

Aliya Tang

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EDUCATION

Columbia University, Barnard College, New York, NY

August 2022 - May 2026

Bachelor of Arts in Computer Science

GPA: 3.8

- **Relevant Coursework:** Deep Learning in Computer Vision, Creative Embedded Systems, Advanced Programming in C, Intro to Databases, Discrete Mathematics, Data Structures and Algorithms in Java, Calculus III, Linear Algebra
- **Activities and Organizations:** Columbia University Robotics Club, Girls Who Code, Rewriting the Code, Gourmand, WBAR
- **Honors:** Barnard College Science Pathways Scholars Program, Dean's List: Fall 2022, Spring 2023, Spring 2024

SKILLS AND LANGUAGES

- **Languages:** Java, Python, C, SQL, C++, MongoDB, Neo4j
- **Technologies/Frameworks:** Git, Unix/Linux, Embedded Systems (Petoï Bittle Robot Dog, CrazyFlye 2.0/2.1, and Raspberry Pi), HTML, CSS, React, MySQL, ROS/micro-ROS, OpenCV, TensorFlow, Edge Impulse

TECHNICAL PROFESSIONAL EXPERIENCE

Barnard College | The Accessible and Accelerated Robotics Lab (A²R Lab)

New York, NY

Undergraduate Research Assistant

January 2023 - Present

- Integrated computer vision algorithms with ROS and micro-ROS, elevating compact *Petoï Bittle Robot Dog* navigation
- Conducted 100+ literature reviews to enhance accessible hardware and software for the robotic platform
- Optimized C++ and Python code for peak performance in direct and feature-based visual odometry algorithms

Computer Vision Research Intern: Drone Racing

May 2024 - August 2024

- Collaborated with a research team to secure research funding from the Barnard College Science Research Institute for developing cost-effective software for tiny drones
- Integrated real-time object identification and trajectory algorithms onto CrazyFlye, improving its navigational precision
- Debugged and enhanced the TinyMPC algorithm codebase, improving its robustness and reliability

Computer Vision Research Intern: Tiny Robots

May 2023 - August 2023

- Received research funds at Barnard College Science Research Institute over Summer 2023 to support computationally constrained vision algorithm deployment on the *Petoï Bittle Robot Dog*
- Enhanced visual estimation algorithms for global mapping on cost-effective computing systems
- Showcased findings through Lida Orzeck '68 Poster Session on the integration of Visual Simultaneous Localization and Mapping (VSLAM) and Visual Inertial Odometry (VIO) on embedded systems

355Code

Remote

Computer Science Instructor

May 2023 - May 2024

- Assisted K-12 students in learning JavaScript, Python, and Java, focusing on improving their debugging skills
- Developed and executed marketing strategies, resulting in a 30% increase in enrollment for 30+ families
- Led high school internship program on computer science, mentoring students in technical and professional skills

SELECTED PROJECTS

Tiny Drone: Computer Vision

May 2024 - Present

Research Project (Python, OpenCV, Git, Ultralytics, Tkinter)

- Developed a real-time object classification algorithm to be integrated with a Model Predictive Control algorithm
- Coordinated with hardware team to refactor computer vision algorithm onto CrazyFlye 2.1

Web Page Downloader

October 2023

Class Project (Sockets API, HTTP, TCP/IP, File I/O, Unix/Linux, Git)

- Developed a web downloader utility using Sockets API, similar to the 'wget' tool with limited functionality
- Implemented HTTP 1.1/1.0 protocol to download a single file from the Internet into the current directory
- Applied network programming techniques for data transmission and incorporated file I/O operations

LEADERSHIP

Columbia University | Gourmand

New York, NY

Digital Committee Lead

May 2023 - Present

- Created 10+ event graphics per month for social media using Canva and Figma
- Delegated tasks amongst 20 member committee, ensuring seamless content creation, to over 2,000 followers