Applied Data Analysis (ADA)

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Part I: Linear Models

Chapter I.4

Linear Models - BLUEs & MLEs

Topics

- To be discussed...
 - ▶ Theorem of Gauß-Markov & BLUEs
 - Maximum Likelihood estimation under normal assumptions

■ 1.4.26 Definition

Let $Y \sim P_{\beta}$, $\beta \in \Theta \subseteq \mathbb{R}^p$, be a statistical model and let $g: \Theta \to \mathbb{R}^k$ be a known function. Then, An estimator $\hat{\xi} = \hat{\xi}(Y)$ is called an **unbiased estimator** of $g(\beta)$ if $E\hat{\xi}(Y) = g(\beta)$ for any

 $\beta \in \Theta$. An estimator $\hat{\xi}(Y) = AY$ with a known matrix $A \in \mathbb{R}^{k \times n}$ is called a **linear estimator**.

I.4.27 Remark

Solution Given a LM with design matrix B, the LSE $\hat{\beta}^+ = (B'B)^+ B'Y$ is a linear estimator.

Solution Given a LM with design matrix B, a linear unbiased estimator $\widehat{\xi}(Y) = AY$ of β with $A \in \mathbb{R}^{p \times n}$ has to satisfy the condition:

$$\mathsf{E}\widehat{\boldsymbol{\xi}}(\mathbf{Y}) = \mathsf{E}(\mathsf{A}\mathbf{Y}) = \mathsf{E}(\mathsf{A}\mathsf{B}\boldsymbol{\beta} + \mathsf{A}\boldsymbol{\epsilon}) = \mathsf{A}\mathsf{B}\boldsymbol{\beta} = \boldsymbol{\beta} \quad \forall \, \boldsymbol{\beta} \in \mathbb{R}^{\mathsf{p}}.$$

Hence, $AB = I_p$ must hold.

• Further, it should be noticed that the assumption of an existing linear unbiased estimator ensures both identifiability and uniqueness of the LSE.

Suppose that a linear unbiased estimator exists. Then, $AB = I_p$ so that $p = rank(AB) \le rank(B)$. Therefore, B has full rank and B'B is a regular matrix. According to Corollary I.4.12, the LSE is unique. Furthermore, it is unbiased due to Theorem I.4.25.

№ I.4.28 Theorem (Gauß-Markov)

Consider a LM with design matrix B. Let $\widehat{\boldsymbol{\xi}}=\widehat{\boldsymbol{\xi}}(Y)=AY$ be a linear unbiased estimator of $\boldsymbol{\beta}$ with $A\in\mathbb{R}^{p\times n}$. Then,

$$\mathsf{Cov}\left(\widehat{\boldsymbol{\xi}}\right) - \mathsf{Cov}\left(\widehat{\boldsymbol{\beta}}\right) \geqslant 0$$
 .

In particular, this yields Var $\left(c'\widehat{\beta}\right)\leqslant$ Var $\left(c'\widehat{\xi}\right)$ for any $c\in\mathbb{R}^p$ and, thus,

$$\text{Var}\left(\widehat{\beta}_{j}\right)\leqslant\text{Var}\left(\widehat{\xi}_{j}\right),\quad j=1,\ldots,p.$$

BLUEs and MLEs

■ 1.4.29 Definition

In the situation of Theorem I.4.28, the LSE $\widehat{\beta}$ is called **best linear unbiased estimator (BLUE)** of β . For $c \in \mathbb{R}^p$, $c'\widehat{\beta}$ is called BLUE of $c'\beta$.

► 1.4.30 Remark

Notice that the derivation of LSEs and BLUEs as well as their means and variances do not depend on the particular distributional assumption. However, their distributions depend on the distribution of the error term ϵ .

■ I.4.31 Theorem

Given a NoLM with a regular matrix B'B and unknown variance parameter $\sigma^2>0,~\widehat{\beta}$ is also the Maximum-Likelihood-Estimator (MLE) of $\beta.$

With $P = I_n - B(B'B)^{-1}B'$, the MLE of σ^2 is given by $\widetilde{\sigma^2} = \frac{1}{n}Y'PY$.

№ I.4.32 Theorem

Let $n \geqslant p$. Given a NoLM as in Definition I.4.3 and $\text{rank}(B) = r \leqslant p$, we have:

- $oldsymbol{\widehat{\beta}}^+$ and $oldsymbol{Y} B oldsymbol{\widehat{\beta}}^+$ are stochastically independent.
- **2** $\|\mathbf{Y} \mathbf{B}\widehat{\mathbf{\beta}}^{+}\|^{2}/\sigma^{2} \sim \chi^{2}(\mathbf{n} \mathbf{r})$
- $\textbf{ 1} \text{ If } r = p \text{ then } \frac{1}{\sqrt{c'(B'B)^{-1}c}} \cdot \frac{c'(\widehat{\beta} \beta)}{\sqrt{\|Y B\widehat{\beta}\|^2/(n-p)}} \sim t(n-p) \text{ for any } c \neq 0.$

I.4.33 Remark

The condition $\operatorname{rank}(B) = p$ in Theorem I.4.32 $extbf{0}$ can be replaced by the condition $c \not\in \operatorname{Ker}((B'B)^+)$.

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Part I: Linear Models

Chapter I.4

Linear Models –Testing

Topics

- To be discussed...
 - Parametrization of LMs
 - Full & reduced LM
 - Variance decomposition
 - Testing statistical hypothesis
 - F-test

Testing in LM

■ 1.4.34 Remark

- Consider a LM $Y = B\beta + \epsilon$ as in Definition I.4.2 with rank $(B) = p \le n$ and orthogonal projection $Q = B(B'B)^{-1}B'$. Then, Im(Q) = Im(B) is called the estimation space.
- If two LM have the same estimation space, then the LSE of EY are identical:

Let $Y = B_1\beta_1 + \epsilon_1$ and $Y = B_2\beta_2 + \epsilon_2$ be two LM with $Im(B_1) = Im(B_2)$. Then, Q is identical for both B_1 and B_2 since it depends only on $Im(B_1) = Im(B_2)$. Thus, the (unique) LSE of EY is given by (see Remark I.4.11)

$$B_1\beta_1 = B_2\beta_2 = QY.$$

In this sense, one may write for the LM

$$EY \in Im(B)$$
, $Cov(Y) = \sigma^2 I_n$,

so that it is independent of the particular chosen parametrization.

Testing in LM

▶ 1.4.35 Example

Consider a simple linear regression with $\mathbf{Y} = (Y_1, \dots, Y_n)'$ and

- $\begin{aligned} \textbf{Y}_j &= \beta_0 + \beta_1 x_j + \epsilon_j, \ j = 1, \dots, n. \ \text{Then, } \textbf{Y} = B \boldsymbol{\beta} + \boldsymbol{\epsilon} \text{ with parameter } \boldsymbol{\beta} = (\beta_0, \beta_1)' \text{ and } \\ \text{design matrix } B_1 &= \begin{pmatrix} 1 & x_1 \\ 1 & x_2 \\ \vdots & \vdots \\ 1 & x_n \end{pmatrix} = [\mathbbm{1}_n \mid \textbf{x}] \in \mathbb{R}^{n \times 2}. \end{aligned}$
- $\begin{aligned} \textbf{Y}_j &= \gamma_0 + \gamma_1(x_j \overline{x}) + \epsilon_j, \ j = 1, \dots, n. \ \text{ Then, } \textbf{Y} = B_2 \boldsymbol{\gamma} + \epsilon \text{ with parameter } \boldsymbol{\gamma} = (\gamma_0, \gamma_1)' \text{ and} \\ \text{design matrix } B_2 &= \begin{pmatrix} \frac{1}{n} \frac{x_1 \overline{x}}{x_2 \overline{x}} \\ \vdots \\ \frac{1}{n} \frac{x_n \overline{x}}{x_n} \end{pmatrix} = [\mathbbm{1}_n \mid \textbf{x} \overline{x} \mathbbm{1}_n] \in \mathbb{R}^{n \times 2}. \end{aligned}$
- Then, $Im(B_1) = Im(B_2)$. Furthermore, provided $rank(B_1) = 2$, $\gamma_0 = \beta_0 + \beta_1 \overline{x}$, $\gamma_1 = \beta_1$ and the respective LSEs are

$$\widehat{\gamma}_1 = \widehat{\beta}_1, \quad \widehat{\gamma}_0 = \widehat{\beta}_0 + \widehat{\beta}_1 \overline{x}.$$

■ 1.4.36 Remark

Testing in LMs means that a restriction is put on the estimation space, that is, we consider a matrix B_0 with $Im(B_0) \subseteq Im(B)$.

 $Y = B_0 \gamma + \varepsilon$, $\varepsilon \sim N_n(0, \sigma^2 I_n)$, $Im(B_0) \subseteq Im(B)$.

Thus, we have

the full NoLM:

$$\mathbf{Y} = \mathbf{B}\mathbf{\beta} + \mathbf{\epsilon}, \quad \mathbf{\epsilon} \sim \mathsf{N}_{\mathsf{n}}(\mathbf{0}, \sigma^{2}\mathbf{I}_{\mathsf{n}}).$$
 (1.3)

the reduced NoLM:

Then, Model I.4 implies Model I.3. Hence, one has to ask whether Model I.4 is true.

From Corollary I.4.10, we get immediately the following identity.

■ I.4.37 Corollary (variance decomposition formula)

Let $\widehat{\beta}$, and $\widehat{\gamma}$ be LSEs in a LM with design matrix B and B₀ such that $\text{Im}(B_0)\subseteq \text{Im}(B)$. Then,

$$\psi(\widehat{\boldsymbol{\gamma}}) = \psi(\widehat{\boldsymbol{\beta}}) + \|\mathbf{B}(\widehat{\boldsymbol{\gamma}} - \widehat{\boldsymbol{\beta}})\|^2$$

(1.4)

№ 1.4.38 Example

Consider a regression model

$$Y_i = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \epsilon_i, \quad 1 \leqslant i \leqslant n.$$

We would like to test whether variable x_2 contributes significantly to the regression model. The reduced model is

$$Y_i = \beta_0 + \beta_1 x_{i1} + \epsilon_i, \quad 1 \leqslant i \leqslant n.$$

Then,

the design matrices are given by

$$B = \begin{pmatrix} \frac{1}{1} & x_{11} & x_{12} \\ \frac{1}{1} & x_{21} & x_{22} \\ \vdots & \vdots \\ \frac{1}{1} & x_{n1} & x_{n2} \end{pmatrix} = [\mathbb{1}_n \mid \mathbf{x}_1 \mid \mathbf{x}_2] = [B_0 \mid \mathbf{x}_2] \in \mathbb{R}^{n \times 3}, \qquad B_0 = \begin{pmatrix} \frac{1}{1} & x_{11} \\ \frac{1}{1} & x_{21} \\ \vdots & \vdots \\ \frac{1}{1} & x_{n1} \end{pmatrix} = [\mathbb{1}_n \mid \mathbf{x}_1] \in \mathbb{R}^{n \times 2}$$

- lacktriangle Clearly $Im(B_0) \subseteq Im(B)$.
- **Solution** Consider LSE under both models with $\beta = (\beta_0, \beta_1, \beta_2)', \gamma = (\beta_0, \beta_1)'$:

$$\widehat{\boldsymbol{\beta}} = (B'B)^+ B' \boldsymbol{Y}, \quad \widehat{\boldsymbol{\gamma}} = (B_0' B_0)^+ B_0' \boldsymbol{Y}.$$

▶ 1.4.39 Theorem

Consider a full NoLM as in (1.3), that is,

 $Y = B\beta + \varepsilon$, $\varepsilon \sim N_n(0, \sigma^2 I_n)$

Furthermore, let $Q = B(B'B)^{-1}B'$ and $Q_0 = B_0(B'_0B_0)^{-1}B'_0$ be the orthogonal projections on the

images of B and B₀, respectively. Furthermore, let r = rank(Q) and $rank(Q - Q_0) = r - r_0$.

$$Y = B_0 \gamma + \epsilon, \quad \epsilon \sim N_n(0, \sigma^2 I_n), \quad \text{Im}(B_0) \subsetneq \text{Im}(B).$$

Then: • If the full Modell (I.3) is true then

$$\frac{Y'(Q-Q_0)Y/(r-r_0)}{Y'(I_n-Q)Y/(n-r)} \sim F(r-r_0,n-r,\beta'B'(Q-Q_0)B\beta/(2\sigma^2)).$$

2 If the reduced Modell (I.4) is true then

Modell (I.4) is true then
$$\frac{Y'(Q-Q_0)Y/(r-r_0)}{Y'(I_n-Q)Y/(n-r)} \sim \mathsf{F}(r-r_0,n-r,0) = \mathsf{F}(r-r_0,n-r).$$

Testing

From Theorem I.4.39, we construct the following testing procedure.

■ 1.4.40 Testing procedure (F-test)

In the situation of Theorem I.4.39, consider the hypothesis

$$H_0: EY = B_0 \gamma$$
 for some γ .

Then, a $(1 - \alpha)$ -level statistical test for H_0 is given by the decision rule

Reject H₀ if
$$\frac{Y'(Q-Q_0)Y/(r-r_0)}{Y'(I_n-Q)Y/(n-r)} > F_{1-\alpha}(r-r_0,n-r)$$

where $F_{1-\alpha}(r-r_0,n-r)$ denotes the $(1-\alpha)$ -quantile of the $F(r-r_0,n-r)$ -distribution.