Ali Toyserkani

Research Assistant by Day, Hardware Enthusiast by Night

+1 (226)-600-7210 | ali.toyserkani1998@gmail.com | linkedin.com/in/alitoyserkani | alitoyserkani.me | github.com/alitoyserkani | grabcad.com/ali.toyserkani-1

SUMMARY OF QUALIFICATIONS

- Competent with -> Machining Tools, **C/C++**, **Java**, SolidWorks, AutoCAD, **Prototyping**, Arduino, Soldering, FDM 3D Printers
- Experience with -> Python, JavaScript, PCB Design (Altium & DipTrace), Troubleshooting, Part Sourcing, Sensors, Statistics
- o Familiar with \rightarrow ROS, **C#**, **HTML/CSS**, **Objective C**, GD&T, Raspberry Pi, MATLAB, NX

Work Experience

~

Additive Manufacturing Laboratory | Research Assistant | University of Waterloo

Dec 2016 - Present

- o Implementing a new big-data processing system using OpenCV for image processing with laser diodes, readings from ultrasonic, temperature and pressure sensors to analyze 5 GB/s of raw data, to decrease analysis time by 60%
- o Developed an O(logn) response algorithm to make swift modifications to the **3D printers' substrate location, internal temperature** and pressure to improve printer's manufacturing quality while maintaining speed

Fluid Mechanics Research Laboratory | Educational Outreach Intern | Waterloo

Jul 2016 - Present

- o Created mechanical models of the human vocal tract using multi-polymer plastics and rubber silicon material
- Used Arduino UNO, sound IoT, 555-timers and amplifiers to emulate a changing human voice
- o Constructed roughly 75 metal, plastic and wood parts for the assemblies of multiple trachea models

Precision Controls Laboratory | Part Manufacturer | University of Waterloo

Jul 2015

- Designed and manufactured assembly parts for industry-grade machines using SolidWorks, AutoCAD, and machining tools
- o Increased project efficiency by 10%, by creating parts quickly and accurately with required specifications

PROJECTS

 \sim

ExtensaArm | Term Project | C++, RobotC, SolidWorks, AutoCAD

Oct 2016 - Dec 2016

- Constructed a multidisciplinary servo-controlled robotic arm with 4-axis freedom to repeat sets of user-taught tasks
- o Developed a custom library to allow game-controller Bluetooth connection with the robotic arm

shYft | *HACKference 2016* | JavaScript, Node.js, Objective C, Firebase Best Workforce Hack, Top 10 Overall

Nov 2016

o Built a scheduling platform where employees can seamlessly swap shifts, contact managers, change availability, and financials

Interactive Physics Simulator | Personal | Java

May 2016

o Created a 2D user-prompted collision simulation program with tools to numerically analyze multi-object collisions

Space Dodgers | School | Python

Feb 2015

o Designed a game using PyGame and tKinter graphics classes that tested user's reaction time and mouse maneuvering abilities

EDUCATION

BASc, Honors Mechatronics Engineering | University of Waterloo

Class of 2021 (Expected)

o Academic Representative: Algorithms (MTE 140) ---- Clubs: Intramural Soccer, Engineering Society, Poker Club

EXTRACURRICULAR ACTIVITIES



- o Robotics: Electrical team member of the university's robotics team, working on power distribution and battery management
- Finance: Top 10 at ICDC (International Career Development Conference) for DECA Stock Market Investing Challenge
- o Track & Field: 2nd best 4x100m Relay Team in West Ontario (OFSAA), 2014-15 School MVP
- o **Piano:** Performed in 4 local community concerts around the Kitchener/Waterloo region