

Ali Toyserkani

+1 (226) 600 7210 • atoyserk@edu.uwaterloo.ca • alitoyserkani.me • github.com/alitoyserkani

EXPERIENCE

WATonomous – SAE Autonomous Vehicle Challenge | *Technical Project Manager* Sep 2017 – Present

- Currently **co-leading a group of over 150 students** in building a level 4 self-driving car
- Created an embedded controls interface to execute planned trajectories using **PID controllers** and **CAN communication**
- Developed data pipelining package in **ROS** and **PCL** to synchronously distribute 150 MB/s of camera, **LiDAR** and **RADAR** data
- Implemented and trained a neural network using **TensorFlow**, **CUDA**, and **cuDNN** for an **OpenCV** detection model

Core Avionics & Industrial, Inc. | *Embedded Software Developer* Jan 2018 – Apr 2018

- Developed safety-critical **GPU** drivers (OpenCL, Vulkan, OpenGL) in **C & C++** for AMD and NVIDIA **embedded graphics** cards
- Built new multithreaded/multipartition sample applications for the drivers, **increasing code coverage by 25%**
- Wrote **Python** scripts to streamline a complex build process to one command, saving time and manual effort

Multi-Scale Additive Manufacturing (3D Printing) Lab | *Research Assistant* May 2017 – Aug 2017

- Built a cross-platform **Qt** application using **OpenGL** and **boost** to create machine toolpaths from imported CAD files
- Co-developed a **new hybrid additive manufacturing method** for making polymer parts without the need for support structures
- Created a **real-time image processing model** using **OpenCV** to adjust process parameters when detecting part defects

PROJECTS

Quadcopter Drone Feb 2018

- Built a semi-autonomous drone with 6 D.O.F. and smooth control using **ROS** on a **Qualcomm DragonBoard 410c** board
- Developed a remote controller using an **Arduino Nano** to send **RF** signals to the quadcopter

4-Axis Robotic Arm Nov 2016

- Created a **multi-purpose robotic arm** with 4 D.O.F. to repeat a user-recorded set of tasks
- Wrote **embedded C** software to wirelessly control the robotic arm's axes with a console joystick

AWARDS & COMPETITIONS

- **3rd Place @ IEEE Hardware Hackathon 2017** for creating a electronic hand glove for smart home automation
- **Winner of CANSOFCOM Military Challenge @ Hack the North 2017** for creating a video surveillance tool
- **Top 15 Autonomous Mars Rover Robot @ International University Rover Competition 2017**
- **Best IoT Project @ Queens University Hackathon 2018** for prototyping a home facial recognition platform

TECHNICAL SKILLS & TOOLS

Languages: C++, C, Python, Bash, JavaScript, Java

Software: ROS, Qt, OpenCV, Arduino, Node.js, OpenGL, TensorFlow, CUDA, MATLAB, Git

Design/Hardware: SolidWorks, AutoCAD, Fusion360, Machining Tools, PCB Design, Soldering, Oscilloscopes, Sensors

EDUCATION

University of Waterloo, Honours Mechatronics Engineering (GPA: 3.82) Sep 2016 – Present

Online Coursework: *ColumbiaX's Robotics Software Engineering, Udacity's Artificial Intelligence for Robotics, Stanford's Convolutional Neural Networks for Visual Recognition (CS 231n)*

INTERESTS

- **Long Distance Running** – Ontario 2014 Track and Field Finalist, Cross Country Runner.
- **Hiking** – Climbed mountains in Alberta, climbed Mount Damavand, looking to climb Mount Kilimanjaro