

LEC-4 Deep Generative Modeling

Unsupervised Learning

n data, no labels \rightarrow learn hidden / underlying structure

Generative modeling

Goal: Take as input training samples from some distribution & learn a model that represents that distribution

Density estimation

sample generation

Outlier detection

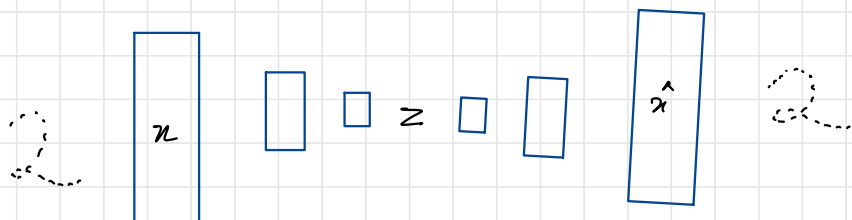
Latent Variable models

Autoencoders &
Variational encoders

Generative Adversarial
Networks (GANs)

Autoencoders

Encoder learns mapping from the data x to a low dimensional latent space z



$$\mathcal{L}(x, \hat{x}) = \|x - \hat{x}\|^2$$

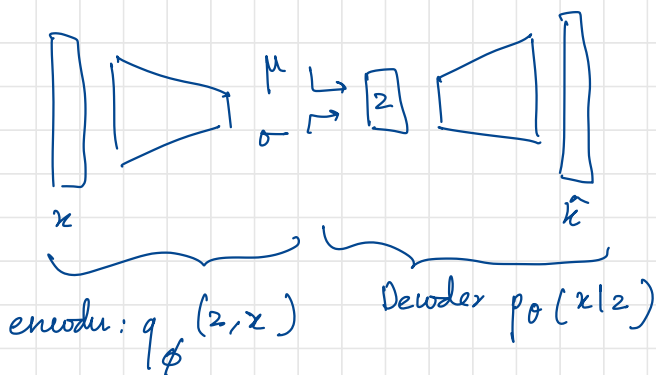
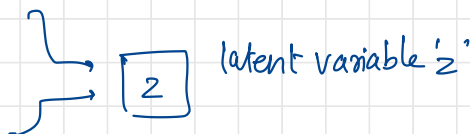
Bottleneck hidden layer forces network to learn a compressed latent representation

Reconstruction loss forces latent representation to capture/encode as much information as possible.

Variational Autoencoder \rightarrow probabilistic twist on traditional autoencoder
 \rightarrow non-deterministic

mean vector

standard deviation vector



$$\mathcal{L}(\phi, \theta, x) = (\text{reconstruction loss}) + (\text{regularization loss})$$

\uparrow encoder \uparrow decoder

$$D(q_{\phi}(z|x) \parallel p(z))$$

difference between probability distributions

$$D(q_\phi(z|x) \parallel p(z))$$

Inferred latent distribution

fixed prior on latent distribution

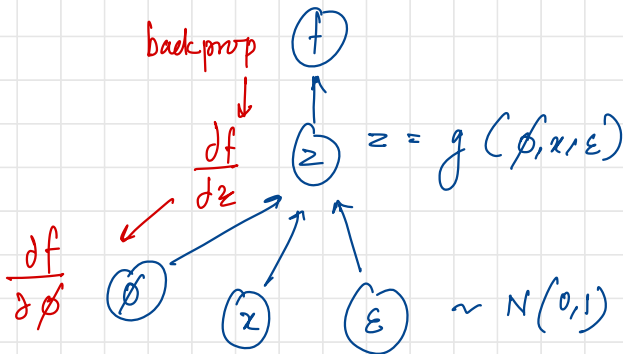
$$K\text{-L divergence} = -\frac{1}{2} \sum_{j=0}^{K-1} (\sigma_j + \mu_j^2 - 1 - \log \sigma_j)$$

Reparameterizing the sampling layer

* fixed μ vector

* fixed σ vector scaled by random constants drawn from the prior distribution

$$\Rightarrow z = \mu + \sigma \odot \epsilon$$

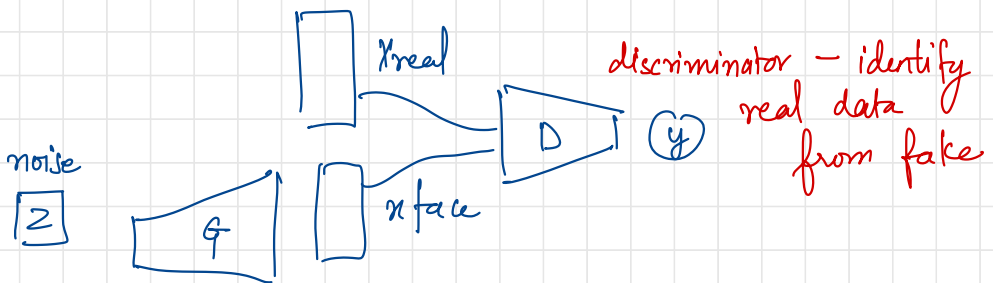
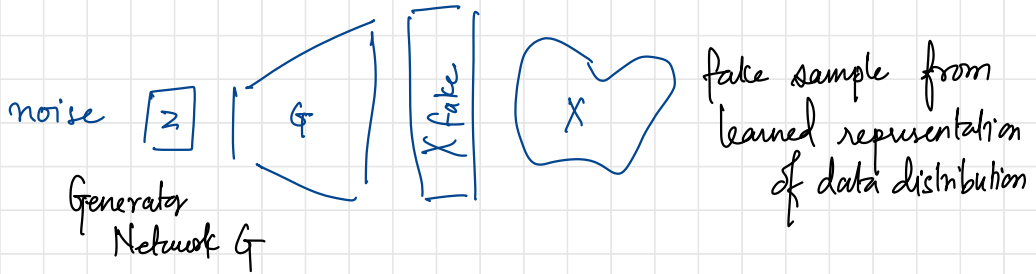


$$\mathcal{L}(\theta, \phi; x, z, \beta) = \underbrace{E_{q_\phi(z|x)} [\log p_\theta(x|z)]}_{\text{reconstruction}} - \underbrace{\beta D_{KL}(q_\phi(z|x) \parallel p(z))}_{\text{regularization}}$$

Generative Adversarial Networks

Idea: do not explicitly model density - use samples for new instances

Solution: sample from something simple (noise) learn a transformation to the data distribution



generator turns noise into an imitation of data to trick discriminator

GAN loss function

$$\arg \max_D E_{z, x} \left[\overbrace{\log D(G(z))}^{\text{Fake}} + \overbrace{\log (1 - D(x))}^{\text{Real}} \right]$$

Discriminator tries to identify synthesized images

Generator

$$\arg \min_G E_{z, x} \left[\log D(G(z)) + \log (1 - D(x)) \right]$$

final loss function

$$\arg \max_D \min_G E_{z, x} \left[\log D(G(z)) + \log (1 - D(x)) \right]$$