



Internet-of-Things MCA 5036

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Outline

- Arduino Uno
- Sensor
- Programming Construct
- Examples



Arduino Uno

Arduino:

- **Arduino is an open-source electronics platform based on easy-to-use hardware and software.**
- **Arduino boards are able to read inputs - light on a sensor, a finger on a button, or a Twitter message - and turn it into an output - activating a motor, turning on an LED, publishing something online.**



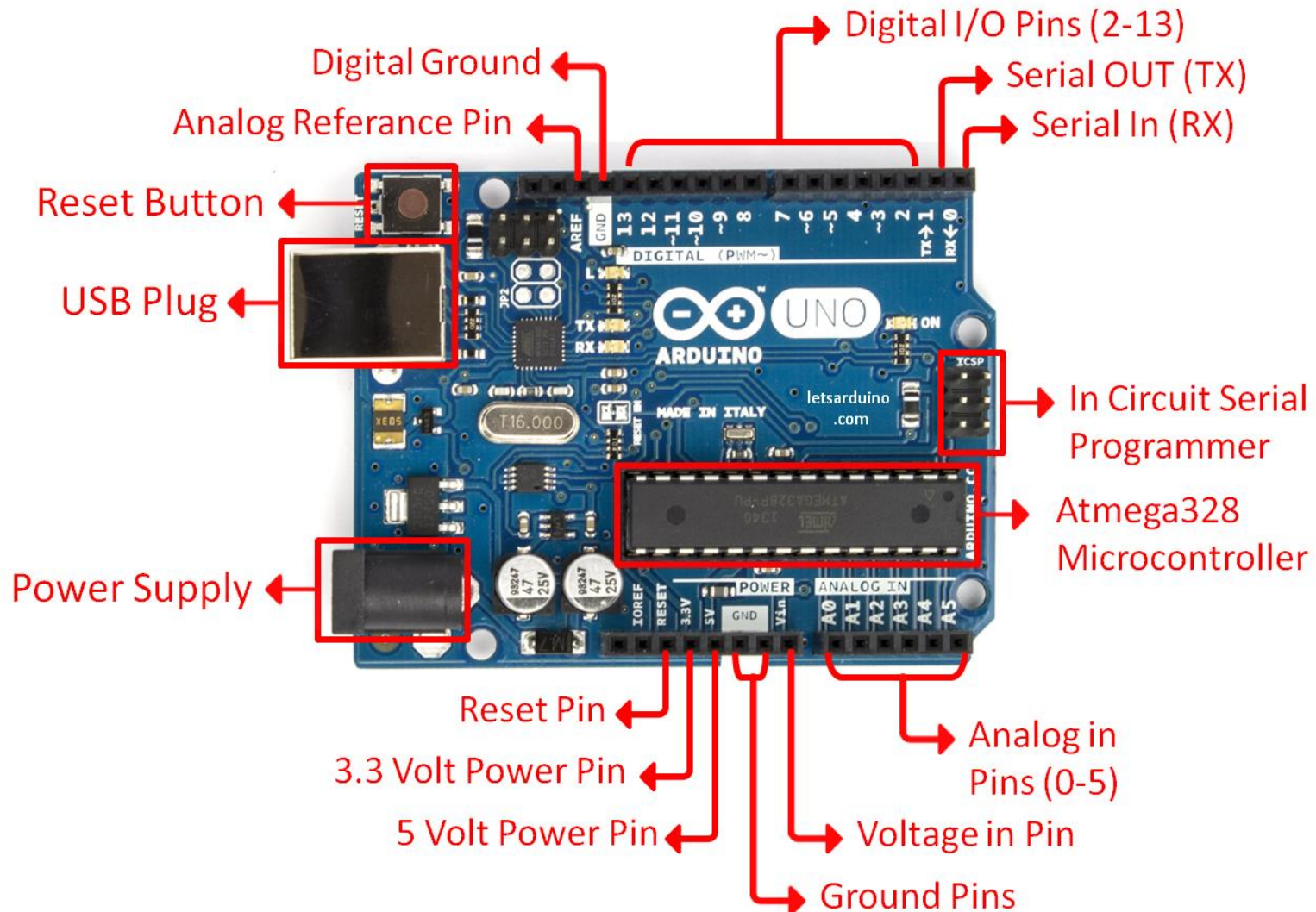
Arduino Uno (contd..)

Arduino UNO:

- **Arduino Uno is a microcontroller board based on the ATmega328P.**
- **It has 14 digital input/output pins (of which 6 can be used as PWM outputs), 6 analog inputs, a 16 MHz quartz crystal, a USB connection, a power jack, an ICSP header and a reset button.**
- **"Uno" means one in Italian and was chosen to mark the release of Arduino Software (IDE) 1.0. The Uno board and version 1.0 of Arduino Software (IDE) were the reference versions of Arduino, now evolved to newer releases.**

Arduino Uno

(contd..)

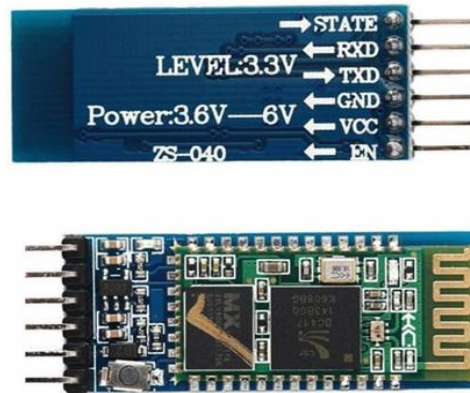




Hardware



USB Type A/B for
Arduino



HC-05 Bluetooth



ESP-8266 WiFi

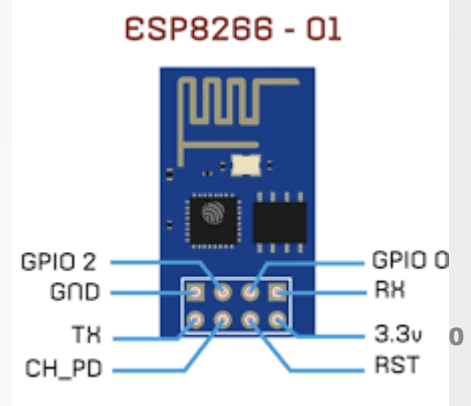
Xbee
Zigbee
Module



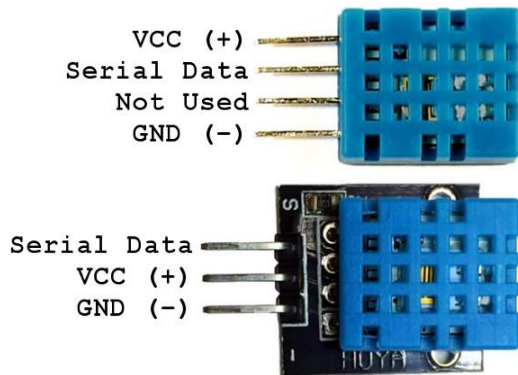
XBee Module

XBee			
1	VCC	ADD/DIO0/CMSN BTN	20
2	DOUT	AD1/DIO1	19
3	DIN/CONFIG	AD2/DIO2	18
4	DIO12	AD3/DIO3	17
5	RESET	RTS/DIO6	16
6	PWM0/RSSI/DIO10	ASC/DIO5	15
7	DIO11	VREF	14
8	RESERVED	ON/SLEEP	13
9	DTR/SLEEP_RQ/DIO8	CTS/DIO7	12
10	GND	DIO4	11

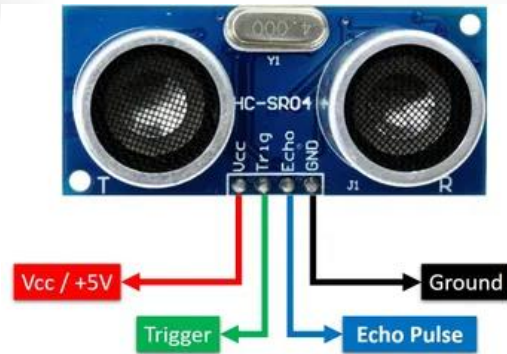
XBee Pin Configuration



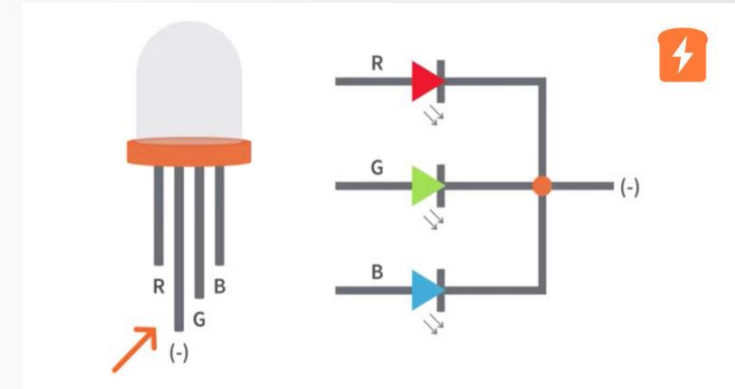
Hardware



DHT-11/22 Sensor

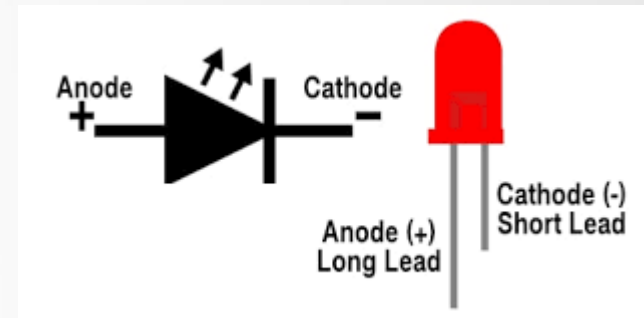
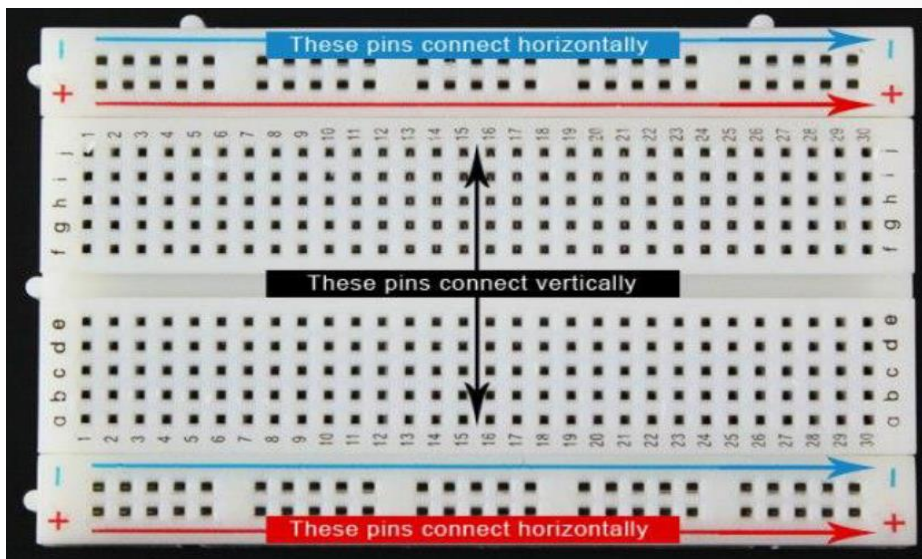


Ultra Sonic Sensor



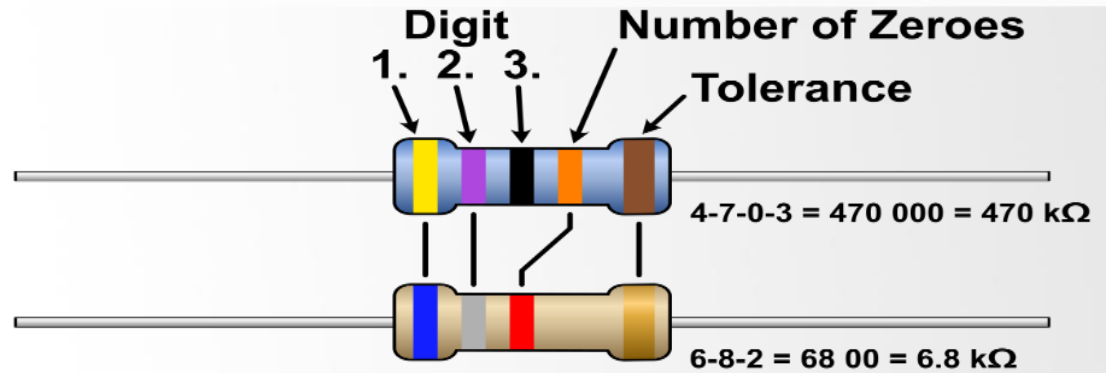
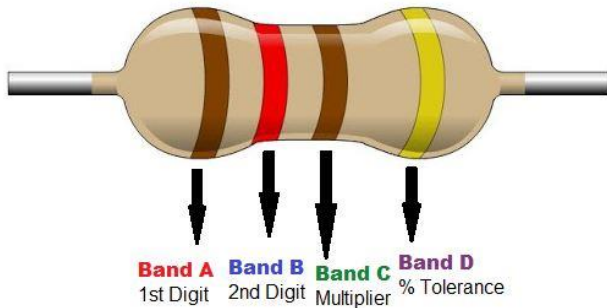
LED

Bread Board



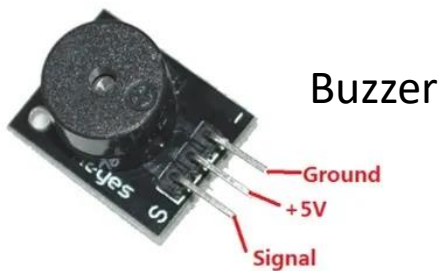


Hardware



Digit	0	1	2	3	4	5	6	7	8	9
Tolerance	Silver ±10 %	Gold ±5 %	±1 %	±0.5 %	±0.1 %					

Register and calculation



Connecting Cables





Hardware



DC motor & Wheel



Servo motor



OLED display and LCD display

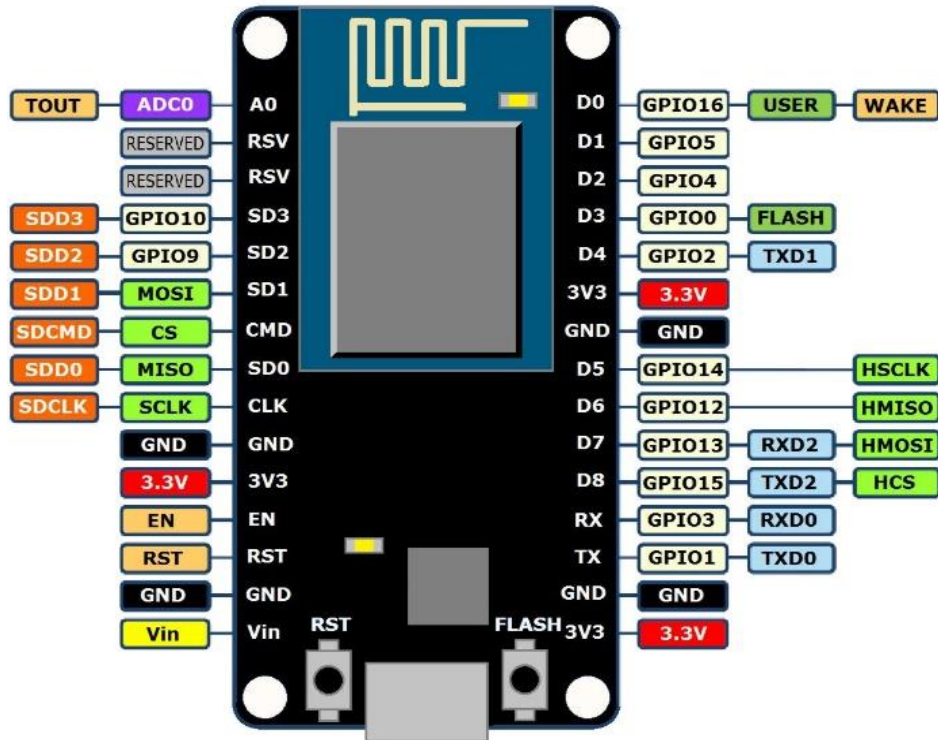


3x3 and 4x4 Key pad





Hardware



NodeMCU

Arduino Shields:

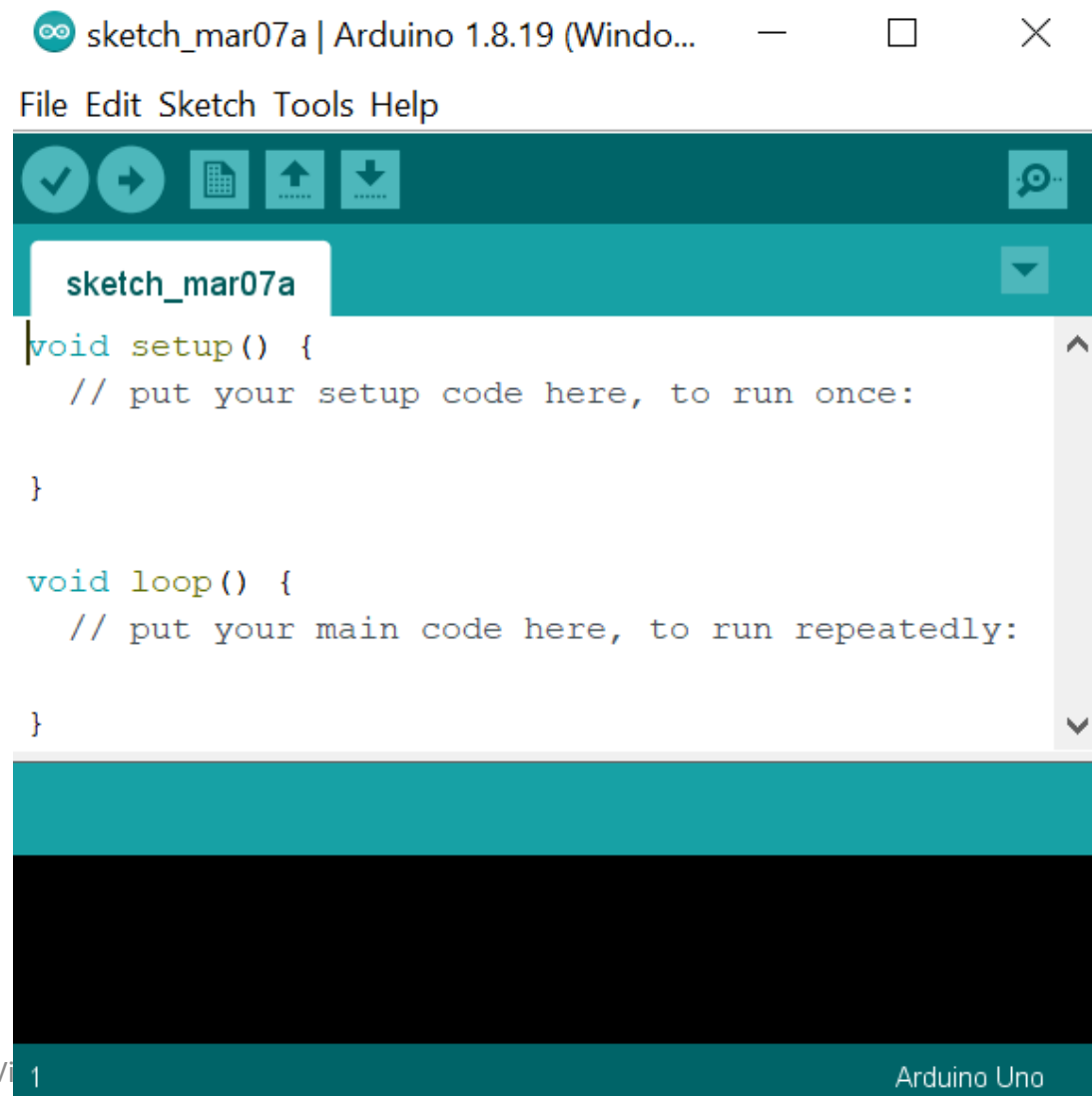
1. WiFi Shield
2. LCD Shield
3. GPS Logger Shield
4. MP3 Music Maker Shield
5. Ethernet Shield
6. Motor/Stepper/Servo Shield



Arduino IDE

Arduino programs run on two basic sections:

```
void setup() {  
  
    //setup motors,  
    sensors etc  
  
}  
void loop() {  
  
    // get information  
    from sensors  
    // send commands to  
    motors  
  
}
```





Comments

Comments

```
// this is for single line comments
```

```
// it's good to put at the top and before anything 'tricky'
```

```
/* this is for multi-line comments
```

```
    Like this...
```

```
    And this...
```

```
*/
```




Comments

A screenshot of the Arduino IDE window titled "BareMinimum | Arduino 1.0.5". The menu bar includes "File", "Edit", "Sketch", "Tools", and "Help". Below the menu is a toolbar with icons for checking, running, uploading, and downloading. The main text area shows the "BareMinimum" sketch with the following code:

```
BareMinimum $  
// Name of sketch  
// Brief Description  
// Date:  
//  
  
void setup()  
{  
  // put your setup code here, to run once:  
}  
  
void loop()  
{  
  // put your main code here, to run repeatedly:  
}
```

Three red arrows point from the right towards the comment lines: "// Name of sketch", "// Brief Description", and "// Date:". The word "comments" is written in red text to the right of these arrows. The IDE interface includes a status bar at the bottom and a scrollbar on the right.



Few commands to know...

```
pinMode(pin, INPUT/OUTPUT);
```

```
ex: pinMode(13, OUTPUT);
```

```
digitalWrite(pin, HIGH/LOW);
```

```
ex: digitalWrite(13, HIGH);
```

```
digitalRead(pin, HIGH/LOW);
```

```
ex: digitalRead(14, INPUT);
```

```
delay(time_ms);
```

```
ex: delay(2500); // delay of 2.5 sec.
```

**NOTE: -> commands are CASE-sensitive
Camel casing**



Few commands to know...

- `Serial.println(value);`
- `Serial.println(value, format);`
 - Prints the value to the Serial Monitor on your computer

Ex: `Serial.println(analogValue);`
`Serial.println(analogValue, DEC);`
- `analogRead(pin);`
 - Reads a digital value (HIGH or LOW) on a pin set for input

Ex: `val = analogRead(analogPin);`
- `analogWrite(pin, value);`
 - Writes the digital value (HIGH or LOW) to a pin set for output

Ex: `analogWrite(ledPin, val / 4);`



SETUP()

- The setup section is used for assigning input and outputs (Examples: motors, LED's, sensors etc) to ports on the Arduino
- It also specifies whether the device is OUTPUT or INPUT
- To do this we use the command “pinMode”

```
void setup() {  
    pinMode(9, OUTPUT);  
}
```

port #

Input or Output



LOOP()

```
void loop() {  
    digitalWrite(9, HIGH);  
    delay(1000);  
    digitalWrite(9, LOW);  
    delay(1000);  
}
```

Port # from setup

Turn the LED on or off

Wait for 1 second or 1000 milliseconds



DECLARING A VARIABLE

```
int val = 5;
```

Type

variable name

assignment
“becomes”

value



USING VARIABLES

```
int delayTime = 2000;
int greenLED = 9;
void setup() {

    pinMode(greenLED, OUTPUT);

}

void loop() {

    digitalWrite(greenLED, HIGH);
    delay(delayTime);
    digitalWrite(greenLED, LOW);
    delay(delayTime);

}
```

Declare delayTime variable

Use delayTime



USING VARIABLES

```
int delayTime = 2000;
int greenLED = 9;

void setup() {
    pinMode(greenLED, OUTPUT);
}

void loop() {
    digitalWrite(greenLED, HIGH);
    delay(delayTime);
    digitalWrite(greenLED, LOW);
    delayTime = delayTime - 100;
    delay(delayTime);
}
```

← subtract 100 from
delayTime to gradually
increase LED's blinking
speed



CONDITIONS

- To make decisions in Arduino code we use an 'if' statement
- 'If' statements are based on a TRUE or FALSE question

```
if (true)  
{  
    "perform some action"  
}
```



IF EXAMPLE

```
int counter = 0;

void setup() {
  Serial.begin(9600);
}

void loop() {

  if(counter < 10)
  {
    Serial.println(counter);
  }
  counter = counter + 1;

}
```



VALUE COMPARISONS

GREATER THAN

$a > b$

GREATER THAN OR EQUAL

$a \geq b$

LESSER

$a < b$

LESS THAN OR EQUAL

$a \leq b$

EQUAL

$a == b$

NOT EQUAL

$a != b$



SERIAL INPUT & OUTPUT

Transferring data from the computer to an Arduino is done using Serial Transmission

To setup Serial communication we use the following

```
void setup() {  
  
    Serial.begin(9600) ;  
  
}
```




WRITING TO THE CONSOLE

```
void setup() {  
  
    Serial.begin(9600);  
    Serial.println("Hello World!");  
  
}  
  
void loop() {}
```



IF - ELSE CONDITION

```
if( "answer is true")
{
    "perform some action"
}
else
{
    "perform some other action"
}
```



IF - ELSE EXAMPLE

```
int counter = 0;
void setup() {
    Serial.begin(9600);
}
void loop() {
    if(counter < 10)
    {
        Serial.println("less than 10");
    }
    else
    {
        Serial.println("greater than or equal to 10");
        Serial.end();
    }
    counter = counter + 1;}
29
```



IF - ELSE IF Condition

```
if( "answer is true")
{
    "perform some action"
}
else if( "answer is true")
{
    "perform some other action"
}
```



IF - ELSE IF Example

```
int counter = 0; void
setup() {
    Serial.begin(9600);
}
void loop() {

    if(counter < 10)
    {
        Serial.println("less than 10");
    }
    else if (counter == 10)
    {
        Serial.println("equal to 10");
    }
    else
    {
        Serial.println("greater than 10");
        Serial.end();
    }
    counter = counter + 1;
}
```



BOOLEAN OPERATORS - AND

- If we want all of the conditions to be true we need to use 'AND' logic (AND gate)
- We use the symbols **&&**
- Example

```
if ( val > 10 && val < 20)
```




BOOLEAN OPERATORS - OR

- If we want either of the conditions to be true we need to use 'OR' logic (OR gate)
- We use the symbols `||`
- Example

```
if ( val < 10 || val > 20)
```



BOOLEAN VARIABLES

```
boolean done = true;
```

```
boolean done = false;
```

```
void setup() {
```

```
  Serial.begin(9600);}
```

```
void loop() {
```

```
  if(!done) {
```

```
    Serial.println("HELLOWORLD");
```

```
    done = true; }
```

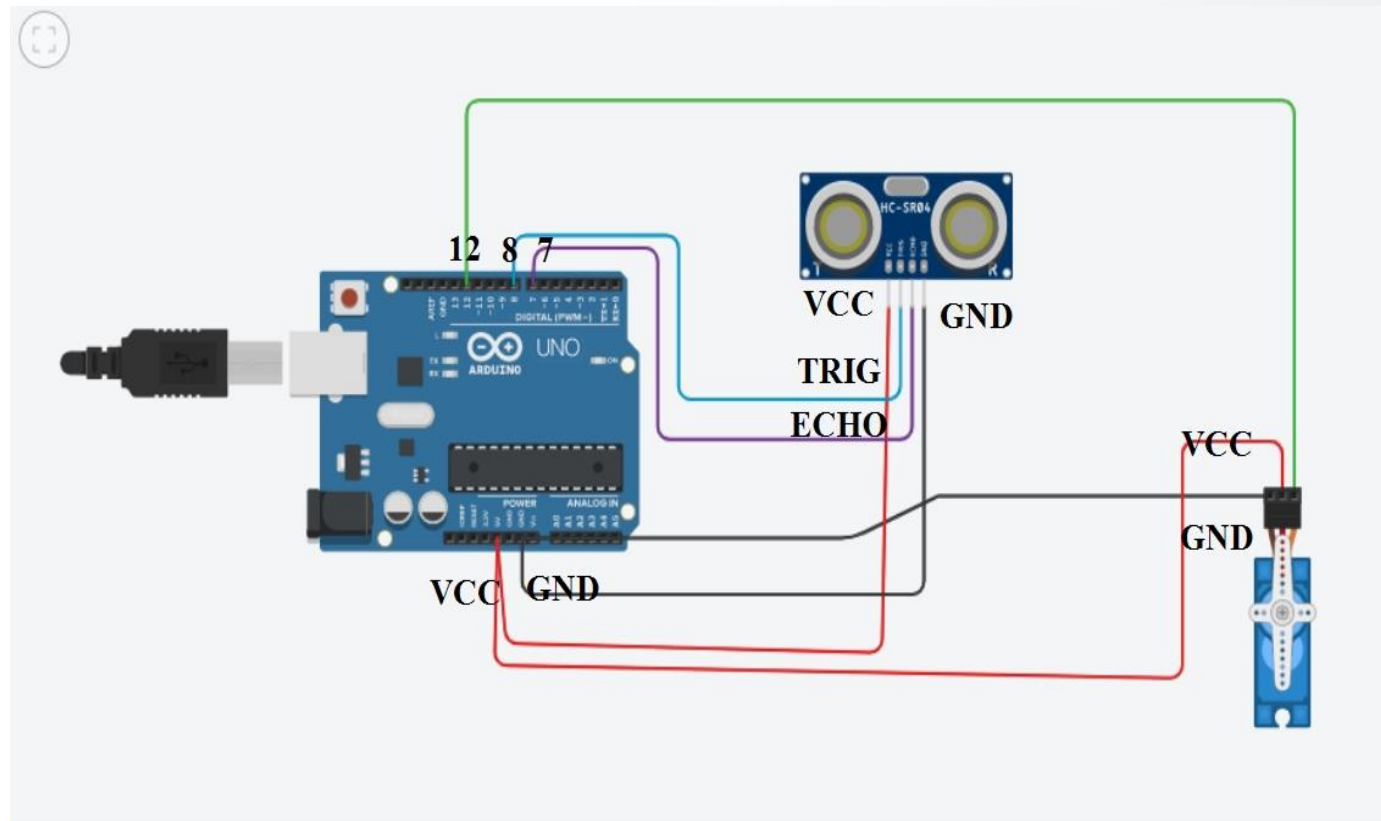
```
}
```

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Project-1 Ultra Sonic sensor and Servo motor

Ultra Sonic Sensor---live demo

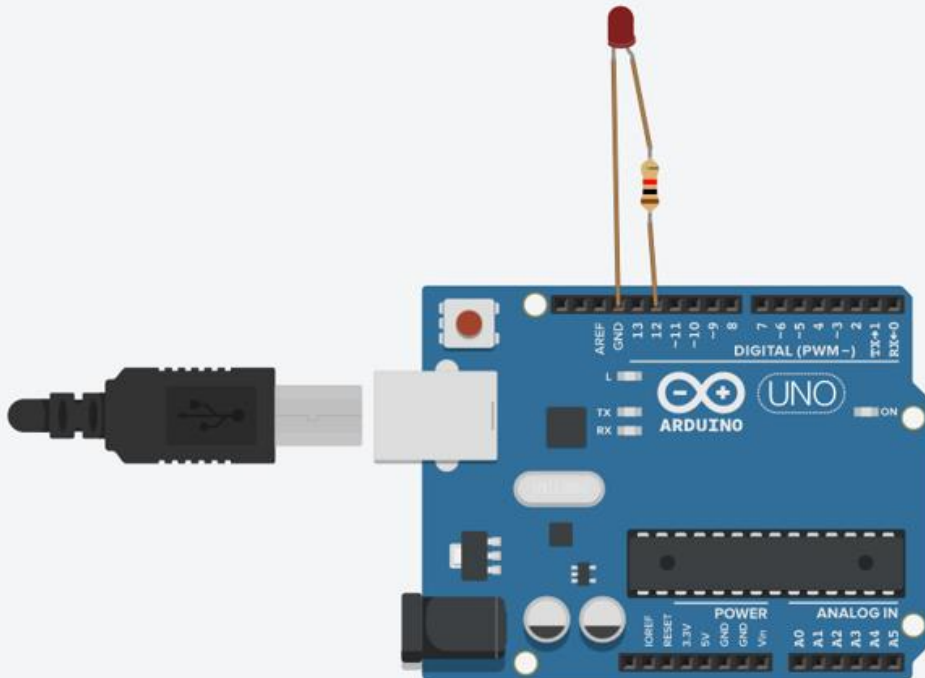


Open Arduino IDE



Project 2- LED Blink

- Consider the following circuit and following code: Create a new Tinkercad project with the circuit in the figure and type the provided code. Make sure circuit works by verifying that the LED is blinking when you run the simulation.
- Study the code and make sure you understand its functionality.
- The resistor used is 220 Ohms.

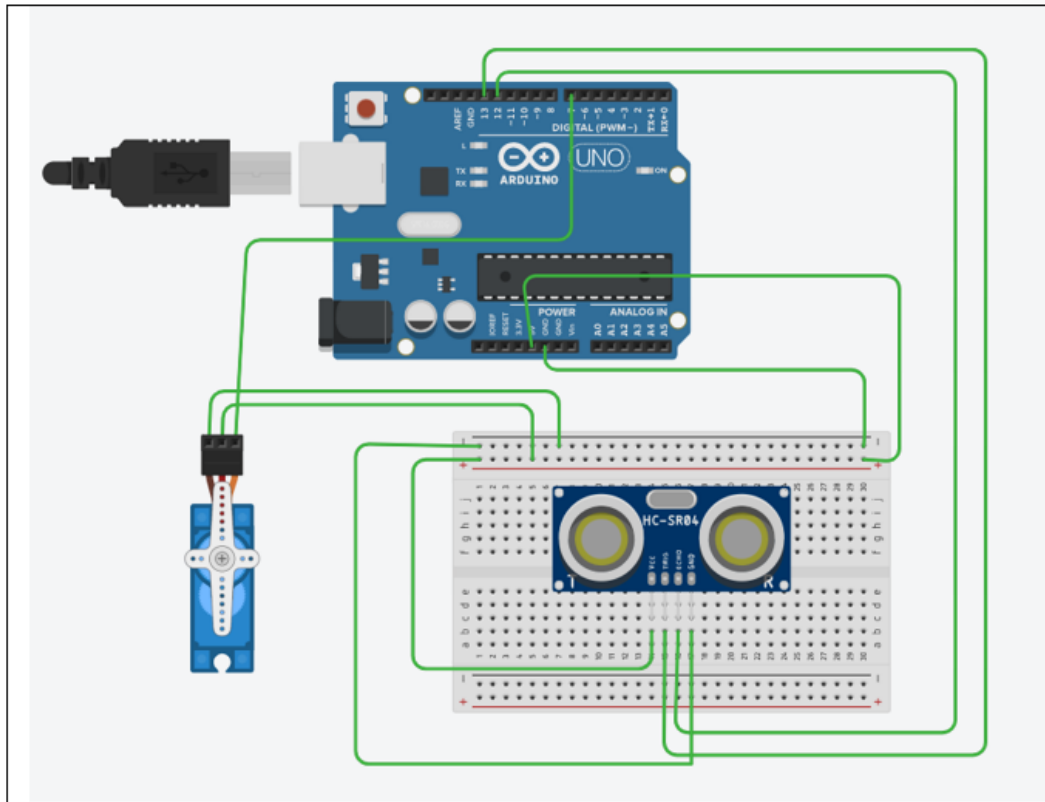


LED	Arduino
+ve (anode)	GND
-ve (cathode)	Register front
Register	Arduino
End of register	Pin 12



Project 3 – Ultra Sonic Sensor and Servo Motor

- Consider the following circuit and the following code.
- Create a Tinkercad project with the circuit in the figure and type the provided code. Make sure the servo more rotates when the distance sensor measures an object close by.
- Study the code and make sure you understand its functionality.

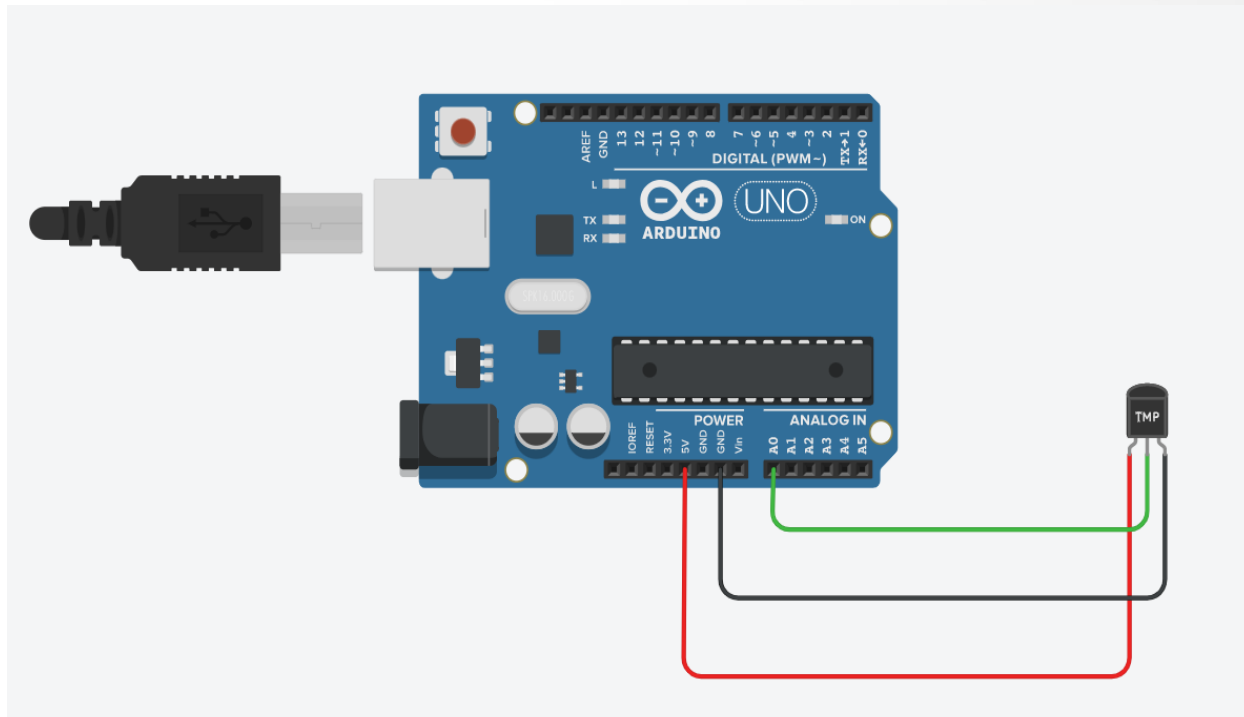


<u>Ultra Sonic</u>	<u>Arduino</u>
VCC	VCC
GND	GND
Trig	13
Echo	12
<u>Servo</u>	<u>Arduino</u>
VCC	VCC
GND	GND
Signal	7



Project 4 – Temperature sensor

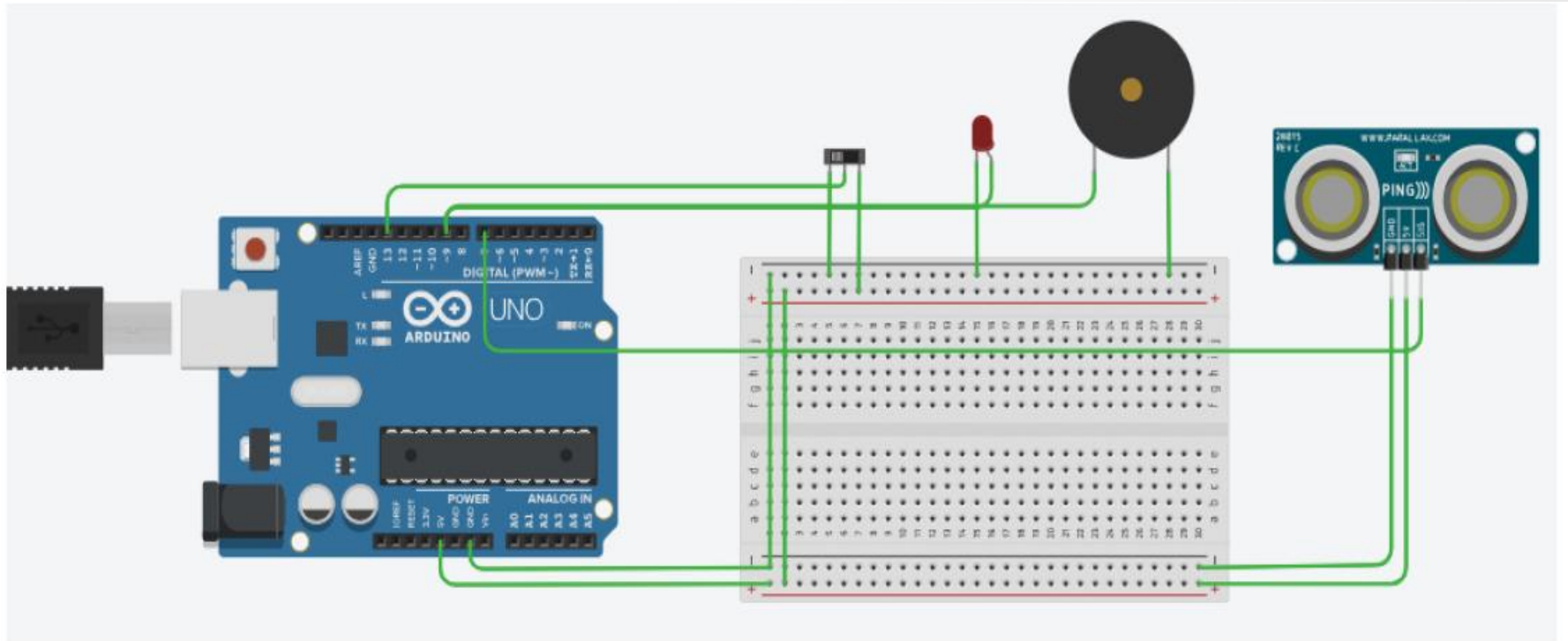
- Consider the following circuit and the following code. Create a Tinkercad project with the circuit in the figure and type the provided code.
- Make sure the temperature data is printed on the serial monitor for every 3 seconds delay.
- The signal pin of the temperature sensor is connected to A0 of Arduino.
- Study the code and make sure you understand its functionality.





Question 1— Ultra Sonic Sensor with Speaker and LED

Develop an application with the following circuit of Ultra Sonic Sensor, Speaker, LED and Transistor. Make sure the speaker is beeping when the distance sensor measures an object close by. Make documentation of each hardware component you are using.

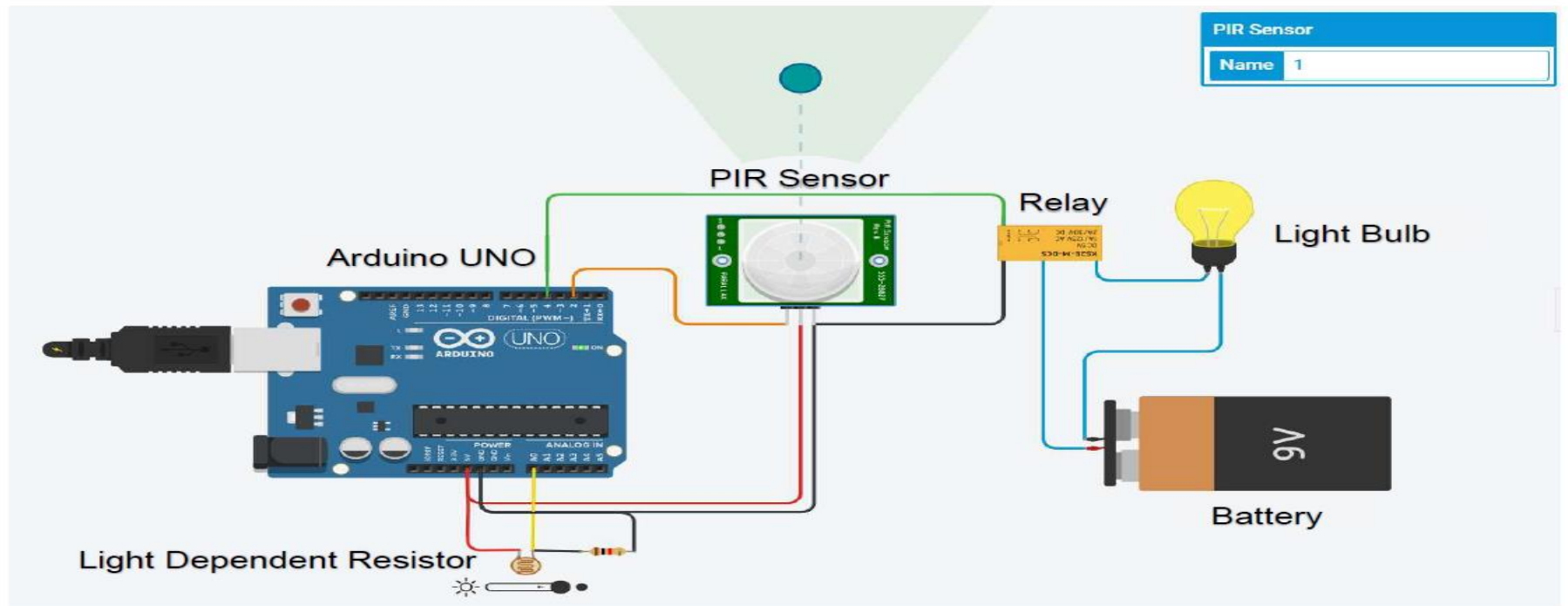




Question -2: Smart lighting

Develop a circuit shown below representing a smart lighting system using TinkerCad.

Action: Slide the point on bar towards Day or Night on the LDR, it detects the brightness intensity. The Raw values can be seen on Serial Monitor. Any value below 500 means it is dark outside and any value above 500 means it is bright. Based on this value, the bulb should switch ON at night and switch OFF during day. Also, if the blue dot of PIR sensor is clicked and dragged to create a physical movement in front of the sensor, then the PIR sensor should turn red and bulb should ON.





WHAT
NEXT?

IoT and M2M: SDN and NFV for IoT