DYNAMIC ROUTING PROTOCOLS

The Evolution of Dynamic Routing Protocols

- Dynamic routing protocols used in networks since the late 1980s
- Newer versions support the communication based on IPv6

Routing Protocols Classification

	Interior Gateway Protocols				Exterior Gateway Protocols
	Distance Vector		Link-State		Path Vector
IPv4	RIPv2	EIGRP	OSPFv2	IS-IS	BGP-4
IPv6	RIPng	EIGRP for IPv6	OSPFv3	IS-IS for IPv6	BGP-MP

Purpose of Dynamic Routing Protocols

Routing Protocols are used to facilitate the exchange of routing information between routers.

The purpose of dynamic routing protocols includes:

- Discovery of remote networks
- Maintaining up-to-date routing information
- Choosing the best path to destination networks
- Ability to find a new best path if the current path is no longer available

Purpose of Dynamic Routing Protocols (cont.)

Main components of dynamic routing protocols include:

- **Data structures -** Routing protocols typically use tables or databases for its operations. This information is kept in RAM.
- **Routing protocol messages -** Routing protocols use various types of messages to discover neighboring routers, exchange routing information, and other tasks to learn and maintain accurate information about the network.
- **Algorithm -** Routing protocols use algorithms for facilitating routing information for best path determination.

The Role of Dynamic Routing Protocols

Advantages of dynamic routing include:

- Automatically share information about remote networks
- Determine the best path to each network and add this information to their routing tables
- Compared to static routing, dynamic routing protocols require less administrative overhead
- Help the network administrator manage the time-consuming process of configuring and maintaining static routes

Disadvantages of dynamic routing include:

- Part of a router's resources are dedicated for protocol operation, including CPU time and network link bandwidth
- Times when static routing is more appropriate

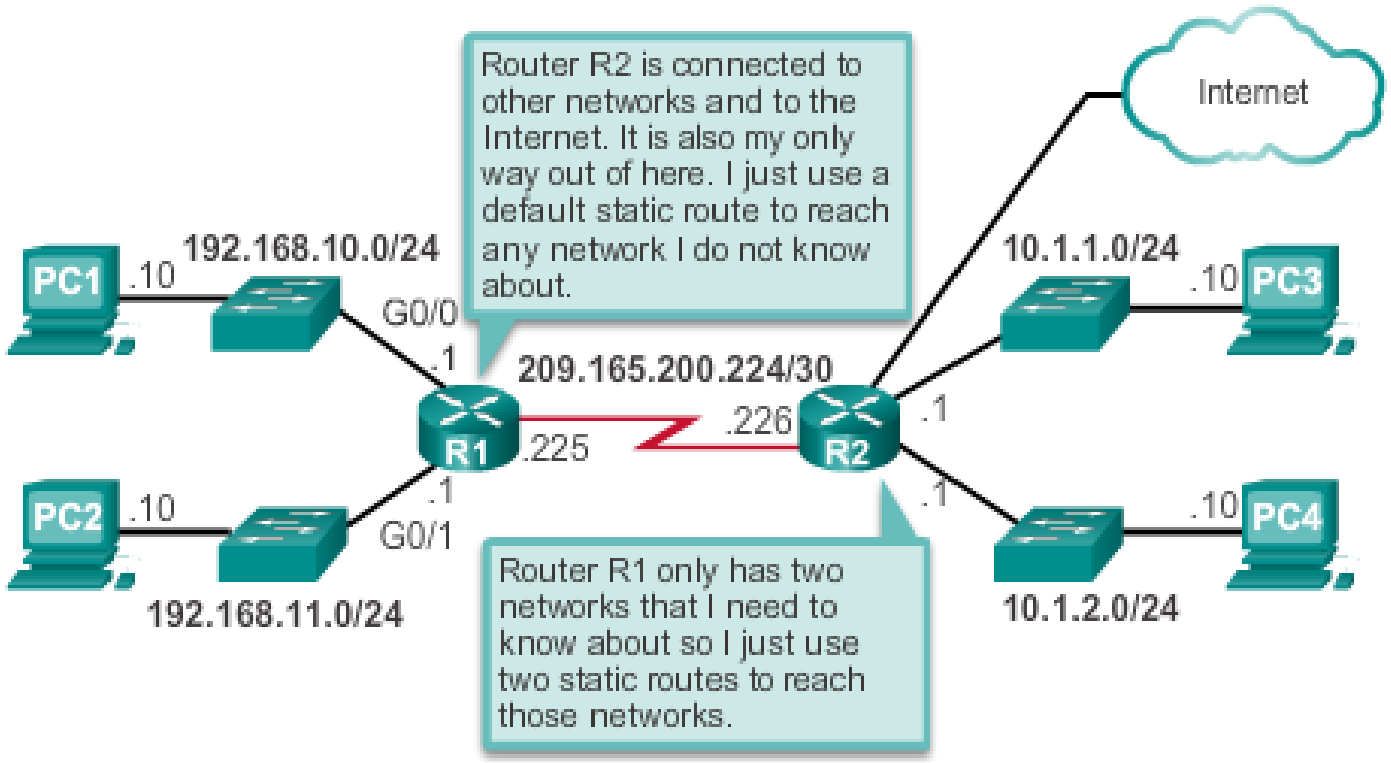
Using Static Routing

Networks typically use a combination of both static and dynamic routing.

Static routing has several primary uses:

- Providing ease of routing table maintenance in smaller networks that are not expected to grow significantly.
- Routing to and from a stub network. A network with only one default route out and no knowledge of any remote networks.
- Accessing a single default router. This is used to represent a path to any network that does not have a match in the routing table.

Using Static Routing (cont.)



Static Routing Scorecard

Static Routing Advantages and Disadvantages

Advantages	Disadvantages
Easy to implement in a small network.	Suitable only for simple topologies or for special purposes such as a default static route. Configuration complexity increases dramatically as network grows.
Very secure. No advertisements are sent as compared to dynamic routing protocols.	
Route to destination is always the same.	Manual intervention required to re-route traffic.
No routing algorithm or update mechanism required; therefore, extra resources (CPU or RAM) are not required.	

Dynamic Routing Scorecard

Dynamic Routing Advantages and Disadvantages

Advantages	Disadvantages
Suitable in all topologies where multiple routers are required.	Can be more complex to implement.
Generally independent of the network size.	Less secure. Additional configuration settings are required to secure.
Automatically adapts topology to reroute traffic if possible.	Route depends on the current topology.
	Requires additional CPU, RAM, and link bandwidth.

Dynamic Routing Protocol Operation

In general, the operations of a dynamic routing protocol can be described as follows:

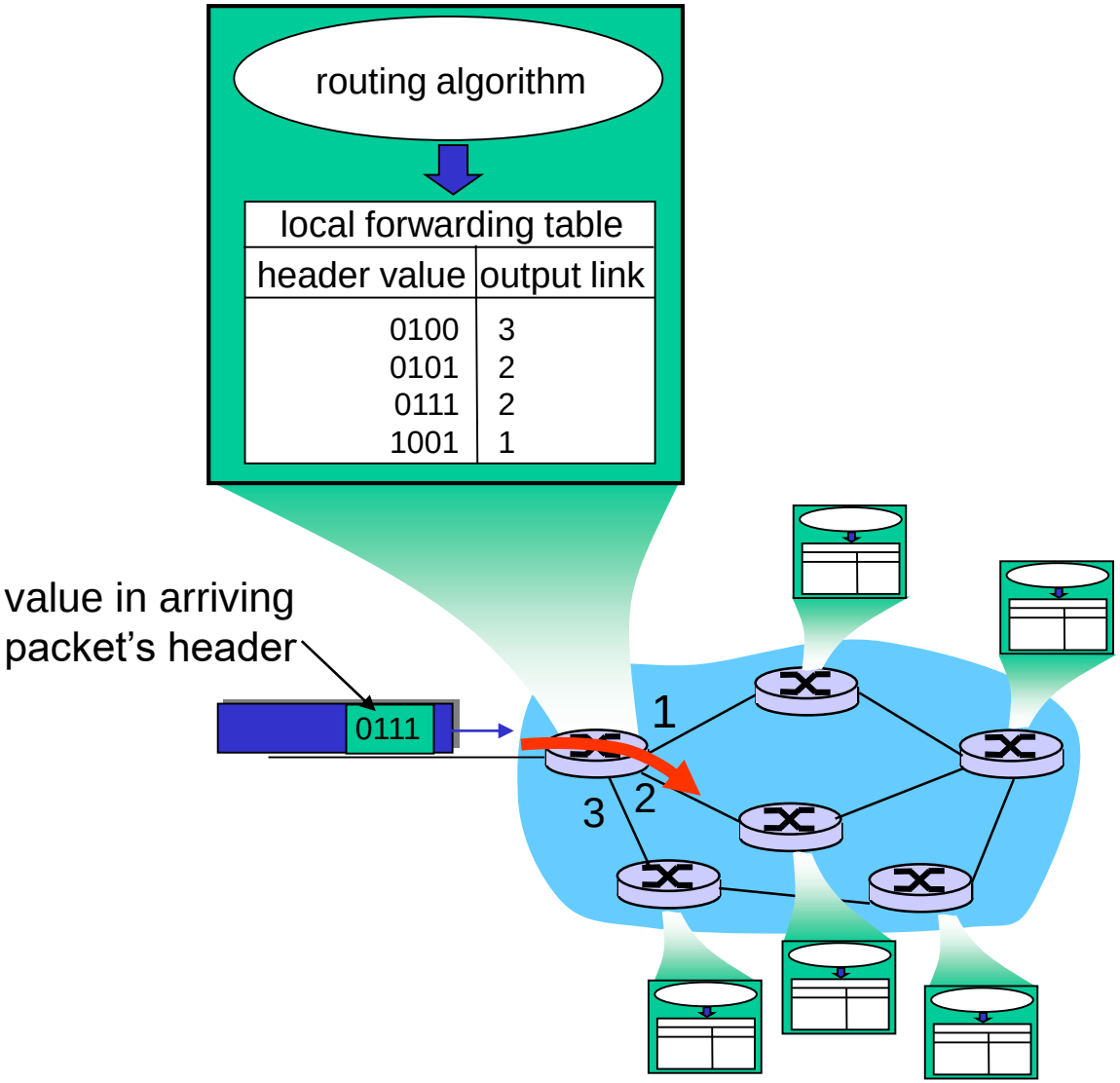
1. The router sends and receives routing messages on its interfaces.
2. The router shares routing messages and routing information with other routers that are using the same routing protocol.
3. Routers exchange routing information to learn about remote networks.
4. When a router detects a topology change the routing protocol can advertise this change to other routers.

Network Layer

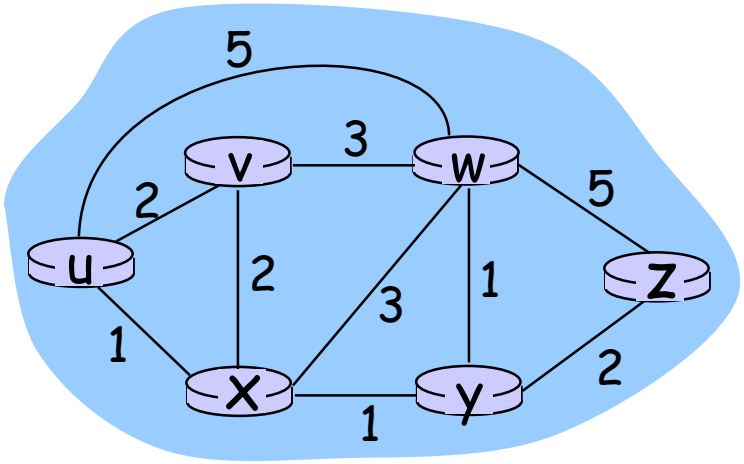
Routing algorithms

- Link state
- Distance Vector

Interplay between routing, forwarding



Graph abstraction



Graph: G = (N,E)

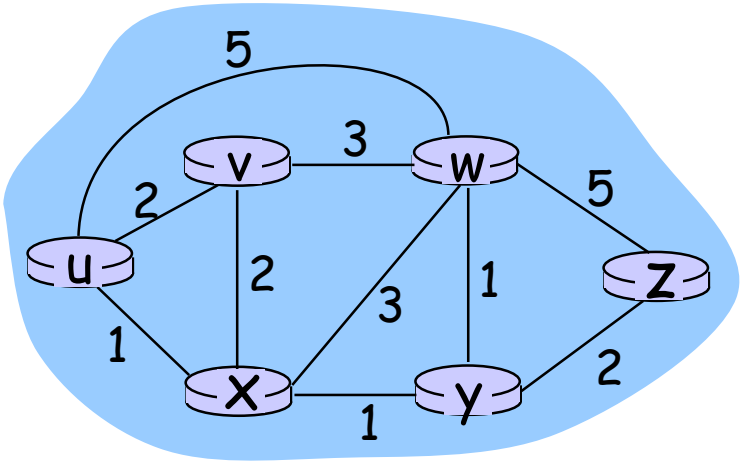
N = set of routers = { u, v, w, x, y, z }

E = set of links ={ (u,v), (u,x), (v,x), (v,w), (x,w), (x,y), (w,y), (w,z), (y,z) }

Remark: Graph abstraction is useful in other network contexts

Example: P2P, where N is set of peers and E is set of TCP connections

Graph abstraction: costs



- c(x,x') = cost of link (x,x')

  - e.g., c(w,z) = 5

- cost could always be 1, or inversely related to bandwidth, or inversely related to congestion

Cost of path $(x_1, x_2, x_3, \ldots, x_p) = c(x_1,x_2) + c(x_2,x_3) + \ldots + c(x_{p-1},x_p)$

Question: What's the least-cost path between u and z ?

Routing algorithm: algorithm that finds least-cost path

Routing Algorithm classification

Global or decentralized information?

Global:

- all routers have complete topology, link cost info
- "link state" algorithms

Decentralized:

- router knows physically-connected neighbors, link costs to neighbors
- iterative process of computation, exchange of info with neighbors
- "distance vector" algorithms

Static or dynamic?

Static:

- routes change slowly over time

Dynamic:

- routes change more quickly
  - periodic update
  - in response to link cost changes

Network Layer

Routing algorithms

- Link state
- Distance Vector

A Link-State Routing Algorithm

Dijkstra's algorithm

- net topology, link costs known to all nodes
  - accomplished via "link state broadcast"
  - all nodes have same info
- computes least cost paths from one node ('source") to all other nodes
  - gives *forwarding table* for that node
- iterative: after k iterations, know least cost path to k dest.'s

Notation:

- c(x,y): link cost from node x to y; = ∞ if not direct neighbors
- D(v): current value of cost of path from source to dest. v
- p(v): predecessor node along path from source to v
- N': set of nodes whose least cost path definitively known

Dijsktra's Algorithm

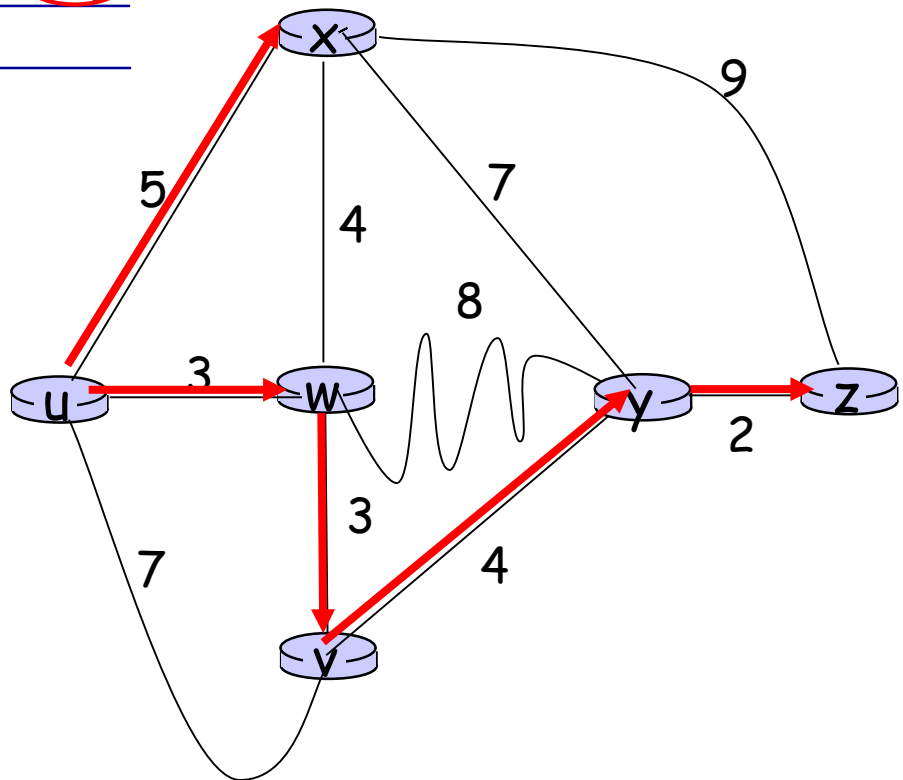
```
1  Initialization:
2    N' = {u}
3    for all nodes v
4      if v adjacent to u
5           then D(v) = c(u,v)
6      else D(v) = ∞
7
8   Loop
9     find w not in N' such that D(w) is a minimum
10    add w to N'
11    update D(v) for all v adjacent to w and not in N' :
12        D(v) = min( D(v), D(w) + c(w,v) )
13    /* new cost to v is either old cost to v or known
14     shortest path cost to w plus cost from w to v */
15  until all nodes in N'
```

Dijkstra's algorithm: example

Step	N'	D(v) p(v)	D(w) p(w)	D(x) p(x)	D(y) p(y)	D(z) p(z)
0	u	7,u	3,u	5,u	∞	∞
1	uw	6,w		5,u	11,w	∞
2	uwx	6,w			11,w	14,x
3	uwxv				10,v	14,x
4	uwxvy					12,y
5	uwxvyz					

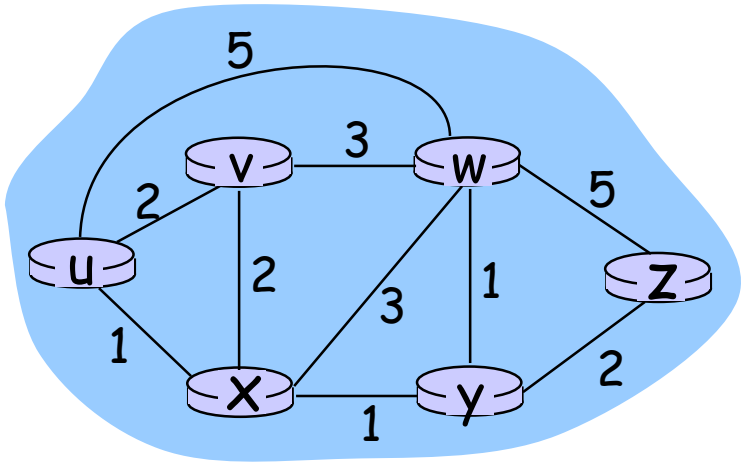
Notes:

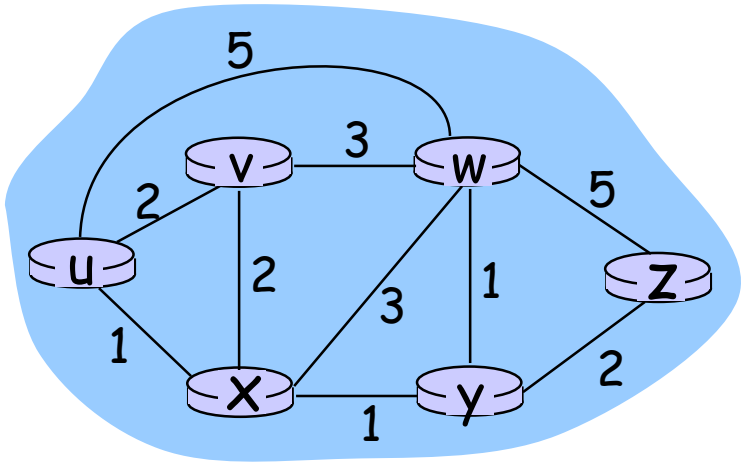
- construct shortest path tree by tracing predecessor nodes
- ties can exist (can be broken arbitrarily)



Dijkstra's algorithm: another example

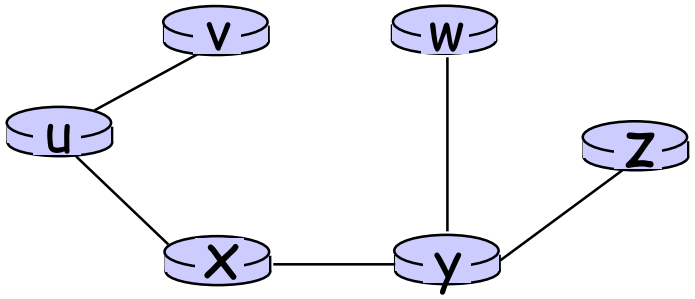
Step	N'	D(v),p(v)	D(w),p(w)	D(x),p(x)	D(y),p(y)	D(z),p(z)
0	u	2,u	5,u	1,u	∞	∞
1	ux	2,u	4,x		2,x	∞
2	uxy	2,u	3,y			4,y
3	uxyv		3,y			4,y
4	uxyvw					4,y
5	uxyvwz					




5
3
v
w
2
5
u
2
1
3
z
1
2
x
y
1

Dijkstra's algorithm: example (2)

Resulting shortest-path tree from u:



Resulting forwarding table in u:

destination	link
v	(u,v)
x	(u,x)
y	(u,x)
w	(u,x)
z	(u,x)

Network Layer

Routing algorithms

- Link state
- Distance Vector

Distance Vector Algorithm

Bellman-Ford Equation (dynamic programming)

Define

$d_x(y)$:= cost of least-cost path from x to y

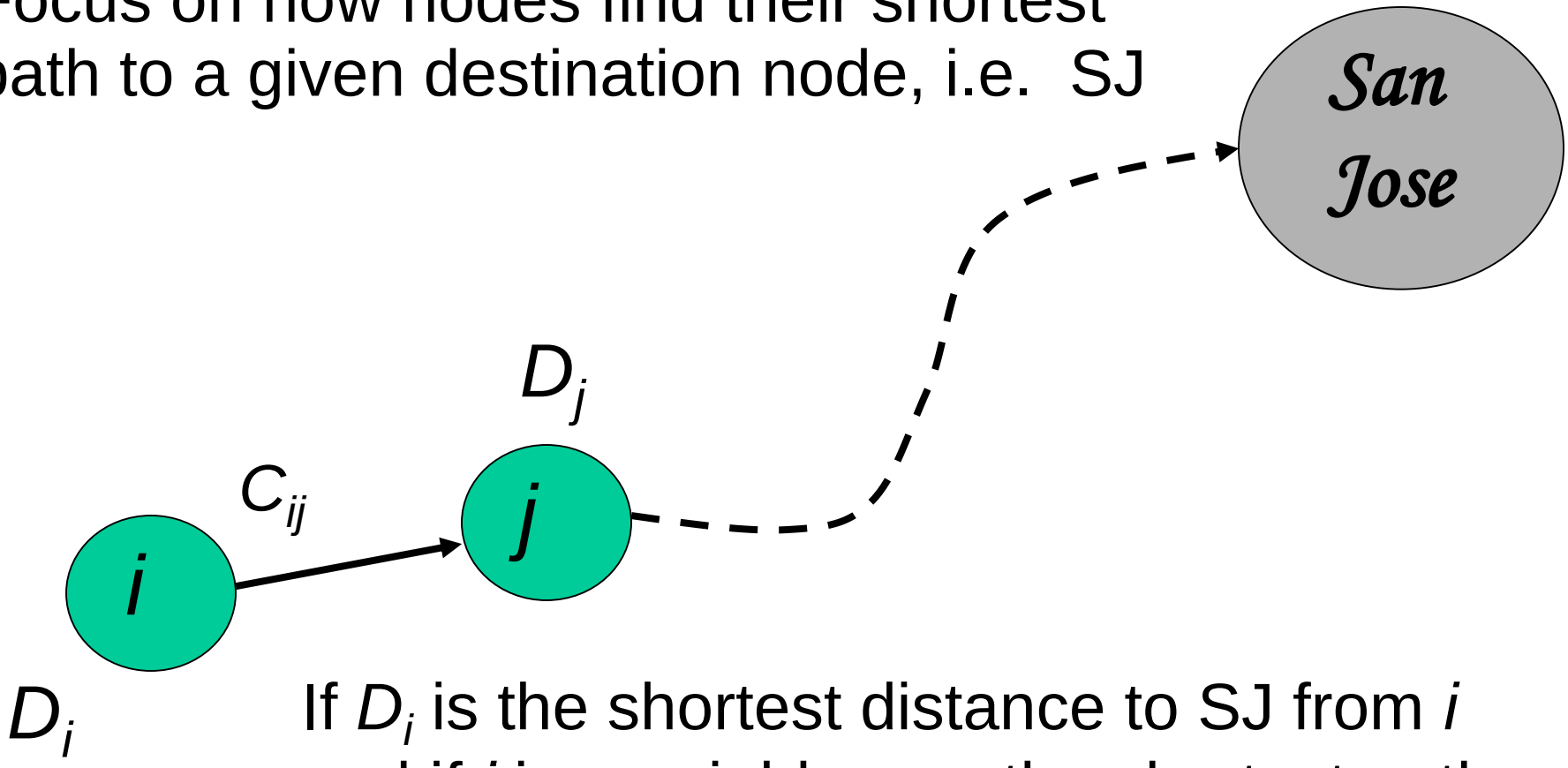
Then

$$d_x(y) = \min_v \{c(x,v) + d_v(y)\}$$

where min is taken over all neighbors v of x

Shortest Path to SJ

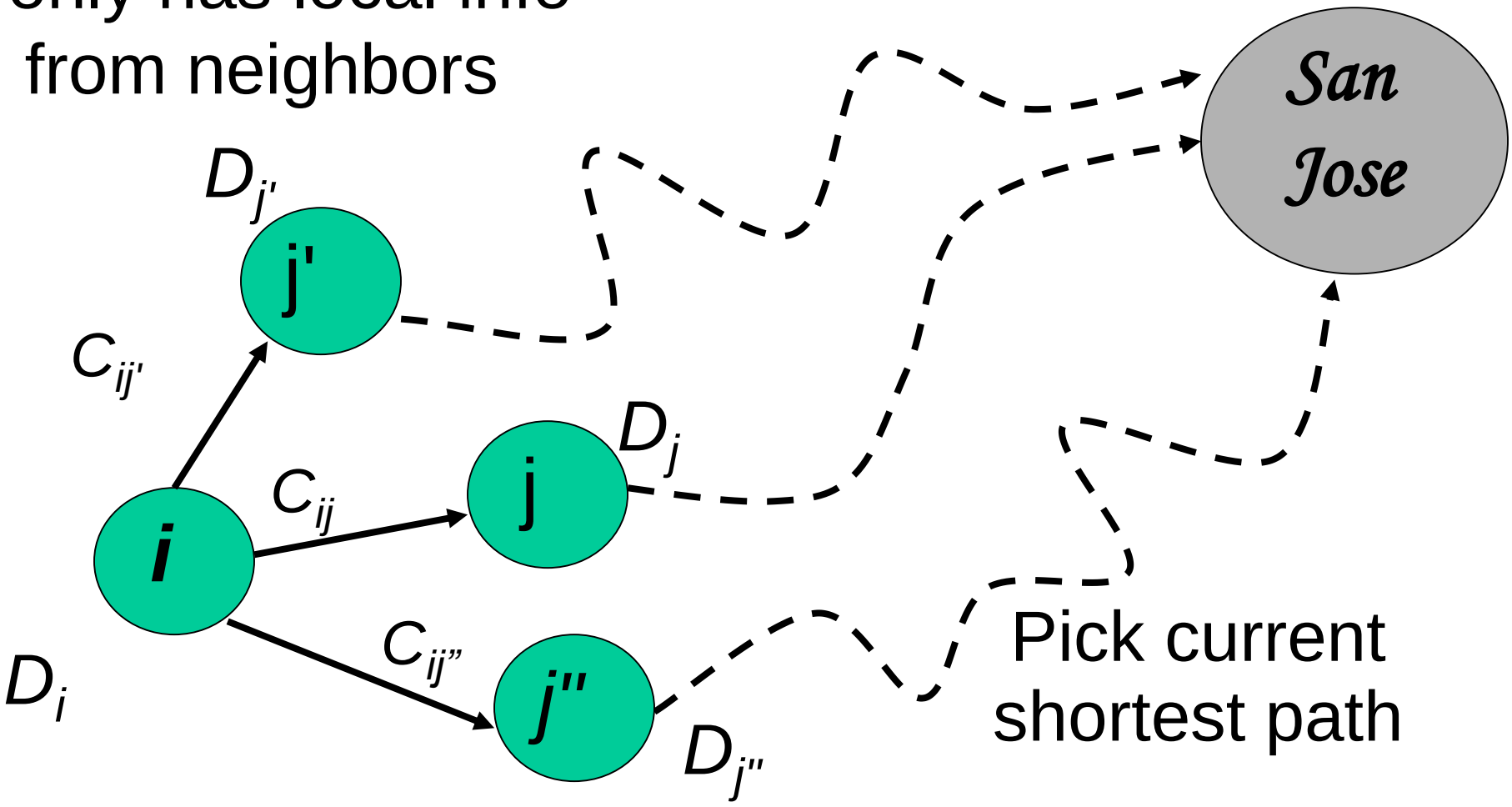
Focus on how nodes find their shortest path to a given destination node, i.e. SJ



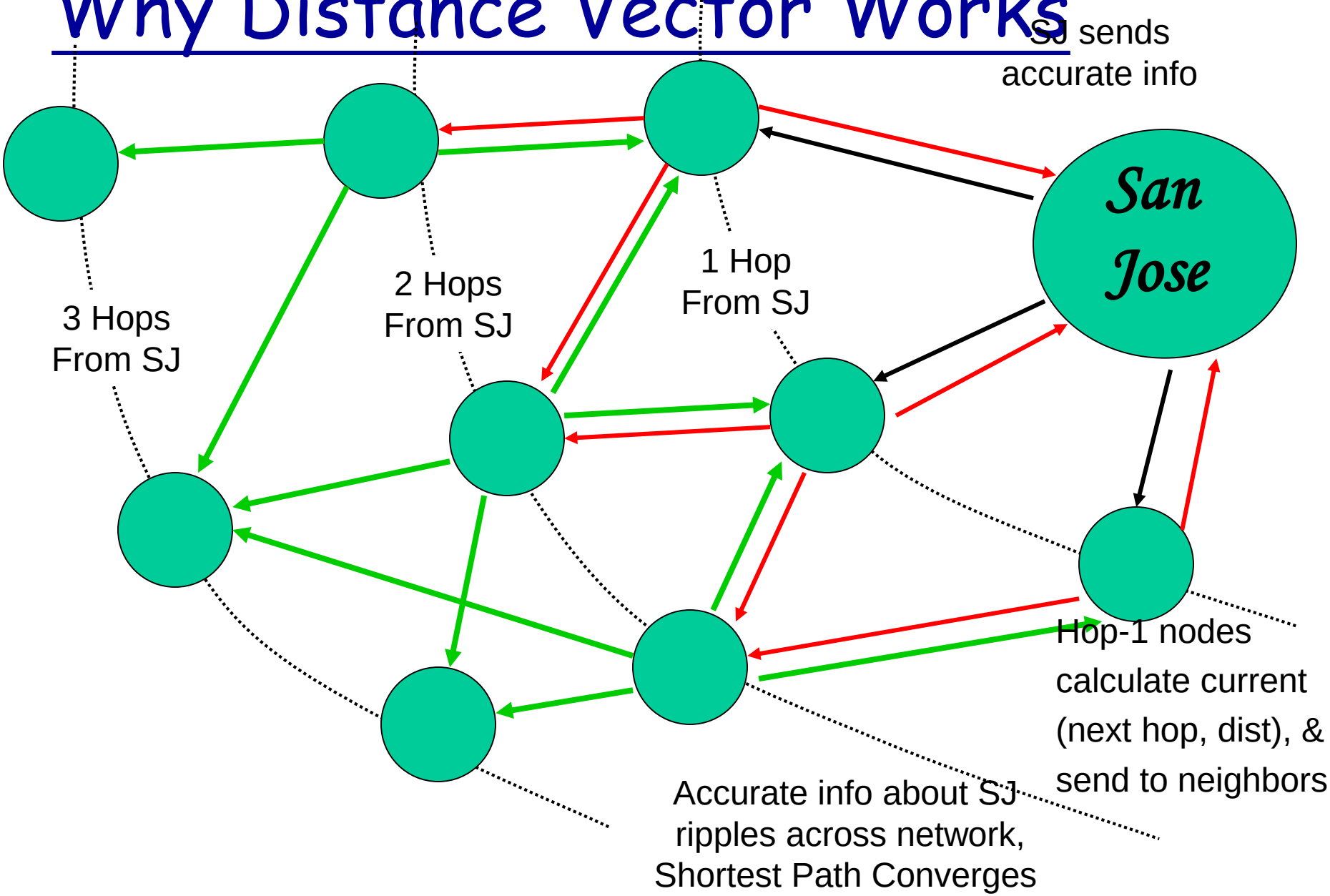
If D_i is the shortest distance to SJ from *i* and if *j* is a neighbor on the shortest path, then $D_i = C_{ij} + D_j$

But we don't know the shortest paths

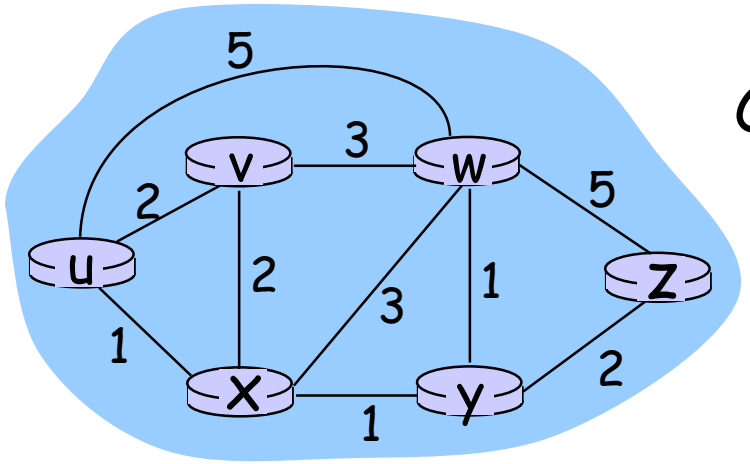
i only has local info from neighbors



Why Distance Vector Works



Bellman-Ford example



Clearly, $d_v(z) = 5$, $d_x(z) = 3$, $d_w(z) = 3$

B-F equation says:

$$d_u(z) = \min \{ c(u,v) + d_v(z), \; c(u,x) + d_x(z), \; c(u,w) + d_w(z) \}$$
$$= \min \{2 + 5, \; 1 + 3, \; 5 + 3\} = 4$$

Node that achieves minimum is next hop in shortest path ➜ forwarding table

Distance Vector Algorithm

- $D_x(y)$ = estimate of least cost from x to y
  - x maintains distance vector $\mathbf{D}_x = [D_x(y): y \in N]$
- node x:
  - knows cost to each neighbor v: $c(x,v)$
  - maintains its neighbors' distance vectors. For each neighbor v, x maintains $\mathbf{D}_v = [D_v(y): y \in N]$

Distance vector algorithm (4)

Basic idea:

- from time-to-time, each node sends its own distance vector estimate to neighbors
- when x receives new DV estimate from neighbor, it updates its own DV using B-F equation:

$$D_x(y) \leftarrow \min_v\{c(x,v) + D_v(y)\} \quad \text{for each node } y \in N$$

- under minor, natural conditions, the estimate $D_x(y)$ *converge to the actual least cost* $d_x(y)$

Distance Vector Algorithm (5)

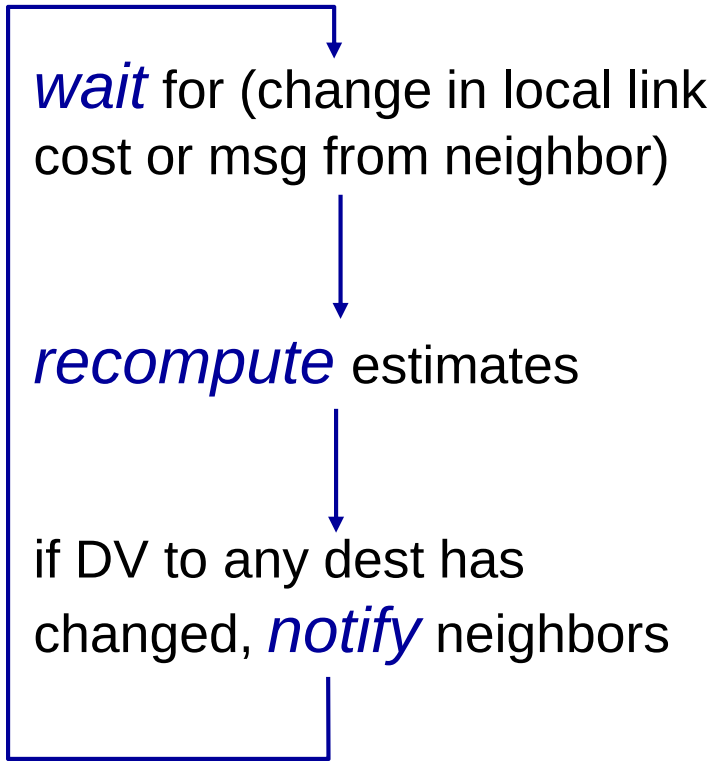
Iterative, asynchronous:
each local iteration caused by:

- local link cost change
- DV update message from neighbor

Distributed:

- each node notifies neighbors *only* when its DV changes
  - neighbors then notify their neighbors if necessary

Each node:



Distance Vector Algorithm

- c(x,v) = cost for direct link from x to v
  - Node x maintains costs of direct links c(x,v)
- $D_x(y)$ = estimate of least cost from x to y
  - Node x maintains distance vector $\mathbf{D}_x = [D_x(y): y \in N]$
- Node x maintains its neighbors' distance vectors
  - For each neighbor v, x maintains $\mathbf{D}_v = [D_v(y): y \in N]$
- Each node v periodically sends D_v to its neighbors
  - And neighbors update their own distance vectors
  - $D_x(y) \leftarrow \min_v\{c(x,v) + D_v(y)\}$ for each node $y \in N$
- Over time, the distance vector D_x converges

```
1  Initialization:
2     for all destinations y in N:
3        D_x(y) = c(x,y)    /* if y is not a neighbor then c(x,y) = ∞ */
4     for each neighbor w
5        D_w(y) = ? for all destinations y in N
6     for each neighbor w
7        send distance vector D_x = [D_x(y): y in N] to w
8
9  loop
10    wait (until I see a link cost change to some neighbor w or
11          until I receive a distance vector from some neighbor w)
12
13    for each y in N:
14       D_x(y) = min_v{c(x,v) + D_v(y)}
15
16    if D_x(y) changed for any destination y
17       send distance vector D_x = [D_x(y): y in N] to all neighbors
18
19 forever
```

$D_x(y) = \min\{c(x,y) + D_y(y),\ c(x,z) + D_z(y)\}$
$= \min\{2+0\ ,\ 7+1\} = 2$

$D_x(z) = \min\{c(x,y) +$
$D_y(z),\ c(x,z) + D_z(z)\}$
$= \min\{2+1\ ,\ 7+0\} = 3$

node x table

from \ cost to	x	y	z
x	0	2	7
y	∞	∞	∞
z	∞	∞	∞

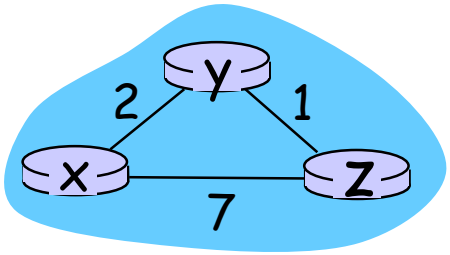
from \ cost to	x	y	z
x	0	2	3
y	2	0	1
z	7	1	0

node y table

from \ cost to	x	y	z
x	∞	∞	∞
y	2	0	1
z	∞	∞	∞

node z table

from \ cost to	x	y	z
x	∞	∞	∞
y	∞	∞	∞
z	7	1	0



time

$D_x(y) = \min\{c(x,y) + D_y(y),\ c(x,z) + D_z(y)\}$
$= \min\{2+0\ ,\ 7+1\} = 2$

$D_x(z) = \min\{c(x,y) + D_y(z),\ c(x,z) + D_z(z)\}$
$= \min\{2+1\ ,\ 7+0\} = 3$

node x table

from	cost to x	y	z
x	0	2	7
y	∞	∞	∞
z	∞	∞	∞

from	cost to x	y	z
x	0	2	3
y	2	0	1
z	7	1	0

from	cost to x	y	z
x	0	2	3
y	2	0	1
z	3	1	0

node y table

from	cost to x	y	z
x	∞	∞	∞
y	2	0	1
z	∞	∞	∞

from	cost to x	y	z
x	0	2	7
y	2	0	1
z	7	1	0

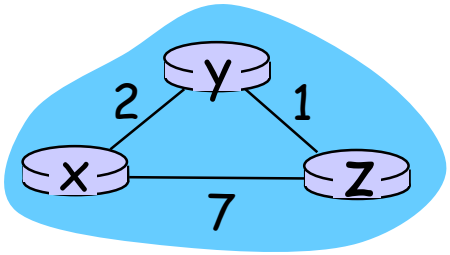
from	cost to x	y	z
x	0	2	3
y	2	0	1
z	3	1	0

node z table

from	cost to x	y	z
x	∞	∞	∞
y	∞	∞	∞
z	7	1	0

from	cost to x	y	z
x	0	2	7
y	2	0	1
z	3	1	0

from	cost to x	y	z
x	0	2	3
y	2	0	1
z	3	1	0

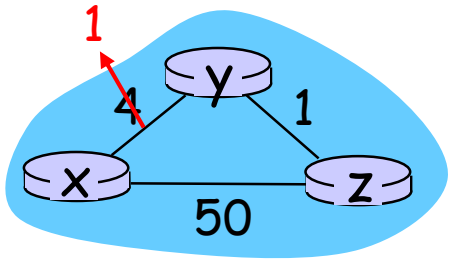


time

Distance Vector: link cost changes

Link cost changes:

- node detects local link cost change
- updates routing info, recalculates distance vector
- if DV changes, notify neighbors



"good news travels fast"

t_0 : y detects link-cost change, updates its DV, informs its neighbors.

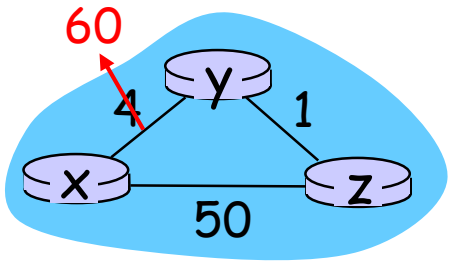
t_1 : z receives update from y, updates its table, computes new least cost to x , sends its neighbors its DV.

t_2 : y receives z's update, updates its distance table. y's least costs do *not* change, so y does *not* send a message to z.

Distance Vector: link cost changes

Link cost changes:

- good news travels fast
- bad news travels slow - "count to infinity" problem!
- 44 iterations before algorithm stabilizes.



Poisoned reverse:

- If Z routes through Y to get to X :
  - Z tells Y its (Z's) distance to X is infinite (so Y won't route to X via Z)
- will this completely solve count to infinity problem?

Routing Protocol

Hierarchical routing

our routing study thus far - idealization

- all routers identical
- network "flat"

… *not* true in practice

scale: with 600 million destinations:

- can't store all dest's in routing tables!
- routing table exchange would swamp links!

administrative autonomy

- internet = network of networks
- each network admin may want to control routing in its own network

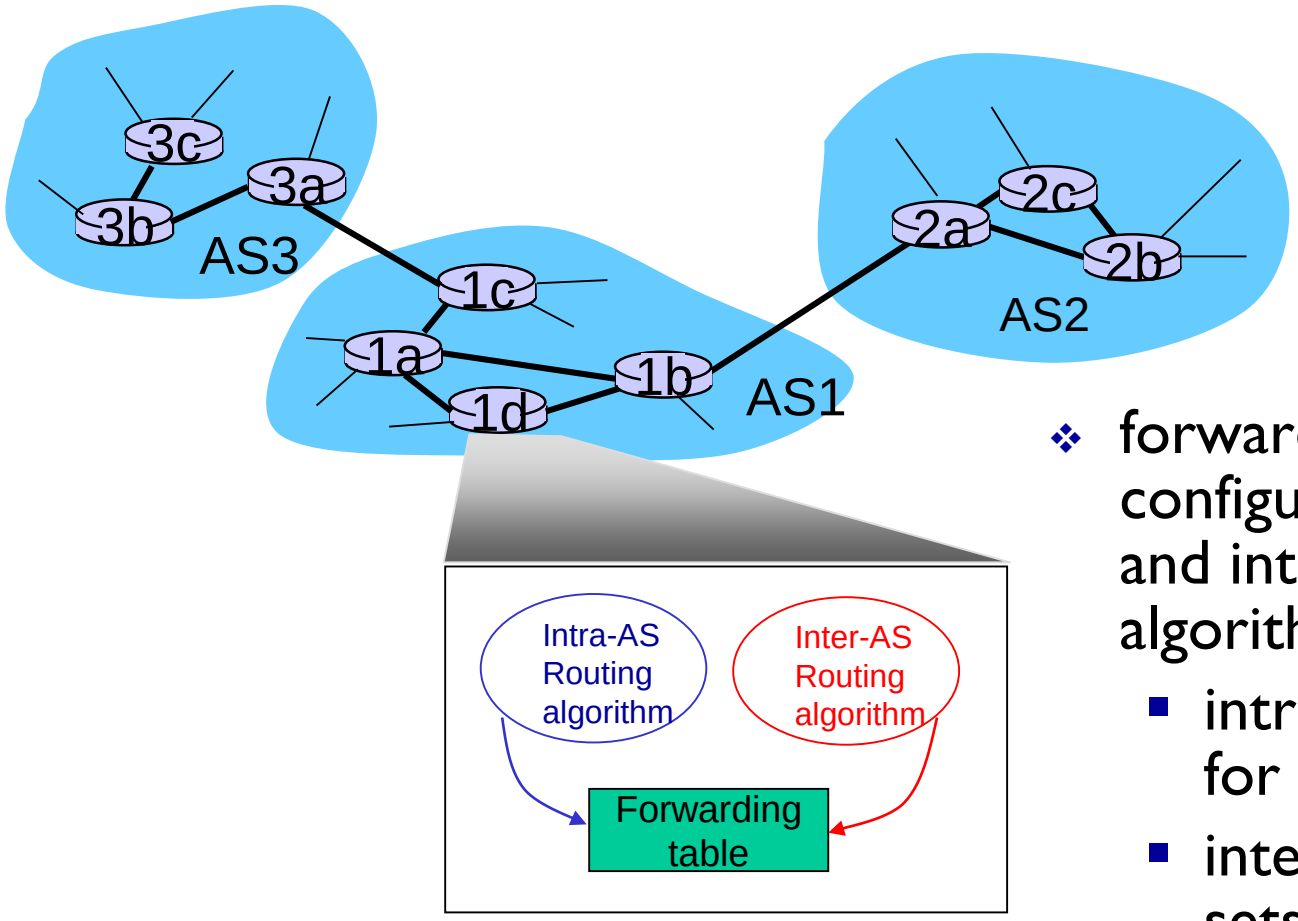
Hierarchical routing

- aggregate routers into regions, "autonomous systems" (AS)
- routers in same AS run same routing protocol
  - "intra-AS" routing protocol
  - routers in different AS can run different intra-AS routing protocol

gateway router:

- at "edge" of its own AS
- has link to router in another AS

Interconnected ASes



- forwarding table configured by both intra- and inter-AS routing algorithm
  - intra-AS sets entries for internal dests
  - inter-AS & intra-AS sets entries for external dests

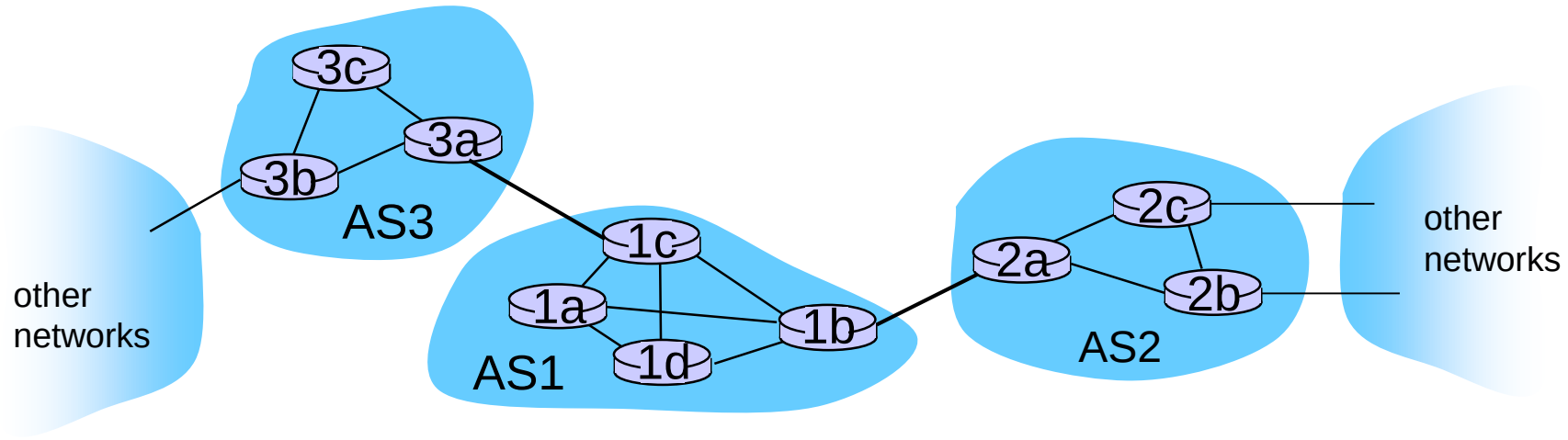
Inter-AS tasks

- suppose router in AS1 receives datagram destined outside of AS1:
  - router should forward packet to gateway router, but which one?

AS1 must:

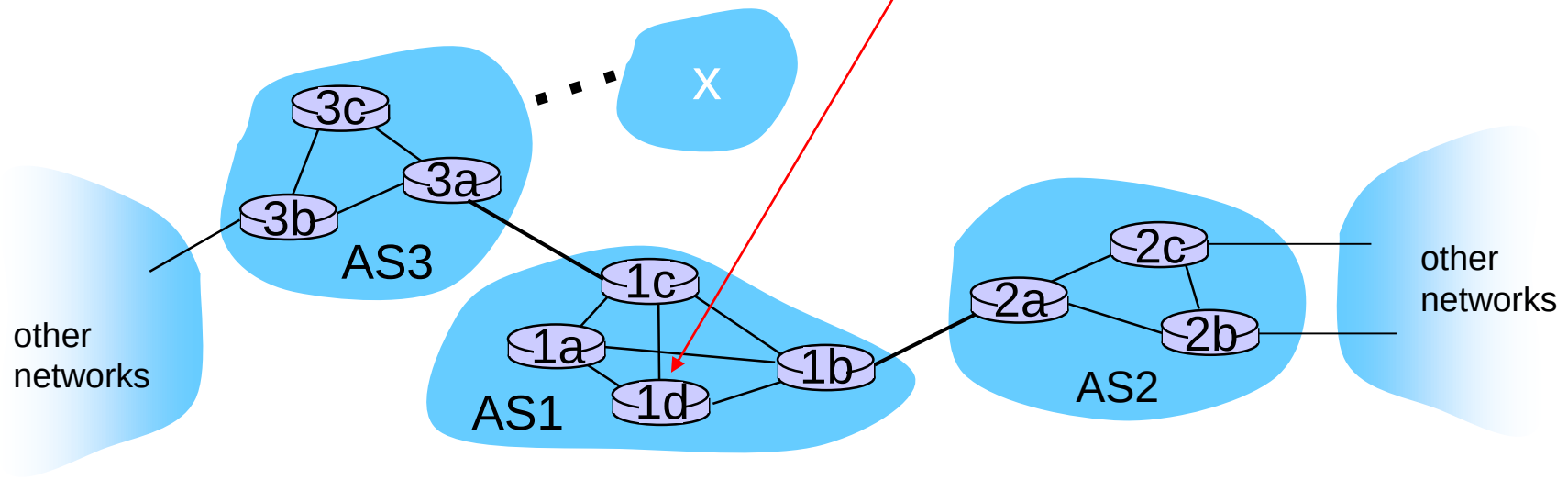
1. learn which dests are reachable through AS2, which through AS3
2. propagate this reachability info to all routers in AS1

job of inter-AS routing!



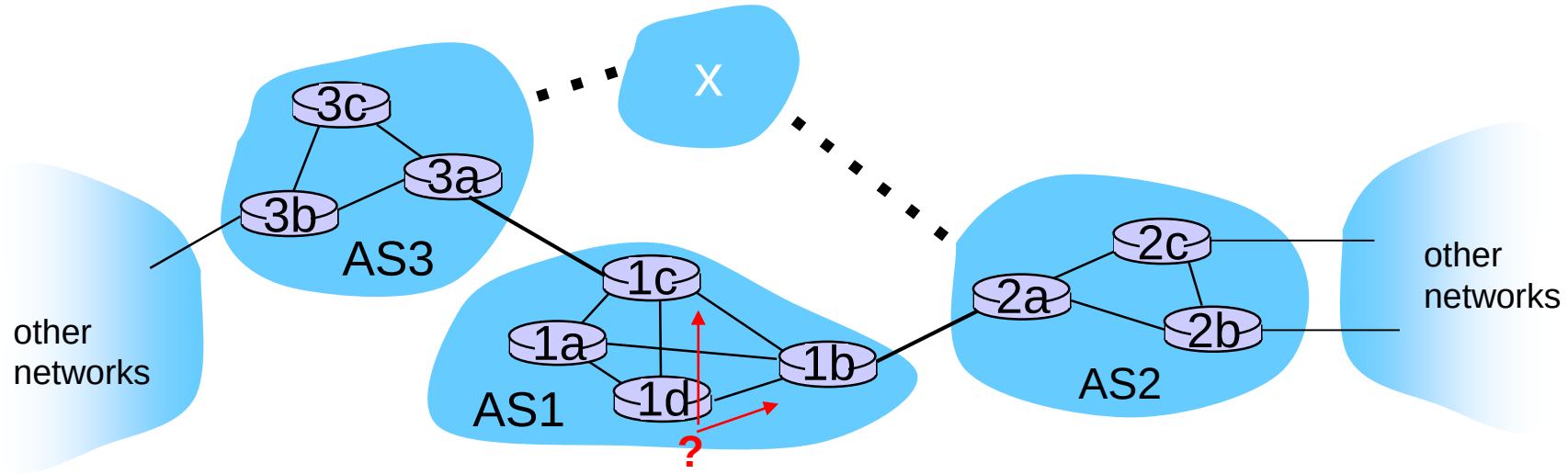
Example: setting forwarding table in router 1d

- suppose AS1 learns (via inter-AS protocol) that subnet *x* reachable via AS3 (gateway 1c), but not via AS2
  - inter-AS protocol propagates reachability info to all internal routers
- router 1d determines from intra-AS routing info that its interface *I* is on the least cost path to 1c
  - installs forwarding table entry *(x,I)*



Example: choosing among multiple ASes

- now suppose AS1 learns from inter-AS protocol that subnet *x* is reachable from AS3 *and* from AS2.
- to configure forwarding table, router 1d must determine which gateway it should forward packets towards for dest x
  - this is also job of inter-AS routing protocol!

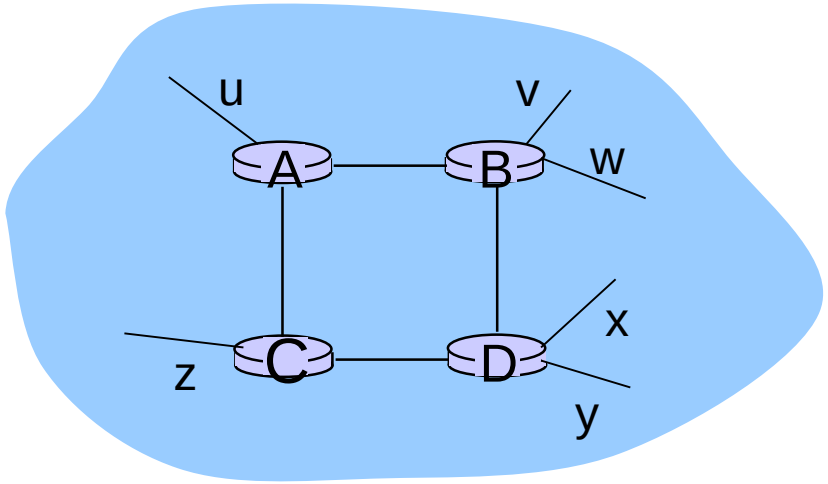


Intra-AS Routing

- also known as *interior gateway protocols (IGP)*
- most common intra-AS routing protocols:
  - RIP: Routing Information Protocol
  - OSPF: Open Shortest Path First
  - IGRP: Interior Gateway Routing Protocol (Cisco proprietary)

RIP (Routing Information Protocol)

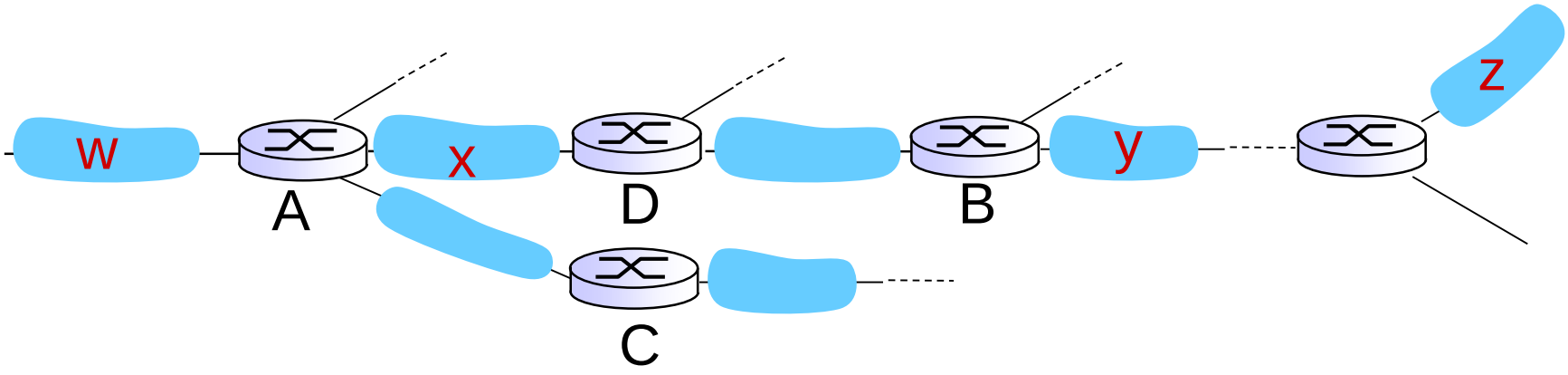
- included in BSD-UNIX distribution in 1982
- distance vector algorithm
  - distance metric: # hops (max = 15 hops), each link has cost 1
  - DVs exchanged with neighbors every 30 sec in response message (aka advertisement)
  - each advertisement: list of up to 25 destination *subnets (in IP addressing sense)*



from router A to destination *subnets:*

subnet	hops
u	1
v	2
w	2
x	3
y	3
z	2

RIP: example



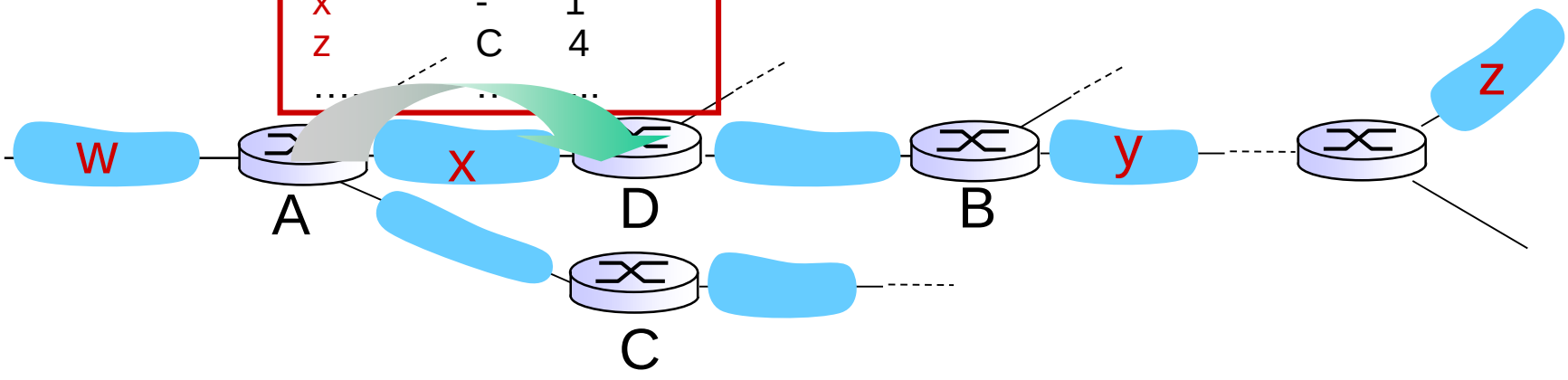
routing table in router D

destination subnet	next router	# hops to dest
w	A	2
y	B	2
z	B	7
x	--	1
….	….	….

RIP: example

A-to-D advertisement

dest	next	hops
w	-	1
x	-	1
z	C	4
....	....	....



routing table in router D

destination subnet	next router	# hops to dest
w	A	2
y	B	2
z	B A	7 5
x	--	1
....	....	....

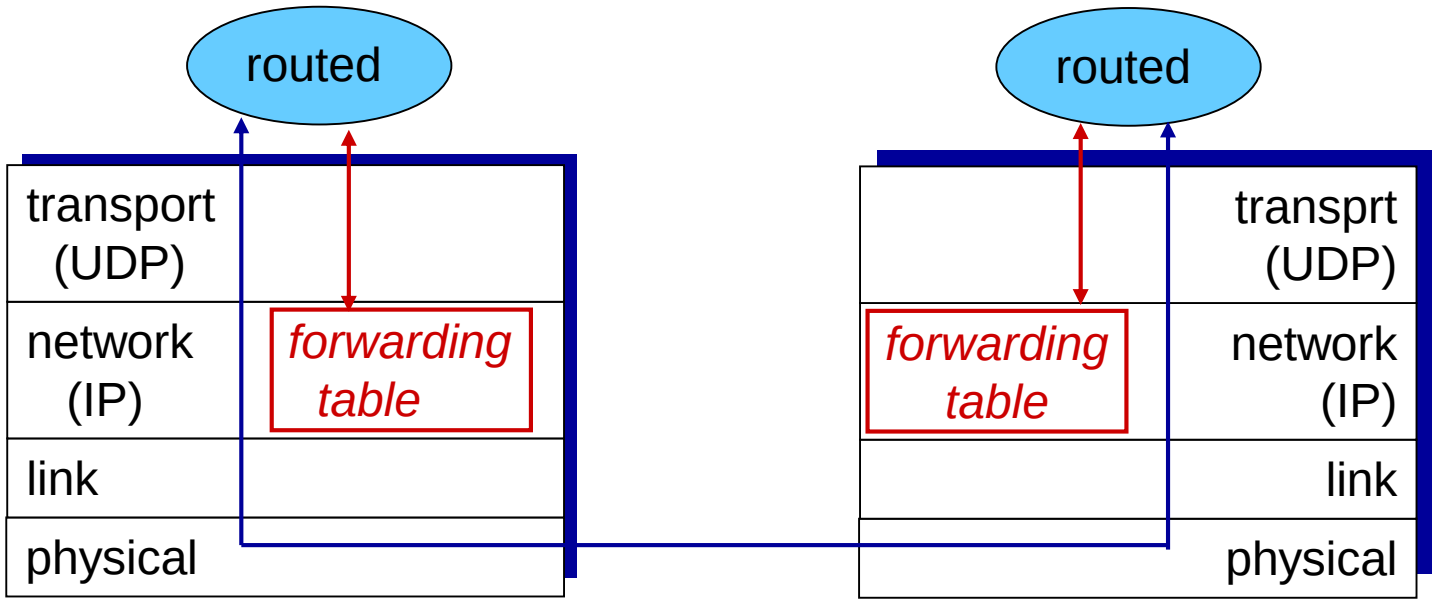
RIP: link failure, recovery

if no advertisement heard after 180 sec -->
neighbor/link declared dead

- routes via neighbor invalidated
- new advertisements sent to neighbors
- neighbors in turn send out new advertisements (if tables changed)
- link failure info quickly (?) propagates to entire net
- *poison reverse* used to prevent ping-pong loops (infinite distance = 16 hops)

RIP table processing

- RIP routing tables managed by *application-level* process called route-d (daemon)
- advertisements sent in UDP packets, periodically repeated



OSPF (Open Shortest Path First)

- "open": publicly available
- uses link state algorithm
  - LS packet dissemination
  - topology map at each node
  - route computation using Dijkstra's algorithm
- OSPF advertisement carries one entry per neighbor
- advertisements flooded to *entire* AS
  - carried in OSPF messages directly over IP (rather than TCP or UDP
- *IS-IS routing* protocol: nearly identical to OSPF

Routing Algorithms

- IP v6
- Routing algorithms
  - Link state
  - Distance Vector

IPv6

- Initial motivation: 32-bit address space soon to be completely allocated.
- Additional motivation:
  - header format helps speed processing/forwarding
  - header changes to facilitate QoS

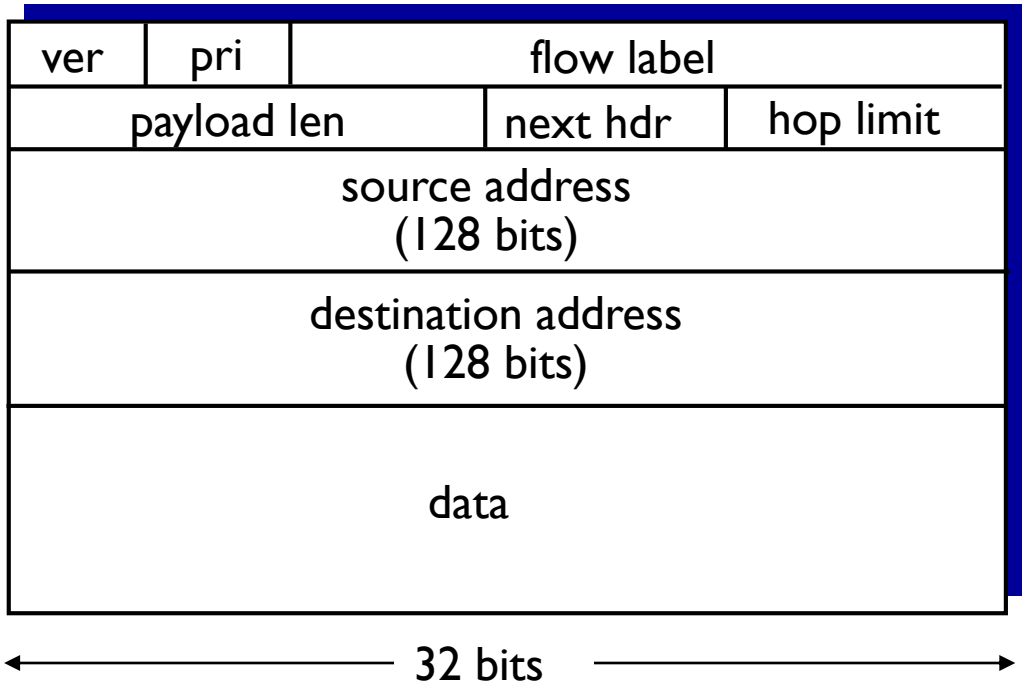
  IPv6 datagram format:
  - fixed-length 40 byte header
  - no fragmentation allowed

IPv6 Header (Cont)

Priority: identify priority among datagrams in flow

Flow Label: identify datagrams in same "flow."
(concept of"flow" not well defined).

Next header: identify upper layer protocol for data



Other Changes from IPv4

- *Checksum:* removed entirely to reduce processing time at each hop
- *Options:* allowed, but outside of header, indicated by "Next Header" field
- *ICMPv6:* new version of ICMP
  - additional message types, e.g. "Packet Too Big"
  - multicast group management functions

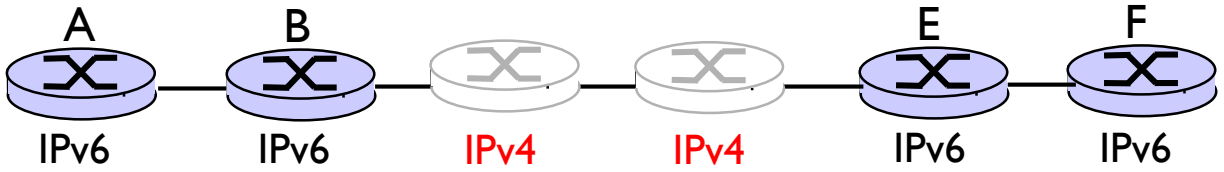
Transition From IPv4 To IPv6

- Not all routers can be upgraded simultaneous
  - no "flag days"
  - How will the network operate with mixed IPv4 and IPv6 routers?
- *Tunneling:* IPv6 carried as payload in IPv4 datagram among IPv4 routers

Tunneling

Logical view:

Physical view:



Tunneling

Logical view:

Physical view: