

Mean Estimation from One-bit Measurements

Alon Kipnis (Stanford)
John Duchi (Stanford)

Allerton
October 2017

Table of Contents

Introduction

Motivation

Preliminary

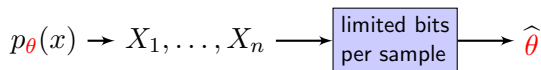
Adaptive Encoding

Distributed Encoding

Summary

Motivation

Point estimation under communication constraints:



Estimation error is due to:

- (i) limited data
- (ii) limited bits

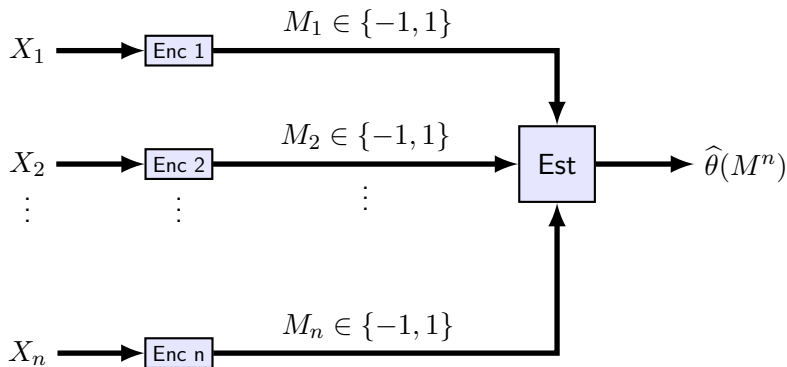
Relevant scenarios:

- ▶ big data
- ▶ low-power sensors
- ▶ distributed computing / optimization (bottleneck is due to communication between processing units)

This talk:

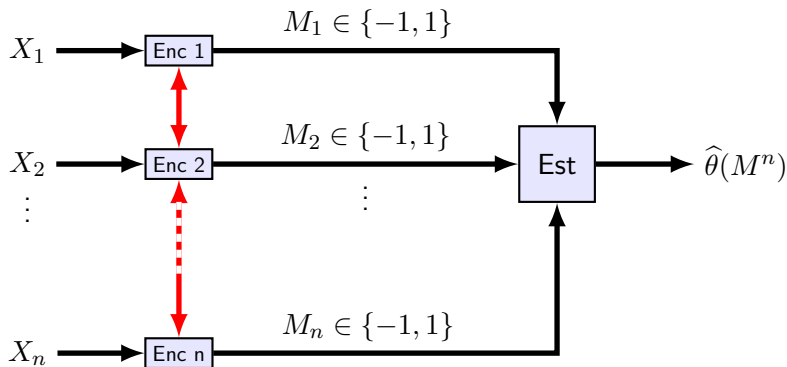
Estimating the mean θ of a normal distribution $\mathcal{N}(\theta, \sigma^2)$ from one-bit per sample (σ is known)

Three Encoding Scenarios



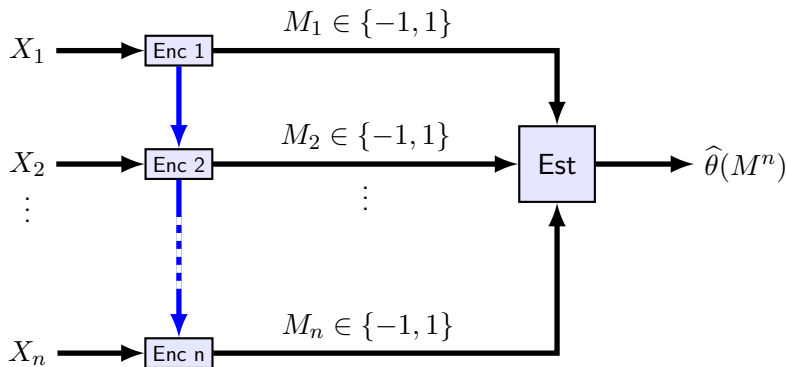
- Distributed: $M_i = f_i(X_i)$

Three Encoding Scenarios



- ▶ Distributed: $M_i = f_i(X_i)$
- ▶ Centralized: $M^n = (M_1, \dots, M_n) = f(X_1, \dots, X_n)$

Three Encoding Scenarios



- ▶ Distributed: $M_i = f_i(X_i)$
- ▶ Centralized: $M^n = (M_1, \dots, M_n) = f(X_1, \dots, X_n)$
- ▶ Adaptive / Sequential: $M_i = f_i(X_i, M^{i-1})$

Related Work

- ▶ Estimation via compressed information [Han '87], [Zhang & Berger '88]
- ▶ Distributed hypothesis testing under quantization [Tsitsiklis '88]
- ▶ Estimation from multiple machines subject to a bit constraint [Zhang, Duchi, Jordan, Wainwright '13]
- ▶ Remote multiterminal source coding (CEO) [Berger, Zhang, Viswanathan '96], [Oohama '97]

Consistency

Q: in what setting consistent estimation is possible?

Consistency

Q: in what setting consistent estimation is possible?

A: all !

$$M_i = \mathbf{1}(X_i > 0), \quad i = 1, \dots, n$$

(as in the distributed setting)

$$\frac{1}{n} \sum_{i=1}^n M_i \rightarrow \mathbb{P}(X < 0) = \Phi(X/\sigma < \theta)$$

Efficiency

Definition: *asymptotic relative efficiency (ARE)* of an estimator:

$$\text{ARE}(\hat{\theta}) \triangleq \lim_{n \rightarrow \infty} \frac{\mathbb{E} \left[\left(\hat{\theta} - \theta \right)^2 \right]}{\sigma^2/n}$$

(σ^2/n is the minimax risk without communication constraints)

Efficiency

Definition: *asymptotic relative efficiency (ARE)* of an estimator:

$$\text{ARE}(\hat{\theta}) \triangleq \lim_{n \rightarrow \infty} \frac{\mathbb{E} \left[\left(\hat{\theta} - \theta \right)^2 \right]}{\sigma^2/n}$$

(σ^2/n is the minimax risk without communication constraints)

Q: in what scenarios the ARE is finite?

Efficiency

Definition: *asymptotic relative efficiency (ARE)* of an estimator:

$$\text{ARE}(\hat{\theta}) \triangleq \lim_{n \rightarrow \infty} \frac{\mathbb{E} \left[\left(\hat{\theta} - \theta \right)^2 \right]}{\sigma^2/n}$$

(σ^2/n is the minimax risk without communication constraints)

Q: in what scenarios the ARE is finite?

This talk: all three scenarios

ARE under Centralized Encoding

Proposition

If the parameter space Θ is bounded, then the ARE under centralized encoding is 1

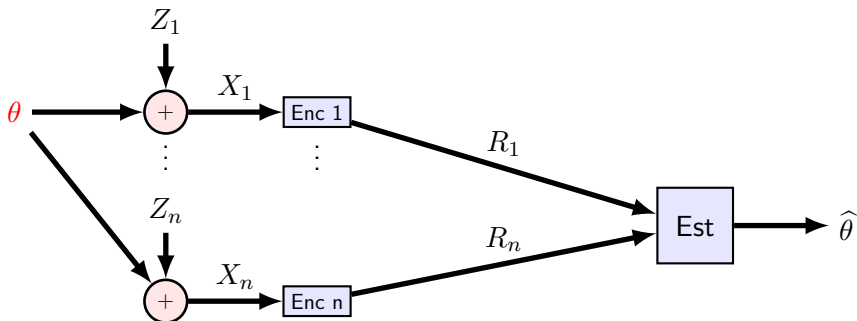
Proof:

$$\mathbb{E} \left(\theta - \hat{\theta} \right)^2 = \overbrace{\mathbb{E} \left(\theta - \bar{\theta} \right)^2}^{\sigma^2/n} + \mathbb{E} \left(\bar{\theta} - \hat{\theta} \right)^2$$

- ▶ Encoder is required to describe $\bar{\theta}$ using n bits
 - ▶ divide parameter space Θ into 2^n regions of equal size
 - ▶ send region index where $\bar{\theta}$ falls
- ▶ MSE in estimating $\bar{\theta}$ decreases exponentially in n

Note: globally optimal strategy for a finite n is hard to derive since mean of $\bar{\theta}$ is unknown

Relation to CEO



Assume:

- ▶ $\theta \sim \mathcal{N}(0, \sigma_\theta^2)$,
- ▶ $Z_1, \dots, Z_n \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(0, \sigma^2)$

Encode k instances:

- ▶ $R_1 = \dots = R_n = 1$
- ▶ $D_{CEO} = \frac{1}{k} \sum_{j=1}^k \mathbb{E} \left(\theta_j - \hat{\theta}_j \right)^2$

From [K., Rini, Goldsmith '17]:

$$D_{CEO} \leq \frac{4}{3} \frac{\sigma^2}{n} + o(1)$$

ARE of $4/3$ can be attained in a fully distributed encoding (with encoding over blocks of multiple problem instances)

Conclusion

Distributed encoding is almost not a limiting factor (although inability to exploit concentration of measure in high dimension – might!)

Table of Contents

Introduction

Motivation

Preliminary

Adaptive Encoding

Distributed Encoding

Summary

Main Results (adaptive encoding)

Theorem (converse)

No estimator have ARE lower than $\pi/2$

Theorem (achievability)

Assume that Θ is a bounded interval. There exists an estimator with ARE equals to $\pi/2$

Theorem (one-step optimal strategy)

The next step one-bit message that minimizes the MSE is of the form $M = \text{sign}(X - \tau)$ where τ satisfies the fixed-point equation

$$\tau = \frac{1}{2} \left(\frac{\int_{-\infty}^{\tau} \theta \pi(d\theta)}{\int_{-\infty}^{\tau} \pi(d\theta)} + \frac{\int_{\tau}^{\infty} \theta \pi(d\theta)}{\int_{\tau}^{\infty} \pi(d\theta)} \right)$$

Proof

converse ($\text{ARE} \geq \pi/2$)

Assume a prior $\pi(d\theta)$ on Θ with location Fisher information I_π .
The van-Trees inequality (e.g. [Tsybakov '08]) implies

$$\mathbb{E} \left(\theta - \hat{\theta} \right)^2 \geq \frac{1}{\mathbb{E} I_\theta(M^n) + I_\pi} \geq \frac{1}{\sum_{i=1}^n I_\theta(M_i | M^{i-1}) + I_\pi}$$

Lemma

$$I_\theta(M_i | M^{i-1}) \leq 2/(\pi\sigma^2)$$

(proof by induction over a finite set of intervals approximating $M_i^{-1}(1)$ given M^{i-1})

Proof

achievability (existence of an estimator with $\text{ARE} = \pi/2$)

[Polyak & Juditsky '92]:

$$\begin{cases} \theta_i = \theta_{i-1} + \gamma_i \varphi(X_i - \theta_i) & i = 1, \dots, n \\ \hat{\theta} = \frac{1}{n} \sum_{i=1}^n \theta_i \end{cases}$$

where:

- (i) $\gamma_n \rightarrow 0^+$ “not too slow”
- (ii) $\psi(x) = \mathbb{E}\varphi(x + Z)$
- (iii) $\chi(x) = \mathbb{E}\varphi^2(x + Z)$
- (iv) some regularity conditions on φ, χ, ψ

Then

$$\sqrt{n}(\theta - \hat{\theta}) \rightarrow \mathcal{N}(0, V)$$

where $V = \chi(0)/\psi'^2(0)$.

Proof

achievability (existence of an estimator with $\text{ARE} = \pi/2$)

[Polyak & Juditsky '92]:

$$\begin{cases} \theta_i = \theta_{i-1} + \gamma_i \varphi(X_i - \theta_i) & i = 1, \dots, n \\ \hat{\theta} = \frac{1}{n} \sum_{i=1}^n \theta_i \end{cases}$$

where:

- (i) $\gamma_n \rightarrow 0^+$ “not too slow”
- (ii) $\psi(x) = \mathbb{E}\varphi(x + Z)$
- (iii) $\chi(x) = \mathbb{E}\varphi^2(x + Z)$
- (iv) some regularity conditions on φ, χ, ψ

Then

$$\sqrt{n}(\theta - \hat{\theta}) \rightarrow \mathcal{N}(0, V)$$

where $V = \chi(0)/\psi'^2(0)$.

Proof of theorem: take $\varphi(x) = \text{sign}(x)$

One-step optimality

Theorem

Let $\pi(\theta)$ be an absolutely continuous log-concave distribution. For $X \sim \mathcal{N}(\theta, \sigma^2)$ let

$$M = \text{sign}(X - \tau)$$

where τ is the unique solution to

$$\tau = \frac{1}{2} \left(\frac{\int_{-\infty}^{\tau} \theta \pi(d\theta)}{\int_{-\infty}^{\tau} \pi(d\theta)} + \frac{\int_{\tau}^{\infty} \theta \pi(d\theta)}{\int_{\tau}^{\infty} \pi(d\theta)} \right)$$

Then for any $M'(X) \in \{-1, 1\}$ and $\hat{\theta}(M')$:

$$\mathbb{E} \left(\theta - \hat{\theta}(M') \right)^2 \geq \mathbb{E} \left(\theta - \mathbb{E}[\theta|M] \right)^2$$

Interpretation:

The optimal one-bit message is a threshold detector. The threshold is the fixed-point that balances conditional center of masses given the message

One-step Optimal Scheme

Initialization: $P_0(t) = \pi(\theta)$

Repeat for $n \geq 1$:

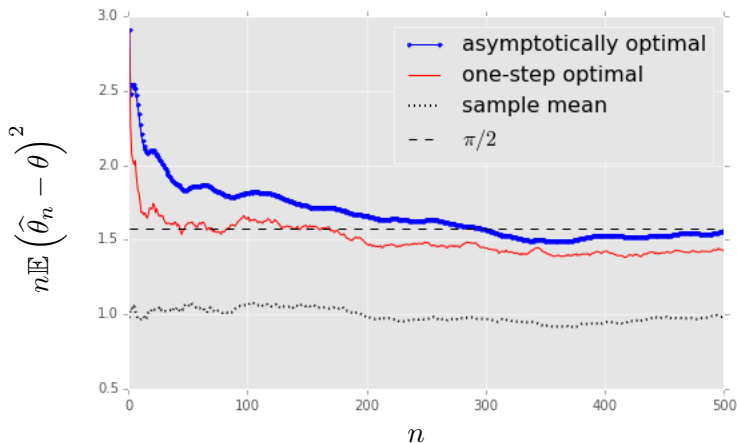
- (i) $P_n(t) = \mathbb{P}(\theta = t | M^n) = \alpha_n P_{n-1}(t) \Phi \left(M_n \frac{t - \tau_{n-1}}{\sigma} \right)$
- (ii) $\hat{\theta} = \mathbb{E}[\theta | M^n] = \int t P_n(t) dt$
- (iii) Find τ_n from

$$\tau_n = \frac{1}{2} \left(\frac{\int_{-\infty}^{\tau} t P_n(t) dt}{\int_{-\infty}^{\tau} P_n(t) dt} + \frac{\int_{\tau}^{\infty} t P_n(t) dt}{\int_{\tau}^{\infty} P_n(t) dt} \right)$$

- (iv) $M_{n+1} = \text{sign}(X_{n+1} - \tau_n)$

Numerical Example

Normalized empirical risk versus number of samples n
(500 Monte Carlo experiments)



$$\theta \sim \text{unif}(-3, 3)$$

Table of Contents

Introduction

Motivation

Preliminary

Adaptive Encoding

Distributed Encoding

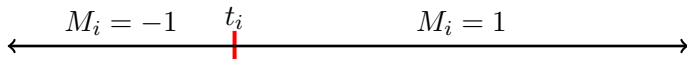
Summary

Distributed Encoding

Threshold Detection

We consider only messages of the form

$$M_i = \text{sign}(X_i - t_i), \quad i = 1, \dots, n$$



Assume:

$$\lambda_n([a, b]) = \frac{1}{n} |[a, b] \cap \{t_i\}|$$

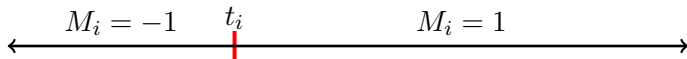
converges weakly to a probability distribution λ

Distributed Encoding

Threshold Detection

We consider only messages of the form

$$M_i = \text{sign}(X_i - t_i), \quad i = 1, \dots, n$$



Assume:

$$\lambda_n([a, b]) = \frac{1}{n} |[a, b] \cap \{t_i\}|$$

converges weakly to a probability distribution λ

Example: t_1, \dots, t_n are drawn independently from a probability distribution λ on \mathbb{R}

Main Results (distributed encoding)

Theorem

(i) For any estimator $\hat{\theta}$:

$$\liminf_{c \rightarrow \infty} \liminf_{n \rightarrow \infty} \sup_{\tau: |\tau - \theta| \leq \frac{c}{\sqrt{n}}} n \mathbb{E} \left(\hat{\theta} - \tau \right)^2 \geq \sigma^2 / K(\theta),$$

where:

$$K(\theta) = \int_{\mathbb{R}} \eta \left(\frac{t - \theta}{\sigma} \right) \lambda(dt)$$
$$\eta(x) = \frac{\phi^2(x)}{\Phi(x)\Phi(-x)}$$

(ii) The Maximum likelihood estimator $\hat{\theta}_{ML}$ satisfies

$$\sqrt{n}(\theta - \hat{\theta}_{ML}) \rightarrow \mathcal{N}(0, \sigma^2 / K(\theta))$$

Interpretations

- ▶ ML estimator is local asymptotically minimax
- ▶ ARE of ML is $1/K(\theta)$ – depends only in the asymptotic threshold density λ



$$1/K(\theta) = \frac{1}{\int \eta\left(\frac{t-\theta}{\sigma}\right) \lambda(dt)} \geq \frac{1}{\int \eta(0) \lambda(dt)} = \pi/2$$

(attained by $\lambda(dt) = \delta_\theta$)

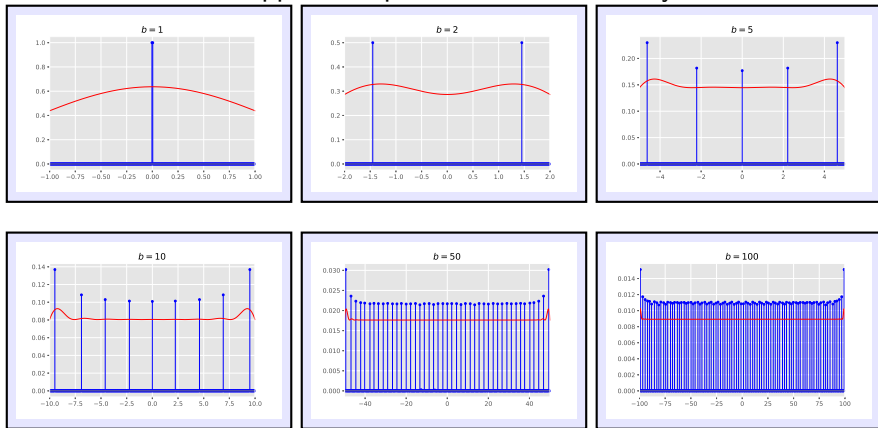
- ▶ Minimax λ for $\theta \in (-b\sigma, b\sigma)$:

$$\text{maximize} \quad \inf_{\tau \in (-b, b)} \int \eta(t - \tau) \lambda(dt)$$

$$\text{subject to} \quad \lambda(dt) \geq 0, \quad \int \lambda(dt) \leq 1.$$

Minimax λ

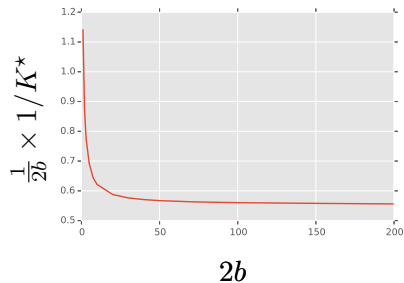
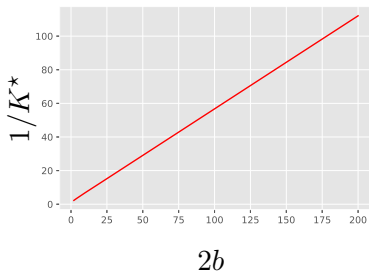
support of optimal threshold density λ^*



$$K^* = \inf_{\theta} K^*(\theta) = \inf_{\theta} \int \eta(t - \theta) \lambda^*(dt)$$

Minimax λ

Minimax ARE vs size of parameter space



- ▶ ARE increases with size of parameter space

Table of Contents

Introduction

Motivation

Preliminary

Adaptive Encoding

Distributed Encoding

Summary

Summary

- ▶ Asymptotic relative efficiency in adaptive setting is $\pi/2$ regardless of size of parameter space – only ~ 1.57 more samples are required due to 1-bit constraints
- ▶ One-step optimal one-bit message is a threshold detector
- ▶ ARE in distributed setting is finite
- ▶ ML estimator is local asymptotically optimal for threshold detection
- ▶ ARE of ML is characterized by asymptotic density of threshold values
- ▶ Minimax ARE of ML depends on size of parameter space

Open question

Is there a distributed encoding scheme with ARE that is both finite and independent of size of parameter space ?