

# Constant Coefficient Differential Equations

- DE with constants as the coefficients to the derivatives of  $y$  so of this form:  $c_n y^{(n)} + c_{n-1} y^{(n-1)} + \dots + c_1 y' + c_0 y = F(x)$

## Homogenous

- just means  $F(x) = 0$

### How to Solve

- Re-write the derivatives of  $y^{(n)}$  with a differential operator to the same power  $D^n$
- treat as polynomial and factor
  - if degree  $> 2$  then factoring may be difficult so us polynomial division
  - there's a thm that says a root must be evenly divisible by the constant at the end so have a finite pool of factors to try
- roots will return basis elements of the solution space

roots	Basis elements
$root = a, a \text{ is real}$	$e^{ax}$
$r = a \pm bi$	$e^{ax} \cos(bx), e^{ax} \sin(bx)$

- **NOTE:** roots with multiplicities result in multiple basis elements with increasing powers of  $x$
- example sol:  $y = c_1 e^{3x} + c_2 x e^{3x} + c_3 \cos(5x) + c_4 \sin(5x)$

## Non-homogenous

- means  $F(x)$  is a function
- requires annihilation

### How to Solve

- solve the homogenous equation
- get a trial solution by finding the annihilator and applying it to both sides
- simplify  $y_T$  by omitting terms from  $y_H$
- get  $y_P$  by plugging  $y_T$  into the original DE and back solving for the constants
- final answer is  $y_H + y_P$  possibly can combine terms to further simplify

Term	Annihilator
$e^{ax}$	$D - a$
$x^k e^{ax}$	$(D - a)^{k+1}$
$x^k$	$D^{k+1}$
$e^{ax} \cos(bx), e^{ax} \sin(bx)$	$D^2 - 2aD + (a^2 + b^2)$
$x^k e^{ax} \cos(bx), x^k e^{ax} \sin(bx)$	$(D^2 - 2aD + (a^2 + b^2))^{k+1}$
$\cos(bx), \sin(bx)$	$D^2 + b^2$

- **NOTE:** if 2 terms are summed then the annihilator is the product of each term's annihilator

# Cauchy Euler Differential Equations

- nth order Cauchy-Euler:
  - $x^n y^{(n)} + a_{n-1} x^{n-1} y^{(n-1)} + \dots + a_1 x y' + a_0 y = 0$
- substitute:  $x = e^z, z = \ln|x|$
- $xy' = D, x^2 y'' = D(D-1), \dots, x^n y^{(n)} = D(D-1)(D-2) \dots (D-(n-1))$ 
  - with  $D$  being a differential operator in terms of  $z$  so you must substitute at the end

## Variation of Parameters

- when the thing to annihilate is not simple

### How to solve

- solve homogenous
  - lets say you get basis elements  $A, B, C, \dots$  to solve the homogenous equation
- let  $u_1 A, \dots, u_n C$  be solutions

- set up a wronskian of the basis elements augmented with  $\vec{0}$  but the last element is the thing to annihilate
- solve this system
  - **NOTE:** you're solving for  $u'_1, \dots, u'_n$
- integrate and plug into the 'sol'
  - this is particular so still need:  $y = y_H + y_P$

## Eigenvalues

- to find eigenvalues simply solve for  $\lambda : \det(A - \lambda I_n) = 0$ 
  - really means cofactor expand a matrix whose diagonal look like  $c - \lambda$  and find the roots
- might need the quadratic formula for this
  - this may mean finding complex roots
  - these come in conjugate pairs

## Eigenvectors

- each eigenvalue has an eigenvector
- to find simply solve for  $(A - \lambda I_n)\vec{v}_\lambda = 0$ 
  - means  $A - \lambda I_n$  augmented with the zero matrix
- the resultant vector will have n parameters
- if  $n \neq \text{mul}(\lambda)$ 
  - matrix is defective

## Complex eigenvalues

- Now suppose we have  $\lambda = a + bi$  with  $\vec{v} = \vec{r} + i\vec{s}$ 
  - and complex conjugate pair
- yields sols:
  - $\vec{u}(t) = e^{at}(\cos(bt)\vec{r} - \sin(bt)\vec{s})$
  - $\vec{v}(t) = e^{at}(\cos(bt)\vec{s} + \sin(bt)\vec{r})$
  - **NOTE:** these are just the vectors so if asked to solve a system of DE make sure to multiply each vector by a constant

## Solving Systems of DE

- find eigenvalues
- find eigenvectors
- solution:  $\vec{x}(t) = c_1 e^{\lambda_1 t} \vec{v}_{1P} + \dots + c_n e^{\lambda_n t} \vec{v}_{nP}$ 
  - where  $\vec{v}_{kP}$  is the corresponding eigenvector but particular
  - choose  $\vec{v}_1 \dots \vec{v}_n$  to be LI

## Defective

- the 1st 2 steps are the same but finding eigenvectors has caveats
  - by the multiplicity, it will be 2, 1 for  $\text{mul} = 3$  or for 2, 2 or 3, 1 for  $\text{mul} = 4$
  - try lowest order but  $(A - \lambda I_n)^n \vec{v}_n = 0$ 
    - \* note if  $(A - \lambda I_n)^n = \vec{0}$  this is the highest order
  - if this is the highest order
    - \* choose and a vector of this form such that it's not order 1
    - \* choose another such that it's LI from the previous
    - \* find their corresponding order 1 by  $\vec{v}_n = A \cdot \vec{u}_n$
  - otherwise you need order 3 so simply choose vec such that not order 2 or order 1
    - \* find the order 2 by  $\vec{v}_2 = A \cdot \vec{v}_3$
    - \* find order 1 by  $\vec{v}_1 = A \cdot \vec{v}_2$
- use the formula to write make sure to only chain where appropriate
- formula:
  - let  $\vec{v}_k$  be the generalized kth order eigenvector
    - \*  $e^{\lambda t} \vec{v}$
    - \*  $e^{\lambda t} (\vec{v}_2 + t\vec{v})$
    - \*  $e^{\lambda t} (\vec{v}_3 + t\vec{v}_2 + \frac{1}{2}t^2\vec{v})$
    - \*  $\vdots$
    - \*  $e^{\lambda t} (\vec{v}_k + t\vec{v}_{k-1} + \dots + \frac{1}{(k-1)!}t^{k-1}\vec{v})$