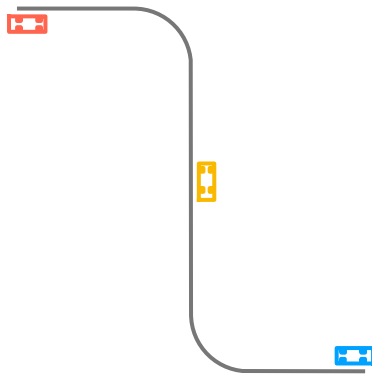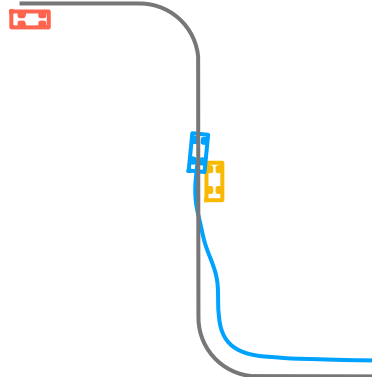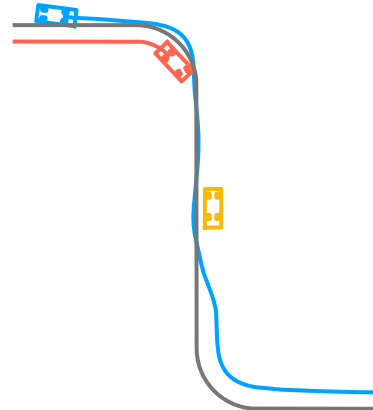# Time-optimal trajectory

Step 1   Step 80   Step 140   Step 145