

```

{
pinMode(1,OUTPUT);
digitalWrite(i,LOW);
}
}
void loop()
{
if (irrecv.decode(Sresults))
{
switch(results. .value)
{
case K2:res=2;break;
case K3:res=3;break;
case K4:res=4;break;
case K5:res=5;break;
case K6:res=6;break;
case K7:res=7;break;
case K8:res=8;break;
case K9:res=9;break;
default:res=0;break;
}
if (res>0)
{
pins[res-2]=1- pins[res-2];
// yorug'lik diodining holatini o'zgartirish

digitalWrite(res, pins[res-2]);
}
irrecv.resume(); // navbatdagi qiymatni olish
}
}

```

Arduino platasiga 25.2 sketchi yuklanadi va Arduino platasining (25.2 chizmaga qaralsin) 2-9 oyoqchalariga ulangan pultdagi 2-9 tugmalarni bosish orqali yorug'lik diodlarining holati o'zgartiriladi.

Mavzu doirasidan qo'shimcha savollar.

1. Masofadan turub boshqarish qanday amalga oshiriladi?
2. IQ yorug'lik qabul qiluvchi asosida kichik loyiha.
3. IQ va motor boshqarish