

Codebook

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1 Basic

1.1 vimrc

```

1 1 set nocompatible
1 2 filetype plugin indent on
1 3 set t_Co=256
2 4 set term=screen-256color
2 5 set number
2 6 set tabstop=4
2 7 set shiftwidth=4
3 8 set softtabstop=4
3 9 set expandtab
3 10 set wrap
4 11 set showcmd
4 12 colorscheme darkblue
4 13 map <F2> :w <CR> :call OP() <CR>
4 14 map! <F2> <ESC> :w <CR> :call OP() <CR> <ESC>
15 map <F9> :w <CR> :call CP_R() <CR> <ESC>
5 16 map! <F9> <ESC> :w <CR> :call CP_R() <CR> <ESC>
5 17 map <HOME> ^
5 18 map! <HOME> <ESC>^i
19 map <ESC>OH <HOME>
5 20 map! <ESC>OH <HOME>
5 21 map <END> $
22 map <ESC>OF <END>
5 23 map! <ESC>OF <ESC><END>a
5 24 function CP_R()
5 25
5 26   if( &ft == 'cpp' )
5 27     let cpl = 'g++ -w -o "%:r.exe" -std=c++11 "%%" |
5     let exc = "%:r.exe"
5 28   elseif( &ft == 'python' )
5 29     let exc = 'python "%%"
5 30   endif
5 31   let pause = 'printf "Press any key to continue..." &&
5     read -n 1 && exit'
5 32   if !exists('exc')
33     echo 'Can''t compile this filetype...'
34     return
35   endif
36   if exists('cpl')
37     let cp_r = cpl . ' && time ' . exc
38   else
39     let cp_r = 'time ' . exc
40   endif
41   execute '! clear && ' . cp_r . ' && ' . pause
42 endfunction
43
44 function OP()
45   execute '!$COLORTERM -x gedit ' . "%" . ";"
46 endfunction

```

2 Number

2.1 Extended GCD

```

1 ll ext_gcd(ll a, ll b, ll &x, ll &y){
2     ll d=a;
3     if(b!=0){
4         d=ext_gcd(b, a%b, y, x);
5         y=(a/b)*x;
6     }
7     else x=1, y=0;
8     return d;
9 }

```

2.2 Modular Inverse

```

1 /*
2  * find the inverse of n modular p
3  */
4 ll mod_inverse(ll n, ll p){
5     ll x, y;
6     ll d = ext_gcd(n, p, x, y);
7     return (p+x%p) % p;
8 }

```

2.3 Line Modular Equation

```

1 /*
2  * ax = b (mod n)
3  * return a set of answer(vector<ll>)
4  */
5 vector<ll> line_mod_equation(ll a, ll b, ll n){
6     ll x, y, d;
7     d = ext_gcd(a, n, x, y);
8     vector<ll> ans;
9     if(b%d==0){
10         x = (x%n + n) % n;
11         ans.push_back((x*(b/d))%(n/d));
12         for(ll i=1; i<d; i++){
13             ans.push_back((ans[0]+i*n/d)%n);
14         }
15         return ans;
16 }

```

2.4 Chinese Remainder Theorem

```

1 /*
2  * solve the chinese remainder theorem(CRT)
3  * if a.size() != m.size(), return -1
4  * return the minimum positive answer of CRT
5  * x = a[i] (mod m[i])
6  */
7 int CRT(vector<int> a, vector<int> m) {
8     if(a.size() != m.size()) return -1;
9     int M = 1;
10    for(int i=0; i<(int)m.size(); i++)
11        M *= m[i];
12    int res = 0;
13    for(int i=0; i<(int)a.size(); i++)
14        res = (res + (M/m[i])*mod_inverse(M/m[i], m[i])
15            *a[i]) % M;
16    return (res + M) % M;
17 }

```

2.5 C(N,M)

```

1 /* P is the modular number */
2 #define P 24851
3 int fact[P+1];
4 /* called by Cmod */
5 int mod_fact(int n, int &e){
6     e = 0;
7     if(n == 0) return 1;
8     int res = mod_fact(n/P, e);
9     e += n / P;

```

```

15 * return C(n, m) mod P
16 */
17 int Cmod(int n, int m){
18     /* this section only need to be done once */
19     fact[0] = 1;
20     for(int i=1; i<=P; i++){
21         fact[i] = fact[i-1] * i % P;
22     }
23     /* end */
24     int a1, a2, a3, e1, e2, e3;
25     a1 = mod_fact(n, e1);
26     a2 = mod_fact(m, e2);
27     a3 = mod_fact(n-m, e3);
28     if(e1 > e2 + e3) return 0;
29     return a1 * mod_inverse(a2 * (a3%P), P) % P;
30 }

```

2.6 Phi

```

1 /*
2  * gen phi from 1~MAXN
3  * store answer in phi
4  */
5 #define MAXN 100
6 int mindiv[MAXN], phi[MAXN];
7 void genphi(){
8     for(int i=1; i<MAXN; i++){
9         mindiv[i] = i;
10        for(int j=2; j*i<MAXN; j++){
11            if(mindiv[j*i] == i)
12                for(int k=j; k*i<MAXN; k+=j)
13                    mindiv[k*i] = j;
14        }
15        phi[1] = 1;
16        for(int i=2; i<MAXN; i++){
17            phi[i] = phi[i/mindiv[i]];
18            if((i/mindiv[i])%mindiv[i] == 0)
19                phi[i] *= mindiv[i];
20            else phi[i] *= (mindiv[i]-1);
21        }
22 }

```

2.7 Miller Rabin

```

1 ll pow_mod(ll x, ll N, ll M) {
2     ll res = 1;
3     x %= M;
4     while(N){
5         if(N&1) res = mul_mod(res, x, M);
6         x = mul_mod(x, x, M);
7         N >>= 1;
8     }
9     return res;
10 }
11 bool PrimeTest(ll n, ll a, ll d) {
12     if(n == 2 || n == a) return true;
13     if((n&1) == 0) return false;
14     while((d&1) == 0) d >>= 1;
15     ll t = pow_mod(a, d, n);
16     while((d!=n-1) && (t!=1) && (t!=n-1)){
17         t = mul_mod(t, t, n);
18         d <<= 1;
19     }
20     return (t==n-1) || ((d&1)==1);
21 }
22 bool MillerRabin(ll n){
23     // test set
24     vector<ll> a = {2, 325, 9375, 28178, 450775,
25         9780504, 1795265022};
26     for(int i=0; i<(int)a.size(); i++)
27         if(!PrimeTest(n, a[i], n-1)) return false;
28     return true;
29 }

```

2.8 FFT

```

1 /*

```

```

7   vector<Complex> res(a);
8   for (int i=1,j=0;i<(int)res.size();i++){
9       for(int k=((int)res.size())>>1;!(j^=k)&k;k
10          >>=1);
11          if(i > j) swap(res[i], res[j]);
12      }
13      return res;
14  }
15  /*
16  * calculate the FFT of sequence
17  * a.size() must be 2^k
18  * flag = 1  -> FFT(a)
19  * falg = -1 -> FFT-1(a)
20  * return FFT(a) or FFT-1(a)
21  */
22  vector<Complex> FFT(vector<Complex> a, int flag=1){
23      vector<Complex> res = reverse(a);
24      for(int k=2;k<=(int)res.size();k<=1){
25          double p0 = -pi / (k>>1) * flag;
26          Complex unit_p0(cos(p0), sin(p0));
27          for(int j=0;j<(int)res.size();j+=k){
28              Complex unit(1.0, 0.0);
29              for(int i=j;i<j+k/2;i++,unit*=unit_p0){
30                  Complex t1 = res[i], t2 = res[i+k/2] *
31                      unit;
32                  res[i] = t1 + t2;
33                  res[i+k/2] = t1 - t2;
34              }
35          }
36      }
37      return res;

```

2.9 Function

```

1  /*
2  * class of polynomial function
3  * coef is the coefficient
4  * f(x) = sigma(c[i]*x^i)
5  */
6  class Function {
7  public:
8      vector<double> coef;
9      Function(const vector<double> c=vector<double>()):
10         coef(c){}
11      double operator () (const double &rhs) const {
12          double res = 0.0;
13          double e = 1.0;
14          for(int i=0;i<(int)coef.size();i++,e*=rhs)
15              res += e * coef[i];
16          return res;
17      }
18      Function derivative() const {
19          vector<double> dc((int)this->coef.size()-1);
20          for(int i=0;i<(int)dc.size();i++)
21              dc[i] = coef[i+1] * (i+1);
22          return Function(dc);
23      }
24      int degree() const {
25          return (int)coef.size()-1;
26      }
27  };
28  /*
29  * calculate the integration of f(x) from a to b
30  * divided into n piece
31  * the bigger the n is, the more accurate the answer is
32  */
33  template<class T>
34  double simpson(const T &f, double a, double b){
35      double c = (a+b) / 2.0;
36      return (f(a)+4.0*f(c)+f(b)) * (b-a) / 6.0;
37  }
38  template<class T>
39  double simpson(const T &f, double a, double b, double
40      eps, double A){
41      double c = (a+b) / 2.0;
42      double l = simpson(f, a, c), R = simpson(f, c, b);

```

```

44  template<class T>
45  double simpson(const T &f, double a, double b, double
46      eps){
47      return simpson(f, a, b, eps, simpson(f, a, b));
48  }

```

2.10 Equation

```

1  /*
2  * called by find
3  * 1 = positive, -1 = negative, 0 = zero
4  */
5  int sign(double x){
6      return x < -EPS ? -1 : x > EPS;
7  }
8  /* called by equation */
9  template<class T>
10 double find(const T &f, double lo, double hi){
11     int sign_lo, sign_hi;
12     if((sign_lo=sign(f(lo))) == 0) return lo;
13     if((sign_hi=sign(f(hi))) == 0) return hi;
14     if(sign_lo * sign_hi > 0) return INF;
15     while(hi-lo>EPS){
16         double m = (hi+lo) / 2;
17         int sign_mid = sign(f(m));
18         if(sign_mid == 0) return m;
19         if(sign_lo * sign_mid < 0)
20             hi = m;
21         else lo = m;
22     }
23     return (lo+hi) / 2;
24 }
25 /*
26 * return a set of answer of f(x) = 0
27 */
28 template<class T>
29 vector<double> equation(const T &f){
30     vector<double> res;
31     if(f.degree() == 1){
32         if(sign(f.coef[1]))res.push_back(-f.coef[0]/f.
33             coef[1]);
34         return res;
35     }
36     vector<double> droot = equation(f.derivative());
37     droot.insert(droot.begin(), -INF);
38     droot.push_back(INF);
39     for(int i=0;i<(int)droot.size()-1;i++){
40         double tmp = find(f, droot[i], droot[i+1]);
41         if(tmp < INF) res.push_back(tmp);
42     }
43     return res;

```

2.11 Permutation

```

1  /*
2  * return the sequence of x-th of n!
3  * max(n) = 12
4  * 0 of 3! -> 123
5  * 5 of 3! -> 321
6  */
7  int factorial[] = {1, 1, 2, 6, 24, 120, 720, 5040,
8      40320, 362880, 3628800, 39916800, 479001600};
9  vector<int> idx2permutation(int x, int n){
10     vector<bool> used(n+1, false);
11     vector<int> res(n);
12     for(int i=0;i<n;i++){
13         int tmp = x / factorial[n-i-1];
14         int j;
15         for(j=1;j<=n;j++)if(!used[j]){
16             if(tmp == 0) break;
17             tmp--;
18         }
19         res[i] = j, used[j] = true;
20         x %= factorial[n-i-1];

```

```

26 * 123 of 3! -> 0
27 * 321 of 3! -> 5
28 */
29 int permutation2idx(vector<int> a){
30     int res = 0;
31     for(int i=0;i<(int)a.size();i++){
32         int tmp = a[i] - 1;
33         for(int j=0;j<i;j++){
34             if(a[j] < a[i]) tmp--;
35         }
36         res += factorial[(int)a.size()-i-1] * tmp;
37     }
38     return res;
39 }

```

3 Matrix

3.1 Gauss Elimination

```

1 /*
2  * return guass eliminated matrix
3  * r will be changed to the number of the non-free
4  * variables
5  * l[i] will be set to true if i-th variable is not
6  * free
7  * ignore flag
8  */
9 Matrix GuassElimination(int &r, vector<bool> &l, int
10    flag=0) {
11     l = vector<bool>(C);
12     r = 0;
13     Matrix res(*this);
14     for(int i=0;i<res.C-flag;i++){
15         for(int j=r;j<res.R;j++){
16             if(fabs(res.at(j, i)) > EPS){
17                 swap(res.D[r], res.D[j]);
18                 break;
19             }
20         }
21         if(fabs(res.at(r, i)) < EPS){
22             continue;
23         }
24         for(int j=0;j<res.R;j++){
25             if(j != r && fabs(res.at(j, i)) > EPS){
26                 double tmp = (double)res.at(j, i) / (
27                     double)res.at(r, i);
28                 for(int k=0;k<res.C;k++){
29                     res.at(j, k) -= tmp * res.at(r, k);
30                 }
31             }
32         }
33         r++;
34         l[i] = true;
35     }
36     return res;
37 }

```

3.2 Solve Matrix (Ax=B)

```

1 /*
2  * Ax = b
3  * it will return the answer(x)
4  * if row != column or there is any free variable, it
5  * will return an empty vector
6  */
7 vector<double> Solve(vector<double> a) {
8     if(R != C) return vector<double>();
9     vector<double> res(R);
10    Matrix t(R, C+1);
11    for(int i=0;i<R;i++){
12        for(int j=0;j<C;j++){
13            t.at(i, j) = a[i];
14        }
15    }
16    int r = 0;
17    vector<bool> l;
18    t = t.GuassElimination(r, l, 1);
19    if(r != R) return vector<double>();
20    for(int i=0;i<C;i++){
21        if(l[i])for(int j=0;j<R;j++){
22            if(fabs(t.at(j, i)) > EPS)
23                res[i] = t.at(j, C) / t.at(j, i);
24        }
25    }
26    return res;
27 }

```

3.3 Inverse Matrix

```

1 /*
2  * return an inverse matrix

```

```

7|   Matrix t(R, R*2);
8|   for(int i=0;i<R;i++){
9|       for(int j=0;j<C;j++){
10|           t.at(i, j) = at(i, j);
11|           t.at(i, i+R) = 1;
12|       }
13|       int r = 0;
14|       vector<bool> l;
15|       t = t.GuassElimination(r, l, R);
16|       if(r != R) return Matrix();
17|       for(int i=0;i<C;i++){
18|           if(l[i]) for(int j=0;j<R;j++){
19|               if(fabs(t.at(j, i)) > EPS){
20|                   for(int k=0;k<C;k++){
21|                       t.at(j, C+k) /= t.at(j, i);
22|                   }
23|               }
24|           }
25|       }
26|       Matrix res(R, C);
27|       for(int i=0;i<R;i++){
28|           for(int j=0;j<C;j++){
29|               res.at(i, j) = t.at(i, j+C);
30|           }
31|       }
32|   }

```

4 Graph

4.1 Bridge And Cut

```

1| /* called by cut_bridge */
2| void _cut_bridge(int x, int f, int d){
3|     vis[x] = 1;
4|     dfn[x] = low[x] = d;
5|     int children = 0;
6|     for(int i=0;i<(int)vc[x].size();i++){
7|         Edge e = vc[x][i];
8|         if(e.to != f && vis[e.to] == 1)
9|             low[x] = min(low[x], dfn[e.to]);
10|         if(vis[e.to] == 0){
11|             _cut_bridge(e.to, x, d+1);
12|             children++;
13|             low[x] = min(low[x], low[e.to]);
14|             if((f == -1 && children > 1) || (f != -1 &&
15|                 low[e.to] >= dfn[x]))
16|                 cut[x] = true;
17|             if(low[e.to] > dfn[x])
18|                 bridge[x][e.to] = bridge[e.to][x] =
19|                     true;
20|         }
21|     }
22| }
23| /*
24| * solve the cut and bridge
25| * store answer in cut(vector<bool>) ans bridge(vector<
26| * vector<bool> >)
27| * cut[i] == true iff i-th node is cut
28| * bridge[i][j] == true iff edge between i-th ans j-th
29| * is bridge
30| */
31| void cut_bridge(){
32|     vis = vector<int>(N+1, 0);
33|     dfn = low = vector<int>(N+1);
34|     cut = vector<bool>(N+1);
35|     bridge = vector<vector<bool> >(N+1, vector<bool>(N
36|         +1, false));
37|     for(int i=0;i<N;i++){
38|         if(!vis[i])
39|             _cut_bridge(i, -1, 0);
40|     }
41| }

```

4.2 BCC

```

1| /* called by BCC */
2| void _BBC(int x, int d){
3|     stk[++top] = x;
4|     dfn[x] = low[x] = d;
5|     for(int i=0;i<(int)vc[x].size();i++){
6|         Edge e = vc[x][i];
7|         if(dfn[e.to] == -1){
8|             _BBC(e.to, d+1);
9|             if(low[e.to] >= dfn[x]){
10|                 vector<int> l;
11|                 do{
12|                     l.push_back(stk[top]);
13|                     top--;
14|                 }while(stk[top+1] != e.to);
15|                 l.push_back(x);
16|                 bcc.push_back(l);
17|             }
18|             low[x] = min(low[x], low[e.to]);
19|         }else low[x] = min(low[x], dfn[e.to]);
20|     }
21| }
22| /*
23| * solve the biconnected components(BCC)
24| * store answer in bcc(vector<vector<int> >)
25| * bcc.size() is the number of BCC
26| * bcc[i] is the sequence of a BCC
27| */
28| void BCC(){

```

```

34     if(dfn[i] == -1)
35         _BBC(i, 0);
36 }

```

4.3 SCC

```

1  /* called by SCC */
2  void _SCC(int x, int d){
3      stk[++top] = x;
4      dfn[x] = low[x] = d;
5      vis[x] = 1;
6      for(int i=0; i<(int)vc[x].size(); i++){
7          Edge e = vc[x][i];
8          if(dfn[e.to] != -1){
9              if(vis[e.to] == 1)
10                 low[x] = min(low[x], dfn[e.to]);
11             }else{
12                 _SCC(e.to, d+1);
13                 low[x] = min(low[x], low[e.to]);
14             }
15         }
16         if(low[x] == dfn[x]){
17             while(stk[top] != x){
18                 scc[stk[top]] = scc_cnt;
19                 vis[stk[top]] = 2;
20                 top--;
21             }
22             scc[stk[top]] = scc_cnt++;
23             vis[stk[top]] = 2;
24             top--;
25         }
26     }
27     /*
28     * solve the strongly connected component(SCC)
29     * store answer in scc(vector<int>)
30     * the value of scc[i] means the id of the SCC which i-
31       th node in (id is based 0)
32     * scc_cnt id the number of SCC
33     */
34     void SCC(){
35         dfn = low = vector<int>(N+1, -1);
36         vis = vector<int>(N+1, 0);
37         scc = vector<int>(N+1, 0);
38         scc_cnt = 0;
39         stk = vector<int>(N+1, -1);
40         top = -1;
41         for(int i=0; i<N; i++){
42             if(dfn[i] == -1)
43                 _SCC(i, 0);
44         }
45     }
46 }

```

4.4 Two Sat

```

1  /*
2  * called by TwoSat
3  * get the value of i-th
4  * 1 = true, 0 = false, -1 = undefined
5  */
6  int TwoSatGet(int x){
7      int r = x > N/2 ? x-N/2 : x;
8      if(twosatans[r] == -1)
9          return -1;
10     return x > N/2 ? !twosatans[r] : twosatans[r];
11 }
12 /*
13 * solve the 2SAT
14 * return true if there exists a set of answer
15 * store the answer in twosatans
16 */
17 bool TwoSat(){
18     SCC();
19     twosatans = vector<int>(N/2+1, -1);
20     for(int i=0; i<N/2; i++){
21         if(scc[i] == scc[i+N/2])
22             return false;
23     }
24     vector<vector<int>> > c(scc_cnt+1);

```

```

29     int x = c[i][j];
30     if(TwoSatGet(x) == 0)
31         val = 0;
32     for(int k=0; k<(int)vc[x].size(); k++){
33         if(TwoSatGet(vc[x][k].to) == 0)
34             val = 0;
35     }
36     if(!val)
37         break;
38     for(int j=0; j<(int)c[i].size(); j++){
39         if(c[i][j] > N/2)
40             twosatans[c[i][j]-N/2] = !val;
41         else
42             twosatans[c[i][j]] = val;
43     }
44 }
45 return true;
46 }

```

5 Path

5.1 Kth Shortest

5.2 EulerCircuit

6 Flow

6.1 Dinic

6.2 StoerWanger

6.3 Mixed Euler

7 Match

7.1 KM

7.2 BiMatch

7.3 General Match

8 MST

8.1 Restricted MST

8.2 MDST

8.3 MRST