

# Parametric Methods

# Probability and Inference

- Result of tossing a coin is Head/1 or Tail/0

- Random variable  $X \in \{1,0\}$

Bernoulli:  $P(X = 1) = p_0^X (1 - p_0)^{1-X}$

- Training set:  $\mathcal{X} = \{X_t\}_{t=1}^N$

Estimation:  $p_0 = \frac{\text{\# of heads}}{\text{\# of tosses}} = \frac{\sum_{t=1}^N X_t}{N}$

- The rule for prediction of the next toss:

Heads if  $p_0 > \frac{1}{2}$ ,

Tails otherwise

- Maximum likelihood estimate of  $p_0$

Define log-likelihood function as

$$\begin{aligned}\mathcal{L}(p_0|X_1, X_2, \dots, X_N) &= \log P(X_1, X_2, \dots, X_N) = \sum_{t=1}^N \log P(X_t) \\ &= \sum_{t=1}^N X_t \log p_0 + (1 - X_t) \log(1 - p_0)\end{aligned}$$

- The maximum likelihood estimate of  $p_0$  can be obtained by solving

$$p_0 = \underset{p_0}{\operatorname{argmax}} \mathcal{L}(p_0|X_1, X_2, \dots, X_N)$$

$$\begin{aligned}\frac{\partial \mathcal{L}(p_0|X_1, X_2, \dots, X_N)}{\partial p_0} &= 0 \\ \Rightarrow \frac{\sum_{t=1}^N X_t}{p_0} - \frac{N - \sum_{t=1}^N X_t}{1 - p_0} &= 0 \\ \Rightarrow p_0 &= \frac{\sum_{t=1}^N X_t}{N}\end{aligned}$$

# Parametric Estimation

- $\mathcal{X} = \{X_t\}_{t=1}^N$  where  $X_t \sim P(X)$

- **Parametric estimation:**

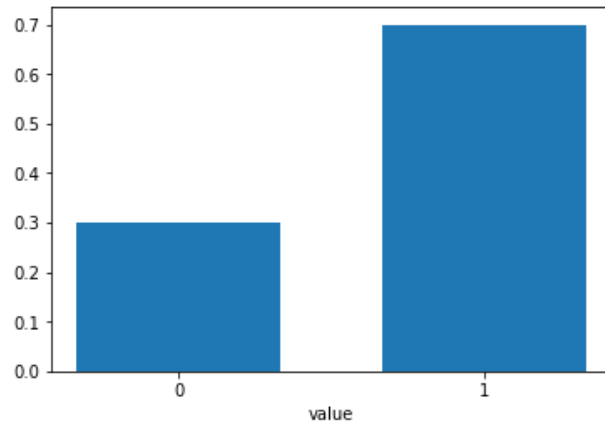
Assume a form for  $P(X|\theta)$  and estimate  $\theta$  by its sufficient statistics  $T(\mathcal{X})$

e.g., Assume  $X_t \sim \mathcal{N}(\mu, \sigma^2)$  and  $\theta = \{\mu, \sigma^2\}$

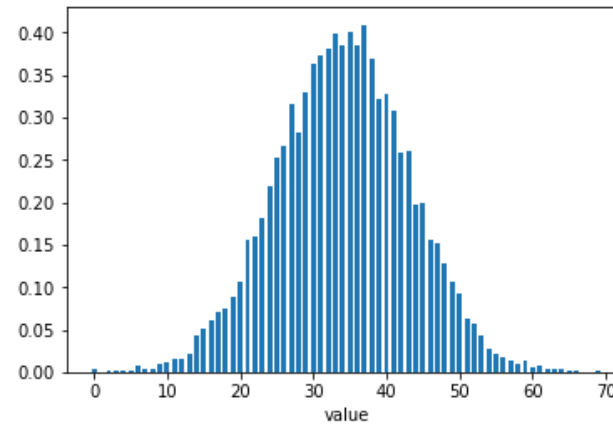
If a statistic  $T(\mathcal{X})$  is a **sufficient statistic of underlying parameter  $\theta$** , we have

$$P(X = a|\theta, T(\mathcal{X})) = P(X = a|T(\mathcal{X})).$$

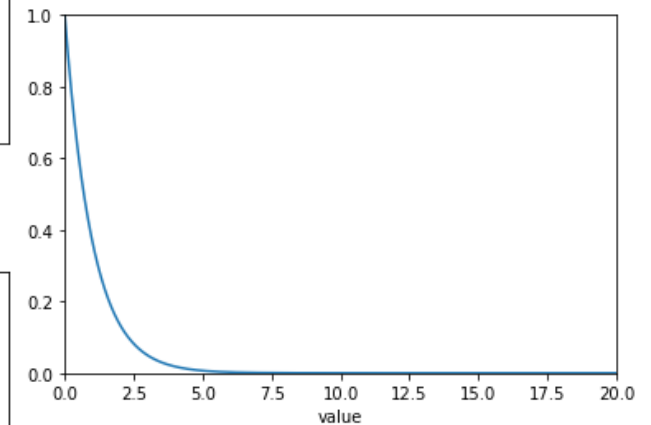
# Well-Known Probability Distributions



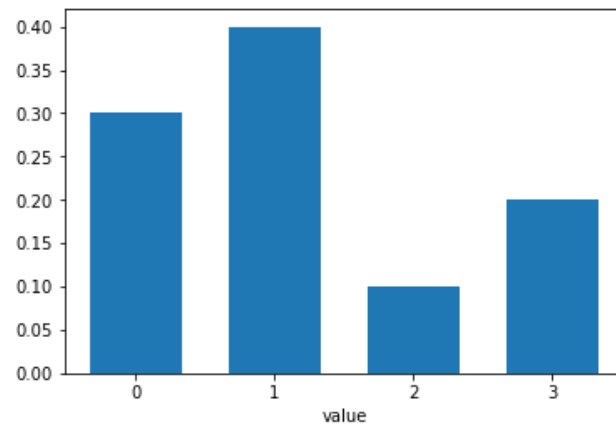
Bernoulli



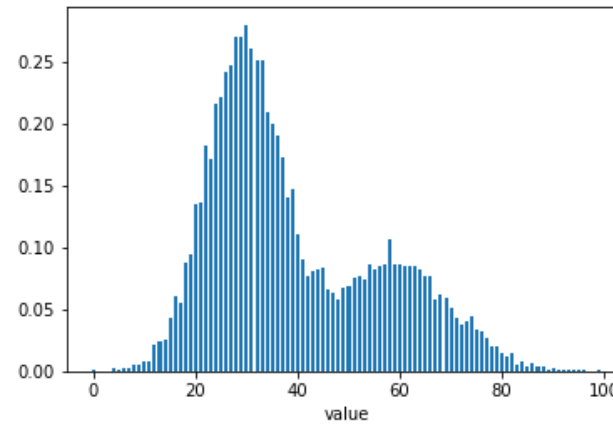
Gaussian



Exponential



Multinomial



Mixture of Gaussians

# Maximum Likelihood Estimation

- Likelihood of  $\theta$  given the sample  $\mathcal{X} = \{X_t\}_{t=1}^N$

$$\ell(\theta | \mathcal{X}) = P(\mathcal{X} | \theta) = \prod_t P(X_t | \theta) \text{ because } X_t \text{ are i.i.d.}$$

- Log-likelihood function

$$\mathcal{L}(\theta | \mathcal{X}) = \log \ell(\theta | \mathcal{X}) = \sum_t \log P(X_t | \theta)$$

- Maximum likelihood estimator (MLE)

$$\theta^* = \underset{\theta}{\operatorname{argmax}} \mathcal{L}(\theta | \mathcal{X})$$

# Bernoulli/Multinomial Density

- **Bernoulli:** Two states, failure/success,  $X_t \in \{0,1\}$ 
  - $P(X) = p_0^X (1 - p_0)^{1-X}$
  - $\mathcal{L}(p_0|\mathcal{X}) = \log \prod_t p_0^{X_t} (1 - p_0)^{1-X_t}$
  - MLE:  $p_0 = \frac{\sum_t X_t}{N}$
- **Multinomial:**  $X_t = [x_{1;t}, \dots, x_{K;t}]$ ,  $K > 2$ ,  $x_{i;t} \in \{0,1\}$ 
  - $P(x_1, \dots, x_K) = \prod_i p_i^{x_i}$
  - $\mathcal{L}(p_1, \dots, p_K|\mathcal{X}) = \log \prod_t \prod_i p_i^{x_{i;t}}$
  - MLE:  $p_i = \frac{\sum_t x_{i;t}}{N}$

# Gaussian (Normal) Distribution

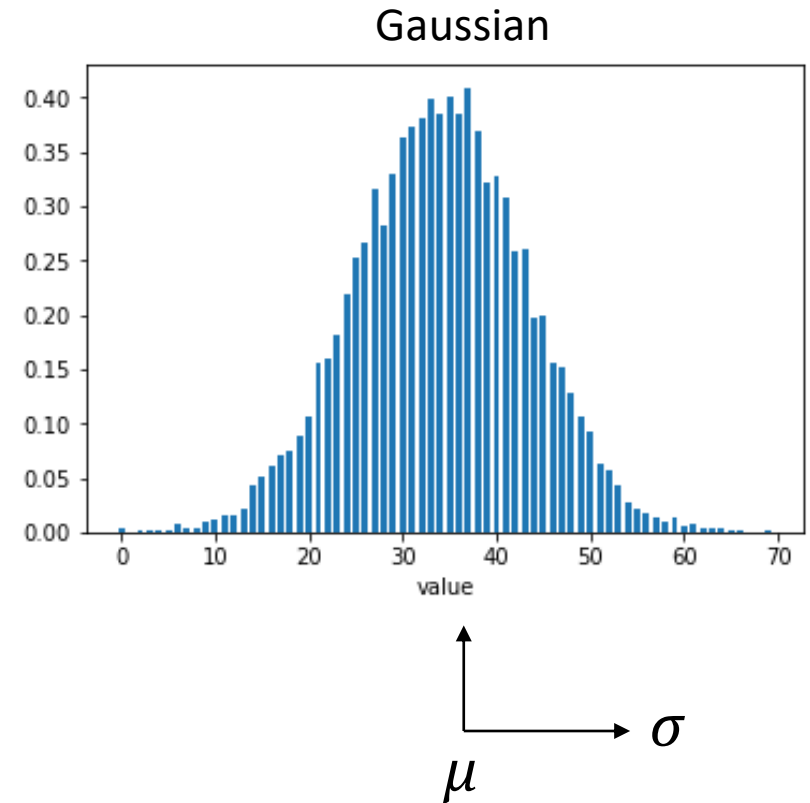
- $P(x) \sim \mathcal{N}(\mu, \sigma^2)$

$$P(x) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(x - \mu)^2}{2\sigma^2}\right)$$

- MLE for  $\mu$  and  $\sigma^2$ :

$$m = \frac{\sum_t x_t}{N} \text{ (sample mean)}$$

$$s^2 = \frac{\sum_t (x_t - m)^2}{N} \text{ (sample covariance)}$$



# Bayes' Estimator

□ Use prior information about the possible value range for the parameter

- Useful for a small number of training examples
- Treat  $\theta$  as a random variable with prior  $P(\theta)$
- Bayes' rule:  $P(\theta|\mathcal{X}) = P(\mathcal{X}|\theta)P(\theta)/P(\mathcal{X}) = P(\mathcal{X}|\theta)P(\theta) / \int P(\mathcal{X}|\theta')P(\theta')d\theta'$

• **Full:**  $P(x|\mathcal{X}) = \int P(x|\theta, \mathcal{X})P(\theta|\mathcal{X})d\theta = \int P(x|\theta)P(\theta|\mathcal{X})d\theta$

$\xleftarrow{\text{sufficient statistics}} \quad \xrightarrow{\quad}$

• **Bayes':**  $\theta_{Bayes} = \int \theta P(\theta|\mathcal{X})d\theta$

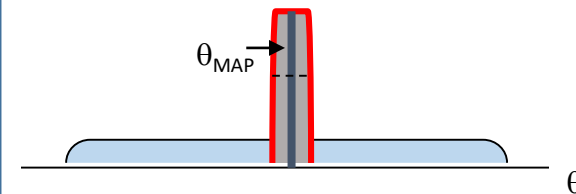
➤ Difficult to evaluate when  $P(\theta|\mathcal{X})$  does not have a simple form

• **Maximum a Posteriori (MAP):**  $\theta_{MAP} = \underset{\theta}{\operatorname{argmax}} P(\theta|\mathcal{X})$

➤ Assume that  $P(\theta|\mathcal{X})$  has a narrow peak around its mode

• **Maximum Likelihood (ML):**  $\theta_{ML} = \underset{\theta}{\operatorname{argmax}} P(\mathcal{X}|\theta)$

➤ Have no prior information about  $\theta$  (i.e.,  $P(\theta)$  is flat)





# An Example of Bayes' Estimator

- $x_t \sim \mathcal{N}(\theta, \sigma^2)$  and  $\theta \sim \mathcal{N}(\mu_0, \sigma_0^2)$ , where  $\sigma^2, \mu_0, \sigma_0^2$  are known
- $\theta_{ML} = m$  (sample mean)

•  $\theta_{MAP} = \theta_{Bayes} = E[\theta|\mathcal{X}] = \frac{\frac{N}{\sigma^2}}{\frac{1}{\sigma_0^2} + \frac{N}{\sigma^2}} \times m + \frac{\frac{1}{\sigma_0^2}}{\frac{1}{\sigma_0^2} + \frac{N}{\sigma^2}} \times \mu_0 \xrightarrow{N \rightarrow \infty} m$

Because  $P(\theta|\mathcal{X})$  is normal

sample mean                      prior mean

# Classification by Likelihood-Based Approaches (Generative Models)

- Estimate  $P(x|C_i)$  and  $P(C_i)$  from training samples.

- Assign  $x$  to Class  $i$   
if  $P(x|C_i)P(C_i) > P(x|C_j)P(C_j), j \neq i$

- Discriminant function:

$$g_i(x) = P(x|C_i)P(C_i)$$

or

$$g_i(x) = \log(P(x|C_i)) + \log(P(C_i))$$

# Classification by Gaussian Generative Models

- If  $P(x|C_i)$  are Gaussian distributions:

$$P(x|C_i) = \frac{1}{\sqrt{2\pi}\sigma_i} \exp\left(-\frac{(x - \mu_i)^2}{2\sigma_i^2}\right)$$

discriminant functions are

$$g_i(x) = -\frac{1}{2}\log(2\pi) - \log(\sigma_i) - \frac{(x - \mu_i)^2}{2\sigma_i^2} + \log P(C_i)$$

- Given the sample:  $\mathcal{X} = \{x_t, \mathbf{r}_t\}_{t=1}^N, \mathbf{r}_t = [r_{1;t}, \dots, r_{K;t}]$

$$x_t \in \mathcal{R}, r_{i;t} = \begin{cases} 1 & \text{if } x_t \in C_i \\ 0 & \text{if } x_t \in C_j, j \neq i \end{cases}$$

Learning

- ML estimates are

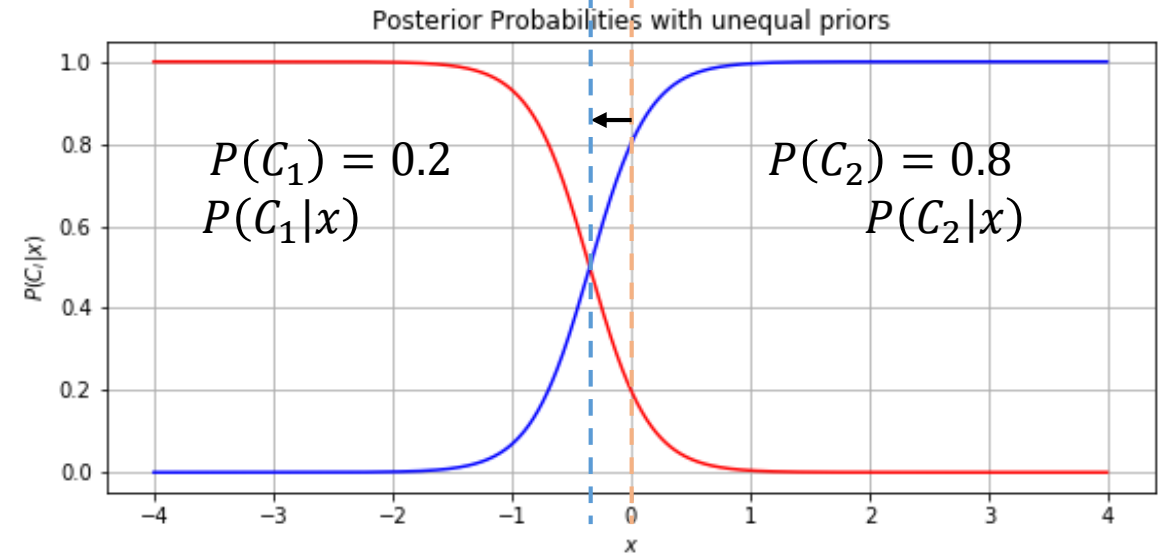
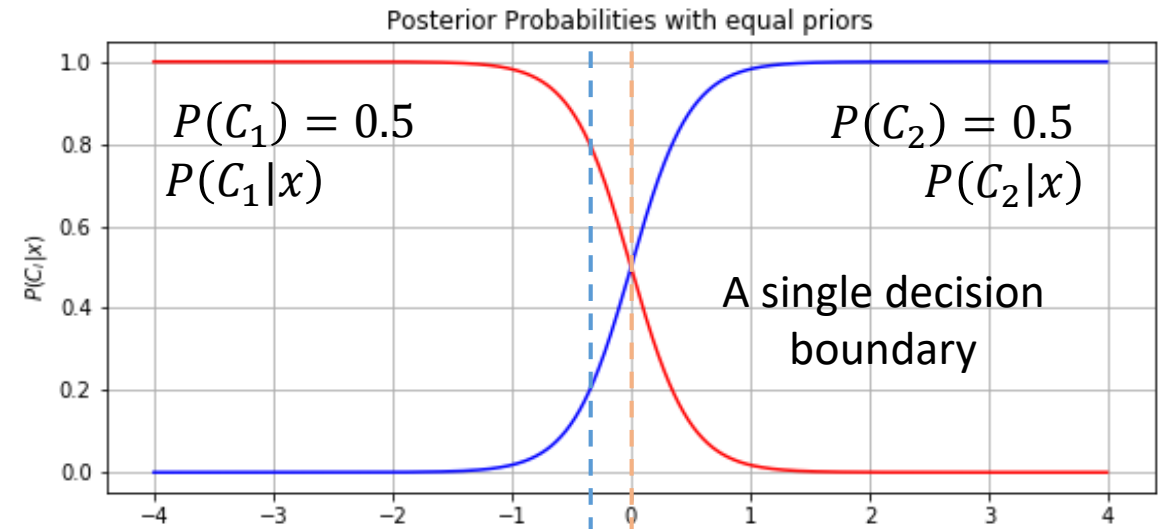
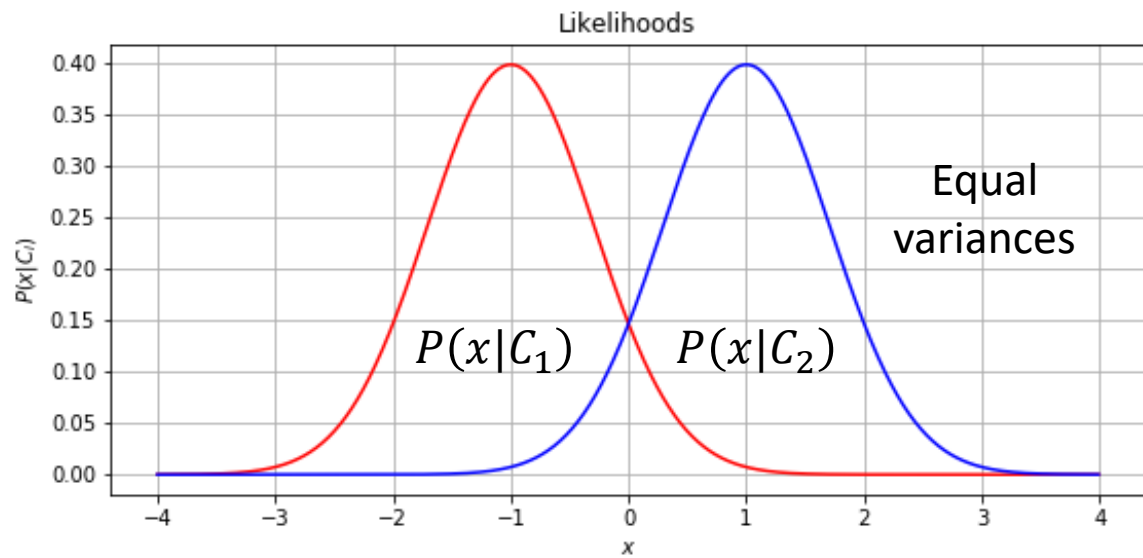
$$\hat{P}(C_i) = \frac{\sum_t r_{i;t}}{N}, m_i = \frac{\sum_t r_{i;t} x_t}{\sum_t r_{i;t}}, s_i^2 = \frac{\sum_t r_{i;t} (x_t - m_i)^2}{\sum_t r_{i;t}}$$

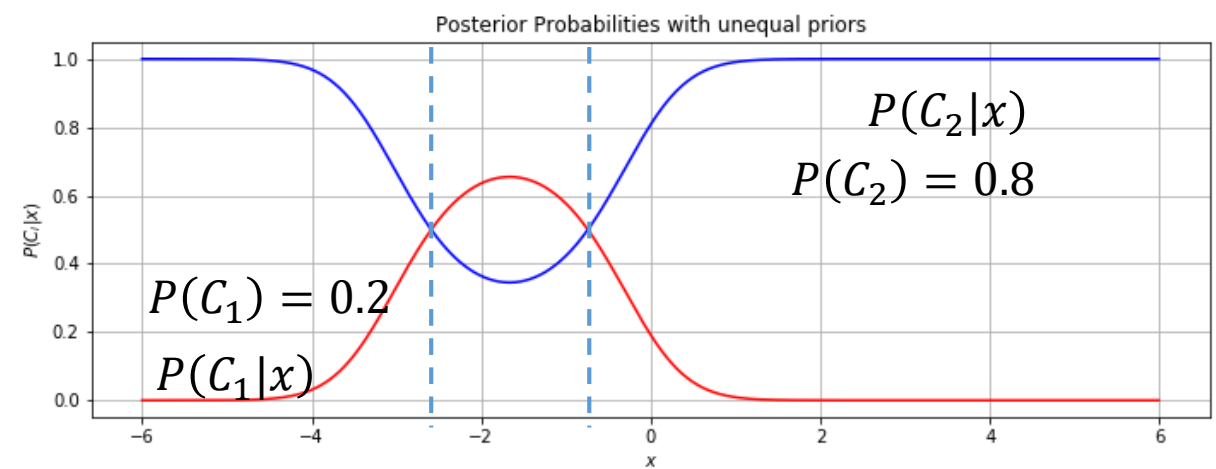
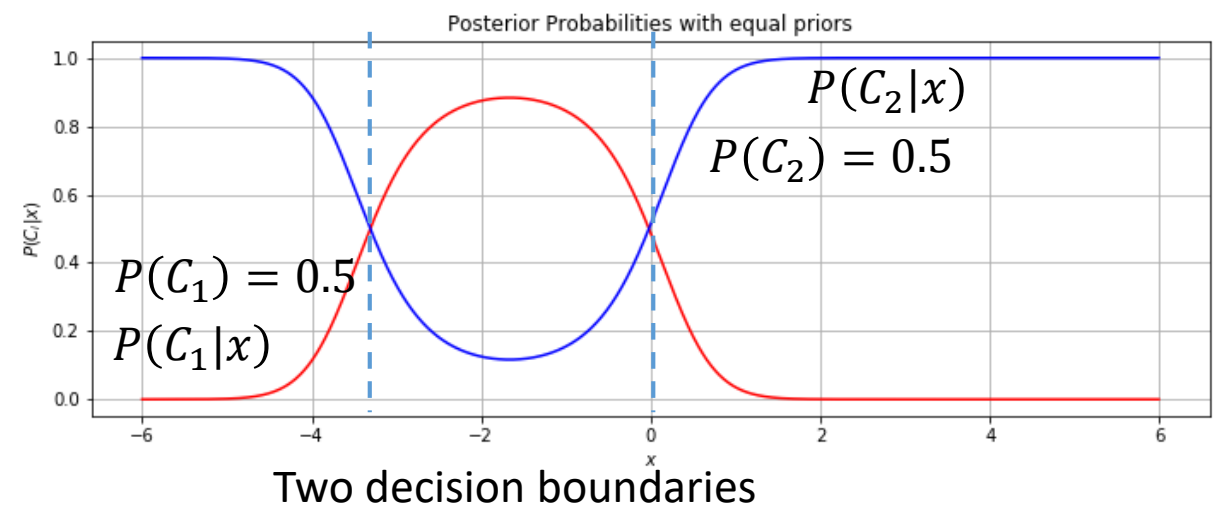
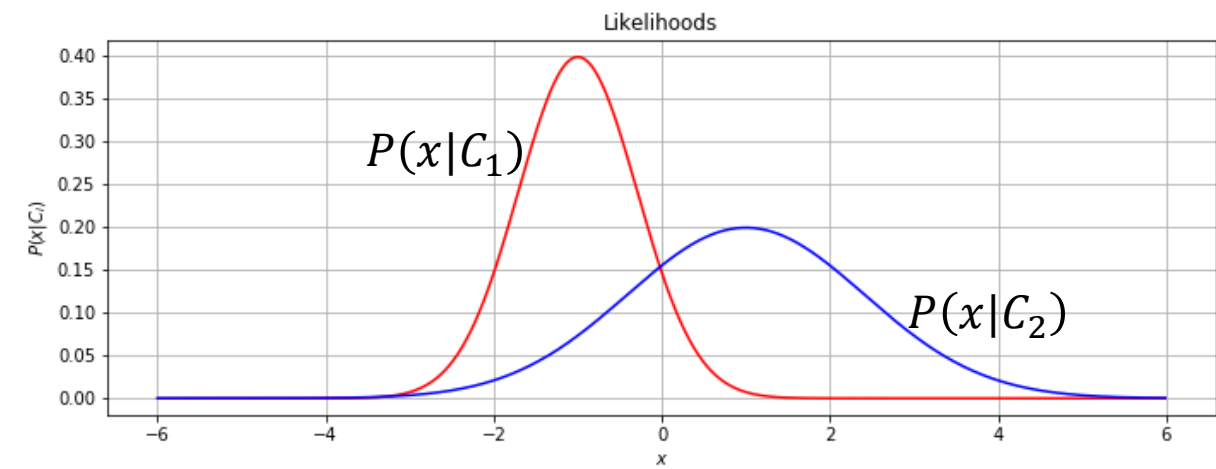
- Discriminant functions are

$$g_i(x) = -\frac{1}{2} \log(2\pi) - \log(s_i) - \frac{(x - m_i)^2}{2s_i^2} + \log \hat{P}(C_i)$$

or

$$g_i(x) = \frac{1}{\sqrt{2\pi}s_i} \exp\left(-\frac{(x - m_i)^2}{2s_i^2}\right) \times \hat{P}(C_i)$$

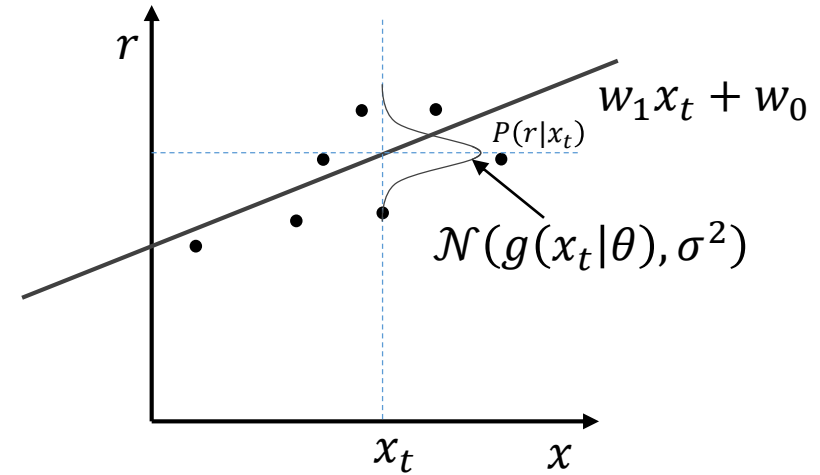




# Regression

$$r = f(x) + \epsilon, \quad \epsilon \sim \mathcal{N}(0, \sigma^2)$$

- Estimator  $g(x|\theta)$
- $P(r|x) \sim \mathcal{N}(g(x|\theta), \sigma^2)$



- Define the log-likelihood function as  $\mathcal{L}(\theta|\mathcal{X}) = \sum_t \log(P(r_t|x_t))$

$$\triangleright \mathcal{L}(\theta|\mathcal{X}) = \log \prod_t P(x_t, r_t) = \log \prod_t P(r_t|x_t)P(x_t) = \log \prod_t P(r_t|x_t) + \boxed{\log \prod_t P(x_t)}$$

ignore

# Regression: From Log-Likelihood to Error

Estimating  $\theta$  by maximization of

$$\begin{aligned}\mathcal{L}(\theta|\mathcal{X}) &= \log \prod_t \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(r_t - g(x_t|\theta))^2}{2\sigma^2}\right) \\ &= -N\log(\sqrt{2\pi}\sigma) - \frac{1}{2\sigma^2} \sum_t (r_t - g(x_t|\theta))^2\end{aligned}$$

is equivalent to estimating  $\theta$  by minimization of

$$E[\theta|\mathcal{X}] = \frac{1}{2} \sum_t (r_t - g(x_t|\theta))^2$$

$\theta^* = \underset{\theta}{\operatorname{argmin}} E[\theta|\mathcal{X}]$  are called least squares estimates



# Linear Regression

- $g(x_t|w_1, w_0) = w_1 x_t + w_0$

$$E[\theta|\mathcal{X}] = \frac{1}{2} \sum_t (r_t - g(x_t|\theta))^2$$

$$\frac{\partial E[\theta|\mathcal{X}]}{\partial w_1} = 0 \Rightarrow \sum_t x_t (r_t - w_1 x_t - w_0) = 0$$

$$\frac{\partial E[\theta|\mathcal{X}]}{\partial w_0} = 0 \Rightarrow \sum_t (r_t - w_1 x_t - w_0) = 0$$

$$\Rightarrow \begin{bmatrix} \sum_t x_t^2 & \sum_t x_t \\ \sum_t x_t & N \end{bmatrix} \begin{bmatrix} w_1 \\ w_0 \end{bmatrix} = \begin{bmatrix} \sum_t x_t r_t \\ \sum_t r_t \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} w_1 \\ w_0 \end{bmatrix} = \begin{bmatrix} \sum_t x_t^2 & \sum_t x_t \\ \sum_t x_t & N \end{bmatrix}^{-1} \begin{bmatrix} \sum_t x_t r_t \\ \sum_t r_t \end{bmatrix}$$

# Polynomial Regression

- $g(x_t|w_k, \dots, w_1, w_0) = \sum_{i=0}^k w_i x_t^i$

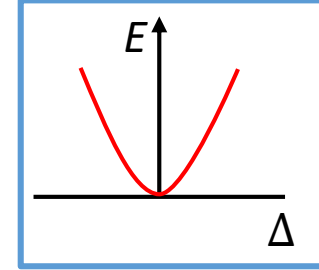
$$\begin{bmatrix} x_1^k & \cdots & x_1 & 1 \\ x_2^k & \cdots & x_2 & 1 \\ \vdots & & \vdots & \vdots \\ x_N^k & \cdots & x_N & 1 \end{bmatrix} \begin{bmatrix} w_k \\ \vdots \\ w_1 \\ w_0 \end{bmatrix} = \begin{bmatrix} r_1 \\ r_2 \\ \vdots \\ r_N \end{bmatrix}$$

$\Rightarrow \mathbf{D}\mathbf{w} = \mathbf{r}$

$\Rightarrow \mathbf{w} = (\mathbf{D}^T \mathbf{D})^{-1} \mathbf{D}^T \mathbf{r}$

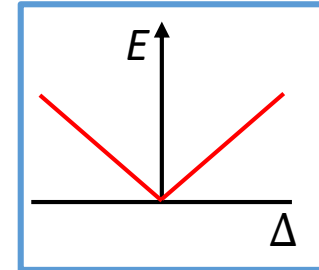
# Error Measures

- **Square Error:**  $E[\theta|\mathcal{X}] = \frac{1}{2} \sum_t \underbrace{(r_t - g(x_t|\theta))}_{\Delta}^2$

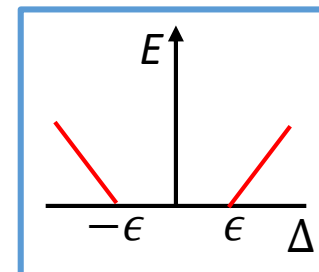


- **Relative Square Error:**  $E[\theta|\mathcal{X}] = \frac{\sum_t (r_t - g(x_t|\theta))^2}{\sum_t (r_t - \bar{r})^2}$ , where  $\bar{r} = \frac{1}{N} \sum_t r_t$

- **Absolute Error:**  $E[\theta|\mathcal{X}] = \sum_t \underbrace{|r_t - g(x_t|\theta)|}_{\Delta}$

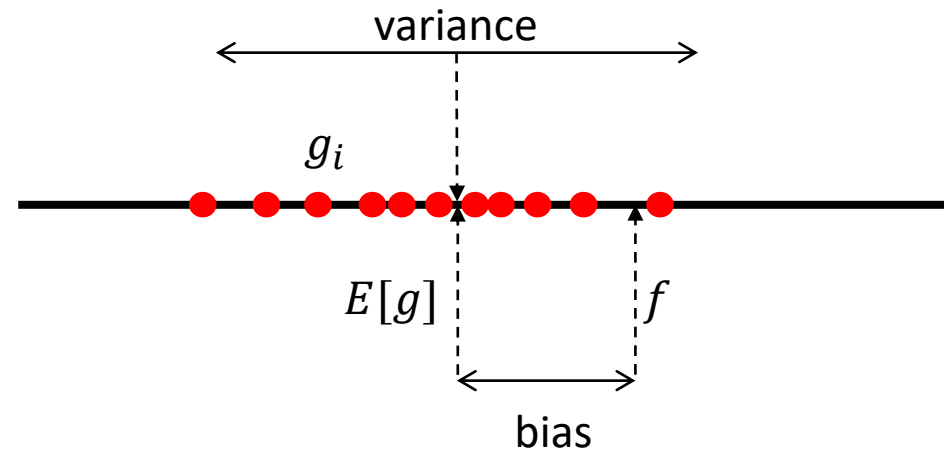


- **$\epsilon$ -sensitive Error:**  $E[\theta|\mathcal{X}] = \sum_t 1(\underbrace{|r_t - g(x_t|\theta)|}_{\Delta} > \epsilon)(\underbrace{|r_t - g(x_t|\theta)|}_{\Delta} - \epsilon)$



# Bias and Variance

- **Bias:** The difference between the expectation of the approximating function and the target function.
- **Variance:** The average squared error between the output on a given particular training set and the average of all training patterns used.



# Estimating Bias and Variance

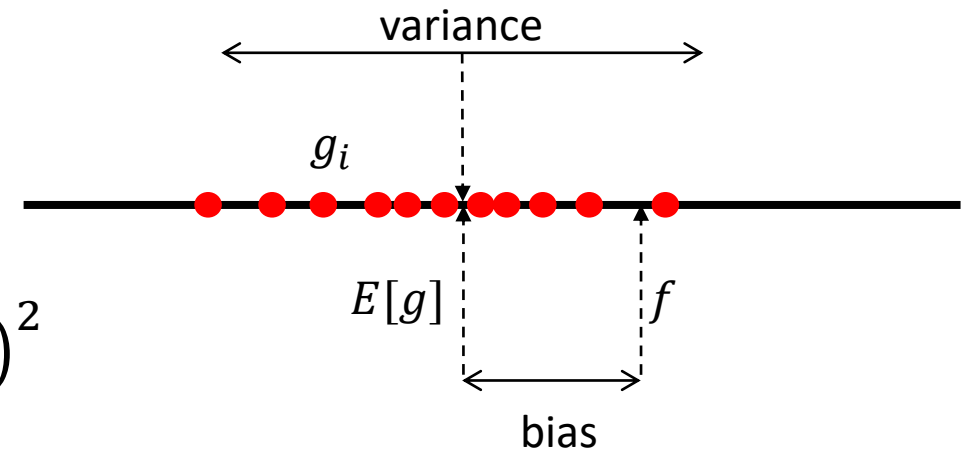
- A training set  $\mathcal{X} = \{x_t, r_t\}_{t=1}^N$  is partitioned into  $M$  sample sets  $\mathcal{X}_i, i = 1, \dots, M$ , to fit  $g_i(x), i = 1, \dots, M$ , respectively

□  $f(x)$ : the target function

- $\bar{g}(x) = \frac{1}{M} \sum_i g_i(x)$

- $Bias^2(g) = \frac{1}{N} \sum_t (\bar{g}(x_t) - f(x_t))^2$

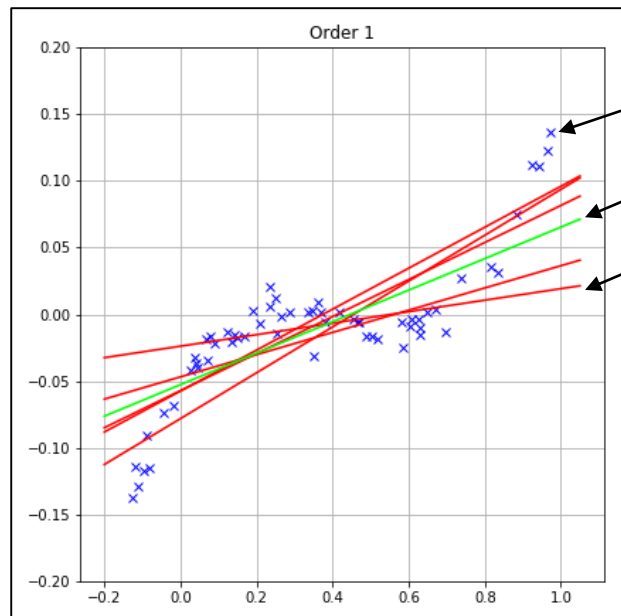
- $Variance(g) = \frac{1}{NM} \sum_t \sum_i (g_i(x_t) - \bar{g}(x_t))^2$



Example:

$g_i(x) = 2$  has no variance and high bias

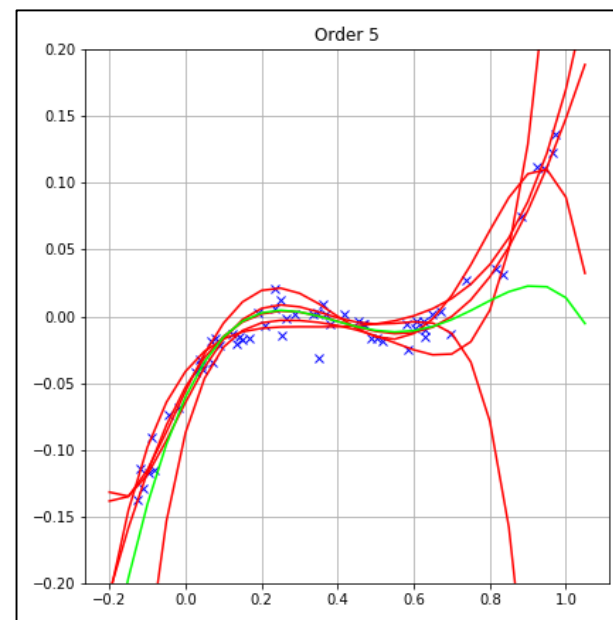
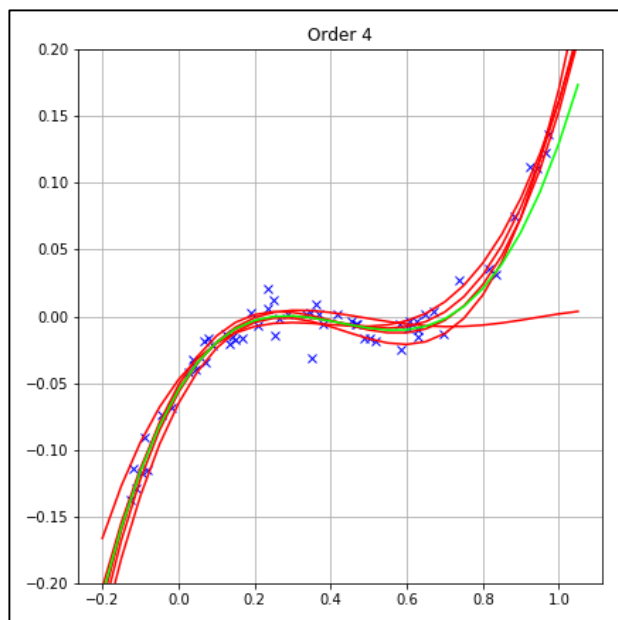
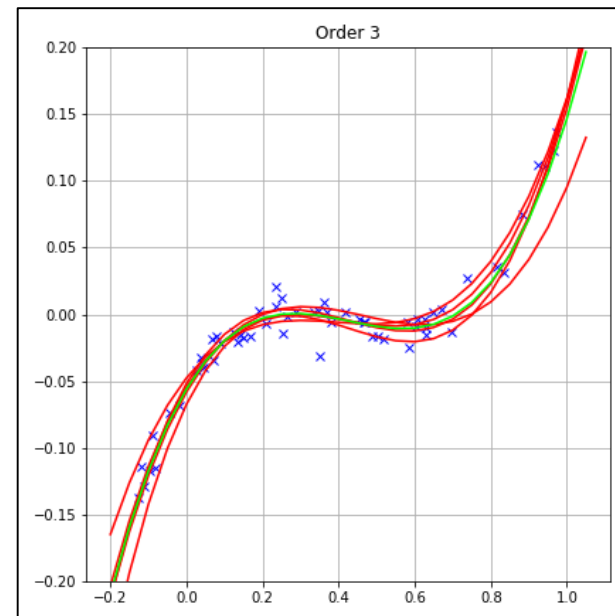
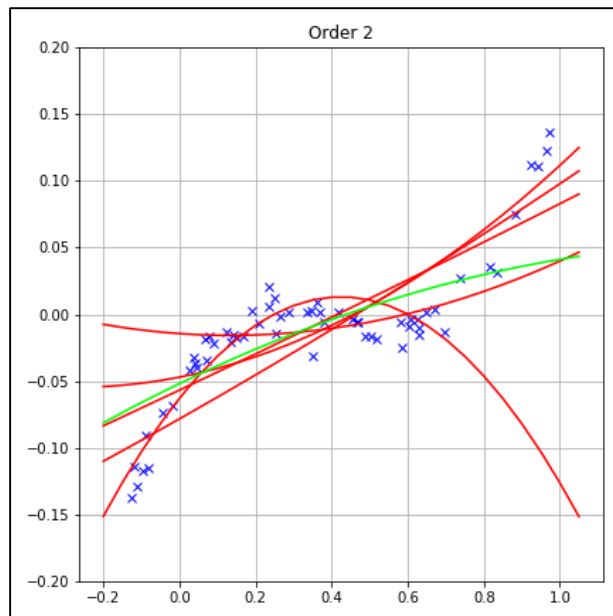
$g_i(x)$  = the average of the  $r$  in the  $i$ th sample set has lower bias with variance



data  
point

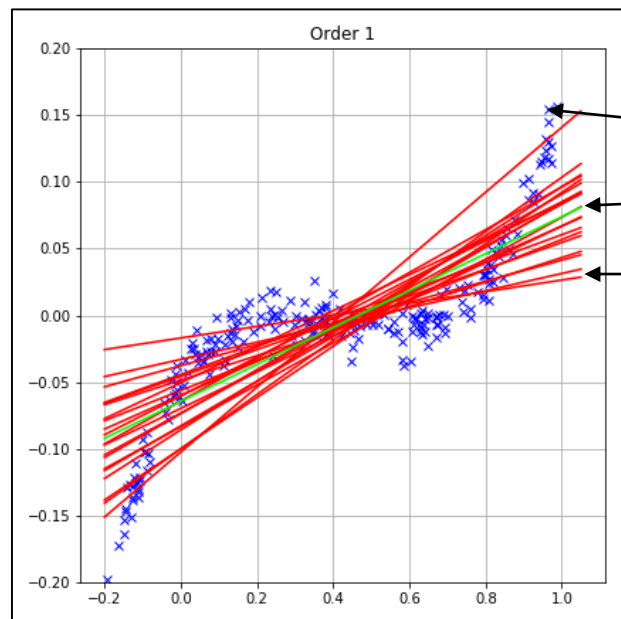
$\bar{g}$

$g_i$

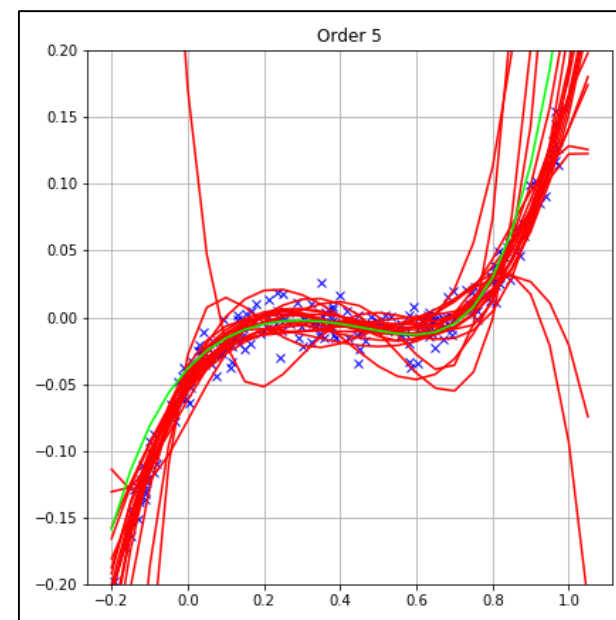
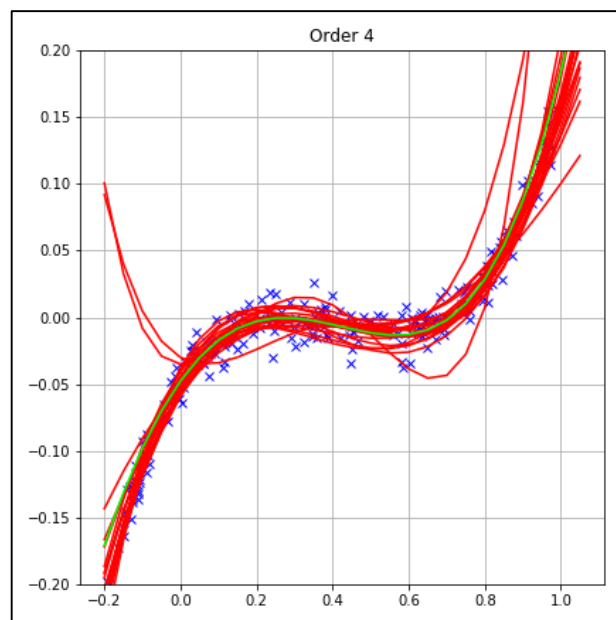
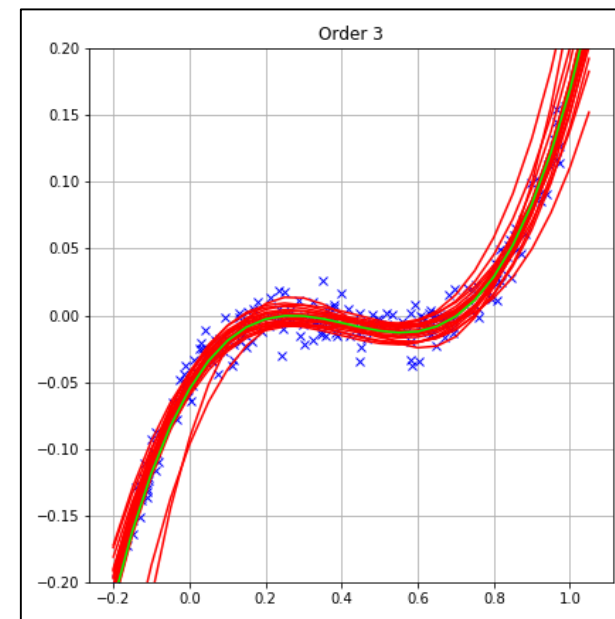
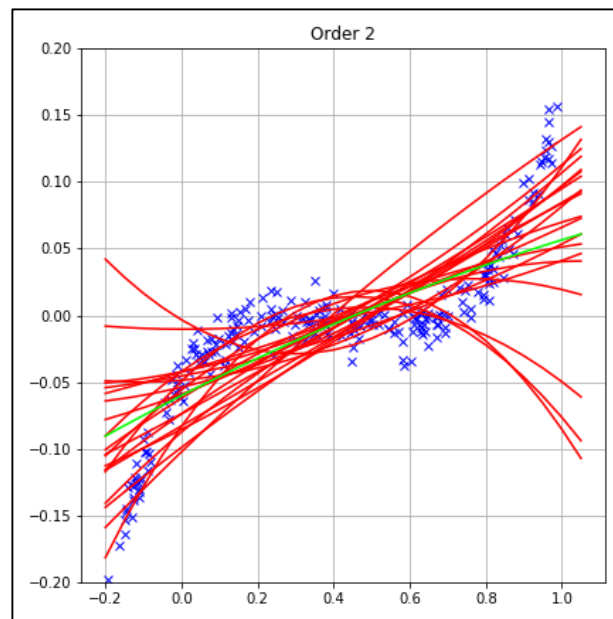


$M=5$

$N=60$



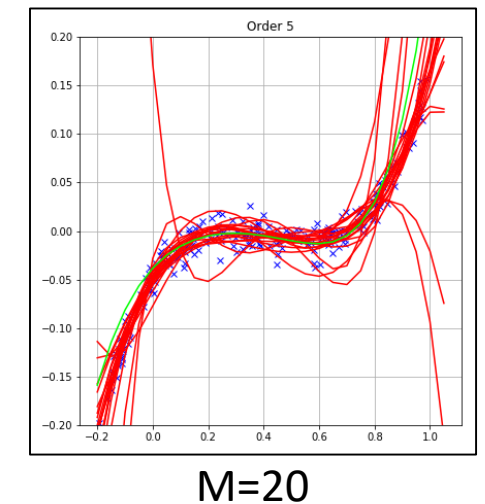
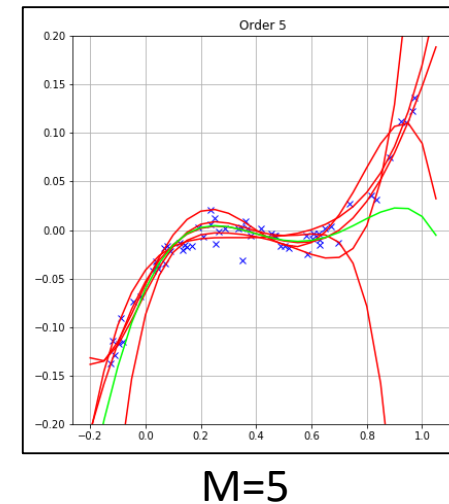
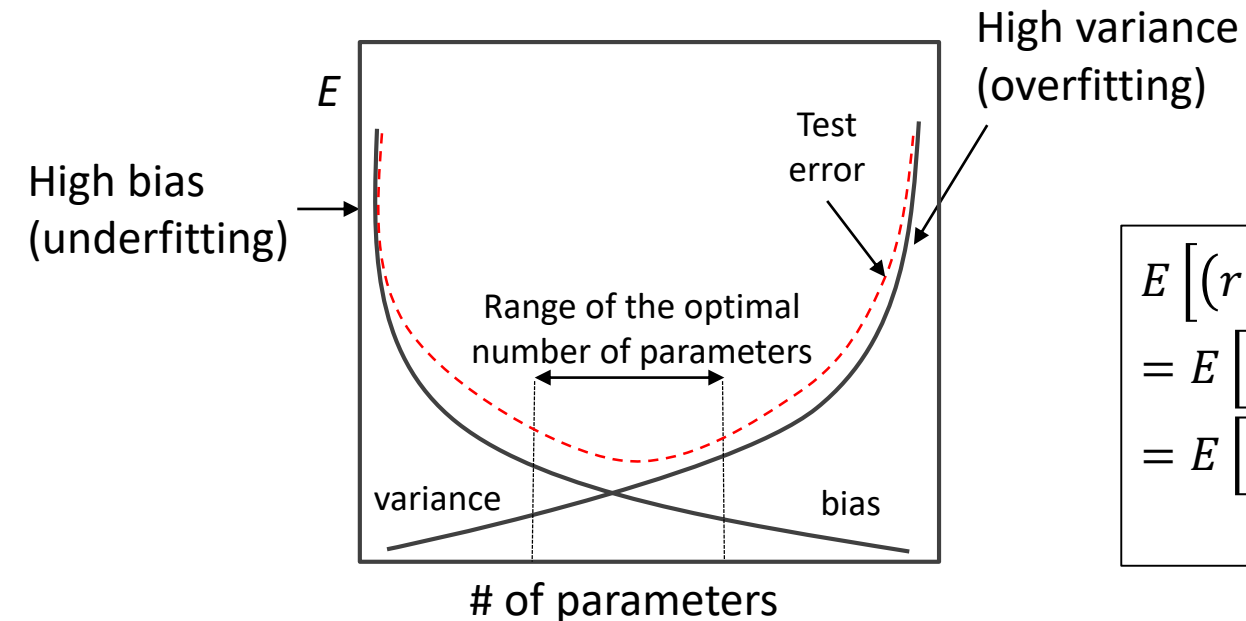
data  
point  
 $\bar{g}$   
 $g_i$



$M=20$   
 $N=240$

# Bias/Variance Dilemma

- As the model complexity increases, bias decreases and variance increases
  - The variance and bias are dependent.
  - Increase the number of training examples.



$$\begin{aligned} & E \left[ (r - g(x))^2 \right] \\ &= E \left[ (r - f(x) + f(x) - \bar{g}(x) + \bar{g}(x) - g(x))^2 \right] \\ &= E \left[ (r - f(x))^2 \right] + E \left[ (f(x) - \bar{g}(x))^2 \right] + E \left[ (\bar{g}(x) - g(x))^2 \right] \\ &\quad \text{noise: } \sigma^2 \qquad \qquad \text{bias}^2 \qquad \qquad \text{variance} \end{aligned}$$



# Model Selection Procedures

- **Cross-validation:** Measure generalization accuracy by testing on the example in the validation set (use this method if there is a large enough validation dataset)

- **Regularization:** Penalize complex models

$$E = \text{error on data} + \lambda \times \text{model complexity} \downarrow$$

- **Criteria for model selection**

- Akaike's information criterion (AIC),

$$\text{AIC} = k - \log(\mathcal{L}), \downarrow$$

- Bayesian information criterion (BIC)

$$\text{BIC} = k \log N - 2 \log(\mathcal{L}), \downarrow$$

where  $\mathcal{L}$  is the largest likelihood of the model,  $k$  is the number of parameters in the model and  $N$  is the number of training examples

- **Structural risk minimization (SRM)**

- **Minimum description length (MDL):** Kolmogorov complexity, shortest description of data

Prefer simpler models

# Bayesian Model Selection

- Bayesian model selection is used when there is prior knowledge on models,  $P(Model)$

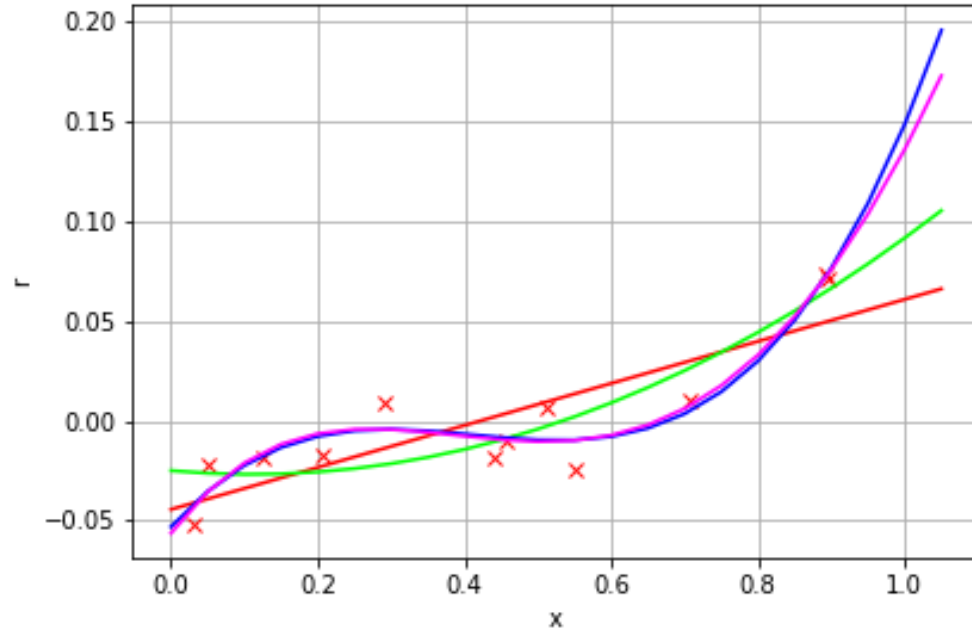
$$P(Model|Data) = \frac{P(Data|Model)P(Model)}{P(Data)}$$

$$\Rightarrow \log(P(Model|Data)) = \underbrace{\log(P(Data|Model)) + \log(P(Model))}_{\text{error on data} + \lambda \times \text{model complexity}} - \log(P(Data))$$

constant  
↓  
if simpler models are favored

- Regularization  $\approx$  the Bayesian approach, when simpler models are favored
- Average over a number of models with high posterior
  - Bayesian optimal classifier (most probable classification),
  - Voting, Ensembles (Chapter 17)

# Regularization Example



Magnitudes may increase as polynomial order increases

Order	$w$	$\ w\ _2^2$
1	[ 0.105,-0.044]	0.114
2	[ 0.140,-0.033,-0.025]	0.156
3	[ 0.867,-1.072,0.406,-0.053]	1.438
4	[-0.387,1.565,-1.470,0.484,-0.056]	2.235

A smoother and flatter fit is desired

*L2 regularization:*  $\|w\|_2^2$

$$E[w|\mathcal{X}] = \frac{1}{2} \sum_t (r_t - g(x_t w))^2 + \lambda \sum_i w_i^2$$

Prior:  $P(w) \sim \mathcal{N}(0, 1/\lambda)$

*L0 regularization:*  $\|w\|_0^2$

*L1 regularization:*  $\|w\|_1^2$

# Bayes Optimal Classifier

- Bayes optimal classifier

- $\underset{y}{\operatorname{argmax}} \sum_{h_i \in H} P(y|x, h_i)P(h_i|Data)$

- Example,

- $P(h_1|Data) = 0.4, P(h_2|Data) = 0.25, P(h_3|Data) = 0.35$

- $h_1$  is the MAP hypothesis.

- For an input  $x$ , suppose

- $P(y = +1|x, h_1) = 1, P(y = -1|x, h_2) = 1, P(y = -1|x, h_3) = 1,$

- where  $y \in \{-1, +1\}$

- The MAP classification of  $x$  is +1
    - The most probable classification of  $x$  is -1
      - $\sum_{h_i \in H} P(+1|x, h_i)P(h_i|Data) = 0.4$
      - ✓  $\sum_{h_i \in H} P(-1|x, h_i)P(h_i|Data) = 0.6$