

... 234. (2)

d) Given $y(1)=0$ show that the system is linear but not time invariant.

$$\begin{aligned} \text{Let } x_1(t) &\rightarrow y_1(t) = \frac{d}{dt} y_1(t) + 2y_1(t) = x_1(t), & y_1(1) &= 0 \\ x_2(t) &\rightarrow y_2(t) = \frac{d}{dt} y_2(t) + 2y_2(t) = x_2(t), & y_2(1) &= 0 \end{aligned}$$

~~$$x_3(t) \rightarrow y_3(t) = \frac{d}{dt} y_3(t) + 2y_3(t) = x_3(t), \quad y_3(1) = 0$$~~

$$\text{Then: } \alpha \frac{d}{dt} y_1(t) + 2\alpha y_1(t) + \beta \frac{d}{dt} y_2(t) + 2\beta y_2(t) = \alpha x_1(t) + \beta x_2(t), \quad \alpha y_1(t) + \beta y_2(t) = 0 \Rightarrow$$

$$\Rightarrow \frac{d}{dt} (\alpha y_1(t) + \beta y_2(t)) + 2(\alpha y_1(t) + \beta y_2(t)) = \alpha x_1(t) + \beta x_2(t), \quad \alpha y_1(t) + \beta y_2(t) = 0$$

It's easy to see that $\alpha x_1(t) + \beta x_2(t) \rightarrow \alpha y_1(t) + \beta y_2(t) \Rightarrow$ linear system

$$\text{Let } x_1(t) = e^t u(t) \rightarrow y_1(t) = y_h(t) + y_p(t) = \left(-\frac{1}{3} e^{3-2t} + \frac{1}{3} e^t\right) u(t) \quad \text{Solved using the methods we know}$$

~~$$\text{Now let } x_2(t) = e^{t-T} u(t-T)$$~~

$$\text{Now let } x_2(t) = x_1(t-T) = e^{t-T} u(t-T) \rightarrow y_2(t) = \left(-\frac{1}{3} e^{3-2t} + \frac{1}{3} e^t\right) u(t-T)$$

$$y_1(t-T) = \left(-\frac{1}{3} e^{3-2t} + \frac{1}{3} e^t\right) u(t-T) \neq y_2(t) \Rightarrow \text{not time invariant}$$

e) Given $y(0)+y(4)=0$, show that the system is linear but not time invariant.

$$\begin{aligned} \text{Let } x_1(t) &\rightarrow y_1(t) = \frac{d}{dt} y_1(t) + 2y_1(t) = x_1(t), & y_1(0)+y_1(4) &= 0 \\ x_2(t) &\rightarrow y_2(t) = \frac{d}{dt} y_2(t) + 2y_2(t) = x_2(t), & y_2(0)+y_2(4) &= 0 \end{aligned}$$

$$\text{Then: } \alpha \frac{d}{dt} y_1(t) + 2\alpha y_1(t) + \beta \frac{d}{dt} y_2(t) + 2\beta y_2(t) = \alpha x_1(t) + \beta x_2(t), \quad \alpha y_1(0) + \alpha y_1(4) + \beta y_2(0) + \beta y_2(4) = 0+0 \Rightarrow$$

$$\Rightarrow \frac{d}{dt} (\alpha y_1(t) + \beta y_2(t)) + 2(\alpha y_1(t) + \beta y_2(t)) = \alpha x_1(t) + \beta x_2(t), \quad \alpha y_1(0) + \alpha y_1(4) + \beta y_2(0) + \beta y_2(4) = 0 \Rightarrow$$

$$\Rightarrow \alpha x_1(t) + \beta x_2(t) \rightarrow \alpha y_1(t) + \beta y_2(t) \Rightarrow \text{linear}$$

$$\text{Let } x_1(t) = e^t u(t) \rightarrow y_1(t) = \frac{d}{dt} y_1(t) + 2y_1(t) = x_1(t)$$

$$y_h(t) = A e^{-2t} u(t), \quad y_p(t) = B e^t u(t) = \frac{1}{3} e^t u(t) \Rightarrow B = \frac{1}{3}$$

$$y_1(0)+y_1(4)=0 = y_h(0)+y_p(0)+y_h(4)+y_p(4) = A e^0 + \frac{1}{3} + A e^{-8} + \frac{1}{3} e^4 \Rightarrow A = \left(-\frac{1}{3} - \frac{1}{3} e^4\right) \cdot \frac{1}{1+e^8}$$

$$y_1(t) = \left(-\frac{1}{3} - \frac{1}{3} e^4\right) \frac{e^{-2t}}{1+e^8} + \frac{1}{3} e^t u(t)$$

$$\text{Let } x_2(t) = x_1(t-T) = e^{t-T} u(t-T)$$

$$y_h(t) = A e^{-2t} u(t-T); \quad y_p(t) = B e^{t-T} u(t-T) = \frac{1}{3} e^{t-T} u(t-T) \Rightarrow B = \frac{1}{3}$$

~~$$y_1(t) + y_2(t) = 0$$~~

Let's take some $T < 0$ and $T < t$

$$y_2(0)+y_2(4)=0 = A e^0 + B e^{0-T} + A e^{-8} + B e^{4-T} \Rightarrow A = \left(-\frac{e^{-T}}{3} - \frac{e^{4-T}}{3}\right) \frac{1}{1+e^8}$$

$$y_2(t) = \left(-\frac{e^{-T}}{3} - \frac{e^{4-T}}{3}\right) \frac{e^{-2t}}{1+e^8} + \frac{1}{3} e^{t-T} u(t-T)$$

$$y_1(t-T) = \left(-\frac{1}{3} - \frac{1}{3} e^4\right) \frac{e^{-2(t-T)}}{1+e^8} + \frac{1}{3} e^{t-T} u(t-T) \neq y_2(t) \Rightarrow \text{not time invariant}$$