# Problem Set 3 MIT CW Linear Algebra (18.06)

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## Section 3.2

Problem 13 (former problem 18)

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 12 \\ 0 \\ 0 \end{bmatrix} + y \begin{bmatrix} 3 \\ 1 \\ 0 \end{bmatrix} + z \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$
 (1)

## Problem 18 (former problem 24)

I don't know.

#### Problem 30 (former problem 36)

This was my wrong solution: if A has a rank of r. That means that the null space of A can be represented as a linear combination of n-r vectors. Any additional row that is contributed by B can be either dependent on the previous rows or not and thus either leaves the rank at r or increase it to r+1 which means that the sub space looses one degree of freedom. So  $N(C) \subset N(A)$ 

The correct solution is that the null space of A should take

$$\begin{bmatrix} A \\ B \end{bmatrix} \begin{bmatrix} \mathbf{x_1} \\ \mathbf{x_2} \end{bmatrix} = \mathbf{0} \tag{2}$$

so both  $Ax_1$  AND  $Bx_2$  should equal 0 and  $N(C) = N(A) \cap N(B)$ 

#### Problem 32 (former problem 37)

$$\begin{bmatrix} -1 & 0 & 1 & -1 & 0 & 0 \\ 1 & -1 & 0 & 0 & -1 & 0 \\ 0 & 1 & -1 & 0 & 0 & -1 \\ 0 & 0 & 0 & 1 & 1 & 1 \end{bmatrix}$$
 (3)

$$\begin{bmatrix} -1 & 0 & 1 & -1 & 0 & 0 \\ 0 & -1 & 1 & -1 & -1 & 0 \\ 0 & 1 & -1 & 0 & 0 & -1 \\ 0 & 0 & 0 & 1 & 1 & 1 \end{bmatrix}$$
 (4)

$$\begin{bmatrix} -1 & 0 & 1 & -1 & 0 & 0 \\ 0 & -1 & 1 & -1 & -1 & 0 \\ 0 & 0 & 0 & -1 & -1 & -1 \\ 0 & 0 & 0 & 1 & 1 & 1 \end{bmatrix}$$
 (5)

$$\begin{bmatrix}
-1 & 0 & 1 & -1 & 0 & 0 \\
0 & (-1) & 1 & -1 & -1 & 0 \\
0 & 0 & 0 & (-1) & -1 & -1 \\
0 & 0 & 0 & 0 & 0 & 0
\end{bmatrix}$$
(6)

$$\begin{bmatrix}
1 & 0 & -1 & 1 & 0 & 0 \\
0 & 1 & -1 & 1 & 1 & 0 \\
0 & 0 & 0 & 1 & 1 & 1 \\
0 & 0 & 0 & 0 & 0 & 0
\end{bmatrix}$$
(7)

$$\begin{bmatrix}
1 & 0 & -1 & 0 & -1 & -1 \\
0 & 1 & -1 & 0 & 0 & -1 \\
0 & 0 & 0 & 1 & 1 & 1 \\
0 & 0 & 0 & 0 & 0 & 0
\end{bmatrix}$$
(8)

Here are the special vectors:

$$\begin{bmatrix} 1\\1\\0\\-1\\0\\1 \end{bmatrix}, \begin{bmatrix} 1\\0\\0\\-1\\1\\0 \end{bmatrix}, \begin{bmatrix} 1\\1\\1\\0\\0\\0 \end{bmatrix}$$
 (9)

# Section 3.3

## worked example 3.3 A

1.

$$\begin{bmatrix}
1 & 2 & 3 & 5 & b_1 \\
2 & 4 & 8 & 12 & b_2 \\
3 & 6 & 7 & 13 & b_3
\end{bmatrix}$$
(10)

$$\begin{bmatrix}
1 & 2 & 3 & 5 & b_1 \\
0 & 0 & 2 & 2 & b_2 - 2 * b_1 \\
0 & 0 & -2 & -2 & b_3 - 3 * b_1
\end{bmatrix}$$
(11)

- $2. \ b_2 + b_3 5b_1 = 0$
- 3. if there was no  $\boldsymbol{b}$  or in other words  $\boldsymbol{b} = \boldsymbol{0}$  then we are talking about all linear combinations of  $A \cdot \boldsymbol{x}$  without restrictions. However in this case there's a restriction  $A \cdot \boldsymbol{x}$  must equal  $\boldsymbol{b}$ . Actually  $\boldsymbol{b}$  is a linear combination and the only restriction that it imposes is  $b_2 + b_3 5b_1 = 0$ . So the plane in  $\boldsymbol{R}^3$  are all the  $\boldsymbol{b}$  that meets  $b_2 + b_3 5b_1 = 0$ .
- 4. first let's continue from a u form to an R form of the matrix:

$$\begin{bmatrix}
1 & 2 & 3 & 5 & b_1 \\
0 & 0 & 1 & 1 & \frac{b_2 - 2 * b_1}{2} \\
0 & 0 & 0 & 0 & b_2 + b_3 - 5b_1
\end{bmatrix}$$
(13)

$$\begin{bmatrix}
1 & 2 & 0 & 2 & b_1 - \frac{3(b_2 - 2 * b_1)}{2} \\
0 & 0 & 1 & 1 & \frac{b_2 - 2 * b_1}{2} \\
0 & 0 & 0 & 0 & b_2 + b_3 - 5b_1
\end{bmatrix}$$
(14)

(15)

first let's find the particular solution:

$$x_{particular} = \begin{bmatrix} 4b_1 - \frac{3b_2}{2} \\ 0 \\ \frac{b_2 - 2*b_1}{2} \\ 0 \end{bmatrix}$$
 (16)

And now for the special solution:

$$s1 = \begin{bmatrix} -2\\1\\0\\0 \end{bmatrix} s2 = \begin{bmatrix} -2\\0\\-1\\1 \end{bmatrix}$$
 (17)

And the null space

$$c_{1} \begin{bmatrix} -2\\1\\0\\0 \end{bmatrix} + c_{2} \begin{bmatrix} -2\\0\\-1\\1 \end{bmatrix} \tag{18}$$

5. I did before... and already got

$$R = \begin{bmatrix} 1 & 2 & 0 & 2 & b_1 - \frac{3(b_2 - 2*b_1)}{2} \\ 0 & 0 & 1 & 1 & \frac{b_2 - 2b_1}{2} \\ 0 & 0 & 0 & 0 & b_2 + b_3 - 5b_1 \end{bmatrix}$$
(19)

with the particular solution: first let's find the particular solution:

$$x_{particular} = \begin{bmatrix} 4b_1 - \frac{3b_2}{2} \\ 0 \\ \frac{b_2 - 2*b_1}{2} \\ 0 \end{bmatrix}$$
 (20)

6. if we assign  $(b_1, b_2, b_3) = (0, 6, -6)$  to the  $x_{particular}$  then we get

$$\boldsymbol{x_{particular}} = \begin{bmatrix} 4b_1 - \frac{3b_2}{2} \\ 0 \\ \frac{b_2 - 2*b_1}{2} \\ 0 \end{bmatrix} = \begin{bmatrix} -9 \\ 0 \\ 3 \\ 0 \end{bmatrix}$$
 (21)

The complete solution:

$$\boldsymbol{x} = \begin{bmatrix} -9\\0\\3\\0 \end{bmatrix} + c_1 \begin{bmatrix} -2\\1\\0\\0 \end{bmatrix} + c_2 \begin{bmatrix} -2\\0\\-1\\1 \end{bmatrix}$$
 (22)

#### worked example 3.3 B

- 1. m >= n = r.
- 2. m is arbitrary, n = 2, r = 1, and  $\boldsymbol{b}$  is a vector of size m. The particular solution requires that  $x_2$  the free variable shall equal 0. So the whole solution can be expressed as:

$$x = x_{particular} + CX_{special} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} + c \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$
 (23)

We know that  $Rx_{particular} = b$ . So we can deduce that R looks as follows:

$$R = \begin{bmatrix} \boldsymbol{b} & \boldsymbol{f} \end{bmatrix} \tag{24}$$

where we so far 'know'  $\boldsymbol{b}$  which is the solution, but have no idea about f. We also know that the special solution has  $x_2 = 1$ :

$$\begin{bmatrix} b & f \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \mathbf{0} \tag{25}$$

so from that we can learn that f = -b so all in all we have here:

$$A = \begin{bmatrix} b & -b \end{bmatrix} \tag{26}$$

so basically the following tells the whole story:

$$\begin{bmatrix} \boldsymbol{b} & -\boldsymbol{b} \end{bmatrix} * \begin{bmatrix} 1 \\ 0 \end{bmatrix} + c \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix} \end{bmatrix} = \boldsymbol{b}$$
 (27)

- 3. m >= n, r < n, Also Ax! = b
- 4. n = 3, m is arbitrary. if C = 0 then  $\boldsymbol{b}$  is in the column space of A, otherwise  $\boldsymbol{b}$  is not in the column space of A. (1,0,1) should be in the null space of A it means that column 1 of A is the negavie to column 3 of A. If the 2nd column is a multiple of columns 1 or 3 then r = 1, otherwise r = 2.
- 5. with infinitely many solutions, the null space must contain non zero solutions and  $\boldsymbol{b}$  should be one of them. The rank r must be smaller than n.

#### worked example 3.3 C

$$\begin{bmatrix}
1 & 2 & 1 & 0 & | & 4 \\
2 & 4 & 4 & 8 & | & 2 \\
4 & 8 & 6 & 8 & | & 10
\end{bmatrix}$$
(28)

$$\begin{bmatrix}
1 & 2 & 1 & 0 & | & 4 \\
0 & 0 & 2 & 8 & | & -6 \\
0 & 4 & 2 & 8 & | & -6
\end{bmatrix}$$
(29)

$$\begin{bmatrix}
1 & 2 & 1 & 0 & | & 4 \\
0 & 1 & \frac{1}{2} & 2 & | & -1\frac{1}{2} \\
0 & 0 & 1 & 4 & | & -3
\end{bmatrix}$$
(30)

$$\begin{bmatrix}
1 & 0 & 0 & -4 & 7 \\
0 & 1 & \frac{1}{2} & 2 & -1\frac{1}{2} \\
0 & 0 & 1 & 4 & -3
\end{bmatrix}$$
(31)

$$\begin{bmatrix}
1 & 0 & 0 & -4 & 7 \\
0 & 1 & 0 & 0 & 0 \\
0 & 0 & 1 & 4 & -3
\end{bmatrix}$$
(32)

 $x_{particular}$  is when the free variable  $x_4 = 0$ . So

$$\boldsymbol{x_{particular}} = \begin{bmatrix} 7\\0\\-3 \end{bmatrix} \tag{33}$$

 $x_{special}$  is when the free variable  $x_4 = 1$ . So

$$x_{special} = \begin{bmatrix} 4\\0\\-4 \end{bmatrix} \tag{34}$$

So,

$$\boldsymbol{x} = \boldsymbol{x}_{particular} + C \cdot \boldsymbol{X}_{special} = \begin{bmatrix} 7 \\ 0 \\ -3 \end{bmatrix} + C \cdot \begin{bmatrix} 4 \\ 0 \\ -4 \end{bmatrix}$$
(35)

Let's denote  $\mathbf{y} = (y_1, y_2, y_3)$ . Instead of calculating  $y_1(row1) + y_2(row2) + y_3(row3)$ , we shall do  $A^T \mathbf{y} = \mathbf{0}$ .

$$\begin{bmatrix}
1 & 2 & 4 & b_1 \\
2 & 4 & 8 & b_2 \\
1 & 4 & 6 & b_3 \\
0 & 8 & 8 & b_4
\end{bmatrix}$$
(36)

$$\begin{bmatrix}
1 & 2 & 4 & b_1 \\
0 & 0 & 0 & b_2 - 2b_1 \\
0 & 2 & 2 & b_3 - b_1 \\
0 & 8 & 8 & b_4
\end{bmatrix}$$
(37)

$$\begin{bmatrix}
1 & 2 & 4 & b_1 \\
0 & 2 & 2 & b_3 - b_1 \\
0 & 8 & 8 & b_4 \\
0 & 0 & 0 & b_2 - 2b_1
\end{bmatrix}$$
(38)

$$\begin{bmatrix}
1 & 2 & 4 & b_1 \\
0 & 1 & 1 & \frac{b_3 - b_1}{2} \\
0 & 0 & 0 & b_4 - 4b_3 + 4b_1 \\
0 & 0 & 0 & b_2 - 2b_1
\end{bmatrix}$$
(39)

$$\begin{bmatrix}
1 & 0 & 2 \\
0 & 1 & 1 \\
0 & 0 & 0 \\
0 & 0 & 0
\end{bmatrix}
\begin{bmatrix}
2b_1 - b_3 \\
\frac{b_3 - b_1}{2} \\
b_4 - 4b_3 + 4b1 \\
b_2 - 2b_1
\end{bmatrix}$$
(40)

The solution for the transposed matrix can be expressed as

$$A^{T} = x_{particular} + C \cdot x_{special} \tag{41}$$

$$= \begin{bmatrix} 2b_1 - b_3 \\ \frac{b3 - b1}{2} \\ 0 \end{bmatrix} + C \cdot \begin{bmatrix} -2 \\ -1 \\ 1 \end{bmatrix}$$
 (42)

$$= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} + C \cdot \begin{bmatrix} -2 \\ -1 \\ 1 \end{bmatrix} \tag{43}$$

Which means that for a zero solution  $y_1 = -2$ ,  $y_2 = -1$  and  $y_3 = 1$ . Let's check:  $(4,2,10) \cdot (-2,-1,1) = -8 - 2 + 10 = 0$  The (4,2,10) is in the column space of A, so it's a linear combination of the other columns. So in much the same way it can be added as the 5th row to the  $A^T$  matrix and as such it should be a linear combination of the rows and thus adhere to  $(r_1, r_2, r_3) \cdot (-2, -1, 1) = 0$  that every row  $(r_1, r_2, r_3)$  in the transposed matrix adheres to.

## section 3.2 Problem 48 (former section 3.3 - problem 17)

1. The problem states that actually there is a vector  $\mathbf{d}$  such that  $B\mathbf{d} = B^{(j)}$  where  $B^{(j)}$  is the j'th column of B. So

$$B\mathbf{d} = B^{(j)}$$

$$A(B\mathbf{d}) = AB^{(j)}$$

$$(AB)\mathbf{d} = AB^{(j)}$$

$$(AB)\mathbf{d} = (AB)^{(j)}$$

or in other words the same linear combination d that was applied on the columns of B and created column j in B, is the same linear combination d that when applied on the columns of AB, creates column j in AB. So AB cannot indeed create a new pivot column out of thin air and indeed  $rank(AB) \le rank(B)$ .

2.

$$A1 = \begin{bmatrix} 1 & 1 \end{bmatrix} \tag{44}$$

$$A2 = \begin{bmatrix} 0 & 0 \end{bmatrix} \tag{45}$$

## section 3.2 Problem 50 (former section 3.3 - problem 19)

Every column of AB is a linear combination of the columns of A. Thus, we can't find in AB a column which is not a linear combination of the columns

in A. So the column space of AB is a subset of the column space of A  $(AB \subseteq A)$  and the rank is thus lower equal.

AB = I which means the rank of AB is n. Since the rank of A is greater equal then the rank of A is n as well which means A is invertible and thus B must be its two sided inverse, that is AB = I as well as BA = I.

#### section 3.2 Problem 56 (former section 3.3 - problem 25)

A = (pivot columns of A) (first r rows of R) =

## section 3.2 Problem 58 (former section 3.3 - problem 27)

a 
$$I_{rxr}, F_{rx(n-r)}, 0_{(m-r)xn}$$

b

$$B = \begin{bmatrix} I \\ 0 \end{bmatrix}$$

where I has dimensions  $r \times r$  and 0 has dimensions  $n \times r$ .

 $\mathbf{c}$ 

$$C = \begin{bmatrix} I & 0 \end{bmatrix}$$

where I has dimensions  $r \times r$  and 0 has dimensions  $(m-r) \times (m-r)$ .

#### section 3.2 Problem 60 (former section 3.3 - problem 28)

I don't understand the question

## section 3.3 Problem 13 (former section 3.4 - problem 13)

a proof that it's not correct by example:

$$x_1 + 2x_2 = 3$$
  
 $x = x_p + C \cdot x_n = \begin{bmatrix} 3 \\ 0 \end{bmatrix} + C \cdot \begin{bmatrix} -2 \\ 1 \end{bmatrix}$ 

however if we claim that

$$x = C1 \cdot x_p + C2 \cdot x_n = C1 \cdot \begin{bmatrix} 3 \\ 0 \end{bmatrix} + C2 \cdot \begin{bmatrix} -2 \\ 1 \end{bmatrix}$$
 (47)

Then for C1 = 2 and C2 = 1 we shall get that the solution is:

$$x = C1 \cdot x_p + C2 \cdot x_n = 2 \cdot \begin{bmatrix} 3 \\ 0 \end{bmatrix} + \begin{bmatrix} -2 \\ 1 \end{bmatrix}$$
 (48)

or in other words:  $x_1 = 4$  and  $x_2 = 1$  and putting this back into the equation we get  $x_1 + 2x_2 = 4 + 2 = 6 \neq 3$ 

b Again by using the same example:

$$x_1 + 2x_2 = 3 \tag{49}$$

One solution is  $x_1 = 3$  and  $x_2 = 0$  Another solution is  $x_1 = 1$  and  $x_2 = 1$ . We demonstrated 2 solutions which is more than one. We can demonstrate endless more :)

c let's look at the following 2x2 set:

$$\left[\begin{array}{cc|c} 1 & \frac{1}{2} & 1 \\ 0 & 0 & 0 \end{array}\right]$$

The solution for this is

$$\begin{bmatrix} 1 \\ 0 \end{bmatrix} + C \cdot \begin{bmatrix} -\frac{1}{2} \\ 1 \end{bmatrix}$$

For the case of C=0, that is with the free variable  $x_2$  equals 0 - then  $x_p=(10)$  and the size is  $\sqrt{1^2+0^2}=1$  For the case of  $C=\frac{1}{2}$  we have  $x_1=\frac{3}{4}$  and  $x_2=\frac{1}{2}$  with the size  $=\sqrt{\left(\frac{3}{4}\right)^2+\left(\frac{1}{2}\right)^2}=\sqrt{\frac{13}{16}}<1$ 

d if A is invertible then there's on solution in the null space:  $x_n = 0$ 

#### section 3.3 Problem 25 (former section 3.4 - problem 25)

- a no solutions can happen if r < m (and the **b** elements are not zero for the rows without pivots.
- b infinitely many solutions for every  $\boldsymbol{b}$  is the case of r = m < n.
- c exactly one solution for some  $\boldsymbol{b}$  is the case of r=n and m>r. If the  $\boldsymbol{b}$  items beyond the first r are 0 then endless solutions. Otherwise no solution.
- d exactly one solution for every b: r = m = n.

#### section 3.3 Problem 28 (former section 3.4 - problem 28)

$$\begin{bmatrix}
 1 & 2 & 3 & 0 \\
 0 & 0 & 4 & 0
 \end{bmatrix}$$

$$\begin{bmatrix}
 1 & 2 & 3 & 0 \\
 0 & 0 & 1 & 0
 \end{bmatrix}$$

$$\left[\begin{array}{c|cc} 1 & 2 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{array}\right] \boldsymbol{x_n} = C \cdot \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}$$

and then -

$$\begin{bmatrix}
1 & 2 & 3 & 5 \\
0 & 0 & 4 & 8
\end{bmatrix}$$

$$\begin{bmatrix}
1 & 2 & 3 & 0 \\
0 & 0 & 1 & 2
\end{bmatrix}$$

$$\left[\begin{array}{c|c} 1 & 2 & 0 & -6 \\ 0 & 0 & 1 & 2 \end{array}\right] \boldsymbol{x_p} = \begin{bmatrix} -6 \\ 0 \\ 2 \end{bmatrix}$$

## section 3.3 Problem 35 (former section 3.4 - problem 35)

Figure 1 charts the vector  $\boldsymbol{x}$ . I used the following python code:

Listing 1: Insert code directly in your document

```
import numpy as np
import matplotlib.pyplot as plt

K = np.zeros((9, 9))

K[0,0]=2
for i in range(0,8):
    K[i+1,i+1]=2
    K[i+1,i]=-1
    K[i, i+1] = -1
print(K)

b=10*np.ones((9,1))
print(b)

base =[i for i in range(1,10)]
x= np.matmul(np.linalg.inv(K),b)

plt.plot(base, x)
plt.show()
```

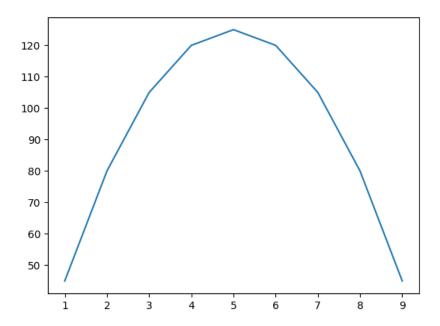


Figure 1: Drawing  ${\pmb x}$ . Multiplying a 9x9 second difference matrix by  ${\pmb x}$  gives  ${\pmb b}=(10,10,\ldots,10)$ 

# section 3.3 Problem 36 (former section 3.4 - problem 36)

My wrong answer: Not necessarily. Let's take for example

$$\begin{bmatrix} 1 & 1 \\ 2 & 2 \end{bmatrix} \cdot \boldsymbol{x} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \tag{50}$$

vs.

$$\begin{bmatrix} 1 & 1 \\ 3 & 3 \end{bmatrix} \cdot \boldsymbol{x} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \tag{51}$$

Same solutions however A doesn't equal C