

Intuitive VR Control Interface of Heavy Machinery

Alena Neumannová



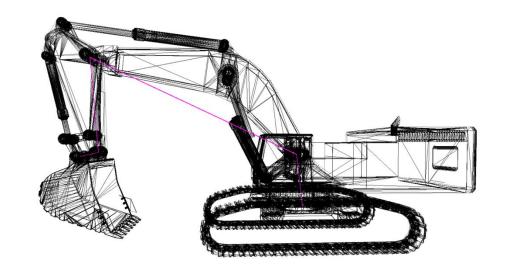
Assignment and Goals

- Design an intuitive VR control system for heavy machinery
- Create a virtual space with an interactive and realistic machine model
- Visualize machine inertia and positional differences
- Simplify complex machinery controls using VR
- Conduct a user study to compare the designed VR system with traditional controls



Motivation

- Explore the **Potential** of VR
- Real-World Impact and Relevance
 - Enhancing Current Systems
 - Making Remote Control More Natural
- Innovation in Interaction





Technologies





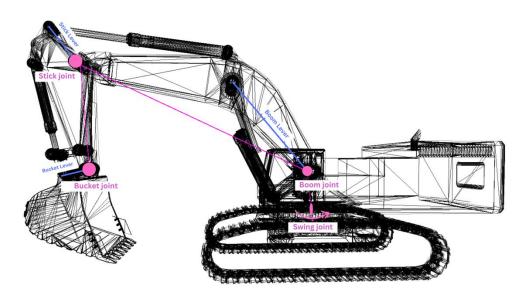
Meta Quest 2



Design

Realistic excavator







DesignControl systems



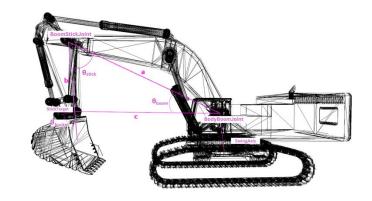


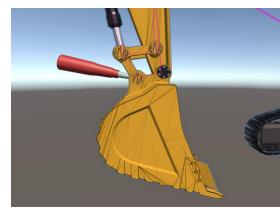


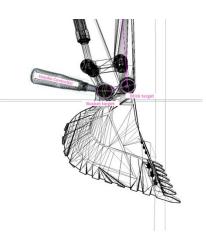
Design

The Miniature Controller











Design

Visual Feedback







Hypotheses

- 1. Speed
- 2. Accuracy
- 3. Precision
- 4. Cognition



User study

- 9 diverse users with varied familiarity with VR.
- Ghost Task (positioning) and Bucket Task (loading/unloading).
- Speed, accuracy, error rates, cognitive workload, usability.



Ghost task



Bucket task



Hypotheses Results

- H1 (Speed) Confirmed
 - The Miniature controller enabled faster task completion in both tasks.
- H2 (Accuracy) Partially confirmed
 - Miniature controller was more accurate in some aspects, but not consistently across all metrics.
- H3 (Error Rate) Rejected
 - Users made more errors with the Miniature controller.
- H4 (Cognitive Workload) Confirmed
 - Miniature controller required significantly less mental effort.



Results

- Speed vs. Accuracy Trade-off:
 - Miniature controller → Faster but higher error rate due to sensitivity.
 - Joystick → Slower but more precise.
- User Preference:
 - Miniature controller was easier to learn, more intuitive, and preferred.
- Future Improvements:
 - Adding haptic feedback and movement isolation for better control of the Miniature interface.
 - Testing with more diverse participants and tasks.



Thank you

