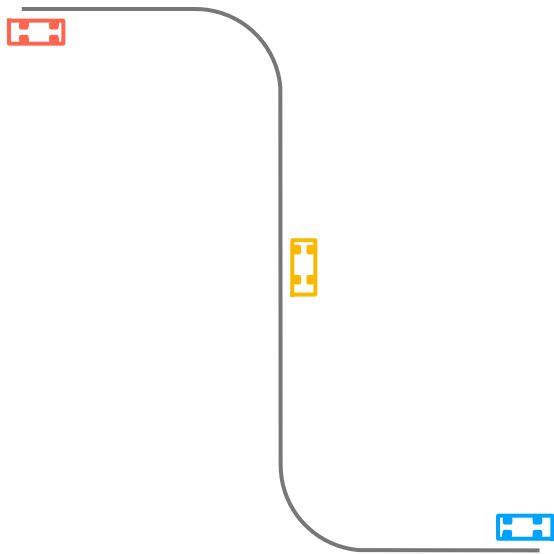
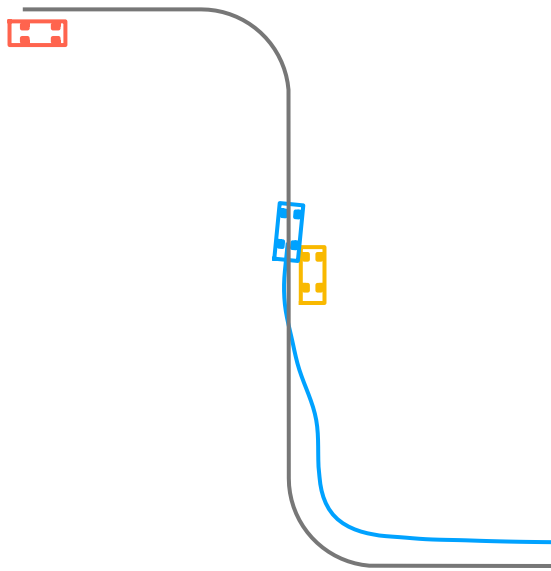


Time-optimal trajectory

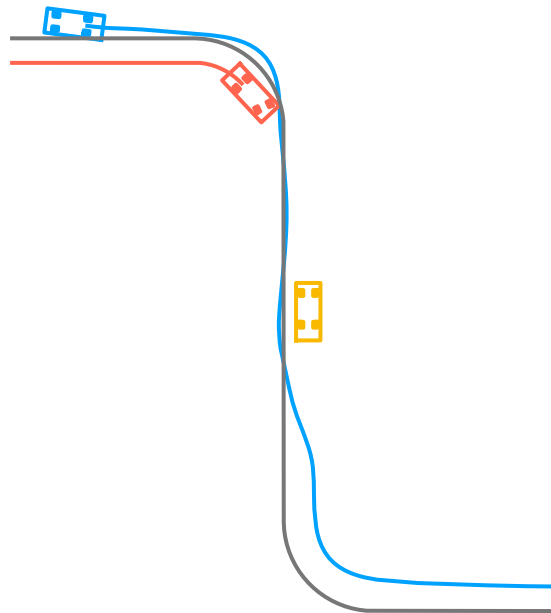
Step 1



Step 80



Step 140



Step 145

