

Artificial Bee Colony Algorithm

Warley Almeida Silva¹

¹Exchange student from UFJF
Supervised by Dr. Gordon Fraser
Universität Passau

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Description

What is it?

The Artificial Bee Colony (ABC) algorithm is a swarm-based algorithm inspired by the foraging behavior of honey bees proposed by Karaboga [1]. It aims to optimize multidimensional and multimodal functions.

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- what is a swarm?
- what is foraging?
- what is multimodal?

Many variations

There are many changed versions of the algorithm for specific needs. It all depends on the problem you are willing to solve. The survey in [2] shows different variations and applications.

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- Employed bees: memorize and exploit specific food sources;
- Onlookers: exploit already known good food sources;
- Scouts: search for new food sources around without prior information.

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- Each **coordinate** represents **parameters** of the solution.
- The **nectar amount** of a food source represents its **fitness value**.
- Each **type of bee** represents a **step** of the algorithm.

Pseudocode

```
procedure ABC(population_size, maximum_cycle_number, limit)
  initialize population_size food_sources
  generate random position for food_sources
  while maximum_cycle_number is not met do
    send employed bees
    calculate the probabilities
    send onlookers
    send scouts
    memorize the best food source
  end while
end procedure
```


Employed bees phase

- Each food source will be exploited once. The exploitation process generates modifications in the parameters of the food source, hoping that a better solution will be found.
- If a better food source is found, the old one is forgotten.

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Equation 1

Given the number of food sources F and the dimension of the problem D , each food source f_i will generate a possible new food source v_i following the formula:

$$v_{ij} = f_{ij} + \phi_{ij}(f_{ij} - f_{kj})$$

where $i \in [1, 2, 3, \dots, F]$, $j \in [1, 2, 3, \dots, D]$, $k \in [1, 2, 3, \dots, F]$ and ϕ_{ij} is a random number $\in [-1, 1]$.

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Equation 2

Given the number of food sources F , the probability p_i for a food source i will be calculated by the formula:

$$p_i = \frac{fit_i}{\sum_{n=1}^F fit_n}$$

where $i \in [1, 2, 3, \dots, F]$.

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where $i \in [1, 2, 3, \dots, F]$.

- The chosen food sources will be exploited. If a new food source with better fitness is found, the old one is forgotten.

Scouts phase

- If a food source was not changed in a cycle, its trial counter will rise.
- At the end of every cycle, the food source with the biggest trial counter will receive a random solution if its trial counter is bigger than the parameter *limit*.

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Why does it work?

- As said by [3] the ABC algorithm performs different selection process:
 - a global selection process performed by the onlookers;
 - a local selection process performed by onlookers and employed bees;
 - a random selection process performed by scouts.

Why does it work?

- As said by [3] the ABC algorithm performs different selection process:
 - a global selection process performed by the onlookers;
 - a local selection process performed by onlookers and employed bees;
 - a random selection process performed by scouts.
- The employed bees and onlookers are responsible for **the exploitation process** in the search space, while the scouts are responsible for the **exploration process**.

Implementation

- You can find the python code on <https://goo.gl/B6tTgv>.

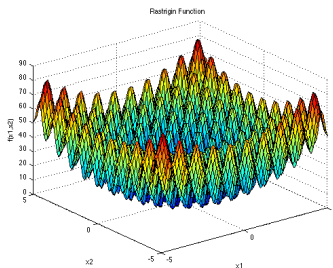
Implementation

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- To validate my implementation, I will test the algorithm with a function from [3] using the same parameters and compare the results.

Rastrigin function

$$f(x_1 \cdots x_n) = 10n + \sum_{i=1}^n (x_i^2 - 10 \cos(2\pi x_i))$$

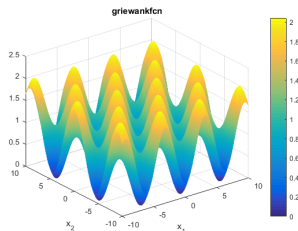
- It is a multimodal function with locations of the minima regularly distributed. The interval is $-15 \leq x_i \leq 15$ and the function has its global minimum at $f(0, \dots, 0) = 0$.



Griewank function

$$f(x_1 \cdots x_n) = 1 + \frac{1}{4000} \sum_{i=1}^n x_i^2 - \prod_{i=1}^n \cos\left(\frac{x_i}{\sqrt{i}}\right)$$

- It is a multimodal function with locations of the minima regularly distributed. The function has a interdependence between variables. The interval is $-600 \leq x_i \leq 600$ and the function has its global minimum at $f(0, \cdots, 0) = 0$.



Parameters

- 50% of employed bees, 50% of onlookers, one scout.
- `population_size`: 125.
- `maximum_cycle_number`: 500.
- `dimension`: 10.
- `limit`: 50.
 - The author did not write about this parameter in [3].
- Each experiment was repeated 30 times.

Results

Table: Comparison of results

	Results from [3]		My results	
	Mean	SD	Mean	SD
Rastrigin	0	0	$1.76 * 10^{-12}$	$2.83367 * 10^{-12}$
Griewank	0.000870	0.002535	0.000142	0.000497

Examples of applications

As showed by [2], the ABC algorithm has already been successfully applied to Search-based Software Engineering problems. Some examples are:

- software test case optimization;
- automated generation of structural tests;
- automated software refactoring;

References

- [1] Dervis Karaboga. An idea based on honey bee swarm for numerical optimization. Technical report, 2005.
- [2] Dervis Karaboga, Beyza Gorkemli, Celal Ozturk, and Nurhan Karaboga. A comprehensive survey: Artificial bee colony (abc) algorithm and applications. *Artif. Intell. Rev.*, 42(1):21–57, June 2014.
- [3] Dervis Karaboga and Bahriye Basturk. A powerful and efficient algorithm for numerical function optimization: Artificial bee colony (abc) algorithm. *J. of Global Optimization*, 39(3):459–471, November 2007.

Thank you for your attention!

<https://goo.gl/B6tTgv>
almeida.warley@outlook.com