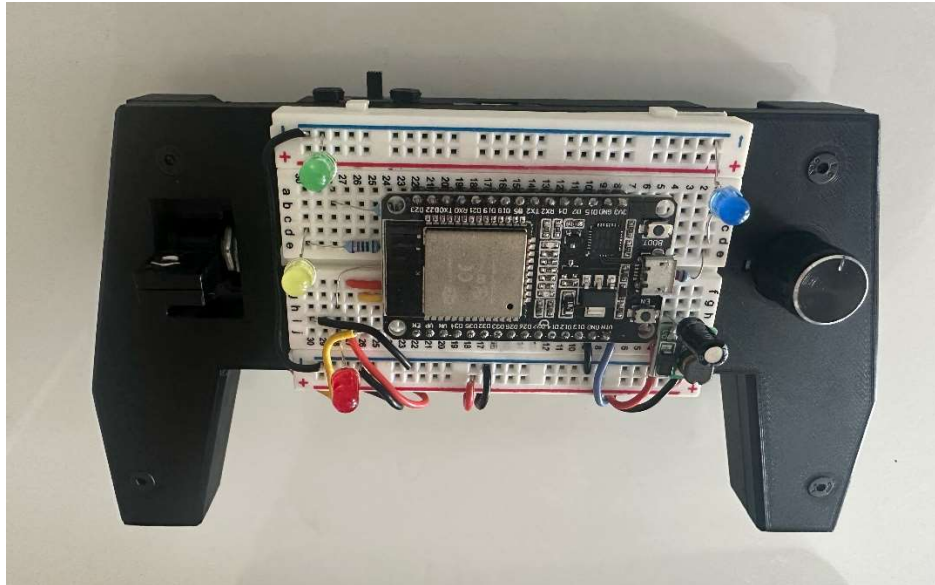


After installing drive motors/wheels and front wheels/steering motors to the frame, it is time to test the robot.

Two ESP32 microcontrollers will be used for testing. A transmitter with two potentiometers attached, one for steering and one for power.

Below is a picture of the transmitter (code can be found in Transmittor_git).



Below is a picture of the receiver, which connects to the servo motors directly and to the drive motors through the L298 motor controller (code can be found in Receiver_git).

