

4.2.2.

[a b c d]

The following ARQ protocol is considered:

- Sending frame continuously
- On rec incorrect: nothing
- on ev correct: sends ACK
- On rec ACK: sender starts sending next frame continuously
- Tx and error prob. are negligible for ACKs

Answer:

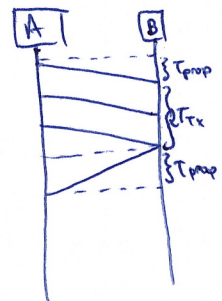
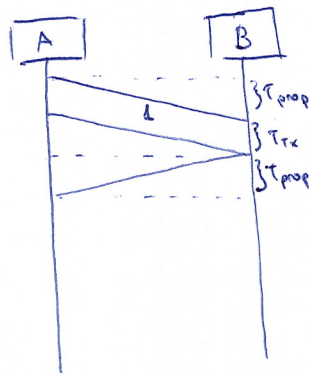
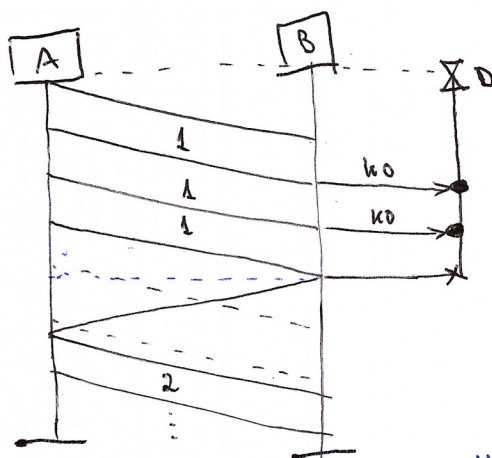
a) Calculate the efficiency of this protocol based on frame error prob. P_e and on

$$a = \frac{T_{prop}}{T_{tx}}$$

b) Is the efficiency $>$ or $<$ than ~~stop~~ SDW? Reason the answer

c) For which P_e is eff. $>$ GBN?

d) Calculate avg. time from tx start of a frame until correct receipt (D)



$$a) P(N_{\text{att}}=1) = \underbrace{(1-P_e)}_{\text{No err}}; P(N_{\text{att}}=2) = \underbrace{P_e}_{\text{err}} \underbrace{(1-P_e)}_{\text{No err}}; P(N_{\text{att}}=k) = P_e^{k-1} (1-P_e)$$

$$T_{\text{tx}}(N_{\text{att}}=1) = 2T_{\text{prop}} + T_{\text{tx}}; T_{\text{tx}}(N_{\text{att}}=2) = 2T_{\text{prop}} + 2T_{\text{tx}}; T_{\text{tx}}(N_{\text{att}}=k) = 2T_{\text{prop}} + kT_{\text{tx}}$$

$$T_{\text{avg}} = \sum_{k=1}^{\infty} P(N_{\text{att}}=k) \cdot T_{\text{tx}}(N_{\text{att}}=k) = \sum_{k=1}^{\infty} P_e^{k-1} (1-P_e) (2T_{\text{prop}} + kT_{\text{tx}}) = (1-P_e) \left(2T_{\text{prop}} \sum_{k=1}^{\infty} P_e^{k-1} + T_{\text{tx}} \sum_{k=1}^{\infty} k P_e^{k-1} \right) =$$

$$= (1-P_e) \left(\frac{2T_{\text{prop}}}{1-P_e} + \frac{T_{\text{tx}}}{(1-P_e)^2} \right) = 2T_{\text{prop}} + \frac{T_{\text{tx}}}{1-P_e}$$

$$\eta = \frac{T_{\text{tx}}}{T_{\text{avg}}} = \frac{T_{\text{tx}}}{2T_{\text{prop}} + \frac{T_{\text{tx}}}{1-P_e}} = \frac{1}{\frac{2T_{\text{prop}}}{T_{\text{tx}}} + \frac{1}{1-P_e}} = \frac{1-P_e}{1 + 2a(1-P_e)}$$

b) It is more efficient than the equivalent system using SDW ($\eta_{\text{SDW}} = \frac{1-P_e}{1+2a}$) because the $(1-P_e)$ factor in the denominator makes it smaller, making the efficiency higher. In this protocol, we remove the need for negative acknowledgment and the delays it brings.