

State Diagrams

Chapter 5



Objectives

In this chapter we will:

- ☐ Introduce the terms used with respect to state diagrams
- ☐ Discuss the context in which state diagrams are used
- ☐ Introduce substates
- ☐ Discuss concurrent state diagrams



Statechart Diagrams

- ☐ State diagrams describe the life of an object using three main elements:
 - States of an object
 - ⇒ Transitions between states
 - ⇒ Events that trigger the transitions
- □ A state diagram or statechart specifies a state machine
 - ⇒ A state machine is described for a class
 - ⇒ Each object has it's own state machine



Why Use Statechart Diagrams?

- ☐ Statecharts typically are used to describe state-dependent behaviour for an object
 - ⇒ An object responds differently to the same event depending on what state it is in
 - Usually applied to objects but can be applied to any element that has behaviour
 - Actors, use cases, methods, subsystems, systems
- ☐ Statecharts are typically used in conjunction with interaction diagrams (usually sequence diagrams)
 - A statechart describes all events (and states and transitions for a single object)
 - ⇒ A sequence diagram describes the events for a single interaction across all objects involved



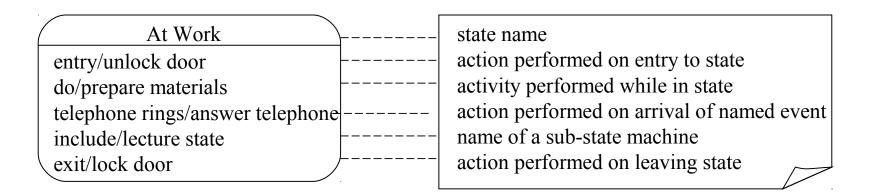
States

- □ Show what the dependencies are between the state of an object and its reactions to messages or other events
- □ State
 - ⇒ is a condition or situation during the life of an object within which it performs some activity, or waits for some events
 - ⇒ Has a name
 - ⇒ Has actions -- execute the state
 - ⇒ Has internal transitions -- transitions cause no change in a state
 - substates -- the nested structure of a state involving disjoint or concurrent substates



States

☐ For example:





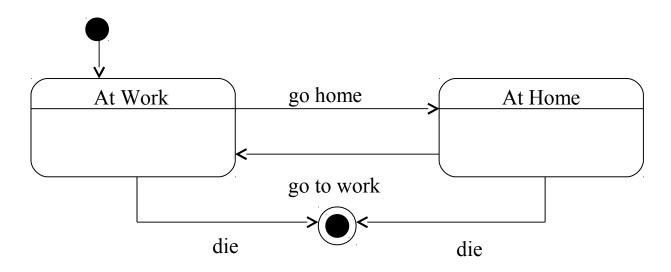
Initial and Final States

- ☐ The initial state of a state machine is indicated with a solid circle
 - ⇒ Known as a pseudo-state
 - ⇒ A transition from this state will show the first real state
- ☐ The final state of a state machine is shown as concentric circles
 - ⇒ A closed loop state machine does not have a final state; the object lives until the entire system terminates
 - ⇒ An open loop state machine represents an object that may terminate before the system terminates



Initial and Final States

☐ An example:





Actions and Activities

□ Action

- ⇒ is an executable atomic computation
- ⇒ includes operation calls, the creation or destruction of another object, or the sending of a signal to an object
- ⇒ associated with transitions and during which an action is not interruptible -- e.g., entry, exit

☐ Activity is associated with states

- ⇒ Non-atomic or ongoing computation
- May run to completion or continue indefinitely
- Will be terminated by an event that causes a transition from the state in which the activity is defined



Events

- ☐ An event signature is described as Event-name (comma-separated-parameter-list)
- Events appear in the internal transition compartment of a state or on a transition between states
- ☐ An event may be one of four types
 - ⇒ Signal event
 - Corresponding to the arrival of an asynchronous message or signal
 - **⇔** Call event
 - Corresponding to the arrival of a procedural call to an operation
 - ⇒ Time event
 - **⇒** Change event



Events

- ☐ A time event occurs after a specified time has elapsed
 - ⇒ Event name is specified as keyword after
 - ⇒ Parameter list is an expression evaluating to a time interval
 - after(10 seconds after state "At Work" is entered)
 - No specified start time implies "since entry to the current state"
 - after(2 seconds)



Events

- ☐ A change event occurs whenever a specified condition is met
 - ⇒ Event name is specified as keyword *when*
 - ⇒ Parameter list is a boolean expression
 - ⇒ The event occurs when both of the following conditions are met, irrespective of the order when they happen
 - The expression evaluates to true
 - The object is in the required state
 - ⇒ For example
 - when (state = At Work)
 - when (date = January 1 2007)



Transitions

- A transition is drawn as an arrow between states annotated with a transition string
- The transition string denotes the event and consequent action
- ☐ Only one form of arrowhead is used on statecharts
 - The distinction between call events and signal events must be deducted from elsewhere e.g. an interaction diagram

A transition string is described as

- □ Event-signature [guard-condition]/action-expression^object.message
- ☐ If the guard condition is met the transition occurs immediately



Transitions

- ☐ A transition whose string contains neither an event signature nor a guard condition is said to be unlabeled
 - **⇒** Occurs immediately
 - May still carry an action expression

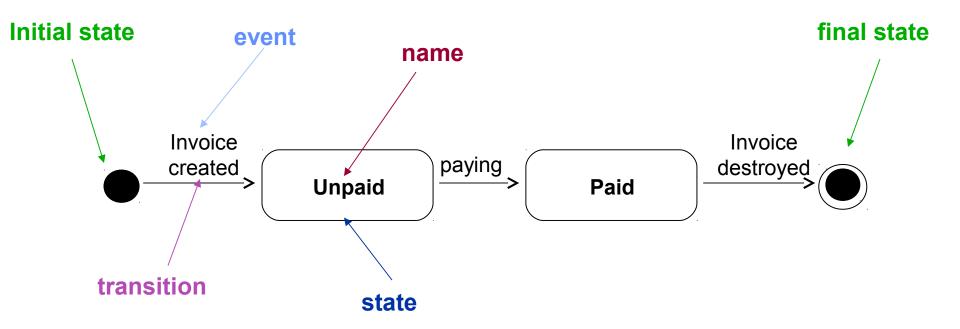


Transitions

- ☐ A transition is triggered when its event occurs
 - ⇒ If the guard condition is met, the transition is fired
 - ⇒ If the condition is not met the event is discarded
 - The guard condition is checked only once
- If there is no guard condition, triggering will always cause firing
- □ Note the distinction between a guard condition and a change event
 - ⇒ A guard condition is evaluated once, when the associated event occurs
 - A change event occurs whenever its associated condition is met
 - Behaviour is as if the condition were being continually evaluated



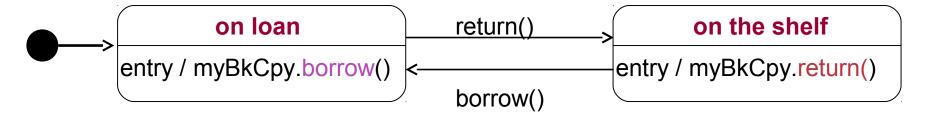
State Diagrams notation



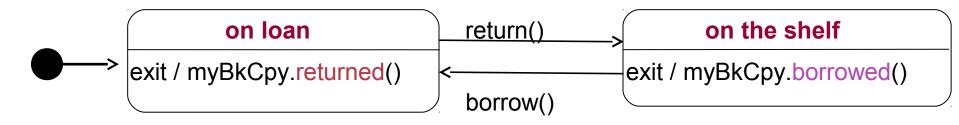


State Diagram Example

This shows the state of an object myBkCpy from a BookCopy class



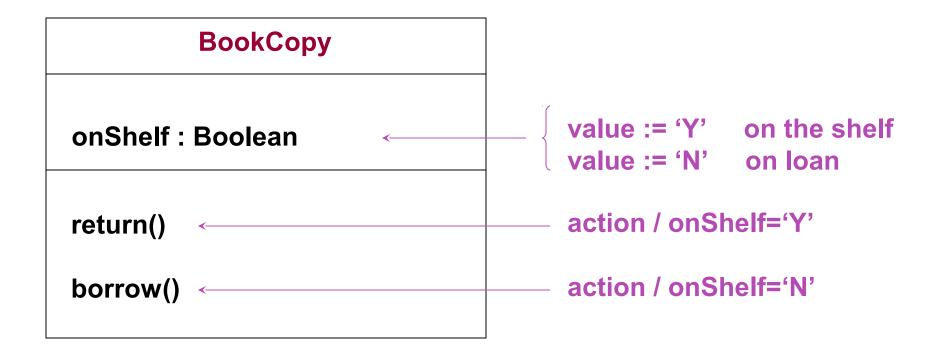
Entry action: any action that is marked as linked to the entry action is executed whenever the given state is entered via a transition



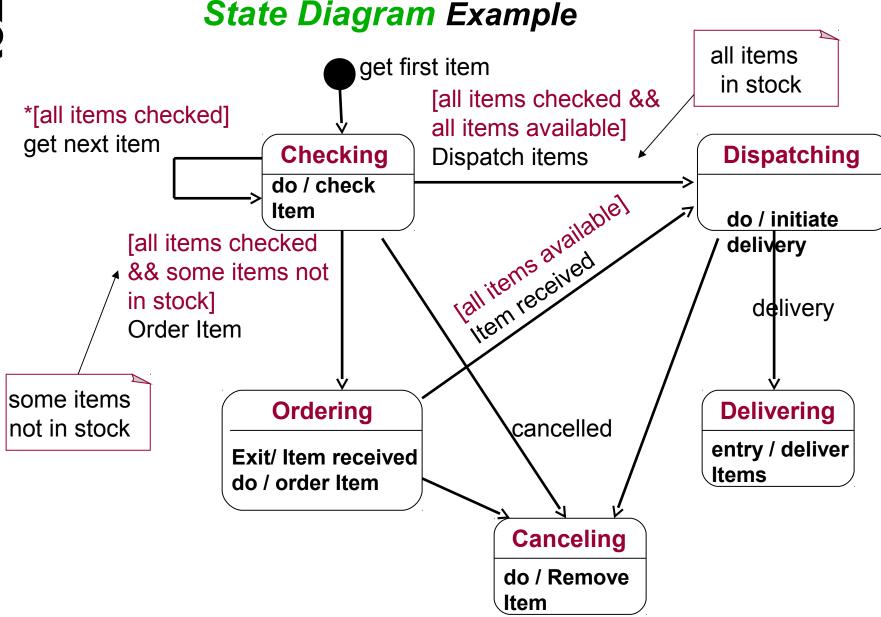
Exit action: any action that is marked as linked to the exit action is executed whenever the state is left via a transition



A Class of BookCopy

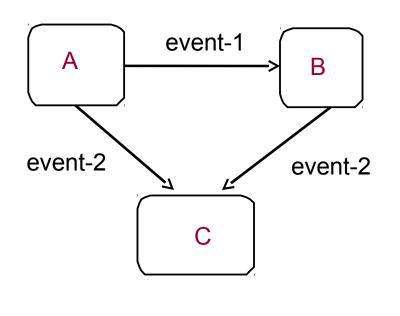


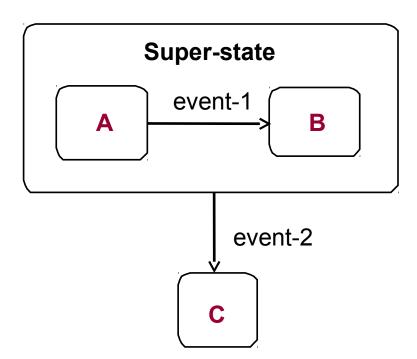






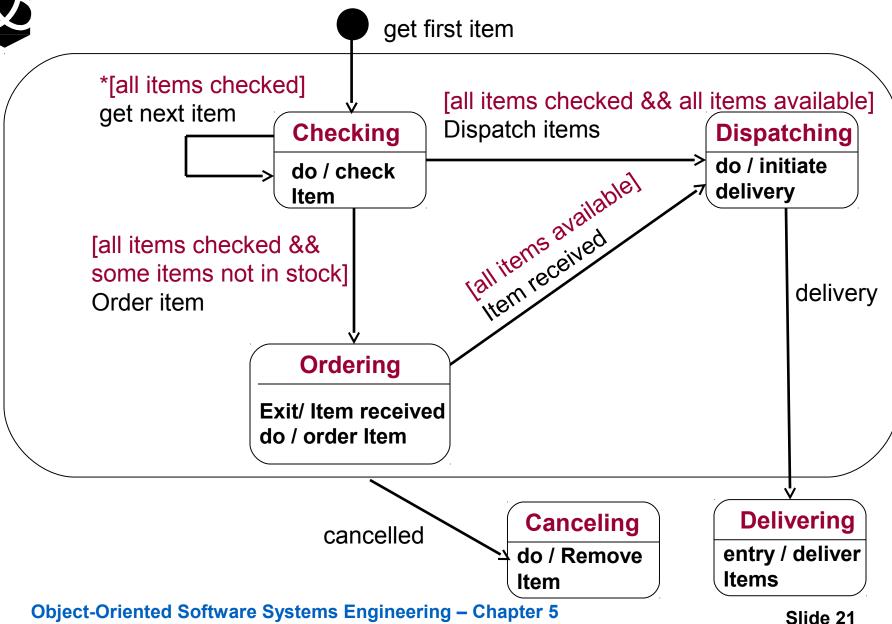
State Diagram - Nested States



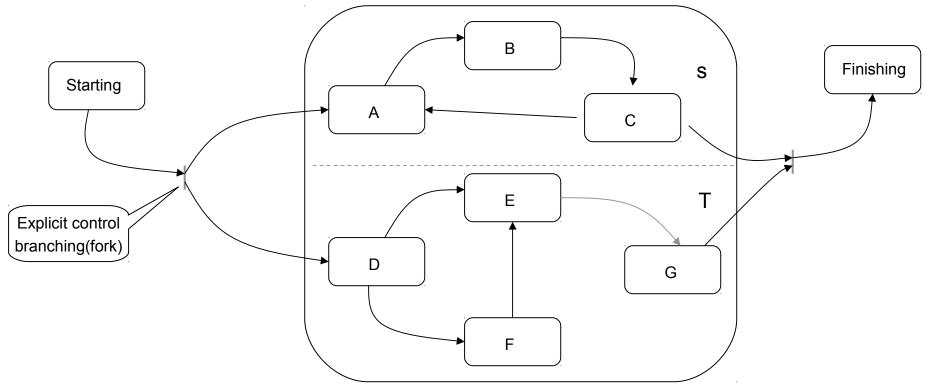


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State Diagram Example including substates







- Orthogonal Components and Concurrency
 - ⇒ shown separated by dashed line
 - supports concurrency
- Objects must be in only one state from each of the orthogonal components



Three different ways for orthogonal components to communicate:

- ☐ Broadcast Events
- □ Propogated Events
- ☐ IN operators



☐ Broadcast events

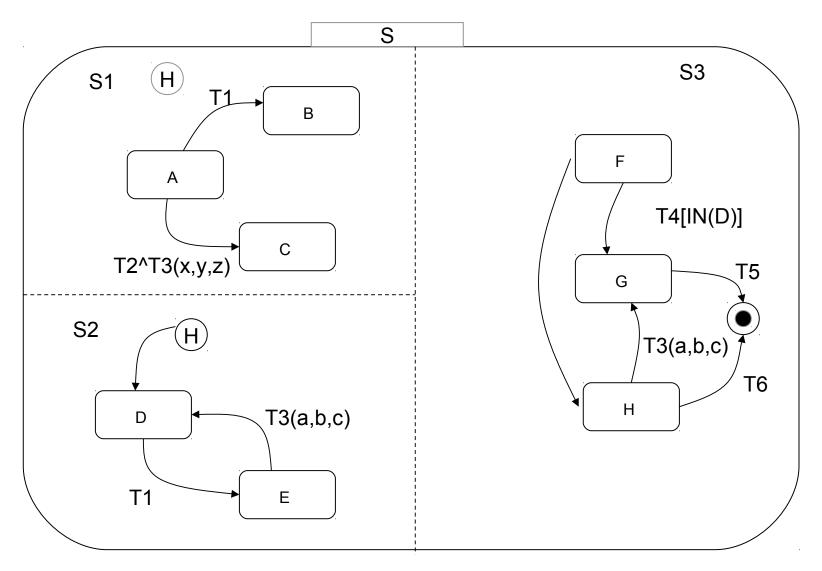
- ⇒ events that more than one orthogonal component accepts
- ⇒ For example an event T1 is sent to all active orthogonal components it need not be acted on by all components
 - what happens if component S1 is in state A, S2 is in state E and S3 is in state G when a T1 event occurs?
 - what happens if S1 is in state A and S2 is in state D when the event T1 occurs?



□ Propagated events are indicated with the caret following the event name (and optional parameters and guard)

□ IN operators are used as a guard on transition T4.
This allows the S3 component to take the transition T4 only if S2 is currently in state D







Summary

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