

# Allan Garcia-casal

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## EDUCATION

### **Northwestern University**

*M.S. in Robotics - GPA: 3.93/4.00*

**Evanston, IL**

Expected Graduation: Fall 2023

*Completed Courses:* Embedded Systems with ROS2, Robotic Manipulation, Machine Learning

*Future Courses:* Sensing, Navigation, and Machine Learning for Robotics (SLAM) in C++ , Advanced Computer Vision, Connected and Autonomous Vehicles

### **Boston University**

*B.S. in Biomedical Engineering - GPA: 3.51/4.00*

**Boston, MA**

Sep 2018 - May 2022

**AWARDS:** Hispanic Scholarship Fund Scholar 2021

## WORK EXPERIENCE

### **Brigham and Women's Hospital, Department of Radiology**

*Image Guided Surgery Research Intern*

**Boston, MA**

Jun 2021 - Aug 2021

- Optimized the registration of 3D meshes from MRI and CT scans
- Used Python point-cloud libraries for image segmentation and registration methods testing
- Created different 3D point-cloud meshes for testing using MeshLab

### **Born Global Foundation**

*Sustainability Engineering Design Intern*

**Boston, MA**

May 2020 - Aug 2020

- Designed a prototype of a sustainable zero waste farming process using biochar

## SELECT PROJECTS

### **Franka Robotic Arm Motion Planning**

*Fall 2022*

- Developed software in Python and ROS2 that allows a 7 DOF robot arm to autonomously prepare a cup of hot chocolate
- Integrated the MoveIt package into a ROS2 motion planning API in Python that was used to interface with the robotic arm

### **Robotic Arm Pen Tracker**

*Fall 2022*

- Used an Intel RealSense camera to detect a pen and then had a px100 robotic arm grab it
- Implemented an object detection algorithm for the pen using the OpenCV Python library

### **MRI Compatible EEG Layer Design**

*Fall 2021, Spring 2022*

- Designed MRI compatible EEG cap layer that helps attenuate noise from EEG/MRI readings
- Developed several cap designs using different insulating fabrics and conductive inks
- **Submitted for Publication:** Levitt, Yang, Williams, Lutschg, Garcia-Casal, Lewis, "EEG-LLAMAS: an open source, low latency, EEG-fMRI neurofeedback platform"

### **Pulse Oximeter Prototype**

*Spring 2021*

- Designed a prototype pulse oximeter with CAD
- Designed and integrated analog filters with an Arduino board for accurate signal collection and processing
- Integrated the circuitry into the modeled CAD housing

### **Human Tissue Cell Incubator**

*Fall 2019*

- Designed and built the enclosure for a temperature-regulated cell sample incubator
- Tested and analyzed the materials that would best fit the working and client parameters
- Managed the electrical components and code using Arduino UI, heaters and fans, and thermistors
- Ensured temperature data was collected and displayed appropriately for the user on LCD display

## LEADERSHIP EXPERIENCE

### **BU Technology Innovation Scholars Program (TISP)**

*FIRST Robotics Engineering Mentor*

**Boston, MA**

Sep 2019 - May 2022

## SKILLS

*Software:* ROS 2/ROS, Git, Linux, Blender, SolidWorks, Gazebo

*Programming:* Python, MATLAB, Machine Learning

*Hardware:* Circuit Design, Materials Testing