view_frames Result Recorded at time: 1643311460.057 world Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1643311460.057 sec old) Buffer length: 0.000 sec base_link Broadcaster: /robot_state_publisher Average rate: 10.213 Hz Most recent transform: 1643311460.008 (0.049 sec old) Buffer length: 4.700 sec link_1 Broadcaster: /robot_state_publisher Average rate: 10.213 Hz Most recent transform: 1643311460.008 (0.049 sec old) Buffer length: 4.700 sec link 2 Broadcaster: /robot_state_publisher Average rate: 10.213 Hz Most recent transform: 1643311460.008 (0.049 sec old) Buffer length: 4.700 sec link_3 Broadcaster: /robot_state_publisher Average rate: 10.213 Hz Most recent transform: 1643311460.008 (0.049 sec old) Buffer length: 4.700 sec link 4 Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1643311460.057 sec old) Buffer length: 0.000 sec link_end Broadcaster: /robot_state_publisher Average rate: 10.213 Hz Most recent transform: 1643311460.008 (0.049 sec old) Buffer length: 4.700 sec link_grip