VIVA: Installation guide (Mac)

一:环境要求

安装 Brew 参考 https://brew.sh/

\$ ruby -e "\$(curl -fsSL https://raw.githubusercontent.com/Homebrew/install/master/install)" 在 ~/.profile file 最后一行加入 export PATH=/usr/local/bin:/usr/local/sbin:\$PATH

安装 Python

Brew install python

安装虚拟环境(virtual environment) 和 Tensorflow 参考 https://www.tensorflow.org/install/install_mac

\$ sudo easy install pip # 安装pip管理器

\$ pip install --upgrade virtualenv # 如果出现错误提示, 需要安装 nose 和 tornado

\$ pip install nose

\$ pip install tornado

\$ virtualenv --system-site-packages ./tensorflow # for Python 2.7 \$ virtualenv --system-site-packages -p python3 ./tensorflow # for Python 3.n

\$ cd tensorflow

\$ source ./bin/activate

(tensorflow)\$ pip install --upgrade tensorflow # for Python 2.7 (tensorflow)\$ pip3 install --upgrade tensorflow # for Python 3.n

安装 Keras 参考 https://keras.io/#installation

\$ pip install keras

安装 "Keras model 存到磁盘"所需的套件

\$ brew install hdf5

\$ pip install h5py # 若在 Keras安装过程没安装此依赖,使用此命令补充安装

安装 Pillow

\$ pip install pillow

安装 XCode

到网页下载安装 XCode https://developer.apple.com/xcode/ 或者App-Store下载

\$ sudo xcode-select --install

\$ sudo xcodebuild -license #滑动到底部并且接受条款

安装 OPENCV 参考: https://www.learnopencv.com/install-opencv3-on-macos/

\$ brew install opency

如果出现权限问题(在brew过程可能会出现创建brew link isl,brew link gcc,brew link hdf5的错误)

\$ sudo chown -R 本机账户:admin /usr/local/bin 例如 sudo chown -R **eddieliu**:admin /usr/local/bin \$ sudo chown -R 本机账户:admin /usr/local/share 例如 sudo chown -R **eddieliu**:admin /usr/local/share

二: 收集素材

图片收集准则:好的data是非常重要的一环,model的好坏,取决于训练的data的质量。

尺寸:大于300x300

张数:每个类别至少100张或以上。如果图片足够,尽量尝试500

张以上, 可以提高精准度。

格式: JPG







airmax270_48.jpg

airmax270_49.jpg

airmax270_50.jpg

图片选择

- -正面产品照
- -穿/戴在人身上
- -在实际世界中,有背景
- -不同的角度
- -不同的亮度







airmax270_56.jpg

g airmax270_57.jpg

airmax270_58.jpg

注意:图片类别的特征要清楚,人眼能够识别.如果是一串小珠子,在图片的细微处,可能会造成辨识度下降。

分类建议:类别要清晰. 容易判断

Machine learning, 可以想像在教机器辨识各种类别分类,他会根据图片内容,自己来定义这个分类。

范例: 牛仔裤











(√) 这是属于好的图片选择,因为牛仔裤占据了图片的主要内容。

想象程序会学习到,长长,蓝色,浅蓝色,上面有或没有一块不同颜色的布料,或者是下面有一双鞋子,都是属于牛仔裤。







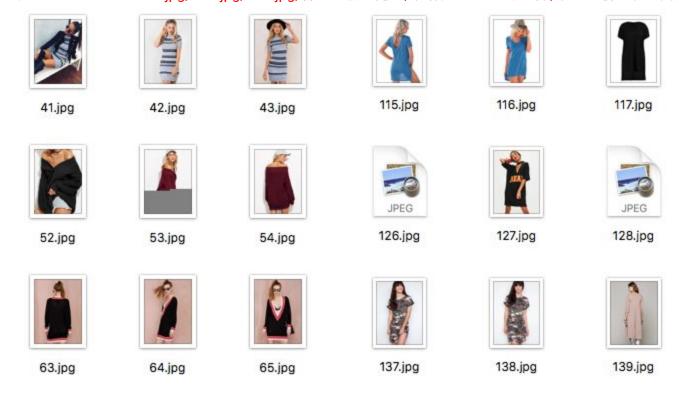




(x) 这是比较不适合的图片选择, 因为它涵盖其他元素 e.g. 都有上半身, 头像, 鞋子, 程序会认为, 必须包含这些部分才叫做"牛仔裤". 而这个训练过程, 可能也会和"衣服"的类别搞混, 特别是如果衣服类别中, 也都有全身的图片.

确保图片的完整性

从网络上大量下载的 jpg, 很可能会出现档案有下载不完整, 必须要再 double check, 否则读取错误, 会造成程序读取错误而跳出. 以下 53.jpg, 126.jpg, 128.jpg, 都是下载不完整, 或有问题的. 务必删除, 或是重新下载该图片



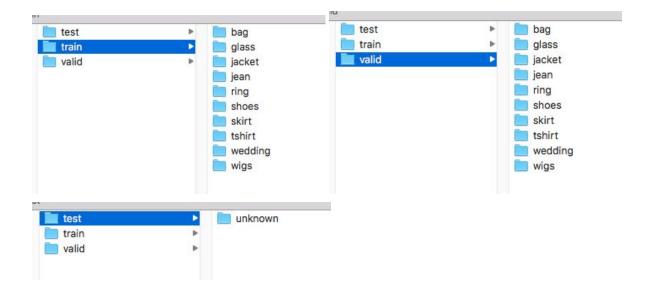
文件夹结构

Train:子目录存放各种分类和图片:会从这个文件夹里面的图片来做训练

Valid:子目录存放各种分类和图片:会从这个文件夹的图片来做验证, 进一步调教 model

Test:子目录存放 "unknown": 最后要用来测试的图片

比例建议Train / Valid / Test: 80% /10% /10%, 也可以尝试70% / 20% / 10% 或是在之间调整



三:训练模型

1.更改 config.json 里面的参数

```
"train_path" :"dataset",
"batch_size_train":"15",
"category_num": "3",
"learning_rate":"0.0003",
"epoch_num":"20",
"steps_per_epoch":"6",
"output name":"model.h5"
}
```

参数	介绍	建议尝试的范围
train_path	训练图片的文件夹 注意:文件夹底下需要有Train, Valid, 和 Test 的文件夹	文件夹的路径
batch_size_train	每个批次训练几张图片	10 ~ 30
category_num	训练几种类别 训练几种类别	
learning_rate	学习变化的幅度 0.001 ~ 0.00001	
epoch_num	总共训练几轮,在每一轮会更新model的weight 100~200	
steps_per_epoch	每轮会训练几个批次 6~10	
output_name	输出档案的名字 xxxxxx.h5	

train model 需要的时间, 与要处理的图片数目batch size, steps per epoch, 和 epoch, 呈线性成长。

-每个 epoch 会处理的图片数目 = batch_size_train * steps_per_epoch

-总共需要 training 的时间 : epoche_num * 每个 epoch 的时间

epoch_num	batch_size_train	steps_per_epoch	总共时间
10	10	10	1 T
10	20	10	2 T
10	10	20	2 T
10	15	20	3 T
80	15	20	24 T

2.命令行: python train_model.py

```
#!/usr/bin/env python
# -*- coding: utf-8 *
import numpy as np
import keras
from keras import backend as K
from keras.layers.core import Dense, Activation
from keras.optimizers import Adam
from keras.metrics import categorical crossentropy
from keras.preprocessing.image import ImageDataGenerator
from keras.preprocessing import image
from keras.models import Model
from keras.applications import imagenet utils
import json
# Open config.json
def jsonReader():
  with open("./config.json", 'r') as load_f:
       jsonDict = json.load(load f)
       return jsonDict
# Read data from config.json
jsonData = jsonReader()
train_path = jsonData['train_path'] + '/train'
valid_path = jsonData['train_path'] + '/valid'
test path = jsonData['train path'] + '/test'
bsize = int(jsonData['batch size train'])
catnum = int(jsonData['category_num'])
lrate = float(jsonData['learning rate'])
steps = int(jsonData['steps per epoch'])
epoch num = int(jsonData['epoch num'])
output name = jsonData['output name']
# Train the model. Default shuffle = true
train batches =
ImageDataGenerator(preprocessing function=keras.applications.mobilenet.preproces
s input).flow from directory( train path, target size=(224,224),
batch size=bsize)
# Validate the model. Default shuffle = true
valid batches =
ImageDataGenerator(preprocessing function=keras.applications.mobilenet.preproces
s input).flow from directory( valid path, target size=(224,224), batch size=10)
# Make prediction with the model trained
test batches =
ImageDataGenerator(preprocessing function=keras.applications.mobilenet.preproces
```

```
s input).flow from directory(test path, target size=(224,224), batch size=2,
shuffle=False)
mobile = keras.applications.mobilenet.MobileNet()
x = mobile.layers[-6].output
predictions = Dense(catnum, activation='softmax')(x)
model = Model(inputs=mobile.input, outputs=predictions)
model.summary()
# Only train the last 5 layers and make the previous layers fixed
for layer in model.layers[:-5]:
   layer.trainable = False
model.compile(Adam(lr=lrate), loss='categorical crossentropy',
metrics=['accuracy'])
model.fit generator(train batches, steps per epoch=steps,
                   validation data=valid batches, validation steps=2,
epochs=epoch num, verbose=2)
# Output the model
model.save(output_name)
# Make prediction with the model
predictions = model.predict generator(test batches, steps=1, verbose=2)
print(predictions)
print(train batches.class indices)
```

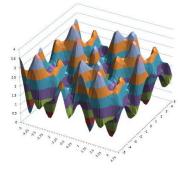
四:调教模型

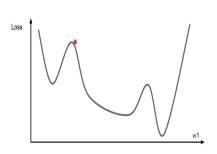
本章节主要会描述各种 train model 的过程, 可能会遇到的一些状况, 以及如何调整参数, 来去做调教.

在训练的过程中, 要注意 loss (模型与实际结果的差别) 和 valid_acc (valid 集合里面的精准度)

想像一下, 我们要找到整个山脉群里面, 最低的地方 (最小的 loss), 而 learning rate 是每次移动的步伐







假设最佳的山谷低点, 在前方 5.25 km 处, 要如何去探索呢?

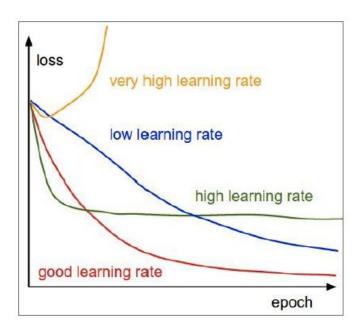
Very high learning rate: 每一步都是 100 km, 跨一步, 都会离目标更远

High learning rate:每一步都是1km,前期 loss rate 下降快速,但会有瓶颈,最后在5~6km之间探索。

Low learning rate:每一步都是 0.001 km, loss rate下降非常地缓慢。

Good learning rate: 每一步 0.1 km, 前期 loss rate 下降快速, 最后趋于平稳, 在 5.2 ~ 5.3 km 附近探索

注:每次训练的内容和顺序都是随机选择的,但是会按照所给的config.json的要求去进行,所以即使初始配置一致,也会出现不同的训练反馈。



让我们来看选择不同数值的训练过程

Very high learning rate: 10 Loss 马上飚高到超过 15 且无法收敛, 可以停止训练了 Epoch 1/100 - 51s - loss: 14.0048 - acc: 0.0537 - val_loss: 16.1181 - val_acc: 0.0000e+00 Epoch 2/100 - 46s - loss: 14.9361 - acc: 0.0733 - val_loss: 16.1181 - val_acc: 0.0000e+00 Epoch 3/100 - 43s - loss: 15.3122 - acc: 0.0500 - val_loss: 16.1181 - val_acc: 0.0000e+00 Epoch 4/100 - 46s - loss: 14.8824 - acc: 0.0767 - val_loss: 16.1181 - val_acc: 0.0000e+00 Epoch 5/100 - 43s - loss: 14.8824 - acc: 0.0767 - val_loss: 16.1181 - val_acc: 0.0000e+00 Epoch 6/100 - 41s - loss: 14.7749 - acc: 0.0833 - val_loss: 16.1181 - val_acc: 0.0000e+00 Epoch 7/100 - 44s - loss: 14.9898 - acc: 0.0700 - val loss: 16.1181 - val acc: 0.0000e+00 - 42s - loss: 14.7212 - acc: 0.0867 - val_loss: 16.1181 - val_acc: 0.0000e+00 Epoch 9/100 - 42s - loss: 15.0436 - acc: 0.0667 - val_loss: 16.1181 - val_acc: 0.0000e+00 Epoch 10/100 - 42s - loss: 14.8824 - acc: 0.0767 - val_loss: 16.1181 - val_acc: 0.0000e+00

High learning rate: 0.01

下一步: 大幅降低 learning rate

前 10 步loss 快速下降, 从 2.7 到 0.5 和 7.1 到 2.1 accuracy 也快速到达 0.7~0.8 和 0.3~0.4

Train 到后面, valid accuracy 到达了瓶颈 0.4~0.5. 注意: 这边 train的 loss 小于 0.1, 且 train accuracy 接近 1.0, 表示model过分贴合训练的模型, 反而造成预测能力下降。(此时的model比较贴合于理想环境,对新数据的内容识别能力下降)

Epoch 1/100

- 42s loss: 2.7851 acc: 0.1833 val_loss: 7.1870 val_acc: 0.0000e+00 Epoch 2/100
- 38s loss: 2.1982 acc: 0.3008 val_loss: 5.9909 val_acc: 0.2000 Epoch 3/100
- 42s loss: 2.0329 acc: 0.3667 val_loss: 3.1621 val_acc: 0.4000 Epoch 4/100
- 41s loss: 1.6221 acc: 0.4867 val_loss: 3.8205 val_acc: 0.2000 Epoch 5/100
- 39s loss: 1.5566 acc: 0.4600 val_loss: 6.1969 val_acc: 0.0000e+00 Epoch 6/100
- 37s loss: 1.4096 acc: 0.5400 val_loss: 5.0262 val_acc: 0.2000 Epoch 7/100
- 37s loss: 0.7210 acc: 0.7500 val_loss: 5.4693 val_acc: 0.0000e+00 Epoch 8/100
- 38s loss: 0.6067 acc: 0.8333 val_loss: 3.3162 val_acc: 0.2000 Epoch 9/100
- 37s loss: 0.4823 acc: 0.8767 val_loss: 2.9067 val_acc: 0.4000 Epoch 10/100
- 36s loss: 0.5013 acc: 0.8733 val_loss: 2.1334 val_acc: 0.3000

Epoch 81/100

- 38s loss: 0.0121 acc: 1.0000 val_loss: 2.5431 val_acc: 0.4000 Epoch 82/100
- 47s loss: 0.0113 acc: 1.0000 val_loss: 2.3135 val_acc: 0.3000 Epoch 83/100
- 44s loss: 0.0086 acc: 1.0000 val_loss: 2.4654 val_acc: 0.4000 Epoch 84/100
- 45s loss: 0.0166 acc: 0.9967 val_loss: 2.8840 val_acc: 0.5000 Epoch 85/100
- 39s loss: 0.0105 acc: 1.0000 val_loss: 2.6925 val_acc: 0.5000 Epoch 86/100
- 38s loss: 0.0083 acc: 1.0000 val_loss: 2.1870 val_acc: 0.4000 Epoch 87/100
- 39s loss: 0.0071 acc: 1.0000 val_loss: 2.2050 val_acc: 0.4000 Epoch 88/100
- 37s loss: 0.0080 acc: 1.0000 val_loss: 2.2907 val_acc: 0.4000 Epoch 89/100
- 39s loss: 0.0068 acc: 1.0000 val_loss: 2.2843 val_acc: 0.4000

下一步:稍微降低 learning rate

Low learning rate: 0.00001

最后10步骤, loss 都大于1, accuracy 停留在0.6 / 0.3

最初10步骤, loss从 3.26 缓慢下降到2.85

Epoch 1/100

- 41s loss: 3.2658 acc: 0.0867 val_loss: 2.9313 val_acc: 0.2000 Epoch 2/100
- 39s loss: 3.3687 acc: 0.0767 val_loss: 2.9106 val_acc: 0.2000 Epoch 3/100
- 42s loss: 3.1668 acc: 0.0667 val_loss: 2.8740 val_acc: 0.2000 Epoch 4/100
- 43s loss: 3.1335 acc: 0.0900 val_loss: 2.8356 val_acc: 0.2000 Epoch 5/100
- 42s loss: 3.1657 acc: 0.0800 val_loss: 2.8029 val_acc: 0.2000 Epoch 6/100
- 38s loss: 3.1580 acc: 0.0872 val_loss: 2.7779 val_acc: 0.2000 Epoch 7/100
- 43s loss: 2.9513 acc: 0.0667 val_loss: 2.7578 val_acc: 0.2000 Epoch 8/100
- 44s loss: 2.9811 acc: 0.0900 val_loss: 2.7353 val_acc: 0.2000 Epoch 9/100
- 42s loss: 2.9064 acc: 0.1100 val_loss: 2.7239 val_acc: 0.2000 Epoch 10/100
- 41s loss: 2.8591 acc: 0.1133 val_loss: 2.7067 val_acc: 0.2000

Epoch 91/100

- 37s loss: 1.4415 acc: 0.5930 val_loss: 1.9144 val_acc: 0.3000 Epoch 92/100
- 40s loss: 1.4591 acc: 0.6167 val_loss: 1.9073 val_acc: 0.3000 Epoch 93/100
- 43s loss: 1.4684 acc: 0.5867 val_loss: 1.9024 val_acc: 0.3000 Epoch 94/100
- 42s loss: 1.4227 acc: 0.5800 val_loss: 1.9028 val_acc: 0.3000 Epoch 95/100
- 43s loss: 1.4395 acc: 0.5800 val_loss: 1.9013 val_acc: 0.3000 Epoch 96/100
- 41s loss: 1.3721 acc: 0.6267 val_loss: 1.8974 val_acc: 0.3000 Epoch 97/100
- 42s loss: 1.4560 acc: 0.6033 val_loss: 1.8928 val_acc: 0.3000 Epoch 98/100
- 43s loss: 1.4318 acc: 0.5700 val_loss: 1.8878 val_acc: 0.3000 Epoch 99/100
- 42s loss: 1.4992 acc: 0.5982 val_loss: 1.8804 val_acc: 0.3000 Epoch 100/100
- 37s loss: 1.3924 acc: 0.6100 val_loss: 1.8779 val_acc: 0.3000

下一步:稍微提升 learning rate

Good learning rate: 0.00005

Good learning rate: 0.00005 最初10步骤, loss从 3下降到1.8 最后10步骤, loss 和 accuracy 都趋于稳定. loss 在 0.3~0.4 / 1.2~1.3; accuracy 在0.95 / 0.7~0.8

Epoch 1/100

- 39s loss: 3.0220 acc: 0.0967 val_loss: 2.5357 val_acc: 0.2000 Epoch 2/100
- 36s loss: 2.8572 acc: 0.1233 val_loss: 2.5735 val_acc: 0.2000 Epoch 3/100
- 36s loss: 2.6347 acc: 0.1533 val_loss: 2.5309 val_acc: 0.2000 Epoch 4/100
- 36s loss: 2.4472 acc: 0.2000 val_loss: 2.5096 val_acc: 0.2000 Epoch 5/100
- 37s loss: 2.4605 acc: 0.1667 val_loss: 2.4614 val_acc: 0.2000 Epoch 6/100
- 45s loss: 2.3777 acc: 0.2151 val_loss: 2.3947 val_acc: 0.3000 Epoch 7/100
- 37s loss: 2.1120 acc: 0.3127 val_loss: 2.3821 val_acc: 0.2000 Epoch 8/100
- 42s loss: 2.0617 acc: 0.3500 val_loss: 2.3293 val_acc: 0.3000 Epoch 9/100
- 43s loss: 1.9819 acc: 0.3667 val_loss: 2.3203 val_acc: 0.4000 Epoch 10/100
- 1136s loss: 1.8970 acc: 0.4033 val_loss: 2.2391 val_acc: 0.3000

Epoch 91/100

- 37s loss: 0.4574 acc: 0.9426 val_loss: 1.2659 val_acc: 0.7000 Epoch 92/100
- 43s loss: 0.3990 acc: 0.9633 val_loss: 1.2293 val_acc: 0.8000 Epoch 93/100
- 42s loss: 0.4320 acc: 0.9600 val_loss: 1.2142 val_acc: 0.8000 Epoch 94/100
- 42s loss: 0.3907 acc: 0.9667 val_loss: 1.2125 val_acc: 0.8000 Epoch 95/100
- 39s loss: 0.3538 acc: 0.9767 val_loss: 1.2097 val_acc: 0.8000 Epoch 96/100
- 42s loss: 0.4138 acc: 0.9600 val_loss: 1.2195 val_acc: 0.7000 Epoch 97/100
- 43s loss: 0.4060 acc: 0.9598 val_loss: 1.2310 val_acc: 0.7000 Epoch 98/100
- 47s loss: 0.3656 acc: 0.9700 val_loss: 1.2328 val_acc: 0.7000 Epoch 99/100
- 42s loss: 0.3816 acc: 0.9667 val_loss: 1.2316 val_acc: 0.8000 Epoch 100/100
- 43s loss: 0.3710 acc: 0.9733 val_loss: 1.2435 val_acc: 0.7000

下一步: 这是适合的 learning rate,仅作微调, 看是否让 accuracy 能够更高

五: TFJS converter (Keras h5 转 TFJS)

参考: https://github.com/tensorflow/tfjs-converter

安装 Tensorflowjs

pip install tensorflowjs

转换format

tensorflowjs_converter \
--input_format=keras \
/tmp/my_keras_model.h5 \
/tmp/my_tfjs_model

六:接入前端网页应用

- 1. 上传转换过后的模型到服务器上,并记下 model.json 的位置
- 2. **创建 MobileNet 物件**,物件内包含加载模型,进行预测及取回预测结果进行商务逻辑

```
var MobileNet = {
 /* TODO: 加载 model 的 url */
 MODEL URL: 'https://your.model.url',
 /* 分辨率为固定值 请勿修改*/
 PREPROCESS DIVISOR: 127.5,
 /* 预测几率在多少以上当成成功*/
 PICKUP RATE: 0.7,
 constructor: function (){},
 /* TODO(1): 加入是否加载过模型 */
 /* TODO(2): 加入判断网络环境 */
 /* 加载 model 的 function */
 load: async function (){
   this.model = await tf.loadModel(this.MODEL URL);
   /* 加载完 model 后进行第一次模拟,可加速用户第一次辨识的速度 */
   this.predict(tf.zeros([1, 224, 224, 3])).dispose();
   /* 加载完后绑定开启相机事件 *可自行加入商务条件 */
   camera ops.setup('detector', 'video', 'closeCamera', 'outputCanvas',
'camera'):
 },
 /* 预测处置,清空模型内预测后的缓存 */
 dispose: function () {
   this.model.dispose();
 /* 预测 function, 先将图片正规化后进行预测 */
 predict: function (screenshot) {
   console.time();
   const offset = tf.scalar(this.PREPROCESS DIVISOR);
   const nomalized = screenshot.sub(offset).div(offset);
   const batched = nomalized.reshape([1,224,224,3]);
   return this.model.predict(batched);
 /* 传入预测结果物件 ,取出预测结果数值进行商务逻辑 */
 getTopResult: async function (logits) {
   /* 取出结果数值*/
   const values = await logits.data();
```

```
/* 将结果传入阵列*/
const valuesAndIndices = [];
for (let i = 0; i < values.length; i++) {
   valuesAndIndices.push({value: values[i], index: i});
}

/*进行排序*/
valuesAndIndices.sort((a, b) => {
   return b.value - a.value;
});

/* TODO: 使用结果阵列引入商务逻辑*/
console.log(valuesAndIndices);
console.timeEnd();
}
```

- 3. 使用 PWA 功能检查用户当下条件是否符合加载模型
 - a. 是否支持 Service Worker

b. 是否已经加载过 model: TODO(1)

```
check_if_model_exist: function () {
   caches.has('https://your.model.url').then(function (result){
     return result;
   });
}
```

c. 未加载过 model 是否当下在 wifi 的环境: TODO(2)

```
check_isWifi: function() {
   if (!navigator.connection || navigator.connection.type != "wifi") {
     return false;
   }
```

```
return true;
}
```

结合后会变成

```
if(!MobileNet.check_if_model_exist()) {
   if (MobileNet.check_isWifi()){
      MobileNet.load();
   }
} else {
   MobileNet.load();
}
```

4. 在 HTML 上引入Tensorflow JS库

5. 在 HTML body 里面加上相机功能和开启相机后的图层

6. 绑定相机以触发预测

```
/* 设置相机物件以触发图形预测 */
var camera_ops = {
    IDENTIFY_WAIT_TIME: 1500, //开启相机后截取图片等待时间
    cameraLayer: undefined, // 相机图层
    video: undefined, // 相机视频 DOM
    closeButton: undefined, // 关闭相机按钮
    middleCanvas: undefined, // 截取视频转换为图片的中间层
    mainContent: undefined, // 相机图层欲覆盖的主要图层
    videoStream: undefined, // 开启相机后的视频串流
```

```
loadingLayer: undefined, // 进行预测是的中间加载效果
 /* 绑定相机事件 */
 setupCamera: function(cameraLayerId, videoId, closeButtonId, middleCanvasId,
cameraTriggerId) {
   this.cameraLayer = document.getElementById(cameraLayerId);
   this.video = document.getElementById(videoId);
   this.closeButton = document.getElementById(closeButtonId);
   this.middleCanvas = document.getElementById(middleCanvasId);
   // TODO: 更改加载图层ID
   this.loadingLayer = document.getElementById('loadingLayer')
   // TODO:更改图层内容主要图层 Class
   this.mainContent = document.getElementsByClassName('yourMainContentClass');
   //setup camera trigger
   this.addCameraEvent(cameraTriggerId);
   this.bindCameraLayerClose();
 },
 /* 检查浏览器是否支持相机功能 */
 checkAvailable: function () {
   if (!navigator.mediaDevices | !navigator.mediaDevices.getUserMedia) {
     return false;
   }
   return true;
 },
 /* 为相机按钮绑上开启相机事件 */
 addCameraEvent: function (id) {
   const w = screen.width;
   const h = screen.width;
   console.log('width:' + w + ", h:" + h);
   const cameraButton = document.getElementById(id);
   cameraButton.addEventListener('click', async function () {
     /* OPTIOAL TODO:可加入其他条件是否继续绑定开启相机事件 */
     /* 检查浏览器是否支持相机功能 */
     if (!camera_ops.checkAvailable()) {
       general_ops.showMessage('You browser not support browser camera api');
       return;
     camera_ops.video.width = w;
     camera_ops.video.height = h;
     /* 设置相机基本参数,参数内容可更动,参数内容请参考:
https://developer.mozilla.org/en-US/docs/Web/API/MediaStreamConstraints */
```

```
camera_ops.videoStream = await navigator.mediaDevices.getUserMedia({
     audio: false,
     video :{
       facingMode: 'environment',
       width: { min: 224, ideal: 448, max: 1344 },
       height: { min: 224, ideal: 448, max: 1344 }
    });
    /* 将串流导入视频物件*/
    camera_ops.video.srcObject = camera_ops.videoStream;
    return (new Promise((resolve) => {
        /* 确认视频串流正确载入后的动作 */
        camera ops.video.onloadedmetadata = () => {
          camera_ops.mainContent[0].style = 'display: none';
          camera_ops.cameraLayer.style.display = 'block';
          camera_ops.video.play();
          camera_ops.video.style.display = 'block';
          camera_ops.closeButton.style.display = 'block';
          console.time();
         resolve('init');
        };
      })).then(function() {
       /* 等待时间截取目前用户的相机画面 */
       setTimeout(function () {
          camera_ops.loadingLayer.classList.add('show');
         this.video.pause();
          camera_ops.snapshot(); },
          camera_ops.IDENTIFY_WAIT_TIME);
     });
  })
  cameraButton.classList.add('fadeIn');
/* 绑定关闭相机图层 */
bindCameraLayerClose: function () {
  this.closeButton.addEventListener('click', function () {
    camera_ops.mainContent[0].style.display = 'block';
    camera_ops.cameraLayer.style.display = 'none';
    camera_ops.video.pause();
    camera_ops.videoStream.getTracks()[0].stop();
```

```
camera_ops.video.style.display = 'none';
     camera_ops.closeButton.style.display = 'none';
     camera_ops.loadingLayer.className = '';
   });
  },
  /* 截取图片到 Canvas 后转成图片物件导入模型进行预测 */
 snapshot: function () {
   console.timeEnd();
   const imageToPredict = document.getElementById('imageToPredict');
   this.middleCanvas.width = camera_ops.video.width;
   this.middleCanvas.height = camera_ops.video.height;
   let canvasContext = this.middleCanvas.getContext('2d');
   canvasContext.drawImage(camera_ops.video, 0, 0, camera_ops.video.width,
camera ops.video.height);
   imageToPredict.src = this.middleCanvas.toDataURL('image/jpeg');
   imageToPredict.width = '224';
   imageToPredict.height = '224';
   imageToPredict.onload = function ()
{predict_ops.runPredict(imageToPredict);}
  }
};
```

7. 链接相机和 Mobilenet 模组

```
/* 链接相机和 Mobilenet 模组*/
var predict_ops = {
  runPredict: function (input) {
    /* 转成 tensorflow 可用的图片格式 */
    const pixels = tf.fromPixels(input).toFloat();
    let result = MobileNet.predict(pixels);
    MobileNet.getTopResult(result);
  }
}
```

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