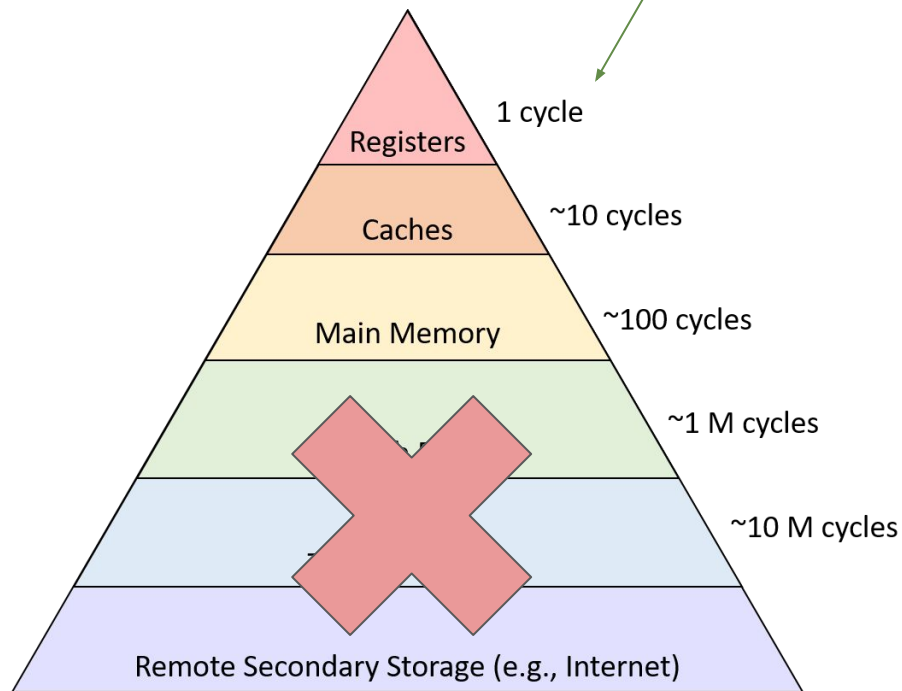




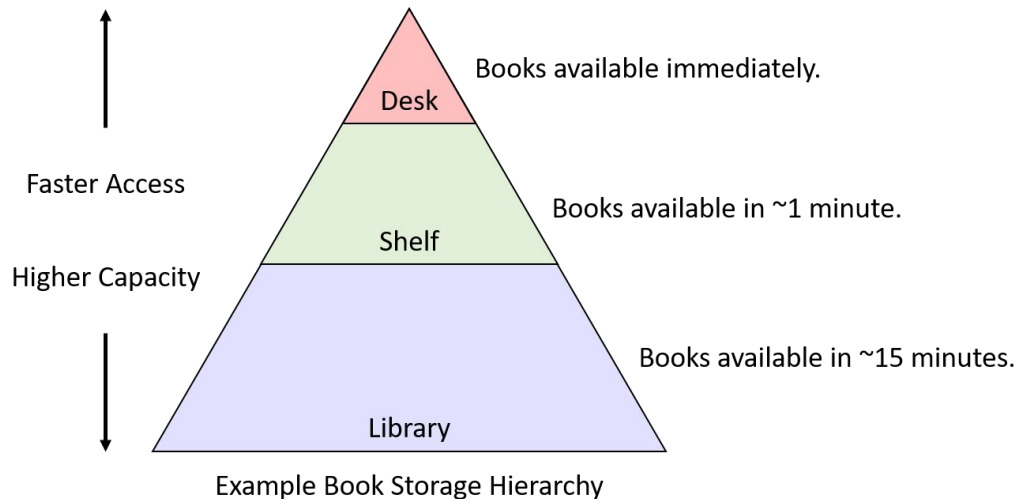
# The Memory Hierarchy

More on these later.



The Memory Hierarchy

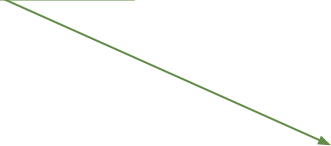
# Temporal locality



← “Temporal” locality

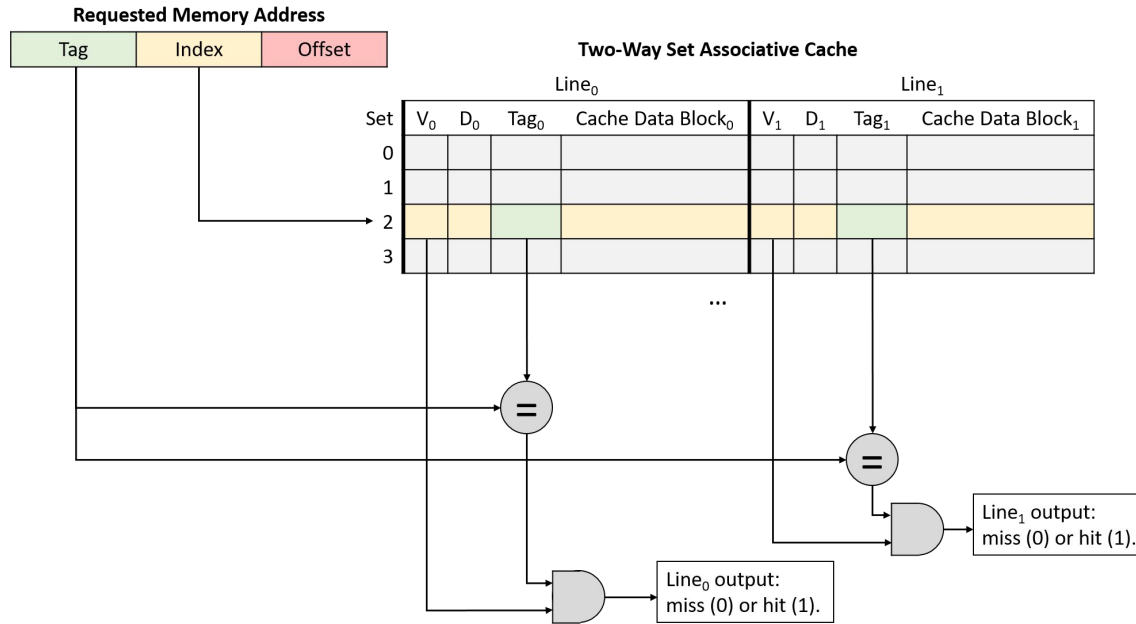
# Spatial locality

```
for (int i = 0; i < size; i++) {  
    sum += array[i];  
}
```



0000000020041fc0	93 11 00 00 00 00 00 00 00 00	01 00 00 00 02 00 00 00
0000000020041fd0	03 00 00 00 04 00 00 00 00 00	05 00 00 00 06 00 00 00
0000000020041fe0	07 00 00 00 08 00 00 00 00 00	09 00 00 00 0a 00 00 00

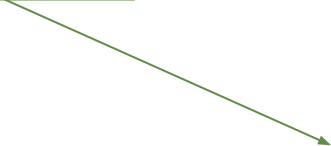
# “Associative” caching



Instructions,  
data have a **tag  
number** which  
allows cache to  
find quickly

# Spatial locality

```
for (int i = 0; i < size; i++) {  
    sum += array[i];  
}
```



0000000020041fc0 93 11 00 00 00 00 00 00 00 01 00 00 00 02 00 00 00

0000000020041fd0 03 00 00 00 04 00 00 00 00 05 00 00 00 06 00 00 00

0000000020041fe0 07 00 00 00 08 00 00 00 00 09 00 00 00 0a 00 00 00

# “Associative” caching

LRU: a one-bit flag that indicates whether the leftmost line<sub>0</sub> of the set was least recently used (LRU = 0) or the rightmost line<sub>1</sub> of the set was least recently used (LRU = 1).

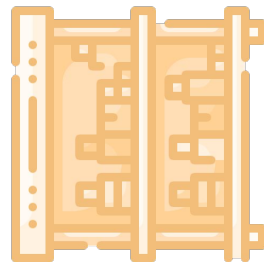
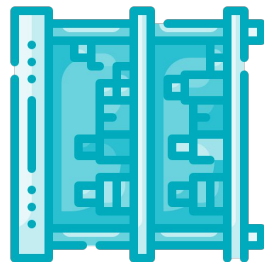
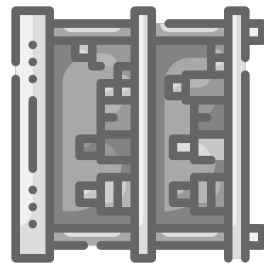
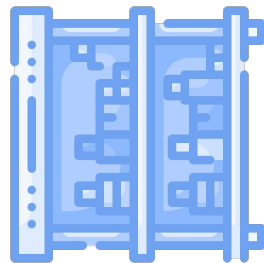
**Two-Way Set Associative Cache**

Set	LRU	Line <sub>0</sub>				Line <sub>1</sub>			
		V <sub>0</sub>	D <sub>0</sub>	Tag <sub>0</sub>	Cache Data Block <sub>0</sub>	V <sub>1</sub>	D <sub>1</sub>	Tag <sub>1</sub>	Cache Data Block <sub>1</sub>
0									
1									
2									
3									

...

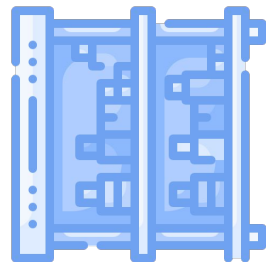
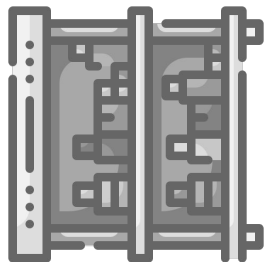
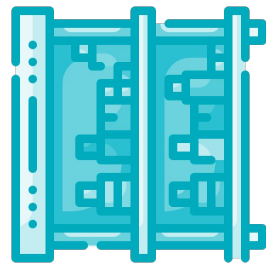
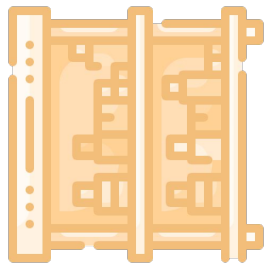
Leads to “cache eviction” if one match used more recently than another, freeing up space.

# Cache rules everything around me



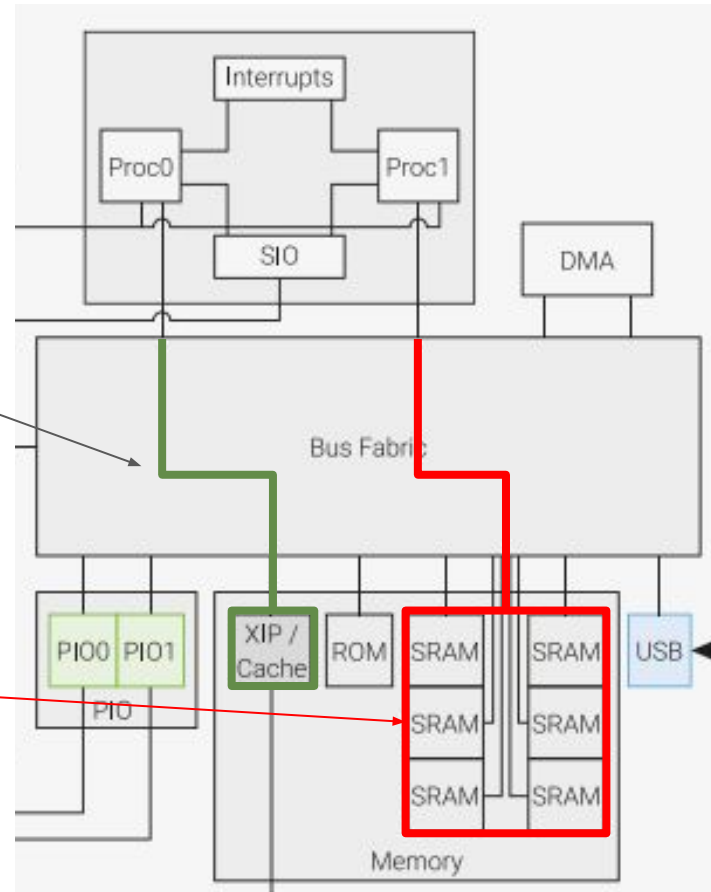


# Cache rules everything around me

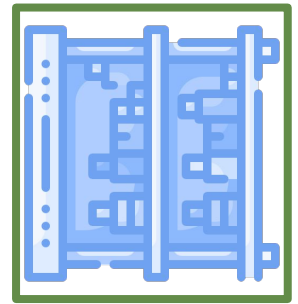
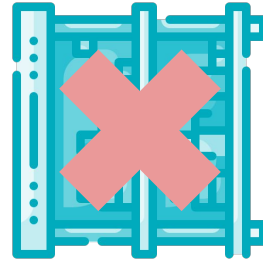
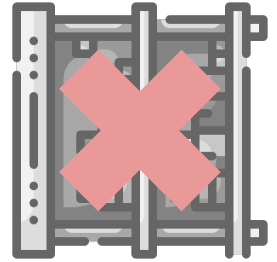
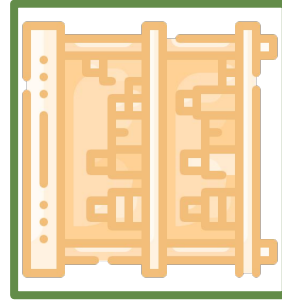
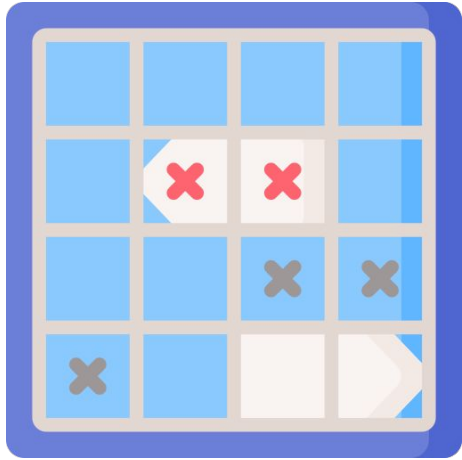


# Why cache at all?

- Single source
- Direct line to processing unit
- Many sources
- First have to figure out *where* data is



# Cache rules everything around me



## Hit or miss

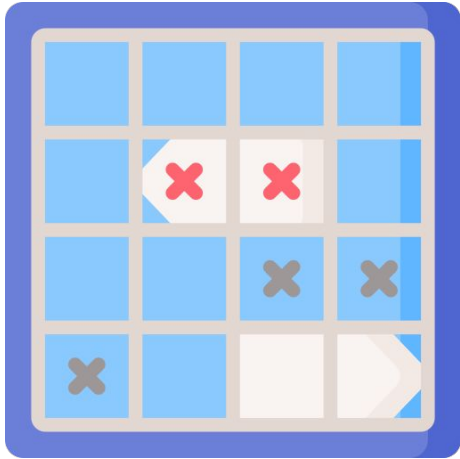
Theoretically...

$$misses = \frac{num_{elements}}{\frac{block\ size}{size_{elements}}}$$

The diagram illustrates the formula for calculating misses. It features three numerical values with green arrows pointing to specific parts of the formula: the value 10 points to the numerator  $num_{elements}$ , the value 32 points to the denominator  $block\ size$ , and the value 4 points to the denominator  $size_{elements}$ .

Value	Target in Formula
10	$num_{elements}$
32	$block\ size$
4	$size_{elements}$

## Hit or miss



$$\textit{hit rate} = \textit{hits} * \frac{100.0}{\textit{accesses}}$$

$$\textit{miss rate} = 1 - \textit{hit rate}$$

## Hit or miss

$$\textit{hit rate} = \textit{hits} * \frac{100.0}{\textit{accesses}}$$

```
float get_cache_hit_rate (void) {  
    return xip_ctrl_hw->ctr_hit * 100.f / xip_ctrl_hw->ctr_acc;  
}
```

## All in the timing

We can naively prove the effectiveness of the cache by looking at program execution times with data *in* and *out* of the cache.

$$\textit{net time} = \textit{time at end} - \textit{time at start}$$

## Movin' on up

To perform this experiment, we actually have to *physically move the code* to a region of the dedicated cache chip which *voids caching* using a special kind of pointer.

The range where the  
cache dares not go

```
func_ptr_t_array sum_array_nocache = (func_ptr_t_array)  
((int)sum_array - CACHE_BASE) + CACHE_BYPASS;
```

Where function “lives”  
right now

The base address of  
that range



# So, I have a problem.

Which one reads *faster* with the lowest *miss rate*?

[i][j] matrix

[j][i] matrix