

→ The no. of op. centers in the op. layer is equal to the no. of I/P " " " " I/P ch. length

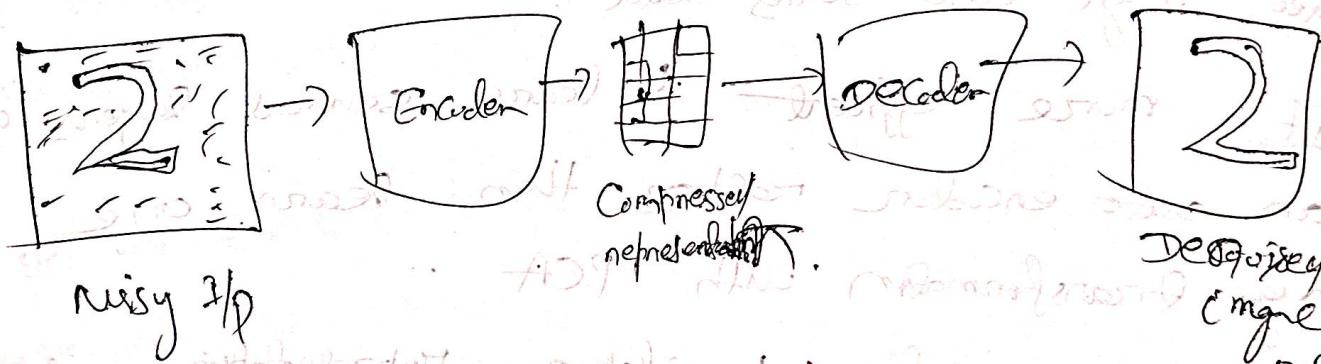
Note Autoencoder

An autoencoder is a type of unsupervised ANN designed to learn efficient (compressed) representations of I/P data and reconstruct the original I/P from those representations.

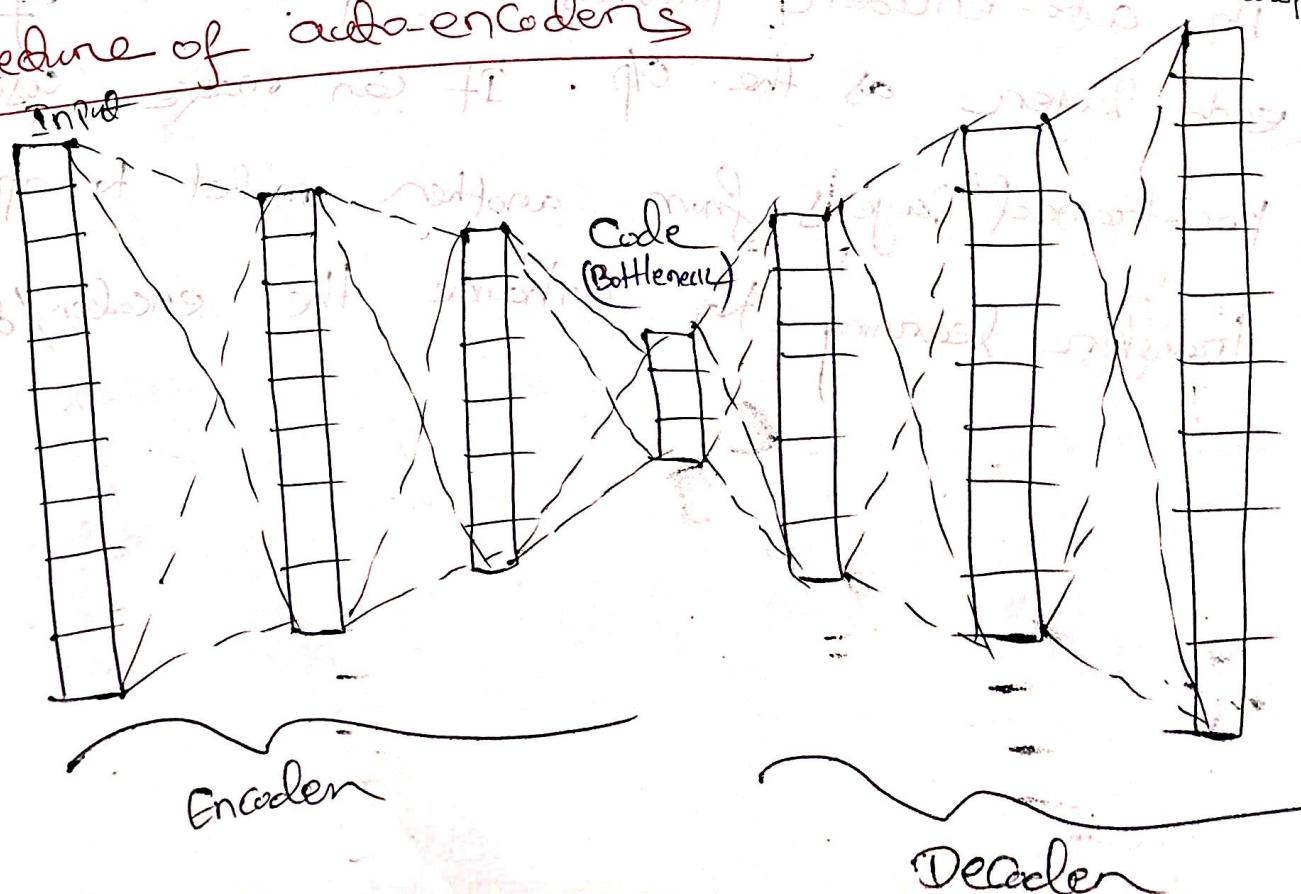
Characteristics

- It learns without labeled data.
- It compresses data into a lower-dimensional representation (latent space) and then reconstruct it.
- It learns to preserve the most essential features of the I/P.

- ## Applications of Autoencoders
- Image Coloring :- Converting any black & white pic into a colored image.
  - Feature Variation :- extracts only the required features and generally by removing noise or unnecessary information.
  - Dimensionality reduction :- \* the reconstructed image is the same as own IP but with reduced dimension  
+ similar image with reduced pixel value.
  - Image denoising :- reconstruct the original IP from the noisy image.
  - Watermark removal :- removing watermarks from images  
+ remove any object while filming a video.
  - Anomaly detection (outlier detection)
  - Sequence to sequence prediction
  - Recommendation systems



Architecture of auto-encoders



- An auto-encoder consists of 3 layers.
- i) Encoder
  - ii) code
  - iii) decoder
- i) Encoder:
- The N/w compresses the I/p info a latent space representation.
  - The encoder layer encodes the I/p image as a compressed representation in a reduced dimension.
  - The compressed image is the distorted version of the original image.
- ii) Code:
- This part of the N/w represents the compressed I/p which is fed to the decoder.
- iii) Decoder:
- This layer decodes the encoded image back to the original dimension.
  - The decoded image is a lossy reconstruction of the original image and it is reconstructed from the latent space representation.

## Hyperparameters of auto-encoders

- Code size:
  - it represents the no. of nodes in the middle layer.
  - smaller size results in more compression.
- No. of layers:
  - The auto-encoder can consist of as many layers as we want.
- No. of nodes per layer:
  - The no. of nodes per layer decreases with each subsequent layer of the encoder, and increases back on the decoder.
  - The decoder is symmetric to the encoder in terms of the layer structure.
- Loss function:
  - we either use MSE or binary-cross-entropy.
  - If the  $\mathbb{I}_p$  values are in the range  $[0, 1]$ , then we typically use cross-entropy; otherwise, we use MSE.

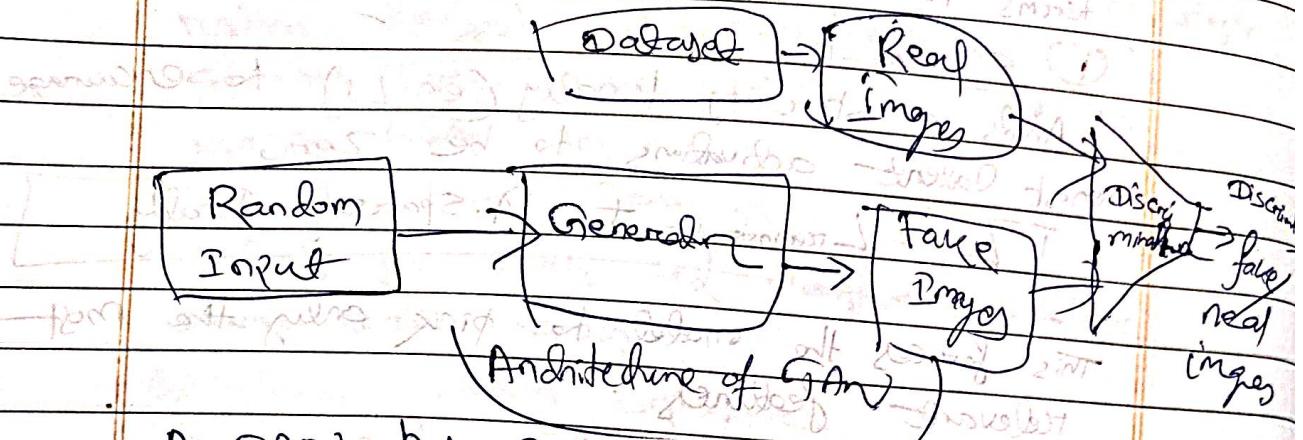
## Chapter-10

Date \_\_\_\_\_

Page No. \_\_\_\_\_

### GAN (Generative Adversarial Network)

It is a form of generative model designed to produce realistic samples of entities such as images, from noise.



→ A GAN has 2 main Components

(i) Generator

(ii) Discriminator

(i) Generator :

→ It creates fake data (e.g. images) from random noise.

→ Its goal is to make the data look as real as possible to fool the discriminator.

(ii) Discriminator :

→ It evaluates data and decides whether it is real (from the dataset) or fake (from the generator).

### Adversarial Training :

→ It refers to a training process in which 2 models are trained simultaneously in competition with each other, with opposing objectives.

\* Generator tries to produce realistic fake data to fool the discriminator.

- \* The discriminator tries to correctly distinguish between real and fake data.
- This creates a minimax game.
- \* The Generator minimizes the discriminator's ability to detect fake samples.
  - \* The Discriminator maximizes its accuracy in identifying real vs fake samples.

### Generator Loss & Discriminator Loss

#### i) Generator loss:

→ gt measures how well the generator fools the discriminator.

Mathematically,

$$L_G = -E_{z \sim P_z} [\log D(G(z))]$$

→ gt penalizes the generator when the discriminator correctly identifies generated samples as fake.

#### ii) Discriminator loss:

→ gt measures how well the discriminator distinguishes real data from fake data.

Mathematically,

$$L_D = -E_{x \sim P_{\text{data}}} [\log D(x)] - E_{z \sim P_z} [\log (1 - D(G(z)))]$$

→ gt penalizes the discriminator when

- \* Real samples are classified as fake.
- \* Fake samples are classified as real.

## Key Challenges of GAN

- Training instability
- Mode collapse
- Sensitive to hyperparameters

## Applications of GAN

- Image Generation
- Data Augmentation
- Medical imaging synthesis
- Super resolution and image enhancement
- Game Content generation