

13 Gaussian Process Regression

[See STAT 4430/5430]

DEF $\underline{x} = (x_1, \dots, x_n)^T$ is $MVN(\underline{\mu}, \Sigma)$ if it has pdf

$$\frac{1}{\sqrt{(2\pi)^n \det \Sigma}} \exp \left(-\frac{1}{2} (\underline{x} - \underline{\mu})^T \Sigma^{-1} (\underline{x} - \underline{\mu}) \right)$$

$$\bullet \underline{\mu} = \begin{pmatrix} E x_1 \\ E x_2 \\ \vdots \\ E x_n \end{pmatrix}$$

↓
Avg behavior of
each variable

$$\bullet \Sigma = \left(\text{Cov}(x_i, x_j) \right)_{i,j=1}^n$$

↓
Covariances / Correlations
between variables

Model For $\underline{x} = (x_1, \dots, x_p)^T$ features & response y ,
the model is:

$$y = f(\underline{x}) + \varepsilon$$

where ε is mean zero uncorrelated error and f is
a random function in some class of functions

DEF A Gaussian process (GP) $f(\underline{x})$ is a random

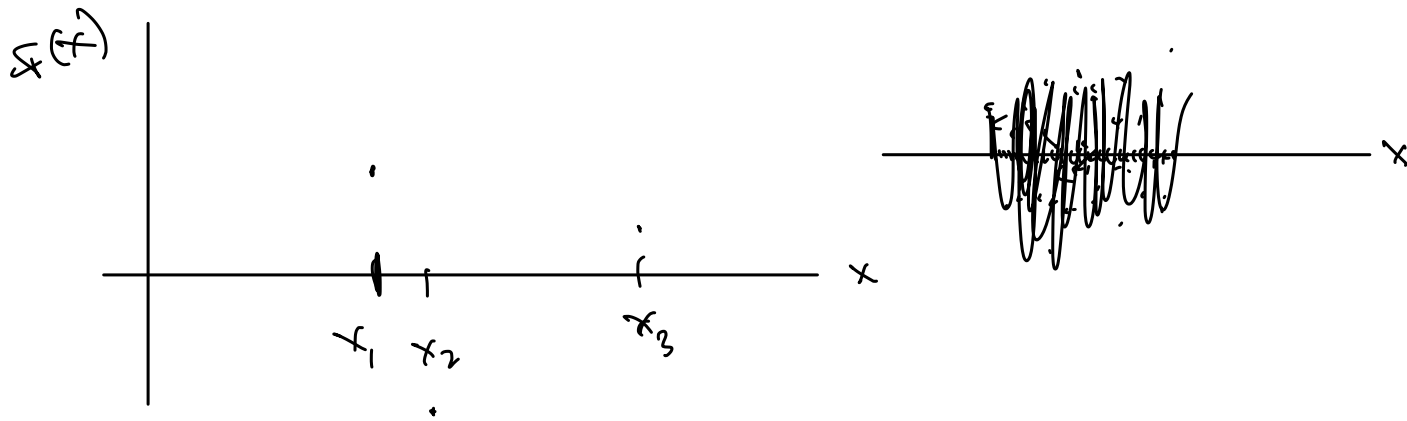
function with

$$\begin{pmatrix} f(\underline{x}_1) \\ f(\underline{x}_2) \\ \vdots \\ f(\underline{x}_n) \end{pmatrix} \sim \text{MVN} \quad \text{for any choices of } \underline{x}_1, \underline{x}_2, \dots, \underline{x}_n$$

Ex

$p=1$, $f(x) \sim N(0,1)$ and independent for any x_i, x_j .

$$\begin{pmatrix} f(x_1) \\ f(x_2) \\ f(x_3) \end{pmatrix} \sim N_3 \left(\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \right)$$



Building GP framework

$f(\underline{x})$ being random \Leftrightarrow putting a prior distribution on f

Simple model

$$f(\underline{x}) = \beta_1 x_1 + \beta_2 x_2 + \dots + \beta_p x_p$$

$$y = f(\underline{x}) + \varepsilon$$

with

- $\varepsilon \stackrel{iid}{\sim} N(0, \sigma^2)$

here
is where
 β gets
random

- $\beta = \begin{pmatrix} \beta_1 \\ \vdots \\ \beta_p \end{pmatrix} \sim N_p(\underline{0}, \Sigma)$ with $\Sigma_{ij} = \text{Cor}(\beta_i, \beta_j)$

Thus,

$$f(\underline{x}) \sim N(0, \underline{x}^T \Sigma \underline{x})$$

$$\text{and } \underline{f} = \begin{pmatrix} f(\underline{x}_1) \\ \vdots \\ f(\underline{x}_n) \end{pmatrix} \sim N(\underline{0}, X^T \Sigma X) \text{ with } X = [\underline{x}_1, \underline{x}_2, \dots, \underline{x}_n]^T$$

$\Rightarrow f(x) \sim \text{Gaussian process}$

Note Given data y at $\underline{x}_1, \dots, \underline{x}_n$, the observational model is $[y | \underline{f}] \sim N(X \underline{f}, \sigma^2 I)$

[looks like AI!]. But goal: get posterior dist of \underline{f} :

$$[\underline{f} | y] = \frac{[y | \underline{f}][\underline{f}]}{[y]}$$

Under this setup

$$\Sigma_{\underline{f} | y} \sim N_p \left(\frac{1}{\sigma^2} \left(\frac{1}{\sigma^2} X^T X + \Sigma^{-1} \right)^{-1} X^T y, \right.$$

$$\left. \left(\frac{1}{\sigma^2} X^T X + \Sigma^{-1} \right)^{-1} \right) = N_p(\underline{f}_{\text{post}}, \Sigma_{\text{post}})$$

Prediction Prediction at new x_* given y is:

$$[f(x_*) | y] \sim N(x_*^T \beta_{\text{post}}, x_*^T \Sigma_{\text{post}} x_*)$$

[looks a lot like OLS prediction]

Problem This model is still linear in each x_i .

Aquid tour Suppose $p=1$. Instead of $y = \beta x + \varepsilon$, use

$$y = \beta_1 \phi_1(x) + \beta_2 \phi_2(x) + \dots + \beta_N \phi_N(x) + \varepsilon$$

for some transformations ϕ_1, \dots, ϕ_N .

Under certain assumptions on ϕ_1, \dots + β_1, \dots
we get, as $N \rightarrow \infty$,

$$E f(x) = 0 \quad \text{and} \quad \text{Cor}(f(x_1), f(x_2)) = k(x_1, x_2)$$

where $k(\cdot, \cdot)$ is a positive definite function.

Remark Most GP models specify a mean function

$$\mathbb{E} f(x) = \mu(x) \quad \text{and a } \underline{\text{covariance function}}$$

$$k(x_1, x_2) = \text{Cov}(f(x_1), f(x_2))$$

- $\mu + k$ tell us how to build $\underline{\mu} + \Sigma$ in $\underline{f} \sim N(\underline{\mu}, \Sigma)$.

Remark Different choices of k imply different behavior of the random function f .

A final note If $y = f(x) + \varepsilon$ observed at x_1, \dots, x_n , and $\mathbb{E}(\varepsilon) = 0$, $\text{var}(\varepsilon) = \sigma^2$, the fitted values of $f(x_1), \dots, f(x_n)$ given data are

$$[\underline{f} | \underline{y}] \sim N(\Sigma(\Sigma + \sigma^2 \mathbf{I})^{-1} \underline{y}, \Sigma - \Sigma(\Sigma + \sigma^2 \mathbf{I})^{-1} \Sigma)$$

$$\text{where } \Sigma = (k(x_i, x_j))_{i, j=1}^n$$