

Gradient Descent Algorithms

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Link to GitHub:

<https://github.com/allisonh0417/Gears-Gradient-Descent>

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Algorithm 1 Adaptive Step Size Function

Input: Switch z , Current Error err , Step Size h , Input Gradients A , B , y_{curr}

Output: h , z

if $z = 0$ **then**

$h_{\text{new}} \leftarrow h \times 1.1$

 ▷ Increase step size

else

$h_{\text{new}} \leftarrow h \times 0.9$

 ▷ Decrease step size

end if

$y_{\text{new}} \leftarrow y_{\text{curr}} + h_{\text{new}} \times f(y_{\text{curr}}, A, B)$

$err_{\text{new}} \leftarrow \|A \times y_{\text{new}} - B\|$

if $err_{\text{new}} \leq err$ **then**

$h \leftarrow h_{\text{new}}$ ▷ Only change step size if new estimated error is smaller than current error

else if $z = 0$ **then**

$z \leftarrow 1$

else

$z \leftarrow 0$

end if

Algorithm 2 Nesterov's Accelerated Gradient (NAG) Algorithm

Input: Input Gradients A, B, y_{curr} , Convergence $\epsilon = 10^{-6}$

Initialize: Step Size $h = \frac{1}{3\|A\|^2}$

while $err > \epsilon$ **do**

$y_{\text{prev}} \leftarrow y_{\text{curr}}$

$y_{\text{curr}} \leftarrow y_{\text{prev}} - h \times f(y_{\text{curr}}, A, B)$

$y_{\text{new}} \leftarrow y_{\text{curr}} + \frac{k-1}{k+2} \times (y_{\text{curr}} - y_{\text{prev}})$

$err \leftarrow \|Ay_{\text{curr}} - B\|$

end while

Algorithm 3 Nesterov's Accelerated Gradient (NAG) Algorithm Adaptive

Input: Input Gradients A, B, y_{curr} , Switch $z = 0$, Convergence $\epsilon = 10^{-6}$

Initialize: Step Size $h = \frac{1}{3\|A\|^2}$

while $err > \epsilon$ **do**

$y_{\text{prev}} \leftarrow y_{\text{curr}}$

$y_{\text{curr}} \leftarrow y_{\text{prev}} - h \times f(y_{\text{curr}}, A, B)$

$y_{\text{new}} \leftarrow y_{\text{curr}} + \frac{k-1}{k+2} \times (y_{\text{curr}} - y_{\text{prev}})$

$err \leftarrow \|Ay_{\text{curr}} - B\|$

\triangleright Adaptive step size adjustment

if $z = 0$ **then**

$h_{\text{new}} \leftarrow h \times 1.005$

\triangleright Increase step size

else

$h_{\text{new}} \leftarrow h \times 0.9$

\triangleright Decrease step size

end if

$y_{\text{prev_test}} \leftarrow y_{\text{curr}}$

\triangleright Test new potential step size

$y_{\text{curr_test}} \leftarrow y_{\text{prev_test}} - h_{\text{new}} \times f(y_{\text{curr}}, A, B)$

$y_{\text{new}} \leftarrow y_{\text{curr_test}} + \frac{k-1}{k+2} \times (y_{\text{curr_test}} - y_{\text{prev_test}})$

$err_{\text{new}} \leftarrow \|Ay_{\text{new_test}} - B\|$

if $err_{\text{new}} < err$ **then**

$h \leftarrow h_{\text{new}}$

$err \leftarrow err_{\text{new}}$

$y_{\text{curr}} \leftarrow y_{\text{new_test}}$

$z \leftarrow 0$

\triangleright Continue increasing step size

else

$z \leftarrow 1$

\triangleright Start decreasing step size

end if

end while

$$x_k = y_{k-1} - s \nabla f(y_{k-1}),$$

$$y_k = x_k + \frac{k-1}{k+2}(x_k - x_{k-1}).$$

If $\epsilon > \|Ax - B\|$, then function converges,
 where ϵ is the tolerance level, $\epsilon = 10^{-6}$.

Algorithm 4 Adaptive Step Size Algorithm

Input: Gradients A, B , y_{curr} , Switch z , Current Error err_{global}

Output: h, z

while $err_{\text{new}} \geq err_{\text{global}}$ **and** $t < 5$ **do**

if $z = 0$ **then**

\triangleright Increase step size

$h_{\text{new}} \leftarrow h \times 1.1$

$y_{\text{new_test}} \leftarrow y_{\text{curr}} + h_{\text{new}} \times f(y_{\text{curr}}, A, B)$

$err_{\text{new}} \leftarrow \|A \times y_{\text{new_test}} - B\|$

if $err_{\text{new}} < err_{\text{local}}$ **then**

$err_{\text{local}} \leftarrow err_{\text{new}}$

$h \leftarrow h_{\text{new}}$

$err_{\text{prev}} \leftarrow err_{\text{new}}$

else if $err_{\text{new}} < err_{\text{global}}$ **then**

$h \leftarrow h_{\text{new}}$

break

else if $err_{\text{prev}} < err_{\text{new}}$ **then**

$z \leftarrow 1$

$err_{\text{prev}} \leftarrow err_{\text{new}}$

else

$err_{\text{prev}} \leftarrow err_{\text{new}}$

end if

else

\triangleright Decrease step size

$h_{\text{new}} \leftarrow h \times 0.9$

$y_{\text{new_test}} \leftarrow y_{\text{curr}} + h_{\text{new}} \times f(y_{\text{curr}}, A, B)$

$err_{\text{new}} \leftarrow \|A \times y_{\text{new_test}} - B\|$

if $err_{\text{new}} < err_{\text{local}}$ **then**

$err_{\text{local}} \leftarrow err_{\text{new}}$

$h \leftarrow h_{\text{new}}$

$err_{\text{prev}} \leftarrow err_{\text{new}}$

else if $err_{\text{new}} < err_{\text{global}}$ **then**

$h \leftarrow h_{\text{new}}$

break

else if $err_{\text{prev}} < err_{\text{new}}$ **then**

$z \leftarrow 0$

$err_{\text{prev}} \leftarrow err_{\text{new}}$

else

$err_{\text{prev}} \leftarrow err_{\text{new}}$

end if

end if

end while

$h_{\text{new}} \leftarrow h$

Algorithm 5 5th Order Gear's Method

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1: while err >  $\epsilon$  do
2:    $y_{\text{prev}} \leftarrow y_{\text{curr}}$ 
3:   switch (num) ▷ case equals n-th Order
4:     case 1:  $y_{\text{curr}} \leftarrow y_{\text{prev}} + h_1 \cdot f(y_{\text{prev}}, A, B)$ 
5:     case 2:  $y_{\text{curr}} \leftarrow \frac{4}{3}y_{\text{prev}} - \frac{1}{3}y_{\text{prev}_0} + \frac{2}{3}h_1 \cdot f(y_{\text{prev}}, A, B)$ 
6:     case 3:  $y_{\text{curr}} \leftarrow \frac{18}{11}y_{\text{prev}} - \frac{9}{11}y_{\text{prev}_1} + \frac{2}{11}y_{\text{prev}_0} + \frac{6}{11}h_1 \cdot f(y_{\text{prev}}, A, B)$ 
7:     case 4:  $y_{\text{curr}} \leftarrow \frac{48}{25}y_{\text{prev}} - \frac{36}{25}y_{\text{prev}_2} + \frac{16}{25}y_{\text{prev}_1} - \frac{3}{25}y_{\text{prev}_0} + \frac{12}{25}h_1 \cdot$ 
        $f(y_{\text{prev}}, A, B)$ 
8:     case 5:  $y_{\text{curr}} \leftarrow \frac{300}{137}y_{\text{prev}} - \frac{300}{137}y_{\text{prev}_3} + \frac{200}{137}y_{\text{prev}_2} - \frac{75}{137}y_{\text{prev}_1} + \frac{12}{137}y_{\text{prev}_0} +$ 
        $\frac{60}{137}h_1 \cdot f(y_{\text{prev}}, A, B)$ 
9:     err  $\leftarrow \|A \cdot y_{\text{curr}} - B\|$ 
10:    if err > last_valid_err then
11:       $[h_1, z] \leftarrow \text{new\_step}(z, \text{err}, h_1, A, B, y_{\text{curr}})$ 
12:      num  $\leftarrow 1$ 
13:    else
14:      last_valid_err  $\leftarrow \text{err}$ 
15:      num  $\leftarrow \min(\text{num} + 1, 5)$ 
16:    end if
17: end while
```
