# Allan Garcia-casal

786-394-3624 | allang@u.northwestern.edu | github.com/allan-gc | allan-gc.github.io

**EDUCATION** 

**Northwestern University** 

**Evanston**, IL

M.S. in Robotics - GPA: 3.93/4.00 Expected Graduation: Fall 2023

Completed Courses: Embedded Systems with ROS 2, Robotic Manipulation, Machine Learning

Future Courses: Sensing, Navigation, and Machine Learning for Robotics (SLAM) in C++, Advanced Computer Vision, Connected and Autonomous Vehicles

Boston University Boston, MA

B.S. in Biomedical Engineering - GPA: 3.51/4.00

AWARDS: Hispanic Scholarship Fund Scholar 2021

**WORK EXPERIENCE** 

## Brigham and Women's Hospital, Department of Radiology

Boston, MA

Image Guided Surgery Research Intern

Jun 2021 - Aug 2021

Sep 2018 - May 2022

- Optimized the registration of 3D meshes from MRI and CT scans
- Used Python point-cloud libraries for image segmentation and registration methods testing
- Created different 3D point-cloud meshes for testing using MeshLab

**Born Global Foundation** 

Boston, MA

Sustainability Engineering Design Intern

May 2020 - Aug 2020

• Designed a prototype of a sustainable zero waste farming process using biochar

**SELECT PROJECTS** 

#### Franka Robotic Arm Motion Planning

Fall 2022

- Developed software in Python and ROS 2 that allows a 7 DOF robot arm to autonomously prepare a cup of hot chocolate
- Integrated the MoveIt package into a ROS 2 motion planning API in Python that was used to interface with the robotic arm

#### **Robotic Arm Pen Tracker**

Fall 2022

- Used an Intel RealSense camera to detect a pen and then had a px100 robotic arm grab it
- Implemented an object detection algorithm for the pen using the OpenCV Python library

### **MRI Compatible EEG Layer Design**

Fall 2021, Spring 2022

- Designed MRI compatible EEG cap layer that helps attenuate noise from EEG/MRI readings
- Developed several cap designs using different insulating fabrics and conductive inks
- **Submitted for Publication:** Levitt, Yang, Williams, Lutschg, Garcia-Casal, Lewis, "EEG-LLAMAS: an open source, low latency, EEG-fMRI neurofeedback platform"

#### **Pulse Oximeter Prototype**

**Spring 2021** 

- Designed a prototype pulse oximeter with CAD
- Designed and integrated analog filters with an Arduino board for accurate signal collection and processing
- Integrated the circuitry into the modeled CAD housing

#### **Human Tissue Cell Incubator**

Fall 2019

- Designed and built the enclosure for a temperature-regulated cell sample incubator
- Tested and analyzed the materials that would best fit the working and client parameters
- Managed the electrical components and code using Arduino UI, heaters and fans, and thermistors
- Ensured temperature data was collected and displayed appropriately for the user on LCD display

## LEADERSHIP EXPERIENCE

**BU Technology Innovation Scholars Program (TISP)** 

Boston, MA

FIRST Robotics Engineering Mentor

Sep 2019 - May 2022

**SKILLS** 

Software: ROS 2/ROS, Git, Linux, Blender, SolidWorks, Gazebo

Programming: Python, MATLAB, Machine Learning

Hardware: Circuit Design, Materials Testing