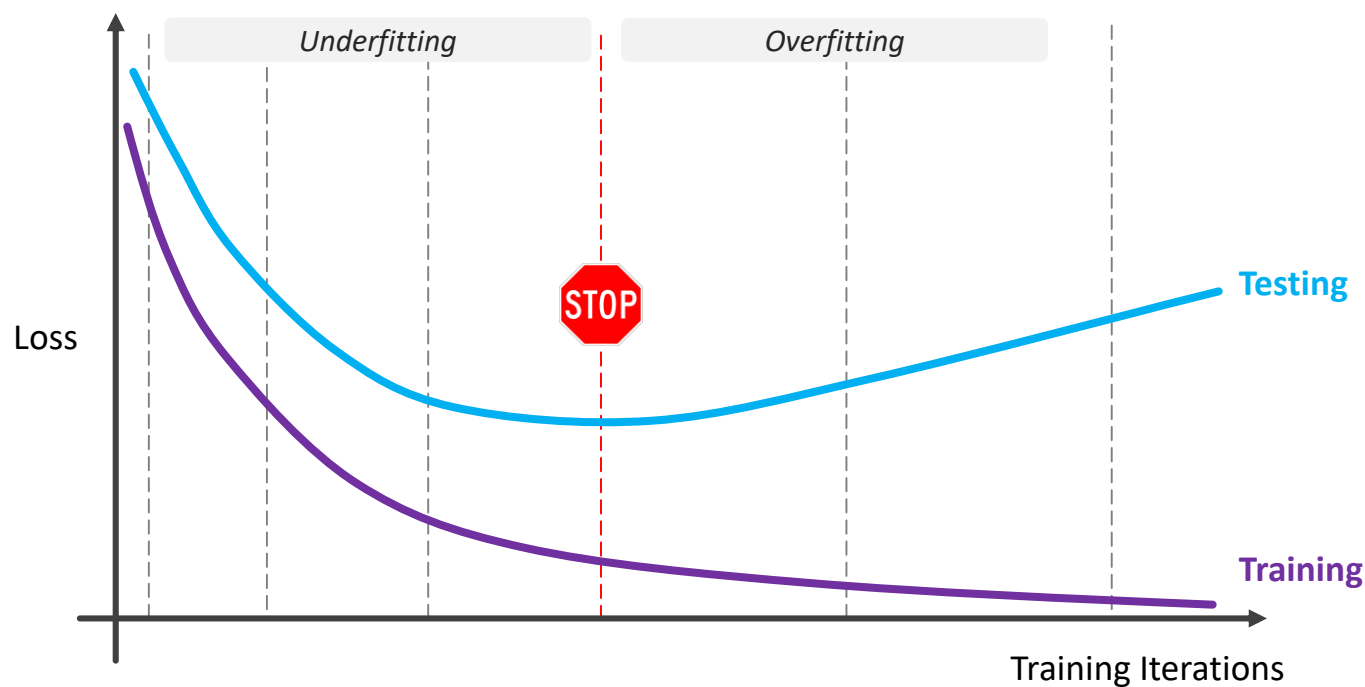
Monitoring the model's
performance

Using a trigger to
stop training

Overfitting Problem

How to avoid Overfitting?

► *Method#4: Early Stopping – continued*

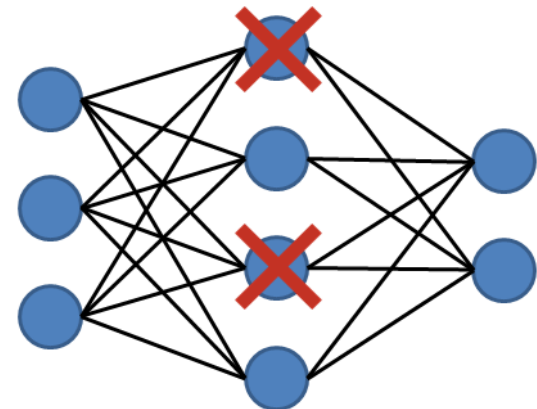


Overfitting Problem

How to avoid Overfitting?

▶ *Method#5: Dropout*

- ▶ A per-layer regularization method that randomly ignores some nodes
 - ▶ **Randomly setting AFs to zero** (params: randomization probability, e.g. 0.2)
- ▶ Making the training process noisy to encourage the network to learn instead of memorize patterns
- ▶ Reduces the capacity of the network (thinning)
- ▶ Can be used on all/any of the hidden layers



Learning Paradigms

Do different ANNs (and particularly, DNNs) learn in a unique manner?

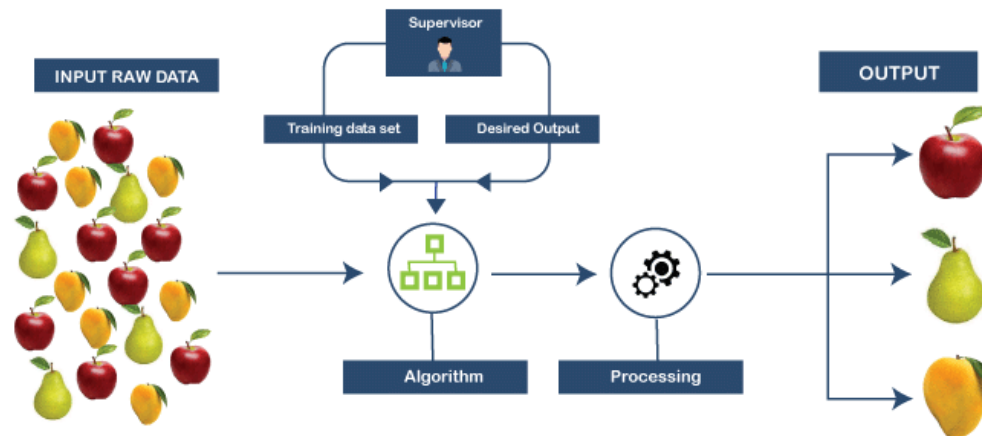
- ▶ **Definitely Not!** It all depends on the learning task



Learning Paradigms

- ▶ Learning with a teacher! (*tagged data*)
- ▶ A set of paired inputs and outputs
 - ▶ **Goal:** producing desired output for each input sample
- ▶ Providing **feedback** on the quality of solutions
- ▶ Applications in classification, regression, pattern recognition, etc.

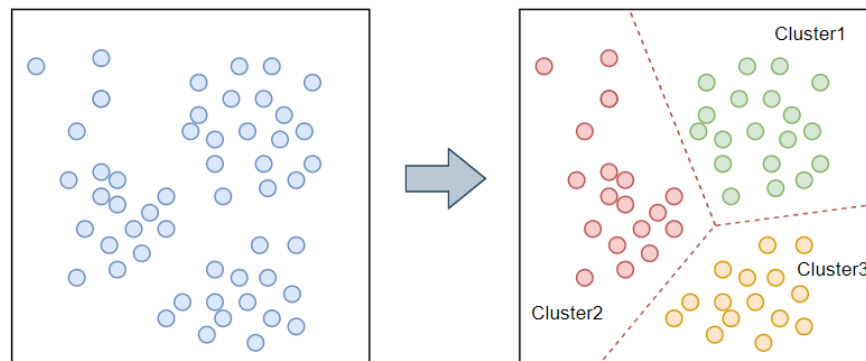
Supervised Learning



Learning Paradigms

- ▶ Input data + output data + error (cost) function
- ▶ Trying to learn patterns from untagged data
- ▶ The outputs are imaginative in most cases
 - ▶ Case study: organizing photos in a gallery (how?)
- ▶ **Note:** *DNNs are mainly impactful on structured data*

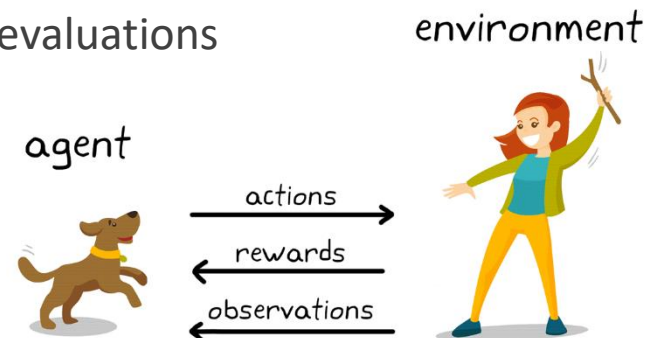
Unsupervised Learning



Learning Paradigms

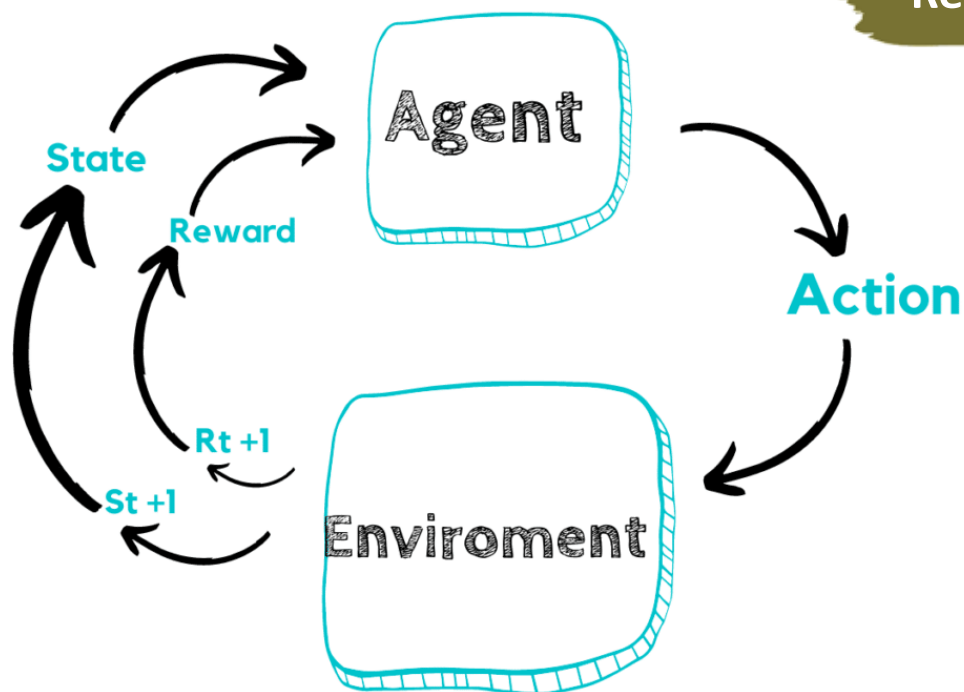
- ▶ Trying to maximize the total (cumulative) reward
 - ▶ An agent learns to achieve a goal in an environment
 - ▶ Based on Reward and Penalty
- ▶ The model itself should find the solution with a maximized reward
 - ▶ Finding a solution with the lowest possible costs in future
 - ▶ Maybe even with trial and error
- ▶ **Advantage:** gaining experience from hundreds of evaluations

Reinforcement Learning



Learning Paradigms

Reinforcement Learning



Learning Paradigms

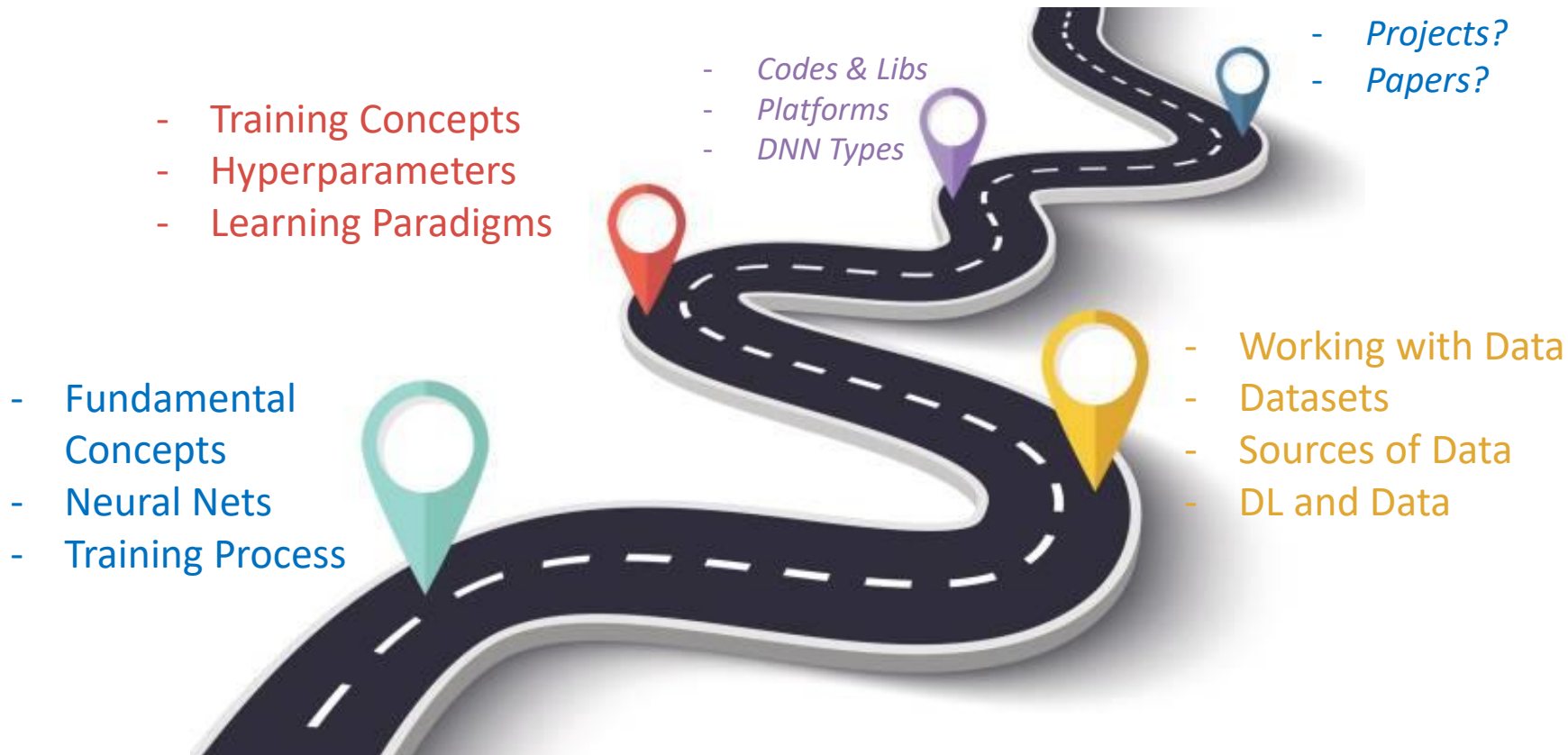


Reinforcement Learning

Case Study:

In autonomous vehicles, the AI module learns from the system's awards and penalties for unseen scenarios.

Roadmap



References

Web pages and Articles

- ▶ <https://towardsdatascience.com/epoch-vs-iterations-vs-batch-size-4dfb9c7ce9c9>
- ▶ <https://towardsdatascience.com/what-are-hyperparameters-and-how-to-tune-the-hyperparameters-in-a-deep-neural-network-d0604917584a>
- ▶ <https://towardsdatascience.com/what-are-overfitting-and-underfitting-in-machine-learning-a96b30864690>
- ▶ <https://www.kdnuggets.com/2019/12/5-techniques-prevent-overfitting-neural-networks.html>
- ▶ <https://towardsdatascience.com/regularization-an-important-concept-in-machine-learning>

References

Web pages and Articles

- ▶ <https://deepsense.ai/what-is-reinforcement-learning-the-complete-guide/>
- ▶ https://en.wikipedia.org/wiki/Artificial_neural_network
- ▶ <https://www.jeremyjordan.me/hyperparameter-tuning/>

Papers

- ▶ N. Srivastava, G. Hinton, A. Krizhevsky, I. Sutskever, and R. Salakhutdinov (2014) **Dropout: A Simple Way to Prevent Neural Networks from Overfitting**, Journal of Machine Learning Research, vol. 15, pp. 1929-1958.

Questions?

