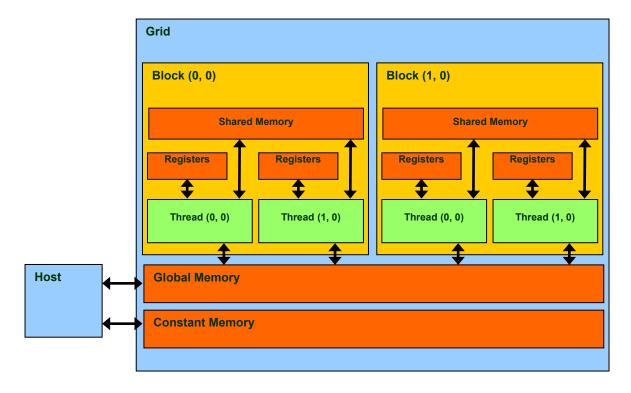
ECE569 Module 16



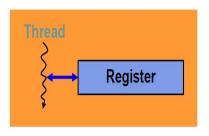
• CUDA Memories

Minimize time spent on memory

- Move frequently accessed data to fast memory
 - local < shared << global << host</p>
 - local is either in registers or L1 cache



Variable declaration	Location	Memory	Cached	Scope	Lifetime
int LocalVar;	On-chip	register	N/A	thread	thread
deviceshared int SharedVar;	On-chip	shared	N/A	block	Threads in a block
device int GlobalVar;	Off-chip	global	Yes	grid	application
deviceconstant int ConstantVar;	Off-chip	constant	Yes	grid	application



Register:

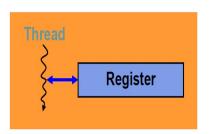
- One version for every thread (private per thread)
 - Carefully selecting a few registers instead of using 50 per thread can easily double the number of concurrent blocks.

Compute Capability (Registers, Shared Memory)

Technical Specifications	3.5	3.7	5.0	5.2	5.3	6.0	6.1	6.2	7.0	7.2	7.5	8.0	8.6
Max # of resident blocks per SM	16 32			32				16	32	16			
Max # of resident warps per SM		64								32	64	48	
Max # of resident threads per SM		2048						1024 2048 1536				1536	
Number of 32-bit registers per SM	64 K	128 K						64 K					
Max # of 32-bit registers/thread block	64 K 32 K 64			1 K	32 K	64 K							
Max # of 32-bit registers per thread			i				255				i	i	•
Maximum shared memory per SM	48 KB	112 KB	64 KB	96 KB	64	KB	96 KB	64 KB	96	KB	64 KB	164 KB	100 KB
Shared memory per thread block			<u>!</u>	48	KB				96 KB	48 KB	64 KB	163 KB	99 KB
Number of shared memory banks						32				•	•		
Local memory per thread					512 KB								
Constant memory size							64 KB						

- To run maximum number of threads on CUDA compute capability 6.1
 - How many registers per thread should be used?

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Register:

- Local memory is used automatically by NVCC when we run out of registers or when registers cannot be used - <u>register spilling</u>.
- Automatic variables reside in a register
 - Except per-thread arrays that reside in global memory

Ways to minimize time spent on memory accesses

- Move frequently accessed data to fast memory
 - Indicate local variables. Choose all that apply:

```
/* using local memory */
// a device or global function runs on the GPU
global void use local memory GPU(float in, float *x)
 float f;
                                                \Box in
 f = x[in];
                                                \sqcup x
                                                \square x[in]
int main(int argc, char **argv)
    /* Call a kernel that shows using local memory */
    use local memory GPU <<<1, 128>>> (2.0f);
```

Ways to minimize time spent on memory accesses

- Move frequently accessed data to fast memory
 - Local > Shared >> Global

```
/* using local memory */

// a __device__ or __global__ function runs on the GPU
__global__ void use_local_memory_GPU(float in, float* x)
{
   float f; //variable "f" is in local memory and private to each thread
   f = x[in]; //parameter "in" is in local memory and private to each
thread
}
int main(int argc, char **argv)
{
    /* Call a kernel that shows using local memory */
    use_local_memory_GPU<<<1, 128>>>(2.0f);
}
```

Registers

What happens if your application uses a little array?

```
global void lap(float *u) {
float ut[3];
int tid = threadIdx.x+blockIdx.x*blockDim.x;
for (int k=0; k<3; k++)
 ut[k] = u[tid+k*gridDim.x*blockDim.x];
for (int k=0; k<3; k++)
u[tid+k*gridDim.x*blockDim.x] =
A[3*k]*ut[0]+A[3*k+1]*ut[1]+A[3*k+2]*ut[2];
```

Local Arrays

compiler converts to scalar registers:

```
global void lap(float *u) {
int tid = threadIdx.x + blockIdx.x*blockDim.x;
float ut0 = u[tid+0*gridDim.x*blockDim.x];
float ut1 = u[tid+1*gridDim.x*blockDim.x];
float ut2 = u[tid+2*gridDim.x*blockDim.x];
u[tid+0*gridDim.x*blockDim.x] =
A[0]*ut0 + A[1]*ut1 + A[2]*ut2;
u[tid+1*gridDim.x*blockDim.x] =
A[3]*ut0 + A[4]*ut1 + A[5]*ut2;
u[tid+2*gridDim.x*blockDim.x] =
A[6]*ut0 + A[7]*ut1 + A[8]*ut2;
```

Local Arrays

- In more complicated cases, it puts the array into device memory
 - still referred to in the documentation as a "local array" because each thread has its own private copy
 - held in L1 cache by default, may never be transferred to device memory
- Assume 48KB of L1 cache and 1024 threads

— What is the largest integer type array size we can declare without spilling over the L1 cache?

Local Arrays

In more complicated cases, it puts the array into device memory

- still referred to in the documentation as a "local array" because each thread has its own private copy
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Assume 48KB of L1 cache and 1024 threads

- What is the largest integer type array size we can declare without spilling over the L1 cache?
 - equates to 12K 32-bit variables, which is only 12 per thread when using 1024 threads
 - If L1 missed we have to go to global memory eventually

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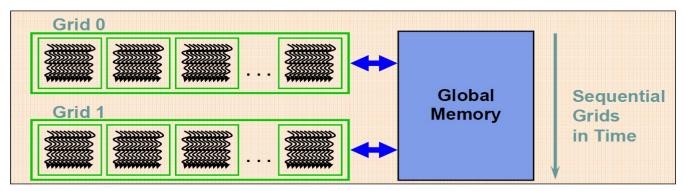
Global:

- __device__ prefix indicates global variable
- read and modify by any kernel
- lifetime of the whole application
- can declare arrays of fixed size
- can read/write by host code using special routines
 - cudaMemcpyToSymbol, cudaMemcpyFromSymbol or with standard cudaMemcpy in combination with cudaGetSymbolAddress

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Global

- One version of the variable, all threads in a grid will see the same version, even though they may not see the most up to date information,
- Blocks can execute out of order (read/write)
 - requires synchronization



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Constant:

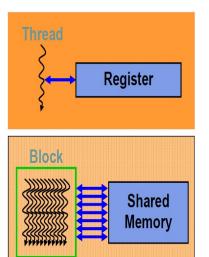
- Very similar to global variables, except that they can't be modified by kernels
- defined using the prefix __constant__
- initialized by the host code
 - cudaMemcpyToSymbol, cudaMemcpyFromSymbol or cudaMemcpy in combination with cudaGetSymbolAddress
- Only 64KB of constant memory
 - big benefit is that each SM has a 8-10KB cache
 - when all threads read the same constant, almost as fast as a register
 - doesn't tie up a register, so very helpful in minimizing the total number of registers required

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__device__ is optional when used with __shared__, or __constant__

Shared

- Explicitly defined and used in the kernel code
- Every block has its own version of the shared memory variable, all threads in a block will read/write to the same version of the shared variable,
 - may not see the most up to date data for the variable, we will need synchronization
- Bank conflicts can slow access down.
- Fastest when
 - all threads read from different banks or
 - all threads of a warp read exactly the same value



Next

- CUDA Memory Review
 - Exercises