

# Audio source separation with magnitude priors: the BEADS model

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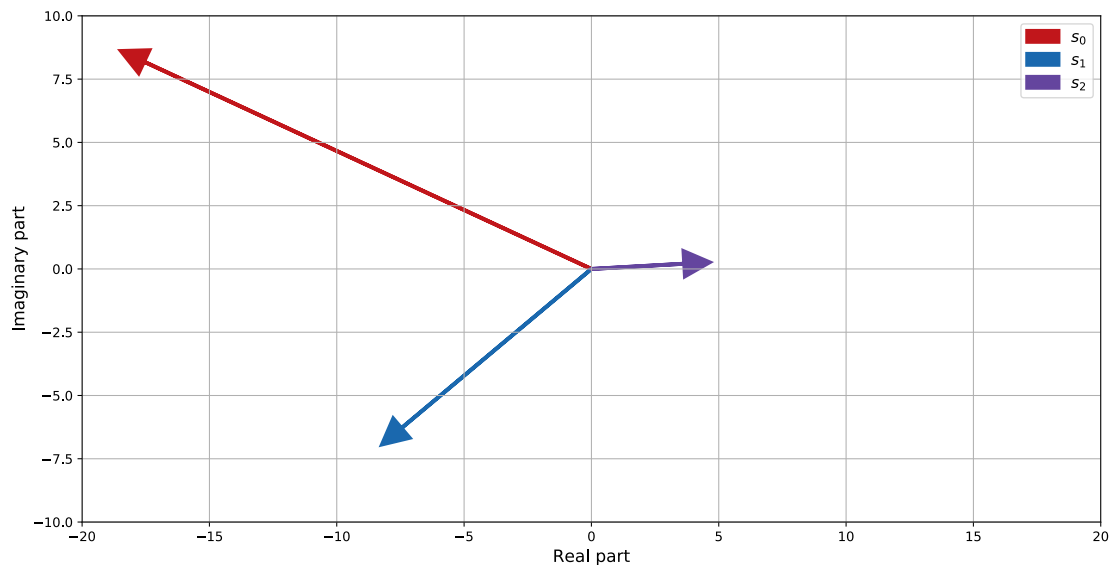


# Context

Separation of complex random variables

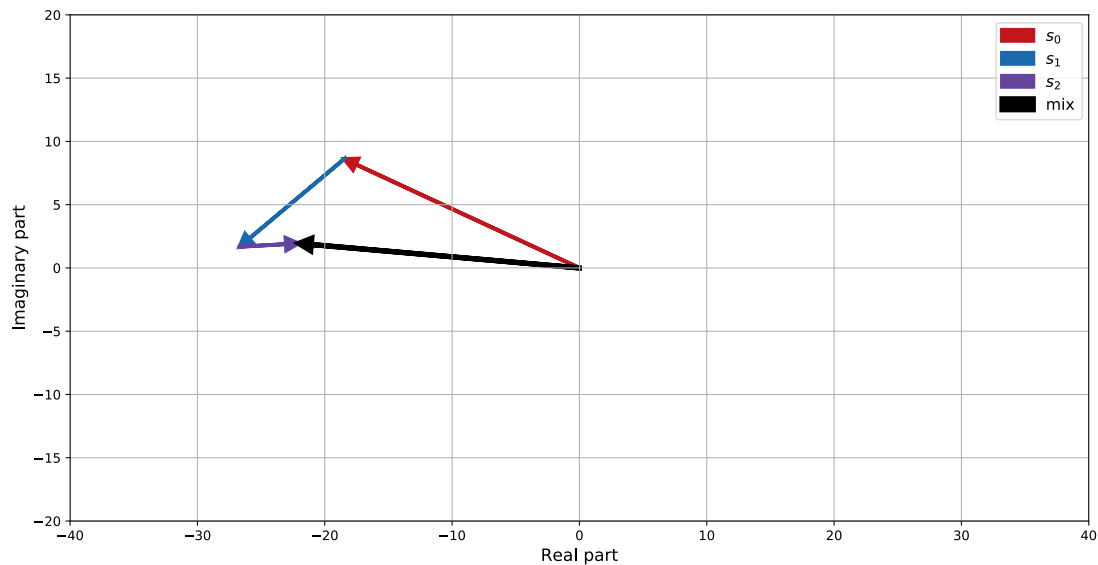
# The source separation problem

For each Time-Frequency bin, the mixture is the sum of sources  $x = \sum_j s_j$

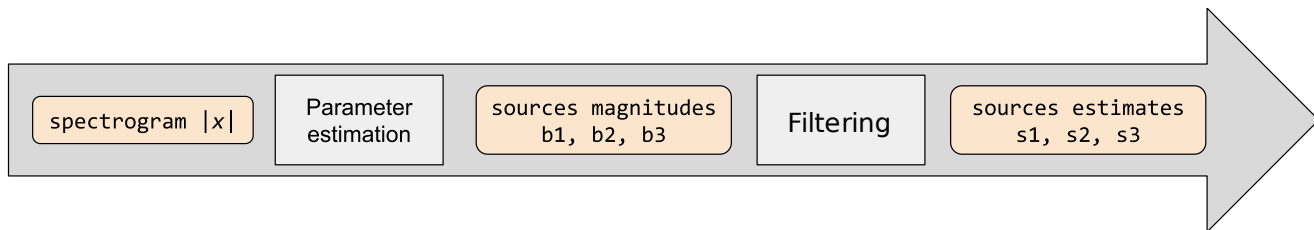


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# Typical separation pipeline



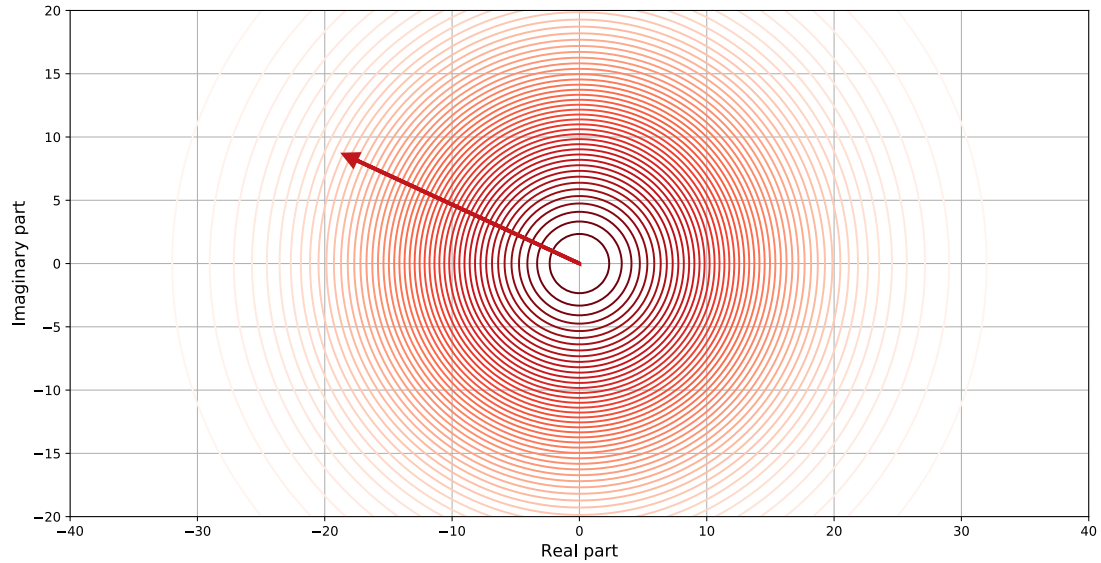
## In this talk

- **Filtering** from magnitude estimates  $b_j > 0$  to separated signals  $s_j \in \mathbb{C}$
- Tractable model for **complex variables**  $s_j$  with (approximately) known magnitude  $b_j$

## In the paper

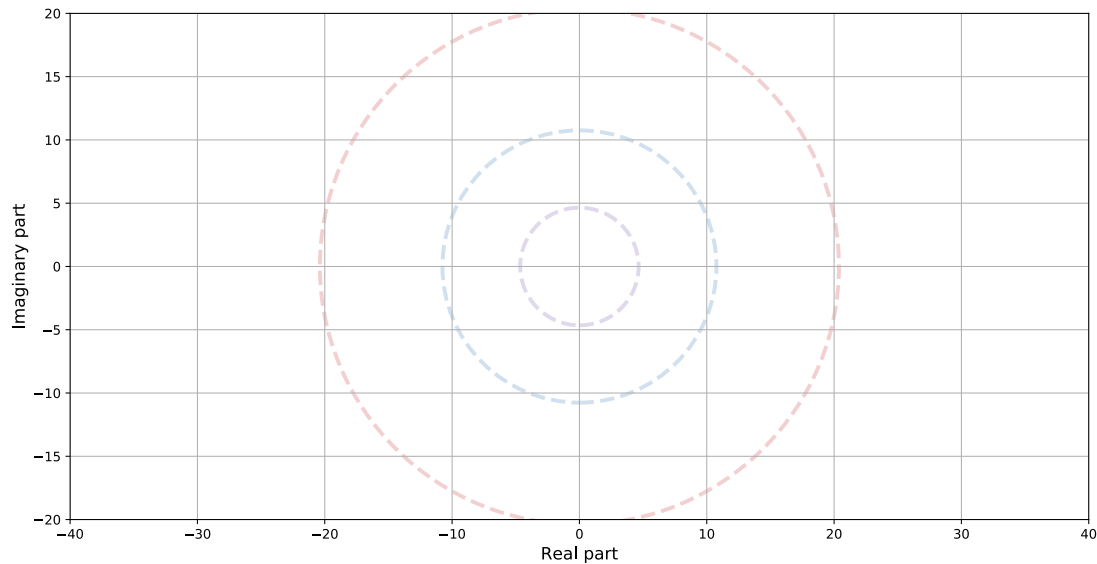
- The multichannel case
- Evaluation for audio coding

The classical Gaussian model  $s_j \sim \mathcal{N}\left(0, \frac{2}{\pi} b_j^2\right)$  matches the prior  $\mathbb{E}[|s_j|] = b_j$

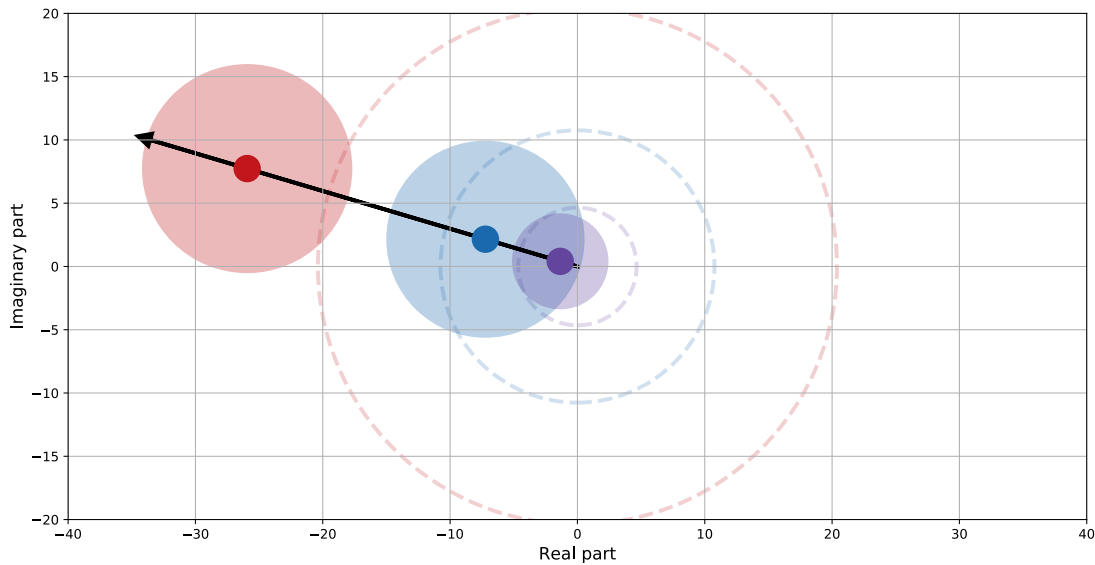


⇒ Highest probability mass on 0

The mixture is Gaussian  $x \sim \mathcal{N}\left(0, \sum_j b_j^2\right)$ , sources are recovered as:  $s \mid x \sim \mathcal{N}\left(\frac{b_j^2}{\sum b^2} x, b_j^2 \left(1 - \frac{b_j^2}{\sum b^2}\right)\right)$

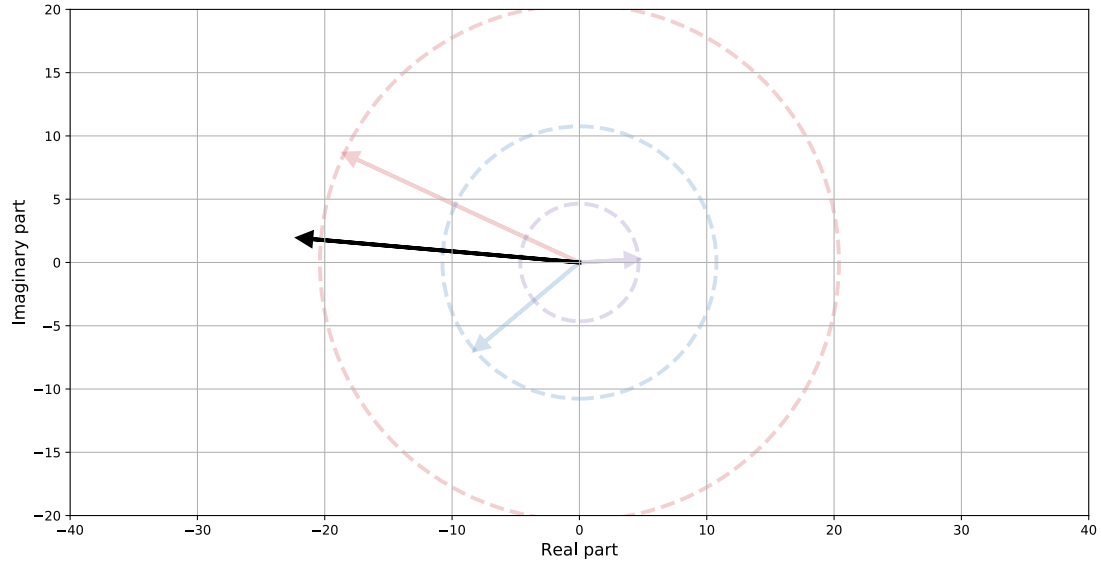


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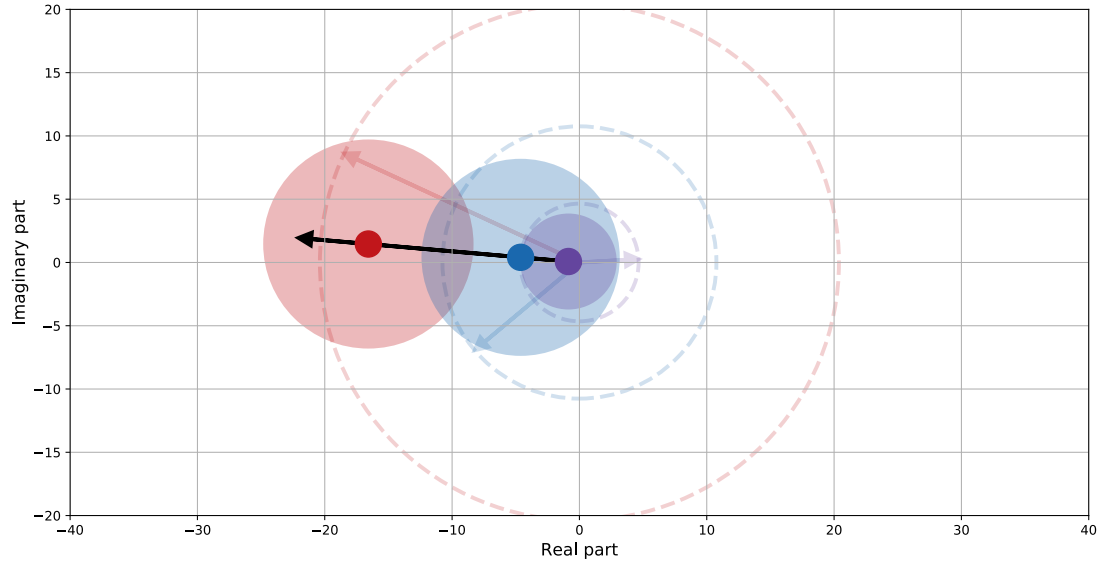




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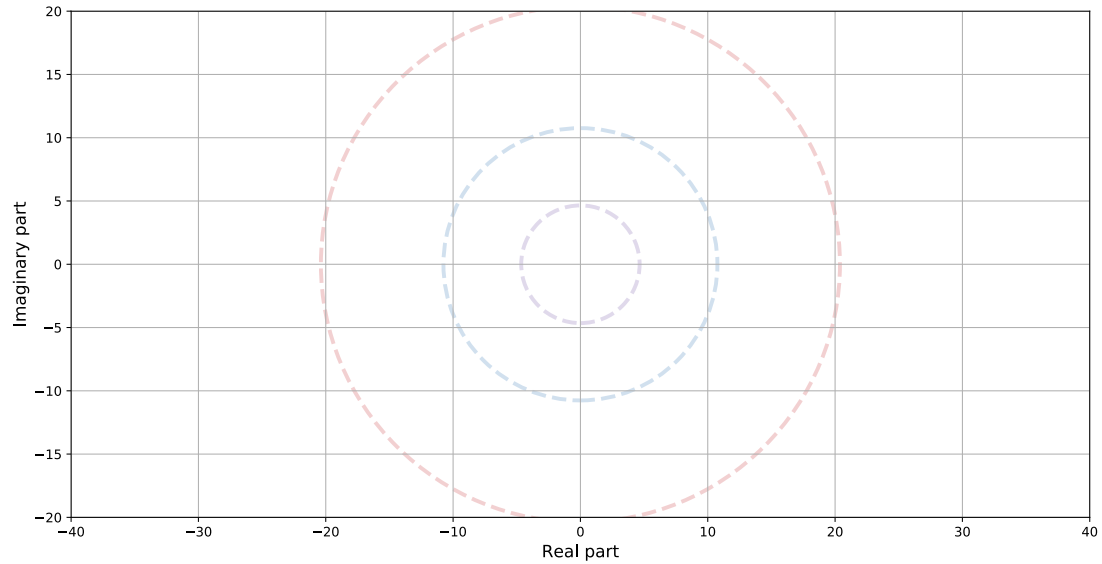
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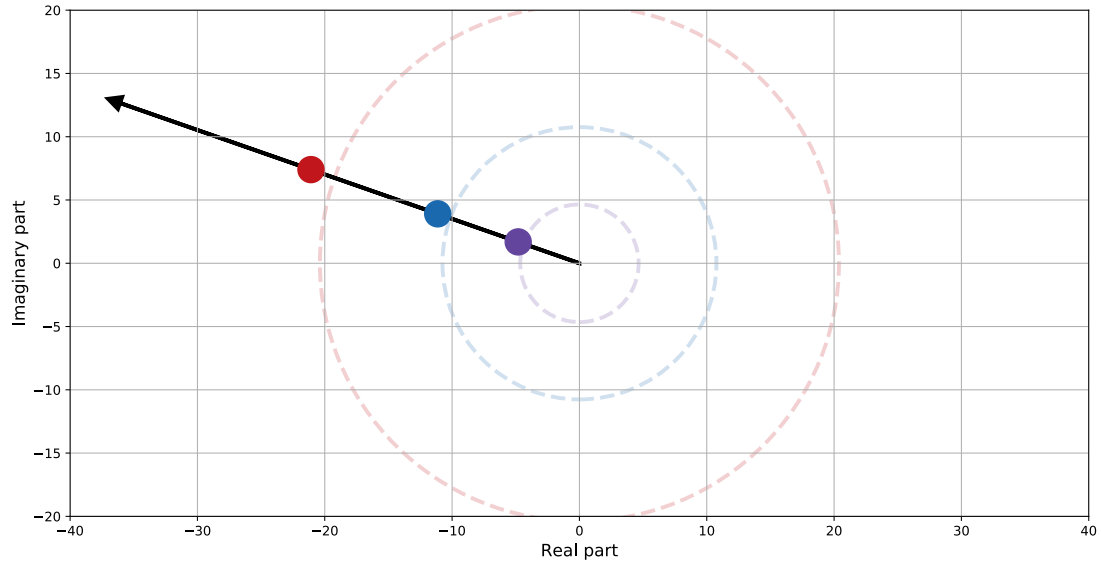
⇒ Aligned estimated sources, magnitudes inconsistent with prior

⇒ Uncertainty independent of the mixture

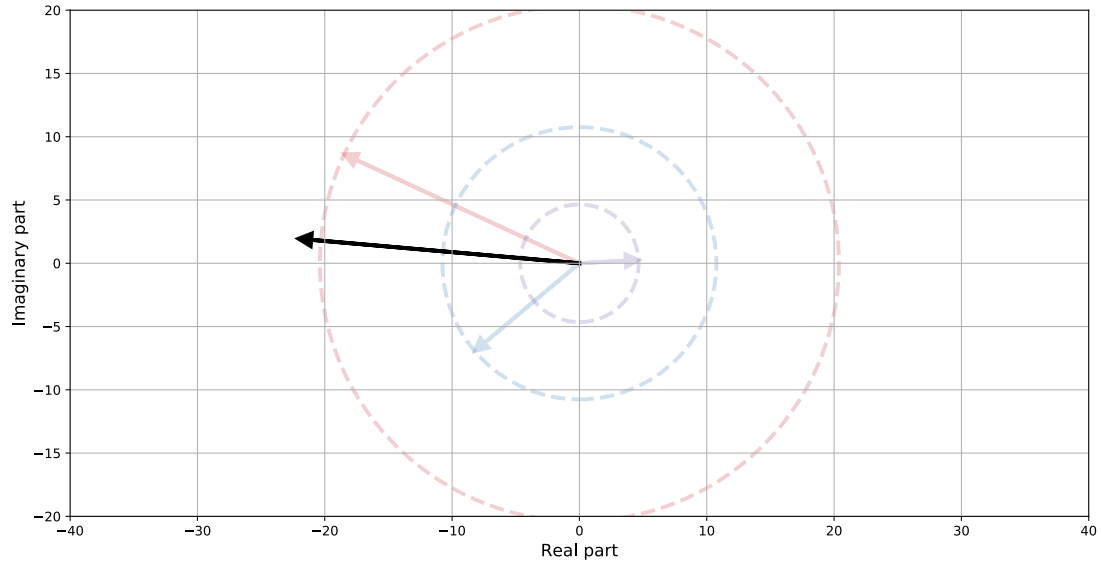
Another classical solution: magnitude ratios:  $\hat{s}_j = \frac{b_j}{\sum b} x$



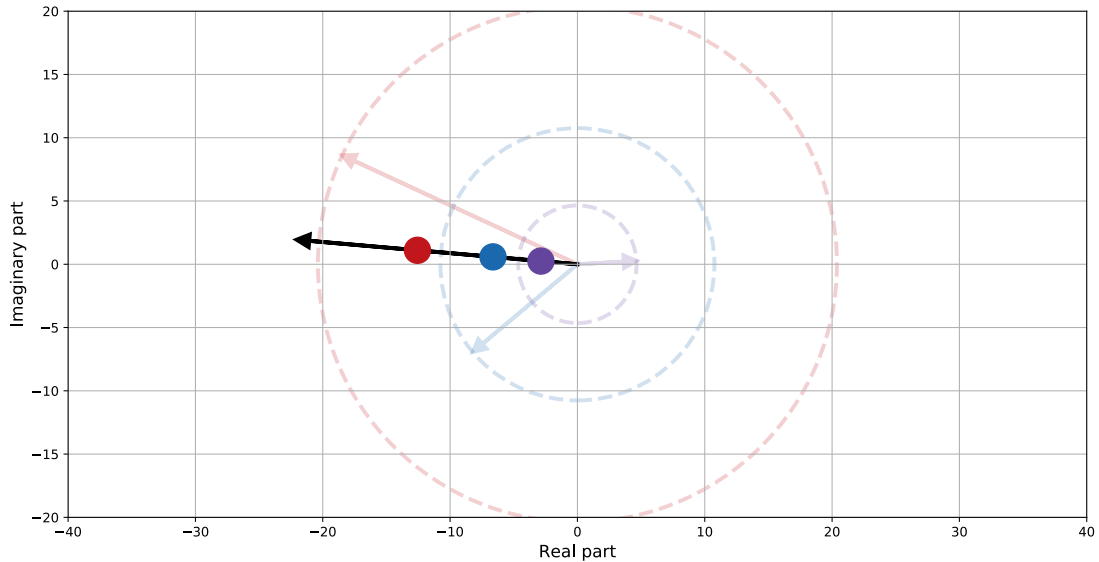
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⇒ Still estimating aligned sources rather than complying with the magnitude prior

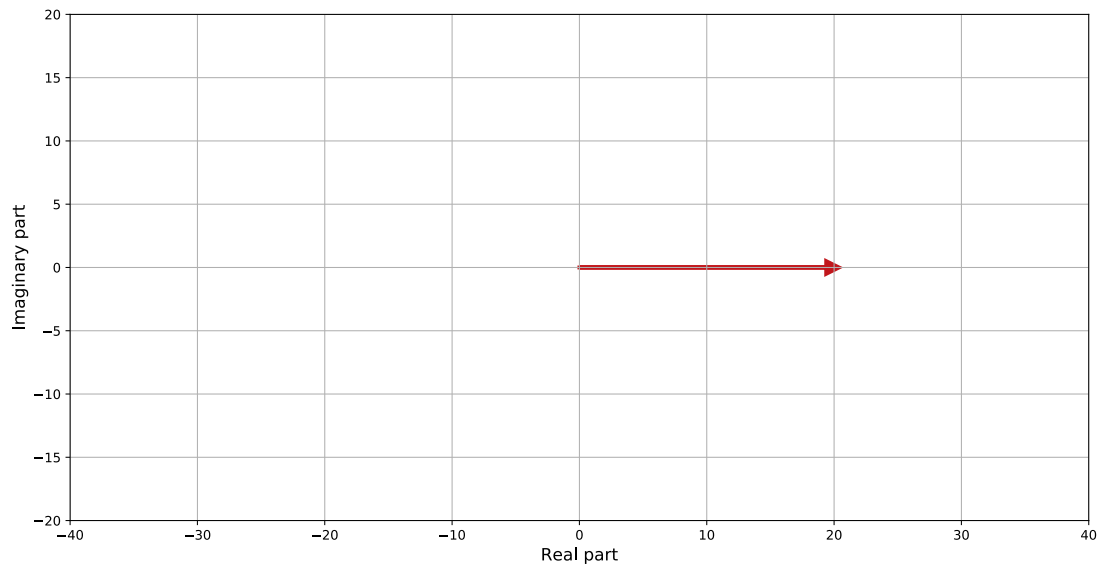
⇒ No tractable uncertainty

# **An ideal model**

**The donut-shaped distribution**

# Objective

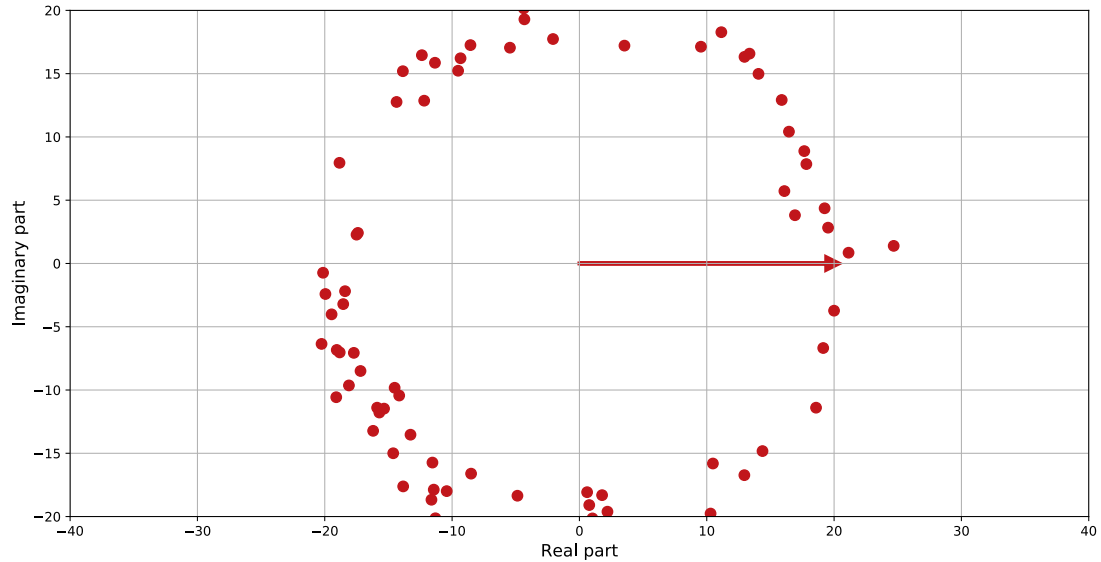
What do we want of a probabilistic model for a complex random variable with (approximately) known magnitude?





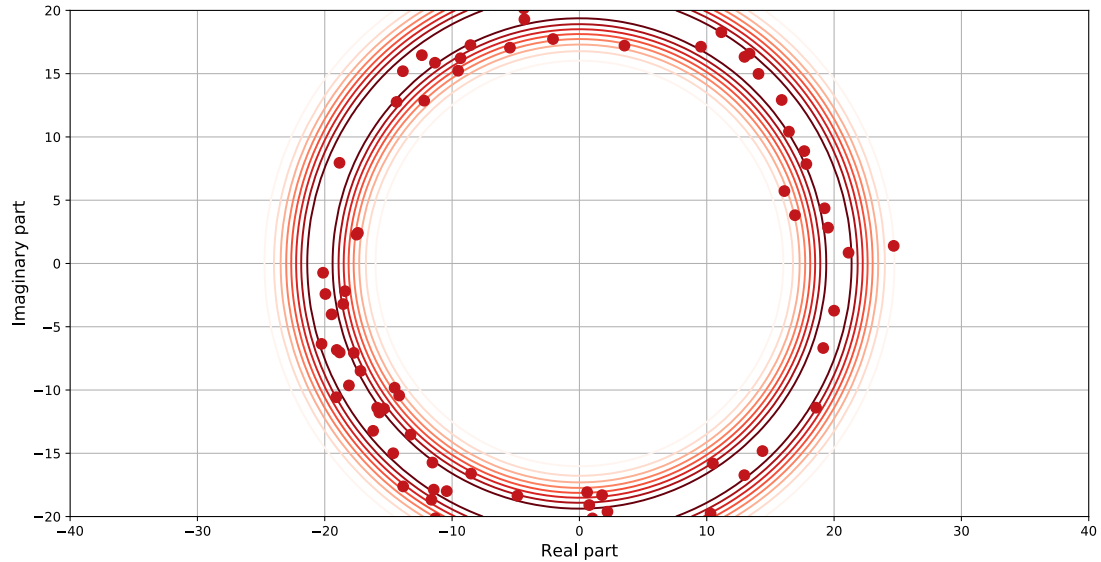
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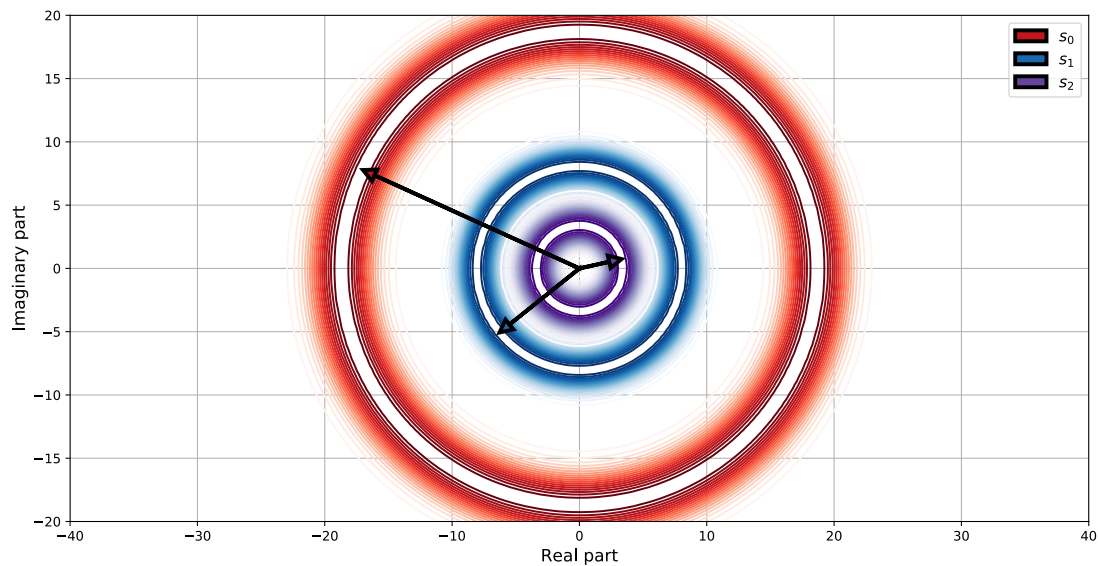


# Objective

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# The Donut distribution for modeling the sources

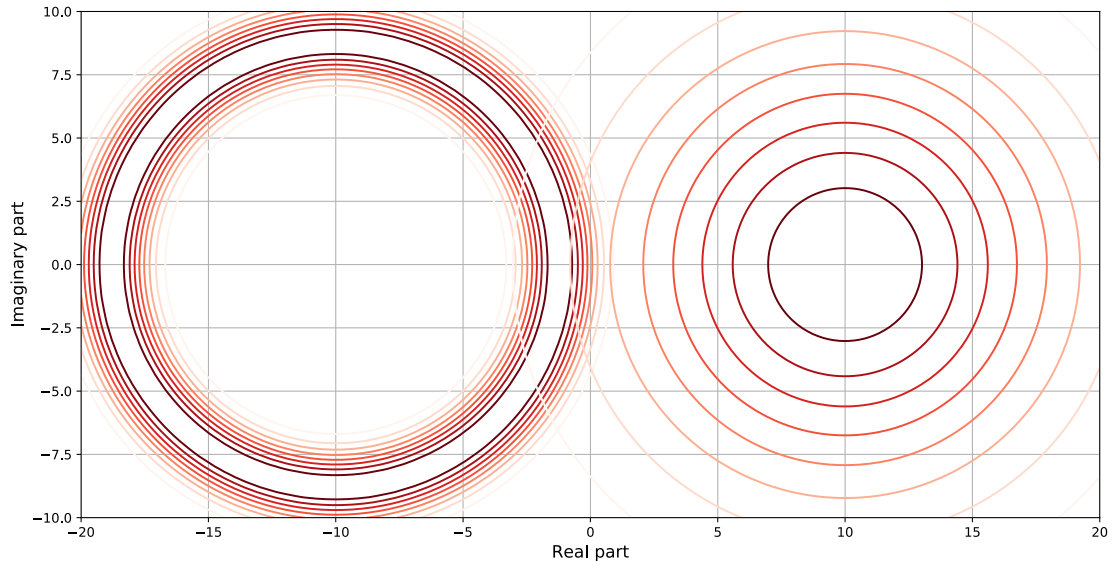


⇒ No model for the sum of donut variables

⇒ No easy way for separation:  $\mathbb{P}[s \mid x]$  non tractable

# Contribution

## BEADS Bayesian Expansion to Approximate the Donut Shape

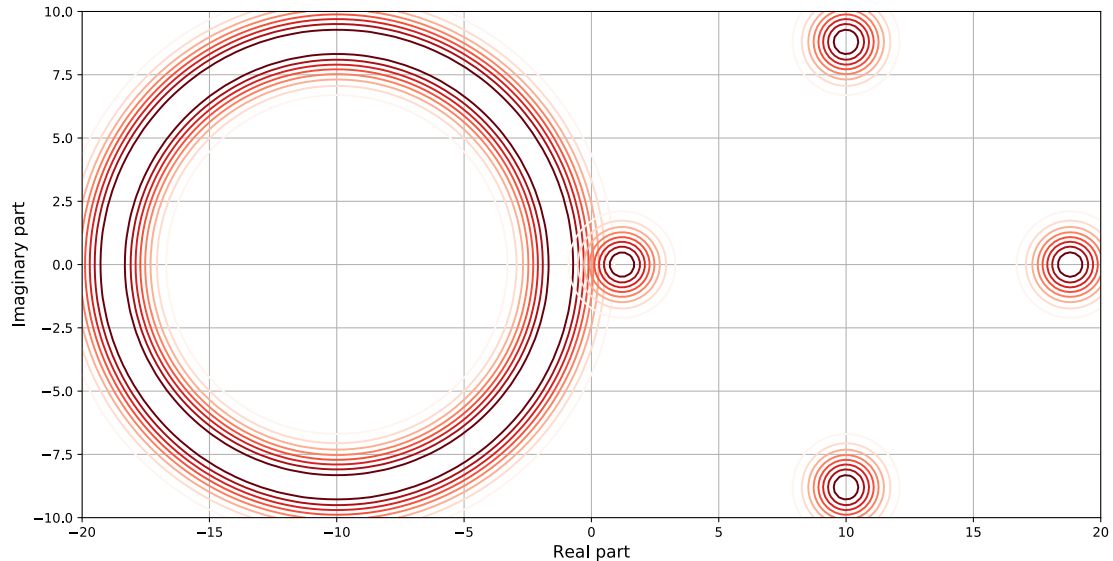


Sources distribution as a Gaussian Mixture Model:  $P[s_j] = \sum_c \pi[c] \mathcal{N}(s_j | b_j \omega^c, \sigma_j)$

⇒ Only two parameters:  $b_j$  and  $\sigma_j$

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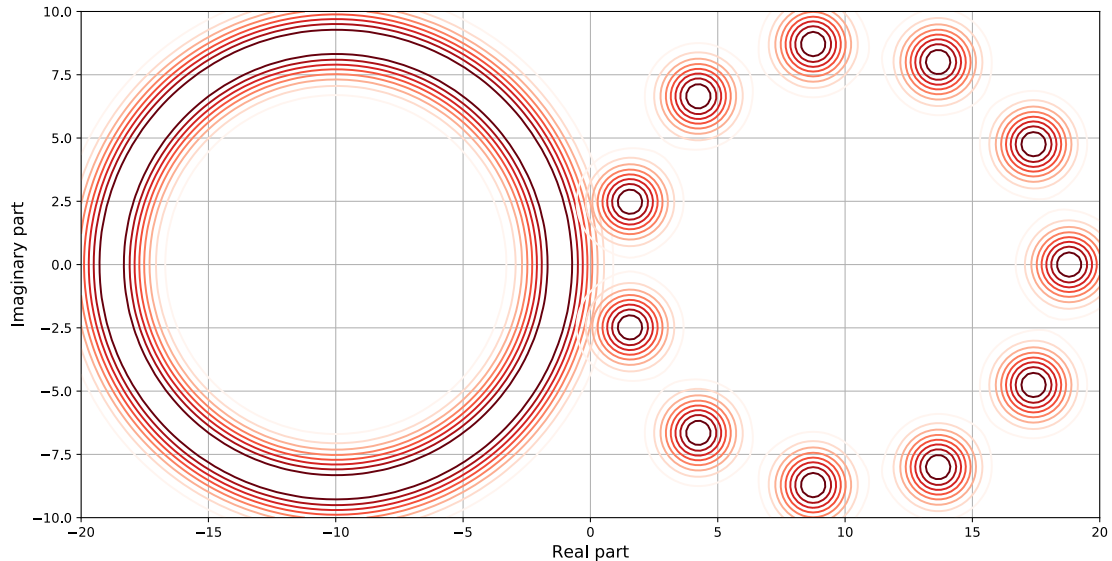


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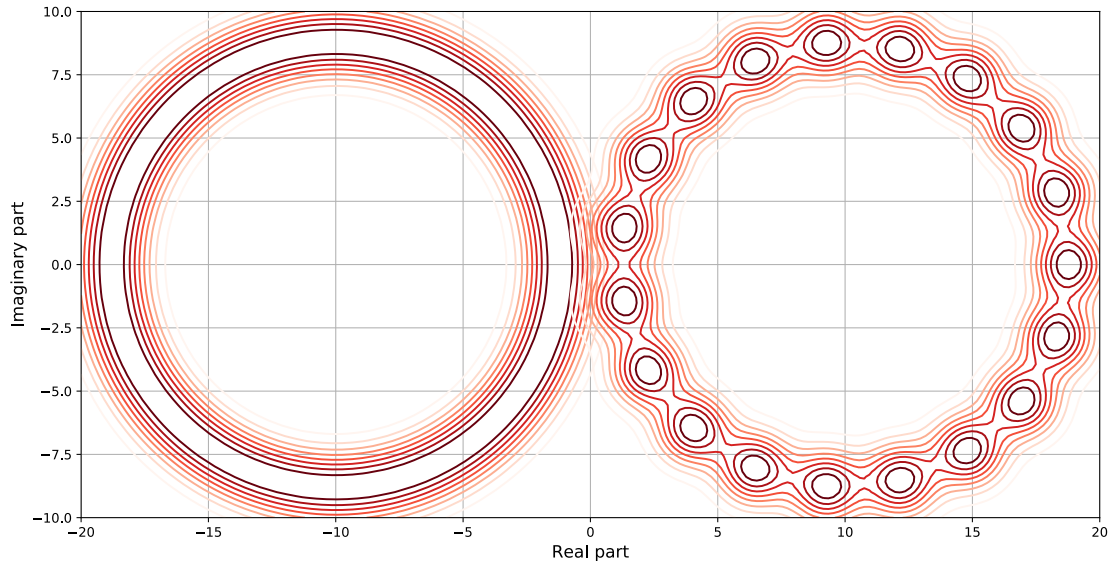


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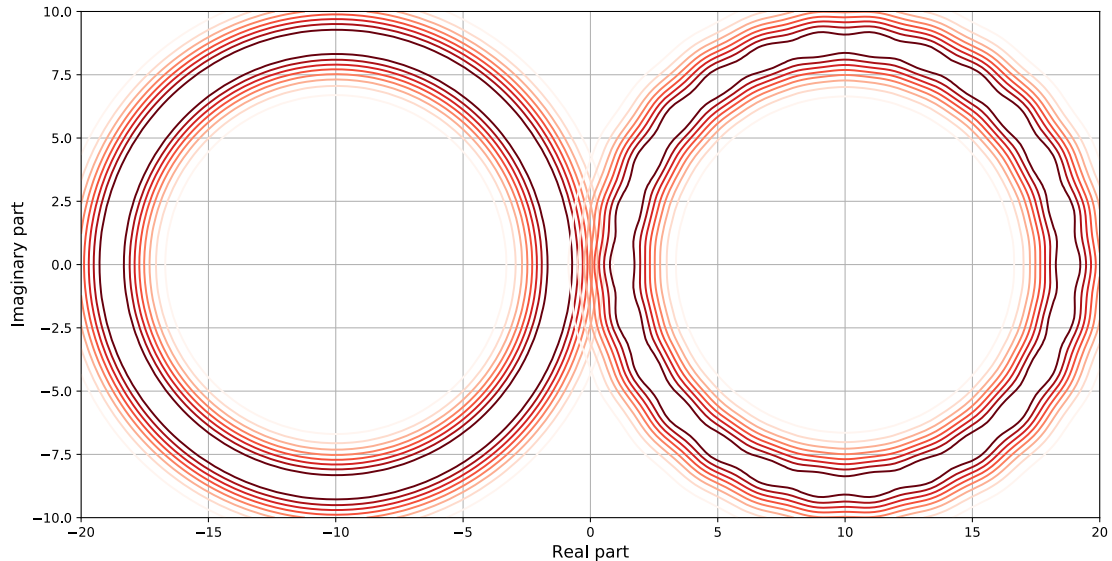


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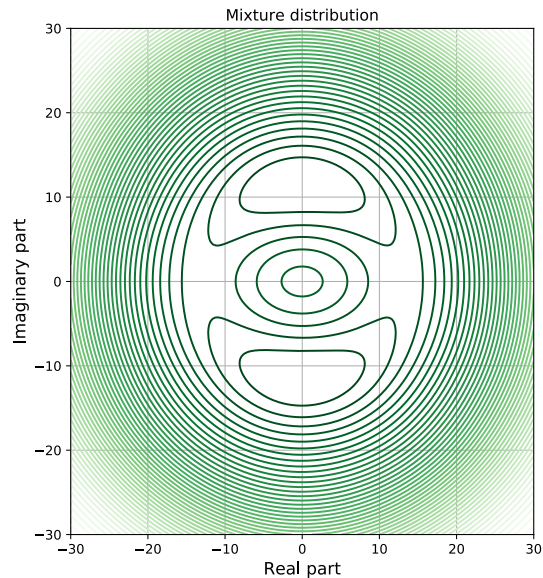
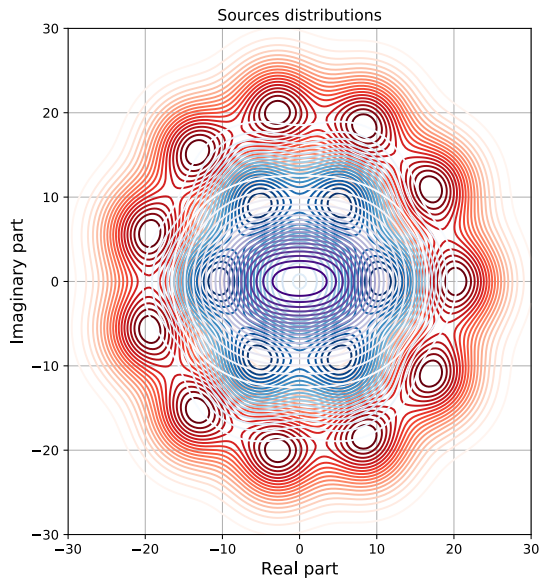
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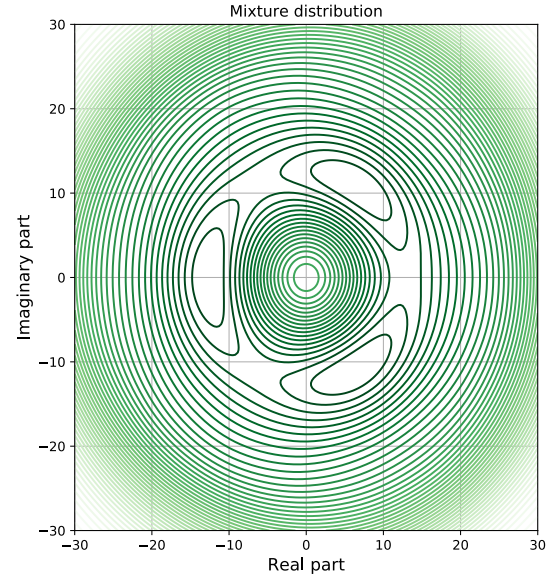
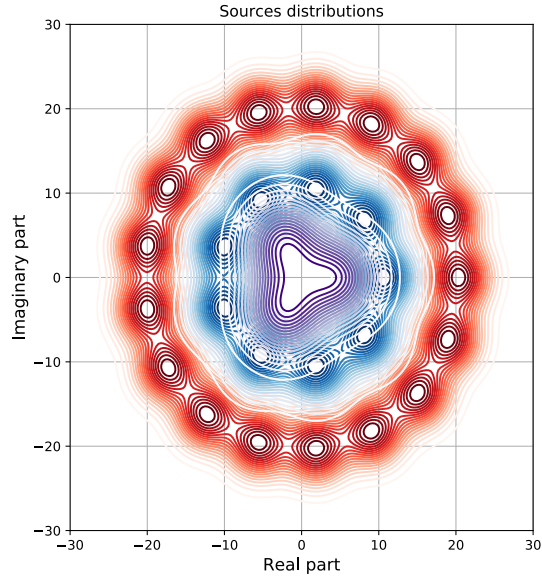
# Summing beads random variables

BEADS model for the sources  $\Rightarrow$  Gaussian Mixture Model for the mixture



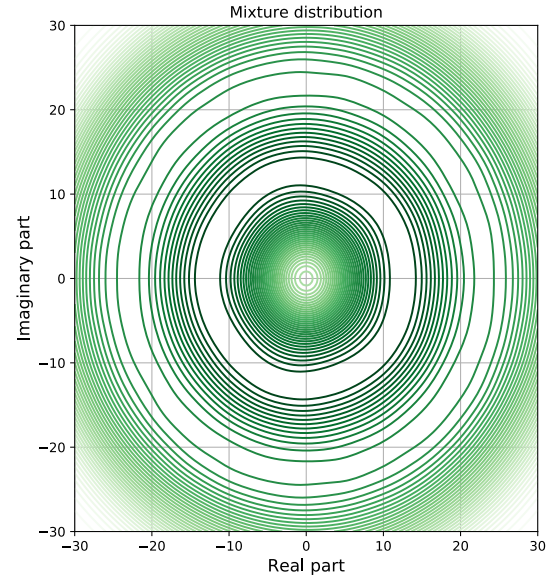
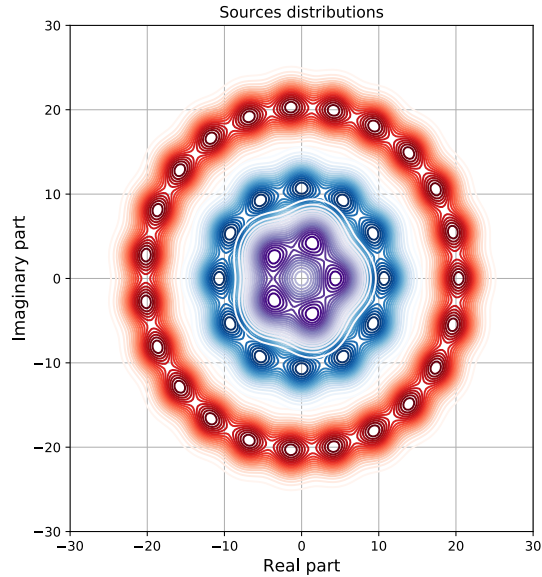
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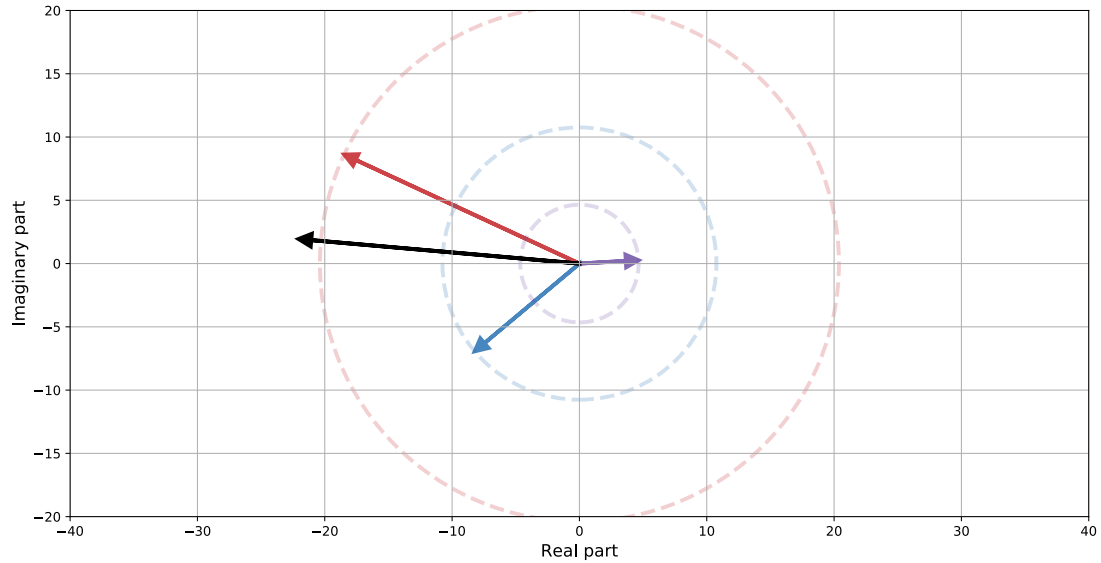


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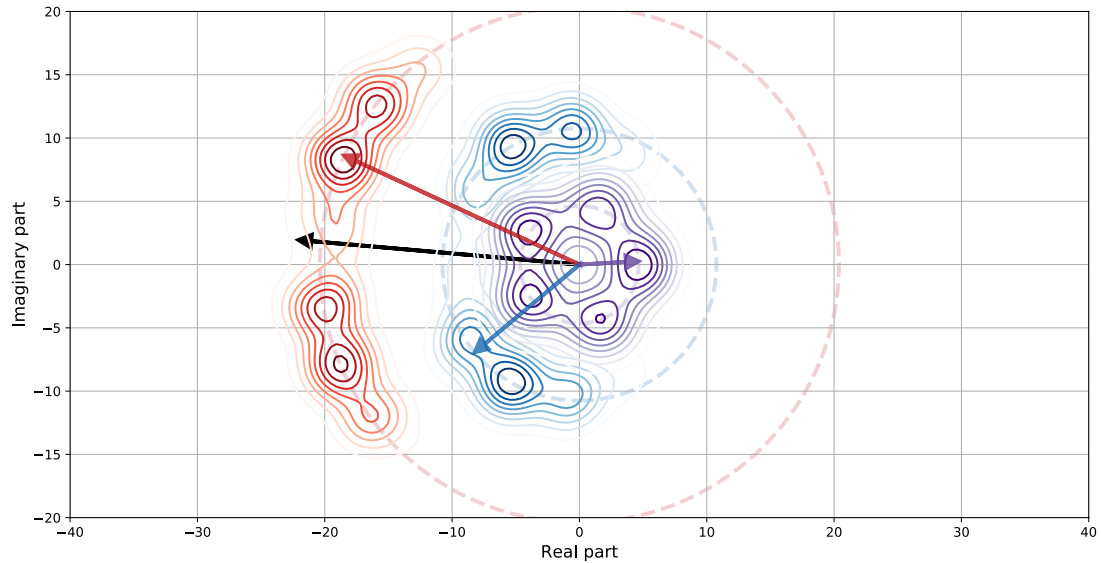
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The sources are estimated through Bayes theorem as  $s \mid x = \sum_c \pi(c \mid x) \mathcal{N}(s \mid \mu_{c|x}, \sigma_{|x})$



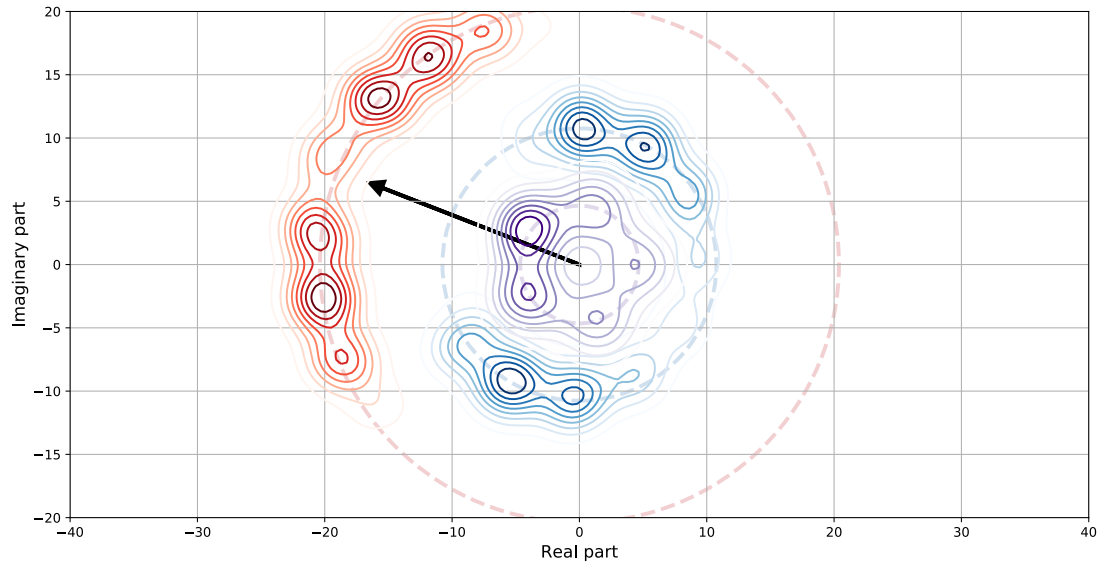
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⇒ Posterior is tractable, estimates consistent with the magnitude prior

⇒ Uncertainty is mix-dependent

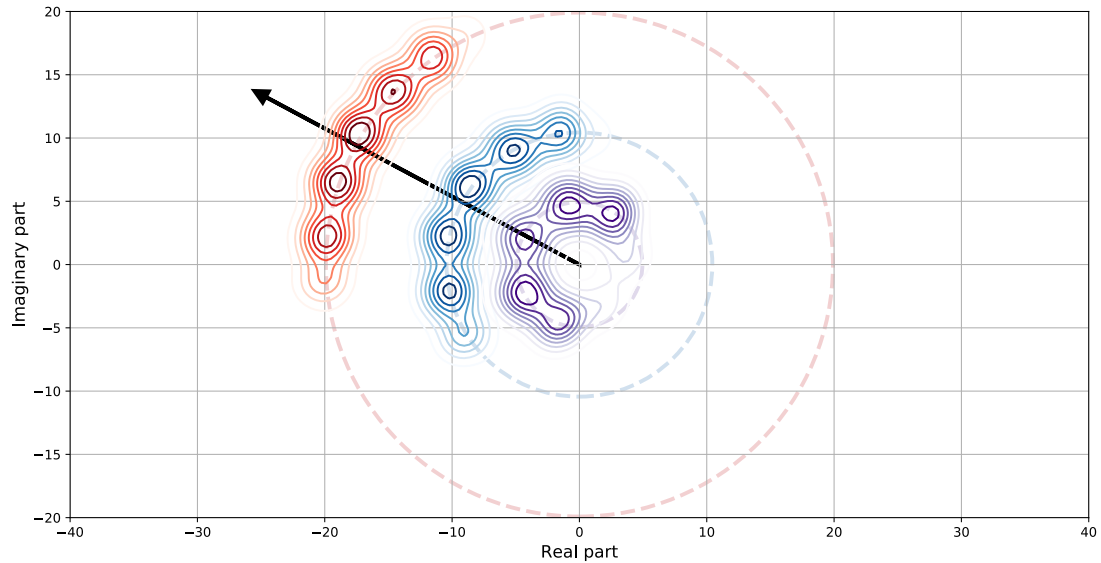
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# Conclusion: The beads model

## Core advantages

- Complex random variables with approximately known magnitudes
- Sums of beads sources is a GMM
- Separation is easy as GMM inference

## To go further

- Generalizes easily to multichannel
- Shared variances for the beads  $\Rightarrow$  computational savings

## Source code for this presentation

<https://github.com/aliutkus/beads-presentation>